

InteliGen 500

Controller for parallel gen-set applications

SW version 1.0.0	
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Global Guide



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1.1 Clarification of notation

Note: This type of paragraph calls readers attention to a notice or related theme.

IMPORTANT: This type of paragraph highlights a procedure, adjustment etc., which can cause a damage or improper function of the equipment if not performed correctly and may not be clear at first sight.

Example: This type of paragraph contains information that is used to illustrate how a specific function works.

1.2 About this Global Guide

This manual contains important instructions for InteliGen 500 controllers family that shall be followed during installation and maintenance of the controllers.

This manual provides general information how to install and operate InteliGen 500 controllers.

This manual is dedicated for:

- Operators
- Control panel builders
- For everybody who is concerned with installation, operation and maintenance

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Name of SW	Modificated	Туре	License condition web address	
CMSIS- FreeRTOS	NO	MIT	https://github.com/ARM-software/CMSIS- FreeRTOS/blob/develop/License/license.txt	
FatFS	NO	BSD	http://elm-chan.org/fsw/ff/00index_e.html	
STpackage (HAL, USB)	YES	MCD- ST Liberty SW V2	http://www.st.com/content/ccc/resource/legal/legal_ agreement/license_agreement/group0/39/50/32/6c/e0/a8/45/2d/ DM00218346/files/DM00218346.pdf/ jcr:content/translations/en.DM00218346.pdf	
mbedTLS	NO	Apache- 2.0	http://www.apache.org/licenses/LICENSE-2.0	
Adafruit GFX	NO	BSD	https://github.com/adafruit/Adafruit-GFX- Library/blob/master/license.txt	
Noto Sans font	YES	SIL Open Font License	https://scripts.sil.org/cms/scripts/page.php?site_id=nrsi&id=OFL web	
heatshrink	NO	ISC License	https://github.com/atomicobject/heatshrink/blob/master/LICENSE	

Used open source software:



Name of SW	Modificated	Туре	License condition web address	
CMSIS	NO	BSD	https://github.com/pfalcon/ARM-CMSIS- BSD/blob/master/CMSIS/CMSIS%20 END%20USER%20LICENCE%20AGREEMENT.pdf	
CMSIS RTOS2 wrapper (cmsis_ os2.c)	YES	Apache- 2.0	www.apache.org/licenses/LICENSE-2.0 Copyright (c) 2013-2019 Arm Limited. All rights reserved.	
LWIP	NO	BSD	http://lwip.wikia.com/wiki/License Copyright (c) 2001-2004 Swedish Institute of Computer Science. All rights reserved	

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General security recommendations and set of measures

- 1. AccessCode
- Change the AccessCode BEFORE the device is connected to a network.
- Use a secure AccessCode ideally a random string of 8 characters containing lowercase, uppercase letters and digits.
- For each device use a different AccessCode.
- 2. Password
- Change the password BEFORE the device enters a regular operation.
- Do not leave displays or PC tools unattended if an user, especially administrator, is logged in.

IMPORTANT: Controller issues WrnDefault Credentials (page 795) or SdDefault Credentials (page 822) alarm, if the factory default password and/or access code are used. It is necessary to change the factory default settings of both password and access code to be able to operate a genset!



3. MODBUS/TCP

• The MODBUS/TCP protocol (port TCP/502) is an instrumentation protocol designed to exchange data between locally connected devices like sensors, I/O modules, controllers etc. From it's nature it does not contain any kind of security – neither encryption nor authentication. Thus it is intended to be used only in closed private network infrastructures.

• Avoid exposing the port TCP/502 to the public Internet.

4. SNMP

• The SNMP protocol (port UDP/161) version 1,2 is not encrypted. Thus it is intended to be used only in closed private network infrastructures.

• Avoid exposing the port UDP/161 to the public Internet.

1.4 General warnings

1.4.1 Remote control and programing

Controller can be remotely controlled. In the event that maintenance of gen-set has to be done, or controller has to be programmed, check the following points to ensure that the engine cannot be started or any other parts of the system cannot be effected.

To be sure:

- Disconnect remote control
- Disconnect binary outputs

1.4.2 SW and HW versions compatibility

Be aware to use proper combination of SW and HW versions.

1.4.3 Dangerous voltage

In no case touch the terminals for voltage and current measurement!

Always connect grounding terminals!

In any case do not disconnect controller CT terminals!



1.4.4 Adjust the setpoints

All parameters are adjusted to their typical values. However the setpoints has to be checked and adjusted to their real values before the first starting of the gen-set.

IMPORTANT: Wrong adjustment of setpoints can destroy the gen-set.

Note: The controller contains a large number of configurable setpoints, because of this it is impossible to describe all of its functions. Some functions can be changed or have different behavior in different SW versions. Always check the Global guide and New feature list for SW version which is used in controller. This manual only describes the product and is not guaranteed to be set for your application.

IMPORTANT: Be aware that the binary outputs can change state during and after software reprogramming (before the controller is used again ensure that the proper configuration and setpoint settings are set in the controller).



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The following instructions are for qualified personnel only. To avoid personal injury do not perform any action not specified in related guides for product.

1.5 Certifications and standards

EN 61000-6-2

- **EN61000-6-4**
- **EN61010-1**
- EN 60068-2-1 (-20 °C/16 h for std version)
- **EN 60068-2-2 (70 °C/16 h)**
- EN 60068-2-6 (2÷25 Hz / ±1,6 mm; 25÷100 Hz / 4,0 g)
- EN 60068-2-27 (a=500 m/s²; T=6 ms)
- EN 60068-2-30:2005 25/55°C, RH 95%, 48hours
- EN 60529 (front panel IP65, back side IP20)



1.6 Document history

Revision number	Related sw. version	Date	Author
1	1.0.0		Vladimír Zubák



1.7 Symbols in this manual



or -	Grounding	Resistor adjustable
t	(ᡎ ⁾⁾⁾⁾ GSM	Resistive
or	GSM modem	RS 232
er d	₽☐IJ IG-AVRi	RS 232 female
d	IG-AVRi	Starter
ng	Jumper	Switch - manually operated
ng	Load	Transformer
	Mains	USB type B
t	Mains	USB type B female
t	Mobile provider	Voltage measuring
ł	Passive	Wifi / WAN / LAN
	sensor کیمیڈ Pick - up	back to Document information
ch	Relay coil	
or	Relay coil of slow- operating	
or ic	Resistor	





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2.1 General description

InteliGen 500 family controllers are comprehensive gen-set controllers for single generating sets operating in stand-by or parallel modes or for multiple gen-sets applications. A modular construction allows upgrades to different levels of complexity in order to provide the best solution for various customer applications. The controllers are equipped with a powerful graphic display showing icons, symbols and bar graphs for intuitive operation, which, together with its high level of functionality, sets new standards in Gen-set controls.

2.1.1 The key features of InteliGen 500

- Easy-to-use operation and installation. The factory default configuration covers most applications
- Various customizations are possible thanks to its configurability
- Excellent remote communication capabilities
- High level of support for EFI engines (most world producers)
- High reliability

2.2 True RMS measurement

This controller measures AC values based on True RMS principle. This principle corresponds exactly to the physical definition of alternating voltage effective values. Under normal circumstances the mains voltage should have a pure sinusoidal waveform. However some nonlinear elements connected to the mains produce harmonic waveforms with frequencies of multiplies of the basic mains frequency and this may result in deformation of the voltage waveforms. The True RMS measurement gives accurate readings of effective values not only for pure sinusoidal waveforms, but also for deformed waveforms.

Note: The harmonic deformation causes that the Power Factor of a generator working parallel with the mains cannot reach values in a certain range around the PF 1.00. The higher the deformation, the wider the power factor dead range. If the requested power factor is adjusted inside the dead range, the controller cannot reach the requested value because of this fact.

2.3 Configurability and monitoring

One of the key features of the controller is the system's high level of adaptability to the needs of each individual application and wide possibilities for monitoring. This can be achieved by configuring and using the powerful PC/mobile tools.



2.3.1 Supported configuration and monitoring tools

- InteliConfig complete configuration and single gen-set monitoring
- WinScope special graphical monitoring software

Note: Use the InteliConfig PC software to read, view and modify configuration from the controller or disk and write the new configuration to the controller or disk.

The firmware of controller contains a large number of binary inputs and outputs needed for all necessary functions available. However, not all functions are required at the same time on the same gen-set and also the controller hardware does not have so many input and output terminals. One of the main tasks of the configuration is mapping of "logical" firmware inputs and outputs to the "physical" hardware inputs and outputs.

2.3.2 Configuration parts

- Mapping of logical binary inputs (functions) or assigning alarms to physical binary input terminals
- Mapping of logical binary outputs (functions) to physical binary output terminals
- Assigning sensor characteristics (curves) and alarms to analog inputs
- Selection of peripheral modules, which are connected to the controller, and doing the same (as mentioned above) for them
- Selection of ECU type, if an ECU is connected
- Changing the language of the controller interface



Image 2.1 Principle of binary inputs and outputs configuration

The controller is shipped with a default configuration, which should be suitable for most standard applications. This default configuration can be changed only by using a PC with the InteliConfig software. See InteliConfig documentation for details.



Note: You need one of communication modules to connect the controller to a PC with InteliConfig. There is a special easy removable service module for cases when no communication module is permanently attached.

Once the configuration is modified, it can be saved to a file for later usage with another controller or for backup purposes. The file is called archive and has the file extension .ail3. An archive contains a full image of the controller at the time of saving (if the controller is online for the PC) except the firmware. Besides configuration it also contains current adjustment of all setpoints, all measured values, a copy of the history log and a copy of the alarm list.

The archive can be simply used for cloning controllers, i.e. preparing controllers with identical configuration and settings.

2.4 PC tools

2.4.1 InteliConfig

Configuration and monitoring tool for InteliGen controllers. See more in InteliConfig Reference Guide.

This tool provides the following functions:

- Direct or internet communication with the controller
- Offline or online controller configuration
- Controller firmware upgrade
- Reading/writing/adjustment of setpoints
- Reading of measured values
- Browsing of controller history records
- Exporting data into a XLS file
- Controller language translation



2.4.2 WebSupervisor

Web-based system for monitoring and controlling of controllers. See more at the WebSupervisor webpage.

This tool provides the following functions:

- Site and fleet monitoring
- Reading of measured values
- Browsing of controller history records
- On-line notification of alarms
- Email notification
- Also available as a smart-phone application

WebSupervisor available at: <u>www.websupervisor.net</u>

Demo account:

- Login: comaptest
- Password: ComAp123





2.4.3 WinScope

Special graphical controller monitoring software used mainly for commissioning and gen-set troubleshooting. See more in the WinScope Reference guide.

This tool provides the following functions:

- Monitoring and archiving of ComAp controller's parameters and values
- View of actual / historical trends in controller
- On-line change of controllers' parameters for easy regulator setup



2.5 Plug-in modules

2.5.1 CM-4G-GPS

GSM/4G module

- Wireless integrated solution
- Quick and easy installation
- Instant alarm SMS notification
- System control over SMS
- Quad Band GPRS/EDGE modem, 850/900/1800/1900 MHz, FDD LTE: Band 1, Band 2, Band 3, Band 4, Band 5, Band 7, Band 8, Band 20, all bands with diversity, WCDMA/HSDPA/HSUPA/HSPA+: Band 1, Band 2, Band 5, Band 8, all bands with diversity
- GPRS multi-slot class 10

2.5.2 CM-GPRS

GSM/GPRS module

- Wireless integrated solution
- Quick and easy installation
- Instant alarm SMS notification
- System control over SMS
- Quad Band GPRS/EDGE modem, 850/900/1800/1900 MHz
- GPRS multi-slot class 10



Vodel: ME9095 - 120

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2.5.3 CM-RS232-485

Communication module with two communication ports.

- RS232 and RS485 interface
- MODBUS
- Serial connection to InteliConfig



2.5.4 EM-BIO8-EFCP

Hybrid current input and binary input/output extension module.

Up to 8 additional configurable binary inputs or outputs



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2.6 CAN modules

2.6.1 Inteli AIN8

The unit offers the user the flexibility to configure the unit to have 8 analog inputs.

Supported sensors:

- Resistor 3-wire input
 - Common resistor: 0-250Ω, 0-2400Ω, 0-10kΩ
 - Temperature sensor: Pt100, Pt1000, Ni100, Ni1000
- Current (active or passive sensors)
 - ±20mA, 0-20mA, 4-20mA
- Voltage
 - ±1V, 0-2,4V, 0-5V, 0-10V
 - Lambda probes
 - Thermocouples are not supported (the measuring loop was designed for lambda probes, what caused non-support of thermocouples)

Impulse/RPM sensor:

- RPM measuring pulses with frequency 4Hz 10kHz
- Impulse
 - Possibility to measure pulses from electrometer, flowmeter (measurement of total consumption, average fuel consumption)



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2.6.2 Inteli AIN8TC

The unit offers flexibility to configure 8 thermocouple inputs.

Supported sensors:

- ▶ J, K or L thermocouples
- thermocouples with and without cold junction compensation are supported



2.6.3 Inteli IO8/8

The unit offers the user the flexibility to configure the unit to have 8 binary inputs, 8 binary outputs, and 2 analog outputs, or 16 binary inputs, 0 binary outputs and 2 analog outputs via switches inside the controller.

Configuration 8/8

- 8 Binary inputs (options: pull up or pull down logic)
- 8 Binary outputs (options: Low side switch (LSS) or High side switch (HSS))
- 2 Analog outputs (options: voltage (0-10V), current (0-20mA) and PWM (5V, adjustable frequency 200Hz-2,4kHz))

Configuration 16/0

- 16 Binary inputs (options: pull up or pull down logic)
- 0 Binary outputs
- 2 Analog outputs (options: voltage (0-10V), current (0-20mA) and PWM (5V, adjustable frequency 200Hz-2,4kHz))





2.6.4 IGS-PTM

The unit offers the user the flexibility to configure the unit to have 8 binary inputs, 8 binary outputs, 4 analog inputs and 1 analog outputs.

- Configurable 8 binary and 4 analog inputs
- Configurable 8 binary and 1 analog output
- LEDs indicate the state of binary inputs/outputs
- Measures values from Pt100 and Ni100 sensors
- Analog inputs (resistance range 0-250 Ohms, voltage range 0-100mV, current range 0-20mA selectable via jumper)
- UL certified



2.6.5 IGL-RA15

Remote annunciator.

- 15 programmable LEDs with configurable colors red-green-yellow
- Lamp test function with status LED
- Customizable labels
- Local horn output
- Maximal distance 200 m from the controller
- Up to 4 units can be connected to the controller
- UL certified

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3 Applications overview

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3.1 SPtM

The typical scheme of a single parallel to mains application is shown below. The controller controls two breakers – a mains breaker and a generator breaker. Feedback from both breakers is required.



Image 3.1 Single parallel to mains application



3.2 MINT

The typical schemes of multiple island-parallel application without mains. The controller controls one breaker only, the generator breaker. Feedback from the generator breaker is required.





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4.1 Package content

The package contains:

- Controller
- Mounting holders
- Terminal blocks

Note: The package does not contain a communication or extension modules. The required modules should be ordered separately.



4.2 Controller installation

4.2.1 Dimensions





1 Plug-in module

Note: Dimension x depends on plug-in module

Note: Dimensions are in millimeters.



Note: Cutout is in millimeters.

4.2.2 Mounting

The controller is to be mounted onto the switchboard door. Requested cutout size is 187×132 mm. Use the screw holders delivered with the controller to fix the controller into the door as described on pictures below. Recommended torque for holders is 0.15 N·m.



Panel door mounting



Note: The final depth of the controller depends on the selected extension module - it can vary between 41 and 56 mm. Mind also a size of connector and cables (e.g. in case of RS232 connector add about another 60 mm for standard RS232 connector and cable).

Note: These devices shall be mounted in a pollution degree 2 environment enclosure having adequate strength and thickness with acceptable spacings being provided.

Note: The accessibility of live parts through openings in the enclosure, reliable retention of guards or barriers for prevention of risk of electric shock, etc., shall be considered in the end product evaluation.

Note: Voltage sensing circuits shall be connected to controlled Overvoltage Category III circuits only in the end product installation.



4.3 Terminal Diagram

① CURRENT MEASUREMENT		② GENERATOR VOLTAGE		③ MAINS/BUS VOLTAGE		④ BINARY INPUTS		⑤ AVR INTERFACE	
T29	СОМ	Т37	Ν	T41	Ν	T45	BIN1	T54	СОМ
Т30	L1	Т38	L1	T42	L1	T46	BIN2	T55	OUT
T31	L2	Т39	L2	T43	L2	T47	BIN3	6 CAN	1
T32	L3	T40	L3	T44	L3	T48	BIN4	T26	L
Т33	COM					T49	BIN5	T27	COM
T34	L1					T50	BIN6	T28	Н
						T51	BIN7		
						T52	BIN8		



⑦ CAN2		(9) RPM		1 BINARY OUTPUTS		() POWER SUPPLY, D+	
T23	L	T16	RPM GND	T05	BOUT1	T01	BATT -
T24	COM	T17	RPM IN	T06	BOUT2	T02	D+
T25	Н	(1) SPEED GOV INTERFACE	/ERNOR	Т07	BOUT3	Т03	BATT +
(8) ANALOG INPUTS		T13	COM	T08	BOUT4	() RS485	
T18	A COM	T14	VOUT	Т09	BOUT5	T56	В
T19	A01	T15	PWM	T10	BOUT6	T57	COM
T20	A02			T11	BOUT7	T58	А
T21	A03			T12	BOUT8	(15) USB	
T22	A04			12 E-STOP		16 USB HOS	т
				T04		1 ETHERN	ΞT



4.4 Recommended wiring



1	Current inputs	29 - 32	Current measurement wiring (page 31)
2	Mains voltage inputs	37 - 40	Voltage measurement wiring - SPtM (page 33) Voltage measurement wiring - MINT (page 35)
3	Bus voltage inputs	41 - 44	Voltage measurement wiring - SPtM (page 33) Voltage measurement wiring - MINT (page 35)
4	Binary inputs	45 - 52	Binary inputs (page 38)
5	AVR	54 - 55	AVR Interface (page 49)
6	CAN1	H, COM, L	CAN bus and RS485 wiring (page 44)
7	CAN2	H, COM, L	CAN bus and RS485 wiring (page 44)
8	Speed governor	13 - 15	Speed governor interface (page 49)
9	Binary outputs	07 - 12	Binary Outputs (page 39)
10	Power supply	"+" D "-"	Power supply (page 28)
1	RS485	A, COM, B	CAN bus and RS485 wiring (page 44)



12	USB	USB B	USB (page 49)
13	USB HOST	USB A	USB HOST (page 49)
14	Ethernet	RJ45	Ethernet (page 49)

4.4.1 General

To ensure proper function:

- Use grounding terminals.
- Wiring for binary inputs and analog inputs must not be run with power cables.
- Analog and binary inputs should use shielded cables, especially when the length is more than 3 m.

Tightening torque, allowable wire size and type, for the Field-Wiring Terminals:			
For Mains(Bus) Voltage, Generator Voltage a	and Current terminals		
	Specified tightening torque is 0,56 Nm (5,0 In-lbs)		
	Use only diameter 2,0 - 0,5 mm (12 - 26 AWG) conductor, rated for 90°C minimum.		
For other controller field wiring terminals			
	Specified tightening torque 0,79 nm (7,0 In-Ib)		
	Use only diameter 2,0 - 0,5 mm (12 - 26 AWG) conductor, rated for 75°C minimum.		
	Use copper conductors only.		

4.4.2 Grounding

The shortest possible length of wire should be used for controller grounding. Use cable min 2.5 mm².

The negative " - " battery terminal must be properly grounded.

Switchboard and engine must be grounded at common point. Use as short cable as possible to the grounding point.

4.4.3 Power supply

To ensure proper function:



▶ Use power supply cable min. 1.5 mm²

Maximum continuous DC power supply voltage is 36 V DC. The controller's power supply terminals are protected against large pulse power disturbances. When there is a potential risk of the controller being subjected to conditions outside its capabilities, an outside protection device should be used.

It is necessary to ensure that potential difference between generator current COM terminal and battery "-" terminal is maximally ± 2 V. Therefore is strongly recommended to interconnect these two terminals together.

Note: The controller should be grounded properly in order to protect against lighting strikes. The maximum allowable current through the controller's negative terminal is 4 A (this is dependent on binary output load).

For the connections with 12 V DC power supply, the controller includes internal capacitors that allow the controller to continue in operation during cranking if the batter voltage dip occurs. If the voltage dip goes during cranking to 0 V and after 50 ms it recovers to 4 V, the controller continues operating. This cycle can repeat several times. During this voltage dip the controller screen backlight can turn off.



Note: Recommended fusing is 4 A fuse.

Note: In case of the dip to 0 V the high-side binary outputs will be temporarily switched off and after recovering to 4 V back on.

IMPORTANT: When the controller is power up only by USB and the USB is disconnected then the actual statistics can be lost.

Note: Suitable conductor protection shall be provided in accordance with NFPA 70, Article 240.

Note: Low voltage circuits (35 volts or less) shall be supplied from the engine starting battery or an isolated secondary circuit.

Note: It is also possible to further support the controller by connecting the external capacitor and separating diode. The capacitor size depends on required time. It shall be approximately thousands of μ F. The capacitor size should be 5 000 μ F to withstand 150 ms voltage dip under following conditions: Voltage before dip is 12 V, after 150 ms the voltage recovers to min. allowed voltage, i.e. 8 V.

Power supply fusing

A 4 A fuse should be connected in-line with the battery positive terminal to the controller and modules. These items should never be connected directly to the starting battery. Fuse value and type depends on number of connected devices and wire length. Recommended fuse (not fast) type - T4 A. Not fast due to internal capacitors charging during power up.





Note: Recommended fusing is 4 A fuse.

IMPORTANT: 4 A fuse is calculated without BOUT consumption nor extension modules. Real value of fuse depends on consumption of binary outputs and modules.

Example: Maximal consumption of binary outputs can be 22 A

- 2 x 10 A on high current outputs (for 10 seconds)
- 2 A on all others binary outputs

4.4.4 Measurement wiring

Use 1.5 mm² cables for voltage connection and 2.5 mm² for current transformers connection. Adjust **Connection type (page 244)**, **Nominal Voltage Ph-N (page 246)**, **Nominal Voltage Ph-Ph (page 246)**, **Nominal Current (page 243)**, **Gen Mains VT Ratio (page 246)** and **CT Ratio (page 244)** by appropriate setpoints in the Basic Settings group.

IMPORTANT: Risk of personal injury due to electric shock when manipulating voltage terminals under voltage. Be sure the terminals are not under voltage before touching them. Do not open the secondary circuit of current transformers when the primary circuit is closed. Open the primary circuit first.

Mains measurement wiring

Connect CT according to following drawings



Image 4.1 Mains measurement wiring



Current measurement wiring

The number of CT's is automatically selected based on selected value of setpoint **Connection type (page 244)** [3Ph4Wire / High Leg D / 3Ph3Wire / Split Ph / Mono Ph].

Generator currents and power measurement is suppressed if current level is bellow <1 % of CT range.

To ensure proper function:

- ▶ Use cables of 2.5 mm²
- Use transformers to 5 A
- Connect CT according to following drawings:

3 phase application:



Image 4.2 3 phase application

IMPORTANT: It is necessary to ensure that potential difference between current COM terminal and power supply "-" terminal is maximally ± 2 V. There are 2 options how to ensure this:

- "Red" option properly ground both terminals
- "Blue" option interconnect these two terminals

Always apply only one option. Never realize both options on one installation.



Split phase application:



Image 4.3 Split phase application

IMPORTANT: The second phase of split phase connection is connected to the terminal, where is normally connected the third phase.

IMPORTANT: It is necessary to ensure that potential difference between current COM terminal and power supply "-" terminal is maximally ± 2 V. There are 2 options how to ensure this:

- "Red" option properly ground both terminals
- "Blue" option interconnect these two terminals

Always apply only one option. Never realize both options on one installation.



Mono phase application:

Connect CT according to following drawings. Terminals phase 2 and phase 3 are opened.



Image 4.4 Mono phase application

IMPORTANT: It is necessary to ensure that potential difference between current COM terminal and power supply "-" terminal is maximally ± 2 V. There are 2 options how to ensure this:

- "Red" option properly ground both terminals
- "Blue" option interconnect these two terminals

Always apply only one option. Never realize both options on one installation.

Voltage measurement wiring - SPtM

There are 4 voltage measurement Connection Type (setpoint **Connection type (page 244)** [3Ph4Wire / High Leg D / 3Ph3Wire / Split Ph / Mono Ph]) options, every type matches to corresponding generator connection type.

Note: For fusing of voltage measurement input use T1A or T2A fuse.

The generator protections are evaluated from different voltages based on Connection type (page 244) setting:

- 3Ph 4W Ph-Ph voltage, Ph-N voltage
- 3Ph 3W Ph-Ph voltage
- Split Ph Ph-N voltage
- Mono Ph Ph-N voltage



ConnectionType: 3 Phase 4 Wires



Image 4.5 3 phase application with neutral

ConnectionType: 3 Phase 3 Wires



Image 4.6 3 phase application without neutral



ConnectionType: Split Phase



Image 4.7 Split phase application

IMPORTANT: The second phase of split phase connection is connected to the terminal, where is normaly connected the third phase.

ConnectionType: Mono Phase



Image 4.8 Mono phase application

Voltage measurement wiring - MINT

There are 4 voltage measurement Connection Type (setpoint **Connection type (page 244)** [3Ph4Wire / High Leg D / 3Ph3Wire / Split Ph / Mono Ph]) options, every type matches to corresponding generator connection type.

Note: For fusing of voltage measurement input use T1A or T2A fuse.

The generator protections are evaluated from different voltages based on Connection type (page 244) setting:



- > 3Ph 4W Ph-Ph voltage, Ph-N voltage
- 3Ph 3W Ph-Ph voltage
- Split Ph Ph-N voltage
- Mono Ph Ph-N voltage

ConnectionType: 3 Phase 4 Wires



Image 4.9 3 phase application with neutral

ConnectionType: 3 Phase 3 Wires



Image 4.10 3 phase application without neutral


ConnectionType: Split Phase



Image 4.11 Split phase application

IMPORTANT: The second phase of split phase connection is connected to the terminal, where is normaly connected the third phase.

ConnectionType: Mono Phase



Image 4.12 Mono phase application

4.4.5 Magnetic pick-up

A magnetic speed sensor (pickup) is the most common method of engine speed measurement. To use this method, mount the pickup opposite to the engine flywheel, connect the cable to the controller as shown on the picture below and adjust the setpoint **Gear Teeth (page 248)** according to the number of teeth on the flywheel. For the details about the pick-up input parameters **see Technical data on page 217**

IMPORTANT: To ensure proper function use a shielded cable.





If engine will not start:

Check ground connection from pick-up to controllers, eventually disconnect ground connection to one of them.

Note: In some cases the controller will measure a RPM value even though the gen-set is not running: RPM is measured from the generator voltage (Gear Teeth = 0). Controller is measuring some voltage value on input terminals due to open fusing. If RPM > 0 the controller will be put into a Not ready state and the engine will not be allowed to start.

4.4.6 Binary inputs

Use minimally 1 mm² cables for wiring of Binary inputs.



Image 4.13 Wiring binary inputs

Note: The name and function or alarm type for each binary input have to be assigned during the configuration.



4.4.7 Binary Outputs

Use min. 1 mm² cables for wiring of binary outputs. Use external relays as indicated on the schematic below for all outputs except those where low-current loads are connected (signalization etc...).

IMPORTANT: Use suppression diodes on all relays and other inductive loads!



Note: Every single binary output can provide up to 0,5 A of steady current.



4.4.8 E-Stop

E stop has dedicated terminal T049. Power supply of binary output 1 and binary output 2 (terminals 4 and 5) is internally connected (in controller) to E-Stop terminal. It means higher security and faster disconnection of these outputs. More information about E-Stop functions **see E-Stop on page 153**.

Note: This function has the same behavior as binary input EMERGENCY STOP (PAGE 665).



Image 4.14 E-Stop wiring

Note: Recommended fusing is 1.2 A fuse.

Note: Grey dashed line symbolizes internal connection between E-Stop and binary outputs 1 and 2.

Note: For proper functionality of E-Stop, the terminal T049 must be always wired. Terminal can be connected to battery+ or to terminal T03 (BATT+)

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4.4.9 Emergency stop

The Emergency Stop function can be made in two ways:

- Connecting a normally closed "mushroom-type" button to the binary input . This is a purely software solution.
- A hard-wired solution, where the button also disconnects the power supply from the controller outputs.



Image 4.15 Hard-wired emergency stop

4.4.10 Analog inputs

The analog inputs are designed for resistive automotive type sensors like VDO or DATCON. The sensors are connected either by one wire (the second pole is the sensor body) or by two wires.

- In the case of grounded sensors, connect the AI COM terminal to the engine body as near to the sensors as possible.
- In the case of isolated sensors, connect the AI COM terminal to the negative power supply terminal of the controller as well as one pole of each sensor.



Analog inputs are typically used for: Oil Pressure, Coolant Temperature and Fuel Level. All of these parameters are connected with relevant protections.



Image 4.16 Grounded sensors

Image 4.17 Isolated sensors

Note: Schemes show only analog input connection overview, not actual wiring.

Note: The name, sensor characteristic and alarm types for each analog input have to be assigned during configuration.

Analog inputs with voltage & current sensors

On each analog input, there is a possibility to connect voltage or current output sensor. Recommended wiring connections for these measurements are bellow.

Voltage sensors



Image 4.18 Wiring of analog input with voltage sensor



Current sensors



Image 4.19 Wiring of analog input with current sensor

Analog inputs with tristate sensors

It is possible to use tristate sensor with each analog input. Select Sensor option Tristate and use this wiring:



Image 4.20 Tristate sensor

Tristate sensor (binary sensor with fail detection)

- **Below 750 Ω** = Inactive
- **Between 750 Ω and 2400 Ω** = Active
- **Below 10** Ω or Over 2400 Ω = sensor failure (wire shorted or interrupted)



Analog inputs with binary sensors

It is possible to use binary sensor with each analog input. Select Sensor option Binary and use this wiring:



Image 4.21 Binary sensor

Binary sensor (binary sensor without fail detection)

- Below 750 Ω = Inactive
- Between 750 Ω and 2400 Ω = Active

4.4.11 CAN bus and RS485 wiring

CAN bus wiring

The wiring of the CAN bus should be provided in such a way that the following rules are observed:

- The maximum length of the CAN bus depends on the communication speed. For a speed of 250 kbps, which is used on the CAN1 bus (extension modules, ECU) and CAN2 bus, the maximum length is 200 m.
- The bus must be wired in linear form with termination resistors at both ends. No nodes are allowed except on the controller terminals.
- Shielded cable¹ has to be used, shielding has to be connected to the terminal T01 (Grounding).
- External units can be connected on the CAN bus line in any order, but keeping line arrangement (no tails, no star) is necessary.
- The CAN bus has to be terminated by 120 Ohm resistors at both ends use a cable with following parameters:

Cable type	Shielded twisted pair
Impedance	120 Ω
Propagation velocity	≥75% (delay ≤4.4 ns/m)
Wire crosscut	≥ 0.25 mm ²
Attenuation (@1MHz)	≤ 2 dB/100 m

¹Recommended data cables: BELDEN (<u>http://www.belden.com</u>) - for shorter distances: 3105A Paired - EIA Industrial RS-485 PLTC/CM (1x2 conductors); for longer distances: 3106A Paired - EIA Industrial RS-485 PLTC/CM (1x2+1 conductors)



Note: Communication circuits shall be connected to communication circuits of Listed equipment.

Note: A termination resistor at the CAN (120 Ω) is already implemented on the PCB. For connecting, close the jumper near the appropriate CAN terminal.



Image 4.22 CAN bus topology

For shorter distances (connection within one building)



Image 4.23 CAN bus wiring for shorter distances

Note: Shielding shall be grounded at one end only. Shielding shall not be connected to CAN COM terminal.



For longer distances or in case of surge hazard (connection out of building, in case of storm etc.)



Image 4.24 CAN bus wiring for longer distances

1 Recommended PT5-HF-12DC-ST¹

RS485 wiring

The wiring of the RS485 communication should be provided in such a way that the following rules are observed:

Note: A termination resistor at the CAN (120Ω) is already implemented on the PCB. For connecting, close the jumper near the appropriate CAN terminal.

- Standard maximum bus length is 1000 m.
- Shielded cable² has to be used, shielding has to be connected to the terminal T01 (Grounding).
- External units can be connected on the RS485 line in any order, but keeping line arrangement (no tails, no star) is necessary.
- The line has to be terminated by 120 Ohm resistors at both ends.
- For shorter distances (connection within one building).



Image 4.25 RS485 wiring for shorter distances

¹Protections recommended: Phoenix Contact (<u>http://www.phoenixcontact.com</u>): PT 5-HF-12DC-ST with PT2x2-BE (base element) or Saltek (<u>http://www.saltek.cz</u>): DM-012/2 R DJ

²Recommended data cables: BELDEN (<u>http://www.belden.com</u>) - for shorter distances: 3105A Paired - EIA Industrial RS-485 PLTC/CM (1x2 conductors); for longer distances: 3106A Paired - EIA Industrial RS-485 PLTC/CM (1x2+1 conductors)



For longer distances or in case of surge hazard (connection out of building, in case of storm etc.)



Image 4.26 RS485 wiring for longer distances

1 Recommended PT5HF-5DC-ST¹

Note: Communication circuits shall be connected to communication circuits of Listed equipment.

¹Recommended protections: Phoenix Contact (<u>http://www.phoenixcontact.com</u>): PT 5-HF-5DC-ST with PT2x2-BE (base element)(or MT-RS485-TTL) or Saltek (<u>http://www.saltek.cz</u>): DM-006/2 R DJ



On board RS485 description

Balancing resistors

The transmission bus into the RS-485 port enters an indeterminate state when it is not being transmitted to. This indeterminate state can cause the receivers to receive invalid data bits from the noise picked up on the cable. To prevent these data bits, you should force the transmission line into a known state. By installing two 620 Ohm balancing resistors at one node on the transmission line, you can create a voltage divider that forces the voltage between the differential pair to be less than 200 mili-Volts, the threshold for the receiver. You should install these resistors on only one node. The figure below shows a transmission line using bias resistors. Balancíng resistors are placed directly on the PCB of controller. Use jumpers PULL UP/PULL DOWN to connect the balancing resistors.







Image 4.28 RS485 on board



4.4.12 USB

This is required for computer connection. Use the shielded USB A-B cable.



Image 4.29 USB connection

4.4.13 USB HOST

USB Flash Drive can be connected into USB A connector.

4.4.14 Ethernet

Ethernet Cat5/Cat6 cable fitted with the RJ45 connector can be connected to the ethernet interface.

4.4.15 AVR Interface

The output from the controller work in the following mode:

- Output type: Voltage in range of -10 V to +10 V maximum
- Maximum load current: 5 mA both sourcing and sinking.
- Precision: 1% of set value +/-100 mV.
- Resolution/minimum step: 3 mV approx.
- Step response: less then 10 ms, measured between 10% and 90%
- Output ripple: 30 mV max. at 50% of PWM
- Galvanic insulation: YES

Pleas see chapter Voltage control outputs (page 107) (Analog output) for more information about set-up of controller's AVR.

Note: For the connection of individual AVRs please refer to concrete AVR manual.

IMPORTANT: Read carefully specific AVR instructions before connecting to controller.

4.4.16 Speed governor interface

The speed governor output is used to control the speed or the power of the engine via the remote speed controlling input provided by the speed governor. The output from the controller can work in the following modes:

- voltage mode -10 to 10 V (10k output resistance can be internally connected by jumper)
 - Maximum load current: 5 mA both sourcing and sinking.
 - Precision: 1% of set value +/-100mV.
 - Resolution/minimum step: 3 mV approx.
 - Step response: less then 10 ms, measured between 10% and 90%.



- Output ripple: 30 mV max. at 50% of pwm.
- Galvanic insulation: NO
- 5 V PWM mode
 - PWM amplitude: 5 V.
 - PWM frequency: 500 to 2900 Hz defined by setpoint Speed Governor PWM Rate (page 347)
 - Maximum load current: 20 mA both sourcing and sinking.
 - PWM Resolution: 14 bit.
 - Galvanic insulation: NO

Pleas see chapter **Speed control outputs (page 105)** (Analog output) for more information about set-up of controller's Speed governor.

Note: For the connection of individual speed governors please refer to concrete speed governor manual.

IMPORTANT: Read carefully specific Speed governor instructions before connecting to controller.

4.5 Plug-in module installation

4.5.1 Installation

Remove the back cover. To do this, press four holders which are located in corners.



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After removing back cover insert the plug-in module. Plug-in module has to be inserted under holders. Start with holders marked by symbol 1. On the controller are also arrows for better navigation. After inserting plug-in module under holders 1 press it down to holders marked by symbol 2 which locks the module.



Insert the plug-in module under holders marked by symbol 1.

		1. 🖂		999999	
Ĩ					
	NDER N				
	SLLOT				
		89 - 194			
		<u> </u>			

After locking the plug-in module into holders, place back the back cover (small cover for connectors has to be removed from back cover). Finally insert the small cover for connectors. Small covers are unique for each plug-in module.



4.6 Maintenance

4.6.1 Backup battery replacement

The internal backup battery lifetime is approx. 6 years. If replacement of backup batter is needed, follow these instructions:

- Connect the controller to a PC and save an archive for backup purposes (not necessary but recommended).
- Disconnect all terminals from the controller and remove the controller from the switchboard.
- Remove the back cover and all plug-in modules.
- Release the rear cover using a flat screwdriver or another suitable tool.



The battery is located in a holder on the circuit board. Remove the old battery with a small sharp screwdriver and push with a finger the new battery into the holder.



- Put the rear cover back. Use slight pressure to lock the snaps into the housing. Pay attention that the cover is in correct position and not upside down!
- Put back the plugin modules and back cover.
- Power the controller on, adjust date and time and check all setpoints.
- back to Installation and wiring

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5 Controller setup

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5.1 Default configuration

5.1.1 Default configuration

Binary inputs

Number	Description	Configured function
BIN1	Generator circuit breaker feedback	GCB FEEDBACK (PAGE 668)
BIN2	Mains circuit breaker feedback	MCB FEEDBACK (PAGE 672)
BIN3	Emergency stop button	EMERGENCY STOP (PAGE 665)
BIN4	Access lock keyswitch	ACCESS LOCK (PAGE 615)
BIN5	Switch controller to OFF mode	REMOTE OFF (PAGE 676)
BIN6	Switch controller to TEST mode	REMOTE TEST (PAGE 678)
BIN7	Suppression of alarms	SD OVERRIDE (PAGE 680)
BIN8	Free slot	NOT USED (PAGE 673)

Binary outputs

Number	Description	Function
BOUT1	Starter motor control	STARTER (PAGE 737)
BOUT2	Fuel solenoid valve	FUEL SOLENOID (PAGE 715)
BOUT3	Indication of breaker state	GCB CLOSE/OPEN (PAGE 716)
BOUT4	Indication of breaker state	MCB CLOSE/OPEN (PAGE 726)
BOUT5	Activation of any devices before start	PRESTART (PAGE 732)
BOUT6	Gen-set can be connected to load	READY TO LOAD (PAGE 734)
BOUT7	Indication of unconfirmed alarm	ALARM (PAGE 695)
BOUT8	Free slot	NOT USED (PAGE 731)

Analog inputs

Number	Configured sensor	Function
AIN1	VDO 10 Bar	OIL PRESSURE (PAGE 774)
AIN2	VDO40-120°C	COOLANT TEMP (PAGE 771)



AIN3	VDOLevel %	FUEL LEVEL (PAGE 772)
AIN4	None	NOT USED (PAGE 773)

5.2 Controller configuration and PC tools connection

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back to Controller setup

This chapter contains brief introduction into the specifics of firmware and archive upload and connection of various PC tools to the controller. If you require detailed information on each PC tool please use the included Help in those PC tools or download their Reference Guides.

5.2.1 USB

You may connect to the controller using the USB port. In this case standard USB A to B cable should be used.

Connection using InteliConfig

ComAp 🔈		LOADED 100%
CONNECT TO CONTROLLER	OPEN OFFLINE ARCHIVE	CREATE NEW CONFIGURATION
Connect to a controller using USB or R5232/485 cable, Ethernet or AirGate connection.	Open an offline archive.	Create an offline gen-set configuration before uploading it to the controller.
S Connect to controller	Open offline archive	Create new configuration

Image 5.1 First screen of InteliConfig - select connect to controller



Image 5.2 Second screen of InteliConfig - select detected controllers



Connection using WinScope

Connection type	Controller type	Address	
	InteliControllers	COM4 COM5 COM6	Unknown Communications Port Qualcomm Gobi 2000 HS-USB NMEA 9205 Qualcomm Gobi 2000 HS-USB Diagnostics
	C ECON INCON till v.3.2	COM11 COM15 COM16	Bth Modem Bth Modem Bth Modem
C Internet	ECON-3	COM41	Inaccessible USB Serial Port (COM44)
	RailCon	CONTR	obb behalt of the of the

Image 5.3 WinScope screen - select direct connection

5.2.2 RS232/RS485

It is possible to connect to the controller using RS232 or RS485 direct connection (serial port or USB to RS232/RS485 converter may be used). The following settings need to be checked in the controller:

- COM1 Mode (page 466) = Direct
- Controller Address (page 252) has to be set to the same value as in the PC tool

Connection using InteliConfig

comap 🔊		LOADED 100%
CONNECT TO CONTROLLER Connect to a controller using USB or R5232/485 cable, Ethernet or AirGate connection.	OPEN OFFLINE ARCHIVE Open an offline archive.	CREATE NEW CONFIGURATION Create an offline gen-set configuration before uploading it to the controller.
S Connect to controller	Open offline archive	Create new configuration

Image 5.4 First screen of InteliConfig - select connect to controller



controller connectiv	n
🛆 AirGate	
Internet /	Ethernet
Serial link	
COM port:	
COM8 - USB Se	rial Port (COM8)
Controller addre	ss:
1	
Password:	

Image 5.5 Second screen of InteliConfig - select Serial link

Connection using WinScope

Connection type	Controller type	Address	
• Direct 🔓	InteliControllers ECON INCON till v.3.2 ENCONE	COM4 COM5 COM6 COM11 COM15 COM16	Unknown Communications Port Qualcomm Gobi 2000 HS-USB NMEA 9205 Qualcomm Gobi 2000 HS-USB Diagnostics Bth Modem Bth Modem Bth Modem
C Internet	C ECON-3 INCON from v.3.3 RailCon	COM41 COM44	Inaccessible USB Serial Port (COM44)

Image 5.6 WinScope screen - select direct connection

Note: Winscope supports only 19200, 38400, 57600 speeds.

5.2.3 Ethernet

It is possible to connect to the controller using ethernet port.

Direct connection

When you use direct connection the controller needs to be reachable directly from the PC you use (i.e. one LAN or WAN without any firewalls and other points that may not allow the connection). The following settings need to be checked in the controller:



- Controller Address (page 252) has to be set to the same value as in the PC tool.
- IP Address Mode (page 255) can be set to AUTOMATIC when there is DHCP service is available. Otherwise it needs to be set to FIXED.
- ▶ IP Address (page 256) is either set automatically or it can be adjusted to a specific requested value.
- **Subnet Mask (page 256)** is either set automatically or it can be adjusted to a specific requested.
- Gateway IP (page 257) can be set here when it is used.

Connection using InteliConfig

-omap 👂		LOADED 100%
CONNECT TO CONTROLLER	OPEN OFFLINE ARCHIVE	CREATE NEW CONFIGURATION
Connect to a controller using USB or RS232/485 cable, Ethernet or AirGate connection.	Open an offline archive.	Create an offline gen-set configuration before uploading it to the controller.
S Connect to controller	Open offline archive	Create new configuration

Image 5.7 First screen of InteliConfig - select connect to controller



ontroller connection	n	
🛆 AirGate		
Internet /	Ethernet	
IP address:		
213.175.33.104	4:23	*
Access code:	Controller	address:
	1	
Password:		
		-

Image 5.8 Second screen of InteliConfig - select Internet/Ethernet

Connection using WinScope

Open connection		
Connection type	Controller type	Address Internet bridge address: 192.168.1.199 Enter IP address
(* Internet	Select Internet connection	VDK X Cancel



AirGate connection

You can use ComAp's AirGate service that allows you to connect to any controller via internet no matter what are the restrictions of the local network (if the controller can connect to the internet AirGate service will work). The following setpoints have to be adjusted:



- Controller Address (page 252) has to be set to the same value as in the PC tool.
- IP Address Mode (page 255) can be set to AUTOMATIC when there is DHCP service is available. Otherwise it needs to be set to FIXED.
- ▶ IP Address (page 256) is either set automatically or it can be adjusted to a specific requested value.
- **Subnet Mask (page 256)** is either set automatically or it can be adjusted to a specific requested.
- Gateway IP (page 257) can be set here when it is used.
- AirGate Connection (page 259) has to be set to Enabled.
- AirGate Address (page 260) currently there is one AirGate server running at URL airgate.comap.cz (enter this URL into the setpoint).

Connection using InteliConfig

comAp 🔈		LOADED 100%
CONNECT TO CONTROLLER	OPEN OFFLINE ARCHIVE	CREATE NEW CONFIGURATION
Connect to a controller using USB or RS232/485 cable, Ethernet or AirGate connection.	Open an offline archive.	Create an offline gen-set configuration before uploading it to the controller.
S Connect to controller	Open offline archive	Create new configuration

Image 5.10 First screen of InteliConfig - select connect to controller



Controller connectio	on		
AirGate ID:	,		
AirGate server:			
airgate.comap.	cz:44445		٣
Access code:		Controller a	address:
		1	
Password:			
			Open
			-
Contraction (

Image 5.11 Second screen of InteliConfig - select AirGate

Connection using WinScope

WinScope doesn't support connection via AirGate.

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5.3.1 Operating Modes

Selecting the operating mode is done through Left and Right buttons on the front panel or by changing the **Controller mode (page 249)** setpoint (from the front panel or remotely).

Note: If this setpoint is configured as password-protected, the correct password must be entered prior to attempting to change the mode.

Note: The mode cannot be changed if Access Lock input is active.

The following binary inputs can be used to force one respective operating mode independent of the mode setpoint selection:

- Remote OFF (page 676)
- Remote TEST (page 678)
- Remote MAN (page 675)
- Remote AUTO (page 675)

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If the respective input is active the controller will change the mode to the respective position according to the active input. If multiple inputs are active, the mode will be changed according to priorities of the inputs. The priorities match the order in the list above. If all inputs are deactivated, the mode will return to the original position given by the setpoint.

OFF

No start of the gen-set is possible. If the gen-set is running, it is not possible to switch directly to OFF mode. First you have to stop the engine. After that the controller will stay in Not ready status and cannot be started any way. The MCB is closed permanently (**MCB Opens On (page 325)** = GenRun) or is open or closed according to whether the mains is present or not (**MCB Opens On (page 325)** = MainsFail). No AMF or Power management function will be performed. The buttons MCB 1/0, GCB 1/0, Start 1 and Stop 0 including the appropriate binary inputs for external buttons are not active.

Note: When engine is running, it is not possible to switch gen-set to OFF mode

No system start activation is possible. If mains is healthy and MCB is opened, then is MCB tryed to close after the delay given by setpoint MCB Close Delay. In case of mains fail and option MCB Open On - Mains Fail is chosen then is MCB tryed to open. In MGCB application is MGCB opened in case is closed. No AMF or Power management function will be performed. The buttons MCB 1/0, GCB 1/0, Start 1 and Stop 1 including the appropriate binary inputs for external buttons are not active.

MAN

The engine can be started and stopped manually using the START and STOP buttons (or external buttons wired to the appropriate binary inputs) in MAN mode.

When the engine is running and generator parameters are in the limits, GCB can be closed to a dead bus or synchronization can be started by the GCB button.

Also MCB can be closed and opened manually using the MCB button, regardless of whether the mains are present or not.

Controller does not respond to external signals and/or conditions. The gen-set is fully in manual control; there is no automatic way to stop it (except protections). The gen-set stays running until STOP button is pressed. Controller does not take place in **Power management (page 79)** in MINT application.

In MAN mode can be the system started by pressing the START button or by activating binary input Start Button. If there is present Gen-set controller, their system start/stop is activated/deactivated via internal communication line. In case of MCB application can be controlled only the MCB breaker by pressing the MCB button or by activating the binary input MCB Button. In case of MGCB application the control of MCB breaker and MGCB breaker is depending on the setting of Setpoint CB Control In MAN Mode. MGCB breaker can be controlled also by pressing the MGCB button or by activating the binary input MGCB Button.

AUTO

Gen-set is controlled based on external signal (**REMOTE START/STOP (PAGE 677)**) or by conditions (AMF, Power management system, ...).

When one condition deactivates the engine does not stop if another condition for automatic starts is active.

The controller does not respond to buttons Start \blacksquare , Stop \bigcirc , MCB ON/OFF $\frac{1/0}{0}$ and GCB ON/OFF $\frac{1/0}{0}$.



IMPORTANT: If a red alarm is present and the gen-set is in AUT mode, it can start by itself after all red alarms become inactive and are acknowledged!!! To avoid this situation, adjust the setpoint Reset To Manual (page 250) to the Enabled position.

System activation is based on external signal (**REMOTE START/STOP (PAGE 677)**) or by conditions (AMF, Power management system, ...).

When one condition deactivates will not be deactivated if another condition for automatic starts is active.

The controller does not respond to buttons Start II, Stop O, MCB ON/OFF ^{1/o} and MGCB ON/OFF

TEST

The behavior of the controller in TEST mode depends mainly on the setting of the setpoints and binary inputs. TEST mode can be activated via front panel of controller or via binary input **REMOTE TEST (PAGE 678)**.

The gen-set will be started when the controller is put to TEST mode and will remain running unloaded. If a mains failure occurs, the MCB will be opened and after **Open Transfer Min Break (page 350)** the GCB will be closed and the gen-set will supply the load. After the mains have recovered, the delay **Mains Return Delay (page 319)** I will count down and if it elapses and the mains is still ok, the controller will transfer the load back to the mains after **Open Transfer Min Break (page 350)** and the gen-set will remain running unloaded again until the mode is changed.

The controller does not respond to buttons Start , Stop , MCB ON/OFF and GCB ON/OFF .

Behavior of TEST mode also depends on setpoints **Transfer BusGen To Mains (page 352)** and **Transfer Mains To Gen Bus (page 351)** and on binary inputs FORCE ISLAND (PAGE 666) and FORCE PARALLEL (PAGE 666).

The system start is activated when the controller is put in to TEST mode.

MCB application - system start is active, if Gen-sets will be started their GCB will be closed in to the parallel state.

MGCB application - system start is active, if Gen-sets will be started their GCB will be closed but MGCB stays opened.

If mains failure occurs, the MCB is opened and in MGCB application will be the MGCB breaker closed.

After the mains return, the back synchronisation is activated and system is transfered back to the TEST mode if the TEST request is still active.

The transfer is depending on the setting see Subgroup: Load Transfer on page 350.

5.3.2 Engine start

Diesel engine

- After the command for start is issued (pressing Start button in MAN mode, auto start condition is fulfilled in AUTO mode or controller is switched to TEST mode), outputs PRESTART (PAGE 732) and GLOW PLUGS (PAGE 720) are energized for time period given by the setpoints Prestart Time (page 273) and Glow Plugs Time (page 275).
- After Prestart Time (page 273) and Glow Plugs Time (page 275), the output FUEL SOLENOID (PAGE 715) is energized and after Fuel Solenoid Lead (page 276) the starter of motor is activated by energizing the output STARTER (PAGE 737).



- When one or more of following conditions are met, the starter output is de-energized:
 - The engine speed exceeds the value of Starting RPM (page 273), or
 - One of Additional running engine indications (page 132) signals becomes active.
- The controller remains in the Starting phase until the engine speed exceeds the value of Starting RPM (page 273), after that it is considered as started and the Idle period will follow.
- The maximum duration that the output STARTER (PAGE 737) is energized is determined by the setpoint Maximum Cranking Time (page 272). If the engine does not start within this period, the output STARTER (PAGE 737) is de-energized and a pause with length determined by Cranking Fail Pause (page 272) will follow. PRESTART (PAGE 732) and GLOW PLUGS (PAGE 720) outputs are active during the pause. After the pause has elapsed, the next start attempt is executed. The number of start attempts is given by the setpoint Cranking Attempts (page 271).
- Once the engine is started, the Idle period follows. The binary output IDLE/NOMINAL (PAGE 723) remains inactive (as it was during the start). The idle period duration is adjusted by the setpoint Idle Time (page 276).
- After the idle period has finished, the output IDLE/NOMINAL (PAGE 723) is activated and the start-up sequence is finished. The Stabilization (page 68) phase follows.





Image 5.12 Flowchart of start of diesel engine



GAS engine

The setpoint Fuel Solenoid (page 271) has to be switched to the Gas position.

- After the command for start is issued (pressing Start button in MAN mode, auto start condition is fulfilled in AUTO mode or controller is switched to TEST mode), outputs PRESTART (PAGE 732) and GLOW PLUGS (PAGE 720) are energized for time period given by the setpoints Prestart Time (page 273) and Glow Plugs Time (page 275).
- After Prestart Time (page 273) and Glow Plugs Time (page 275), starts countdown of Sd Ventilation Time (page 280)
- After Sd Ventilation Time (page 280), the starter of engine is activated by energizing the output STARTER (PAGE 737).
- When the engine speed exceeds 30RPM, the outputs FUEL SOLENOID (PAGE 715) and IGNITION (PAGE 723) are energized.
- When the engine speed exceeds value of Starting RPM (page 273), the starter of engine is de-energized, the engine is considered as started and the Idle period will follow.

IMPORTANT: Additional running engine indications (page 132) signals are not evaluated during the start of a gas engine. The Pickup must be used in any case!

- The maximum duration that the output STARTER (PAGE 737) is energized is determined by the setpoint Maximum Cranking Time (page 272). If the engine does not start within this period, outputs STARTER (PAGE 737) and FUEL SOLENOID (PAGE 715) are de-energized and a pause with length determined by Cranking Fail Pause (page 272) will follow. PRESTART (PAGE 732), GLOW PLUGS (PAGE 720) and IGNITION (PAGE 723) outputs are active during the pause. After the pause has elapsed, the next start attempt is executed. The number of start attempts is given by the setpoint Cranking Attempts (page 271).
- Once the engine is started, the Idle period follows. The binary output IDLE/NOMINAL (PAGE 723) remains inactive (as it was during the start). The idle period duration is adjusted by the setpoint Idle Time (page 276).
- After the idle period has finished, the output IDLE/NOMINAL (PAGE 723) is activated and the start-up sequence is finished. The Stabilization (page 68) phase follows.





Image 5.13 Flowchart of start of gas engine



5.3.3 Stabilization

When the **Engine start (page 63)** sequence is finished, the gen-set goes into the stabilization phase. There are two timers (setpoints) in this phase:

- Minimal Stabilization Time (page 278) starts to count down just after the idle period has finished. Generator voltage and frequency are not checked (respective protections are not evaluated) and the GCB cannot be closed even if the generator voltage and frequency are within limits.
- Maximal Stabilization Time (page 279) starts to count down just after the idle period has finished. Generator voltage and frequency are not checked (respective protections are not evaluated) but, opposite to the previous timer, the GCB can be closed if generator voltage and frequency are within limits.

In situations where the GCB is closed automatically (AUTO, TEST modes), the closing of GCB or starting of synchronization will occur in the first moment when the generator voltage and frequency will get into limits and the **Minimal Stabilization Time (page 278)** has already elapsed.

In the event that the generator voltage or frequency are not within limits within the **Maximal Stabilization Time** (page 279) period, the appropriate protection(s) will be activated and the gen-set will be cooled down and stopped.

Note: The limits for the generator voltage and frequency are given by setpoints in the **Group: Generator** settingsMains Settings (page 304).

Note: The value of the **Minimal Stabilization Time (page 278)** setpoint has to be lower than the value of **Maximal Stabilization Time (page 279)** setpoint.

5.3.4 Connecting to load

When the Stabilization (page 68) phase is finished, the gen-set can be connected to the load.

The command for connecting the gen-set to the load is issued either automatically (AUTO, TEST modes) or manually by pressing the GCB button. The following conditions must be valid:

- The gen-set is running and the Minimal Stabilization Time (page 278) timer has elapsed.
- The gen-set voltage and frequency are within limits.

Note: The speed governor and AVR must be adjusted properly to achieve these limits as the controller does not perform any regulation and the regulation outputs have constant values given by the **Voltage Regulator Bias** (page 354) and **Speed Governor Bias** (page 346) setpoints.

There are two ways to connect the gen-set to the load (bus bar). This depends on the state of **MCB FEEDBACK** (PAGE 672) and on the measured mains/bus voltage.

Connecting to dead bus

SPtM

If the MCB is open, the bus bar is considered as voltage-free and the GCB is closed without synchronization.

MINT

The measured bus voltage is also taken in account and it must be below 2% of the nominal bus voltage together with the open MCB (evaluated by **MCB Feedback (page 672)**) and also others GCB have to be open to close the GCB without synchronization.



Note: If the group of gen-sets is activated and multiple gen-sets have to start simultaneously and connect to the empty bus bar, there is an internal logic to prevent closing of more GCBs to the bus bar at the same moment without synchronization. One of the gen-sets will close the GCB, the others will wait and then they will synchronize to the first one.

Note: There also is a protection of "Bus power loss sensing". The "Bus Measure Error" is detected in MINT application when the voltage on the controller's bus terminals is out of limits 20 seconds after:

- GCB (own) was closed in MAN or AUT mode
- MCB (feedback) was closed in AUT mode
- > Any other GCB in power management group (on CAN bus) was closed.

The alarm is activated after 20s. However, the GCB (own) closing is blocked immediately for safety reasons. This protection can avoid e.g. potential direct closing of GCB while the controller's bus conductors are unintentionally unplugged from the terminals.

Synchronization

Synchronization process

Behavior of synchronization process depends on, which breaker is used for synchronization and in which **Controller mode (page 249)** is controller switched.

Note: When the controller starts to synchronize and the main measuring screen is displayed, it will be automatically change to the synchroscope screen for the entire duration of synchronization. After synchronization the synchroscope screen is automatically changed back to the main measuring screen. It is also possible to change screens manually (arrows up and down) after displaying the synchroscope screen. In this case there is no automatic return to the main measuring screen after synchronization is finished.

Synchronization via GCB in AUTO mode

Gen-set synchronization to the mains (common bus bar) via GCB (available for SPtM and MINT):

- if the mains (bus) voltage or the mains (bus) frequency gets out of the limits then the synchronization continues until the mains fail is confirmed. Then:
 - In SPtM MCB is opened and GCB is closed.
 - In MINT Bus measurement error alarm is issued and controller goes to slow stop.
- if the gen-set voltage or frequency gets out of the limits during the synchronization the synchronization process is interrupted. The synchronization starts again when gen-set parameters gets restored. the synchronization timeout starts count down again.
- If the synchronization timeout gets elapsed the slow stop protection gets active.

Synchronization via GCB in MAN mode

Gen-set synchronization to the mains (common bus bar) via GCB (available for SPtM and MINT):

- Behavior is exactly the same as in AUTO mode but the synchronization does not start again automatically when parameters of the gen-set gets out of limits and back. The breaker control button must be pressed again.
- When the GCB button is pressed during the synchronization, then the synchronization process is interrupted.

Synchronization via MCB in AUTO mode

Gen-set synchronization to the mains (common bus bar) via MCB (available only for SPtM):



- if the mains (bus) voltage or the Mains frequency gets out of the limits during synchronization, then the synchronization process is interrupted and can continue again when mains parameters gets restored after Mains Return Delay (page 319).
- if the gen-set voltage or frequency gets out of the limits during the synchronization, the synchronization process continues until the generator parameters fail is confirmed.
- If the synchronization timeout gets elapsed the Wrn Reverse Synchro Fail (page 810) protection gets active and GCB stays closed. Synchronization is stopped.

Synchronization via MCB in MAN mode

Gen-set synchronization to the mains (common bus bar) via MCB (available only for SPtM):

- Behavior is exactly the same as in AUTO mode but the synchronization does not start again automatically when parameters of the mains gets out of limits and back. The breaker control button must be pressed again.
- When the MCB button is pressed during the synchronization, then the synchronization process is interrupted.

Synchronization types

There are two types of synchronization. Type of synchronization is adjusted via setpoint **Synchronization Type (page 358)**.

Phase match

The phase match synchronization consists of voltage matching and frequency/angle matching. The maximum duration of synchronization is given by the setpoint **Synchronization Timeout (page 358)**. If the synchronization is not successful within this period of time, the **STP Synchronization Fail (page 837)** alarm will be issued.

Voltage matching

The gen-set bus voltage is regulated to match the mains/bus voltage with tolerance given by the setpoint **Voltage Window (page 359)**. The regulation is adjusted by the setpoints **Voltage Gain (page 356)** and **Voltage Int (page 356)**.

Frequency/angle matching

The gen-set bus frequency is regulated to match the mains/bus frequency first. The frequency regulation loop is active (setpoints **Frequency Gain (page 347)** and **Frequency Int (page 348)**). Once the frequency is matched, the regulation loop is switched to match the angle (setpoint **Angle Gain (page 348)**). When the angle is matched with tolerance +/- **Phase Window (page 359)** for a time given by the setpoint **Dwell Time (page 359)** and the voltage is matched too, then the GCB or MGCB is closed.

Note: The matching loops will continue to run even if the GCB or MGCB close command has been already issued until the controller receives **GCB FEEDBACK** (PAGE 668) or MGCB Feedback or a GCB or MGCB fail alarm occurs. After the feedback has been received, the control loops are switched to load and power factor loops or load and power factor sharing respectively.

Slip synchronization

The slip synchronizing is based on frequency/angle matching. The maximum duration of synchronizing is given by the setpoint **Synchronization Timeout (page 358)**. If the synchronizing is not successful within this period of time, the Sync Timeout alarm will be issued.

The Gen-set frequency is regulated to match the mains/bus frequency + **Slip Frequency (page 360)** value and the window is set by setpoint **Slip Frequency Window (page 360)**. When the generator frequency reaches

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(Mains/Bus Frequency + Slip frequency) value regulation loop is stopped (output is frozen at the actual value). If the generator frequency remains inside the window for the time longer than setpoint **Dwell Time (page 359)** the controller will allow GCB closing. The controller calculates periodically so called preclosing angle (based on the actual value **Slip Frequency (page 570)** and CB closing delay given by the setpoint CB Latency). When the preclosing angle is reached the controller issues CB closing command. The breaker will close and CB feedback confirms that to the controller. When the breaker is closed the controller goes to parallel and activates regulation loops again (parallel to Mains regulation loop).



Image 5.14 Slip synchronization

If the generator frequency goes out of the window (either because generator frequency changes or Mains/Bus frequency changes or setpoint **Slip Frequency Window (page 360)** changes) the controller will reactivate regulation loop and try to reach the target value again. The sync timeout timer runs regardless of this. If the generator frequency reaches the target frequency again the regulations are frozen and if the generator frequency remains in the window for the time longer than setpoint **Dwell Time (page 359)** the controller will continue in the standard sequence as seen in the previous case. *If the sync timeout elapses the controller will immediately stop synchronization.



Image 5.15 Slip synchronization

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The window is limited by the actual measured Mains/Bus frequency if one of the window limits is below this value (e.g. for setting where setpoint **Slip Frequency (page 570)** is set to 0.1Hz and setpoint **Slip Frequency Window (page 360)** is set to 0.5Hz).



Image 5.16 Slip synchronization

Slip synchronization has a dead band. When the dead band is reached the frequency regulation is disabled. Once it is disabled it will be enabled again only when the frequency goes out of the slip frequency window. Dead band is introduced to allow the controller to detect the match.



Image 5.17 Slip synchonization - deadband


Note: Due to the nature of this function it is possible that in limit cases the gen-set controller will regulate the generator frequency outside of protection limits. Example: Mains/Bus frequency is high but within its protection limits (e.g. 50.9Hz, limit is 51Hz). **Slip Frequency (page 360)** is set to 0.5Hz. This will cause regulation loop of the gen-set controller to push the gen-set frequency to 51.4Hz and eventually the controller will issue overfrequency delay. It is recommended to set the setpoint **Slip Frequency (page 360)** as low as possible that still enables succesfull synchronization. This minimizes the risk of this problem happening. Furthermore when slip synchronization is used it is recommended to set Mains/Bus Frequency protection limits to more rigid values than the generator frequency protection limits. In this case the setpoint **Slip Frequency (page 360)** can be set to 0.1Hz and the Mains/Bus Frequency overfrequency protection limit is set to 50.9Hz instead of 51Hz. This will ensure that problematic state cannot be reached.



5.3.5 Multiple island operation

This chapter describes the situation where multiple gen-sets are running parallel to each other but not with mains. This situation will occur either when:

- The common bus bar is dead due to opened MCB or there are no mains at all and the group of gen-sets has been activated, or
- > The group was running parallel to mains and the MCB has been opened.

IMPORTANT: The controller in MINT application does not control the MCB! Only the MCB position is evaluated from the binary input MCB FEEDBACK (PAGE 672) and the position is the basic source of information for switching between island and parallel to mains operation.

If the bus bar is empty, the first gen-set will close its GCB without synchronization. Following gen-sets will synchronize to the already energized bus bar. In the event that multiple gen-sets start simultaneously and the bus bar is empty, the system will prevent closing of multiple GCBs to the bus bar without synchronization. Instead of this, one of the gen-sets will close the GCB and energize the bus bar and the others will wait and then synchronize to the bus bar.

When a stop command is received, e.g. from the power management or binary input **REMOTE START/STOP** (PAGE 677) is deactivated or the STOP button is pressed, the GCB will be opened and the gen-set will go to cool down phase.

Behavior of controllers is adjusted via **Power management (page 79)** settings. Please see this chapter for more information.



5.3.6 Parallel to mains operation - SPtM application

After the gen-set has been synchronized to the mains, the parallel to mains operation follows. It consists of the following phases:

Ramping the power

Power up

The first phase of the parallel to mains operation is the ramping of the gen-set up to the desired power level. The speed of the ramp is given by the setpoint **Load Ramp (page 353)**. The setpoint adjusts the ramp time for a change from 0% to 100% of nominal power.

Power down

When a stop command is received the gen-set load is ramped down before opening the GCB. The ramp speed is given by the setpoint Load Ramp (page 353) and the end level is given by Unload MGCB Open LevelGenerator Unload GCB Open Level (page 352).

When the GCB button is pressed, the gen-set load is ramped down before opening the GCB as well. But after the GCB has been opened, the gen-set remains running until a stop command comes or the GCB is pressed again to reclose the GCB.

Load control

Load control ensures that the gen-set keep the certain load in parallel to mains operation (MCB Feedback (page 672) and GCB Feedback (page 668) = active).

There are available two modes of load control. Type of control is adjusted via setpoint **Load Control PTM** (page 230).

Note: In both modes, the lower level of the power is always limited by the setpoint **Minimal Power PTM (page 305)**. If the requested load (given by the active load control mode, e.g. Baseload, Import/Export) is below this limit the requested load is limited to the level adjusted by this setpoint.

Baseload

Load Control PTM (page 230) = Baseload. Genset produces amount of the power given by setpoint Baseload (page 233). The rest of power is supplied from the mains or exported to the mains (depends on proportions of load and Baseload (page 233) setpoint). Even in baseload control mode can be the Import/Export limited. This function can be activated by setpoint Import/Export Limitation (page 235) = Enabled. Then the request for the power of the genset operating in baseload can be limited to prevent the Import/Export go below the limit given by setpoint Import Load (page 234).

Example: Baseload = 1000 kW, load = 700 kW, Import load = 100 kW. Then the Baseload request will be limited to 600 kW to prewent the Import power go below 100 kW.

Example: Baseload = 1000 kW, load = 700 kW, Import load = -100 kW. Then the Baseload request will be limited to 800 kW to prevent the Import power go below -100 kW (actually it is limitation of the export).

Import/Export

Load Control PTM (page 230) = Imp/Exp. Gen-set produces the certain amount of power to keep constant import/export from the mains regardless the demand of the load. The requested import/export is given by setpoint **Import Load (page 234)**. If the value of the setpoint is >0 the power is imported from the mains, if setpoint value is <0, then the power is exported to the mains.



PF control

PF control ensures that the gen-set keep the certain reactive load in parallel to mains operation (MCB Feedback (page 672) and GCB Feedback (page 668) = active).

There are available two modes of PF control. Type of control is adjusted via setpoint **PF Control PTM (page 231)**.

Base PF

The power factor on the gen-set is kept on the level given by the setpoint **Base Power Factor (page 233)** regardless the load demand. The rest of demanded reactive power is supplied from the mains. Values >1 means that capacitive reactive power is supposed to be imported from mains, values <1 means that inductive reactive power is imported from the mains.

Import/Export

Gen-set produces the certain amount of reactive power to keep constant PF imported from the mains regardless the demand of the load. The requested power factor import is given by setpoint **Import PF (page 234)**. Values >1 means that the gen-set is pushing the capacitive power to the system (sytem Gen-set - Load- Mains), values <1 means that the gen-set is pushing the inductive power to the system.

Transfers of load

Type of transfer of load between mains and gen-set and vice versa is adjusted via setpoints **Transfer BusGen To Mains (page 352)** and **Transfer Mains To Gen Bus (page 351)**.

Open	Transfer of the load from generator to mains and vice versa without parallel work and synchronization (one breaker opens and second is closed - checking feedbacks). The setpoint Open Transfer Min Break (page 350) sets the minimal duration of break.
Close Only	Transfer of the load from generator to mains and vice versa with synchronization and parallel work. The maximal time of parallel work is given by setpoint Close Transfer Max Duration (page 350) .
	In case of synchronization fail, MCB stays close and gen-set is stopped.
Close Primarily	Transfer of the load from generator to mains and vice versa with synchronization and parallel work. The time of parallel work is given by setpoint Close Transfer Max Duration (page 350) .
	In case of synchronization fail, open transfer is done.
Soft Transfer	Transfer of the load from generator to mains and vice versa with parallel work and soft loading/unloading of the gen-set. This function is proceeded like the closed transfer, but there is time limitation of loading/unloading of the gen-set adjusted via setpoint Load Ramp (page 353). The transfer is succeed only when the gen-set is fully loaded/unloaded (level of load when mains is considered as unloaded - gen-set is loaded is adjusted via setpoint Mains Unload MCB Open Window (page 353)), level of load when gen-set is considered as unloaded is adjusted via setpoint Unload MGCB Open Level Generator Unload GCB Open Level (page 352)).

Types of transfers



Transfer of load in MAN mode

Behavior of transfer of load in MAN mode is adjusted via setpoint **CB Control In MAN Mode (page 238)**. For details see the setpoint description.

Transfer of load in AUTO mode

Behavior of transfer of load in AUTO mode is affected by binary inputs FORCE ISLAND (PAGE 666), FORCE PARALLEL (PAGE 666) and REMOTE START/STOP (PAGE 677).

When more binary inputs are activated at the same time, their priority is shown in the list below:

- FORCE ISLAND (PAGE 666) (highest priority).
- REMOTE START/STOP (PAGE 677).
- FORCE PARALLEL (PAGE 666) (lowest priority).

Note: AMF function has the highest priority (if it is enabled).

Logical binary input	AUTO mode	TEST mode
Force Island (page 666)	 When activated: starts gen-set the transfer of load from mains to generator is done When deactivated: the transfer of load from generator to mains is done cooling and stopping of the gen-set 	 The gen-set is started anyway due to the TEST mode. When activated: the transfer of load from mains to generator is done When deactivated: the transfer of load from generator to mains is done
Remote Start/S top (page 677)	 When activated: starts gen-set if mains parameters ok - synchronize, run in parallel if mains parameters not ok - run in island When deactivated: unloading (if gen-set was in parallel), cooling and stopping of the gen-set 	 The gen-set is started anyway due to the TEST mode. When activated: if mains parameters ok - synchronize, run in parallel When deactivated: unloading, of the gen-set, opening GCB
Force Parallel (Page 666)	 When activated: check mains parameters - if not ok no action, if ok the procedure follows starts the gen-set, synchronize, parallel operation in case of mains fail - gen-set is stopped (if AMF function is disabled, otherwise it goes to island operation) When deactivated: 	 The gen-set is started anyway due to the TEST mode. When activated: check mains parameters - if not ok no action, if ok the procedure follows synchronize, parallel operation When deactivated: unloading, of the gen-set, opening GCB



Logical binary input	AUTO mode	TEST mode
	 unloading, cooling and stopping of the gen-set 	

Type of transfer of load between mains and gen-set and vice versa is adjusted via setpoints **Transfer BusGen To Mains (page 352)** and **Transfer Mains To Gen Bus (page 351)**.

5.3.7 Parallel to mains operation - MINT application

If the MCB is closed (**MCB FEEDBACK (PAGE 672)** is present) and the gen-set has been synchronized to the bus bar, the parallel to mains operation will follow. It consists of the following phases:

Ramping the power

Power up

The first phase of the parallel to mains operation is the ramping of the gen-set up to the desired power level derived from the **#System BaseLoad (page 235)** or up to the load given by load sharing with other gen-sets connected to the bus bar. The speed of the ramp is given by the setpoint **Load Ramp (page 353)**. The setpoint adjusts the ramp time for a change from 0% to 100% of nominal power.

Power down

When a stop command is received the gen-set load is ramped down before opening the GCB. The ramp speed is given by the setpoint Load Ramp (page 353) and the end level is given by Unload MGCB Open LevelGenerator Unload GCB Open Level (page 352).

When the GCB button is pressed, the gen-set load is ramped down before opening the GCB as well. But after the GCB has been opened, the gen-set remains running until a stop command comes or the GCB is pressed again to reclose the GCB.

Load control

If MCB FEEDBACK (PAGE 672) is active (parallel to mains operation) the load of group of the gen-sets is controlled to reach the power defined by setpoint **#System BaseLoad (page 235)**. Each loaded gen-set takes equal part (relative to their nominal power) from **#System BaseLoad (page 235)** requested value. The load is regulated locally in each controller by load control regulation loop, load-sharing regulation loop is not active. The setpoint **#System BaseLoad (page 235)** is also used for determining which gen-sets have to run or not. Control is adjusted via setpoints **Load Gain (page 348)** and **Load Int (page 349)**.

PF control

If MCB FEEDBACK (PAGE 672) is active (parallel to mains operation) the value of PF (power factor) of group of the gen-sets is controlled to reach the PF defined by setpoint **#System Power Factor (page 236)**. The PF is regulated locally in each controller by PF control regulation loop, VAr-sharing regulation loop is not active. Control is adjusted via setpoints **PF Gain (page 356)** and **PF Int (page 357)**.

5.3.8 AMF operation

The "AMF function" represents the automatic start in the event that the mains have failed and stop after the mains have been restored. The automatic start can be enabled or disabled by binary inputs **AMF START BLOCK**



(PAGE 615) or MAINS FAIL BLOCK (PAGE 671). Note: The AMF function works only in AUTO mode.

Mains failure detection

The mains are considered as faulty when one or more of the following conditions are valid:

- The mains voltage is out of the limits given by the setpoints Mains Undervoltage (page 321) and Mains Overvoltage (page 320) for a time period longer than Mains < > Voltage Delay (page 321).
- The mains frequency is out of the limits given by the setpoints Mains Underfrequency (page 322) and Mains Overfrequency (page 322) for a time period longer than Mains <> Frequency Delay (page 323).
- ▶ The MCB close command was not successful and the alarm Wrn MCB Fail (page 809) was not reset.
- Phase rotation is incorrect.
- The mains import is higher than limit given by setpoints Overload BOC (page 304) for a time longer than Overload Delay (page 304).
- The mains current is higher than limit given by setpoint Short Circuit BOC (page 305) for a time longe than Short Circuit BOC MPR Delay (page 305).
- The IDMT protection is activated due to overcrossing the IDMT curve set by setpoints IDMT Overcurrent Delay (page 306).

Healthy mains detection

The mains are considered to be healthy when all of following conditions are valid:

- The mains voltage is within the limits given by the setpoints Mains Undervoltage (page 321) and Mains Overvoltage (page 320).
- The mains frequency is within the limits given by the setpoints Mains Underfrequency (page 322) and Mains Overfrequency (page 322).
- The alarm Wrn MCB Fail (page 809) is not active (if MCB feedback is active). This condition is not required if MCB is open (MCB feedback is inactive).
- Phase rotation is correct.

The AMF procedure

When the mains failure is detected, the following steps are performed:

- ▶ If the setpoint MCB Opens On (page 325) is set to Mains Fail, the MCB is opened.
- > The timer for automatic start of the gen-set Emergency Start Delay (page 319) begins to count down.
- After the timer has elapsed, the gen-set is started.

Note: The automatic start of the gen-set due to AMF function can be disabled by the binary inputs AMF START BLOCK (PAGE 615) or MAINS FAIL BLOCK (PAGE 671).

If the setpoint MCB Opens On (page 325) is set to Gen Run, the MCB is opened once the generator voltage is within limits (after Minimal Stabilization Time (page 278) elapses).

Note: If the mains are restored to health and the gen-set is still not connected to the load, the controller interrupts the startup process and closes back the MCB.

Note: Signal Gen Run is sent to InteliMains controller through internal distributed signal.



- After Open Transfer Min Break (page 350) elapses, the GCB and MGCB (in case of MGCB application) is closed and the gen-set begins to supply the load.
- > After the mains restored to normal, the timer Mains Return Delay (page 319) begins to count down.
- Transition of load back to mains is adjusted via setpoint Transfer BusGen To Mains (page 352). Behavior of transition is also is affected by binary inputs FORCE ISLAND (PAGE 666), FORCE PARALLEL (PAGE 666) and REMOTE START/STOP (PAGE 677). See more in Transfer of load in AUTO mode (page 76) chapter.

IMPORTANT: Controller has this behavior only in AUTO mode!

5.3.9 Engine cool down and stop

The cool down phase follows after the stop command has been issued and the GCB has been opened.

- Duration of the cool down phase is determined by the setpoint Cooling Time (page 281).
- Cooling is performed either at nominal speed (generator voltage and frequency protections are evaluated) or at idle speed (generator voltage and frequency protections are not evaluated). Selection of the speed is done by the setpoint Cooling Speed (page 280).
- > The cool down can be finished manually in MAN mode by pressing the STOP button.
- If a new start request comes, the cool down will be interrupted and the gen-set will go back to the stabilization phase. If the cooling was at nominal speed, the stabilization timers will not count down again so the GCB is ready to be closed (after 2 seconds delay).

When the cool down is finished, the output FUEL SOLENOID (PAGE 715) is de-energized and STOP SOLENOID (PAGE 738) is energized. The engine will stop within the time period determined by the setpoint Stop Time (page 281). If the engine does not stop within this time, the alarm Wrn Stop Fail (page 811) will be issued.

The output STOP SOLENOID (PAGE 738) is energized until the engine is stopped, but at least for the duration of Stop Time (page 281). If the Stop Time (page 281) has elapsed and the engine has still not stopped, the STOP SOLENOID (PAGE 738) is de-energized for 5 s and then energized again for Stop Time (page 281) and this repeats until the engine is stopped.

Stopped gen-set evaluation

The gen-set is considered as stopped when all of following conditions are valid:

- ▶ The engine speed is lower than 2 RPM.
- The generator voltage in all phases is lower than 10 V.
- None of Additional running engine indications (page 132) signals is active.

5.3.10 Power management

IMPORTANT: Power management is relevant only for MINT application.

IMPORTANT: The gen-set will take part of the power management (= will be active) only if the controller is in AUTO mode!

The Power management function decides how many gen-sets should run and selects particular gen-sets to run. The power management is applicable in cases multiple gen-sets run in parallel to mains or in the island operation. The function is based on the load evaluation in order to provide enough of available running power. Since it allows the system to start and stop gen-sets based on the load demand, it can vastly improve the system fuel efficiency. In other words, an additional gen-set starts when the load of the system raises above certain level. The additional gen-set stops, when the load of the system drops down below a certain level. The process of determining gen-set start and stop is done in each controller; there is no "master slave" system.



Therefore, the system is very robust and resistant to failures of any unit in the system. Each of the controllers can be switched off without influencing the whole system. Except the situation the respective gen-set is not available for the power management.

The power management evaluates so called load reserve. The load reserve is calculated as difference between actual load and nominal power of running gen-sets. The reserve is calculated as absolute value (in kW / kVA) or relatively to the nominal power of gen-set(s) (in %). The setpoint **#Power Management Mode (page 333)** is used to select the absolute or relative mode.

The automatic priority swapping function focuses on efficient run of gen-set in regards to running hours and genset size.

IMPORTANT: The function of the controller is designed to handle the maximum sum of nominal power at 32000 kW (or 3200,0 with decimal number).

Example: There are 20 gen-sets each with 1000 kW of nominal power. The sum of the nominal power is 20000 kW. Therefore the decimal power format in 0.1 kW cannot be used because the sum exceeds 32000. Therefore power format in kW needs to be chosen.

Basic power management

The setpoint **Power Management (page 332)** enables and disables the gen-set to be active within the power management and makes automatic load dependent starts and stops. If the power management is disabled, the start and stop of the gen-set do not depend on the load of the group. If the gen-set remains in AUTO mode, the running condition depends only on the Logical binary inputs **REMOTE START/STOP (PAGE 677)**.

The Logical binary inputs REMOTE START/STOP (PAGE 677) requests the system to start or stop. If the input is not active, the system stops with delay **#System Stop Delay (page 335)** after the input has been deactivated and will not start again if in AUTO mode. If the input is activated again, the delay **#System Start Delay (page 334)** starts to count down. Once the delay elapsed, the system is activated and can be started by the power management. In other words, the power management is activated only if the Logical binary inputs **REMOTE START/STOP (PAGE 677)** is activated, the option of setpoint **Power Management (page 332)** = ENABLED and the AUTO mode is selected.

Note: The gen-set performs load and VAR sharing whenever it is connected to the bus bar i.e. it is independent on whether the controller is in AUTO or MAN mode or whether the power management is active or not.

Function of power management can be temporarily blocked after **REMOTE START/STOP** (PAGE 677) activation a count down of **#System Start Delay** (page 334). The delay is given by setpoint **Power Management Delay** (page 332). In this delay all gen-sets where power management is enabled are running. After this period elapses, only the gen-set(s) needed according to the Power Management calculation stay running and the rest is stopped.

Principle of power management

Internal conditions based on remaining load reserves and priorities are evaluated once a delay is elapsed. If the load reserve is insufficient the gen-set is started after delay given by the setpoint **#Next Engine Start Delay** (page 340) is elapsed. Once the gen-set runs the controller evaluates stopping conditions based on load reserves and priorities. If the reserve is sufficient enough to stop a particular gen-set, it is stopped after delay given by the setpoint **#Next Engine Stop Delay** (page 340) is elapsed. All the time the system stop condition – i.e. the Logical binary inputs **REMOTE START/STOP** (PAGE 677) deactivated – is evaluated as well. Once the delay given by the setpoint **#System Stop Delay** (page 335) has elapsed all gen-sets in AUTO mode are stopped. Following figure depicts the system activation and deactivation logic.





Setpoint **#Overload Next Start Delay (page 341)** is used in case that **#Overload Next Start Protection (page 341)** is enabled and gen-sets are running at **#Overload Next Start Level (page 341)** or more of their nominal power.

Load reserve

The power management is based on the load reserve concept. The load reserve is defined as a difference of the running nominal power of the group within power management and the total load of the system. There are two ways how to determine the load reserve. The absolute power management allows the system to keep the load reserve higher or equal to value in kW given by a relevant setpoint. The relative power management assures that load reserve is kept higher or equal to relative portion in % of the nominal power of group (i.e. running gensets active in power management) given by a relevant set-point. Depending of the situation, load reserves are calculated differently in two cases:



Case #1

This case is used in island operation.

Reserve	Actual Reserve	Start condition	Stop condition
Absolute kW	$ARstrt = \sum Pg_{Nom} - \sum Pg_{Act}$ $ARstp = \sum Pg_{Nom}^* - \sum Pg_{Act}$	ARstrt < #LoadResStrt	ARstp> #LoadResStop
Relative %	$RRstrt = [(\sum Pg_{Nom} - \sum Pg_{Act}) / \sum Pg_{Nom}].100\%$ $RRstp = [(\sum Pg_{Nom}^* - \sum Pg_{Act}) / \sum Pg_{Nom}^*].100\%$	RRstrt < #%LdResStrt	RRstp> #%LdResStop

Case #2

This case is used in parallel to mains operation.

Reserve	Actual Reserve	Start condition	Stop condition
Absolute kW	ARstrt = ∑Pg _{Nom} - BaseLoad ARstp = ∑Pg* _{Nom} - BaseLoad	ARstrt < #LoadResStrt	ARstp> #LoadResStop
Relative %	$RRstrt = [(\sum Pg_{Nom} - BaseLoad) / \sum Pg_{Nom}].100\%$ $RRstp = [(\sum Pg_{Nom}^* - BaseLoad) / \sum Pg_{Nom}^*].100\%$	RRstrt < #%LdResStrt	RRstp> #%LdResStop

List of abbreviations:

- ARstrt .. Actual Absolute reserve in kW or kVA for engine start calculation.
- ARstp .. Actual Absolute reserves in kW or kVA for engine stop calculation.
- RRstrt .. Actual Relative reserve in % for engine start calculation.
- RRstp .. Actual Relative reserves in % for engine stop calculation.
- ΣPgNom .. Sum of Nominal power of all gen-sets on the bus.
- > ΣPg*Nom .. Sum of Nominal power of all gen-sets on the bus apart of the one, which is going to be stopped.
- ΣPgAct .. Sum of Actual power of all gen-sets on the bus = system load.
- BaseLd .. Baseload is given by the setpoint #System BaseLoad (page 235)

Note: System starting sequences may be very different due to their complexity (i.e. gen-sets which do not take part in power management, various nominal powers etc.). Each system should be considered individually.

Starting sequence

As written above, the power management is based on the load evaluation in order to provide enough of available running power. An additional gen-set starts when the load of the system raises above certain level to keep the load reserve big enough. Following figure depicts the situation when an additional gen-set is requested to join the already running gen-set(s) to the bus.





Image 5.18 Start sequence of power management

As shown above, the load of the system has increased above the level defined by the start condition – i.e. the load reserve is not sufficient as required by the appropriate setpoint. Further explanation is provided in chapters **Absolute power management (page 84)** and **Relative power management (page 87)**.

The level is illustrated by the green dashed line. If the load reserve keeps insufficient for longer time than defined by the setpoint **#Next Engine Start Delay (page 340)**, the next gen-set is actually started. The standard starting sequence follows. Once the synchronization procedure is done, the GCB breaker is closed and the gen-set power is ramping up. Once loaded, the system load reserve is raised and becomes sufficient again. Please note the sum of nominal power of all gen-sets on the bus is increased by the nominal power of the additional gen-set.

Stopping sequence

As it is written above, the power management is based on the load evaluation in order to provide enough of available running power. An additional gen-set stops when the load of the system drops below certain level to avoid inefficient run of the gen-set. Following figure depicts the situation when a gen-set is requested to stop due to the power management.





Image 5.19 Stopping sequence of power management

As shown above, the system load has decreased below the level defined by the stop condition – i.e. the load reserve is over a limit given by the appropriate setpoint. Further explanation is provided in chapters **Absolute power management (page 84)** and **Relative power management (page 87)**.

The level is illustrated by the red dashed line. If the load reserve keeps over this limit for longer time than defined by setpoint **#Next Engine Stop Delay (page 340)**, the next gen-set is actually requested to stop. Once the gen-set is unloaded, the GCB breaker is opened. Please note the sum of nominal power of all gen-sets on the bus is decreased by the nominal power of the stopped gen-set. The cooling sequence follows before the gen-set is actually stopped. The gen-set is ready to be started if the system load increases again.

Absolute power management

The power management based on absolute load reserves can be successfully used in cases the load portions are similar to the gen-set capacity or even bigger. The goal of the absolute reserve mode is to provide the same load reserve all the time independently on how many gen-sets are currently running. The mode perfectly fits for industrial plants with large loads.

The absolute power management guarantees adjustable load reserve in kW. This mode is active when **#Power Management Mode (page 333)** is set to ABS [kW] mode.





Image 5.20 Power management based on absolute load reserve

Example: An example of absolute power management is shown on the figure below. There are three gensets with following choice of setpoints:

Gen-set	Nominal power	Power management	#Power management mode	Priority	#Priority Auto Swap	#Starting Load Reserve X	#Stopping Load Reserve X
Gen-set #1	200 kW	ENABLED	ABS (kW)	1	DISABLED	100 kW	125 kW
Gen-set #2	500 kW	ENABLED	ABS (kW)	2	DISABLED	100 kW	125 kW
Gen-set #3	1 000 kW	ENABLED	ABS (kW)	3	DISABLED	100 kW	125 kW





Image 5.21 Absolute power management example

As it is shown on both figures above, the additional gen-set is added once the actual load reserve is below the level given by the appropriate setpoint of load reserve. The additional gen-set is removed once the actual load reserve is above the level set by appropriate setpoint of load reserve.

The green dashed line depicts the value of load at which the additional gen-set is requested to start. This value of the load value is linked with the setpoint **#Starting Load Reserve 1 (page 335)** (or other selected reserve set) in following way:

Sum of nominal power for start - **#Starting Load Reserve 1 (page 335)** (or other selected reserve set) = value of load when additional gen-set requested to start (e.g.: 700 kW – 100 kW = 600 kW).

The red dashed line depicts the value of load at which the additional gen-set is requested to stop. This value of the load value is linked with the setpoint **#Stopping Load Reserve 1 (page 336)** (or other selected reserve set) in following way:

Sum of nominal power for stop - **#Stopping Load Reserve 1 (page 336)** (or other selected reserve set) = value of load when additional gen-set requested to stop (e.g.: 700 kW – 125 kW = 575 kW).



There are 2 sets of setpoints for starting and stopping gen-sets in absolute power management.

- #Starting Load Reserve 1 (page 335) and #Stopping Load Reserve 1 (page 336)
- #Starting Load Reserve 2 (page 337) and #Stopping Load Reserve 2 (page 338) considered if binary input LOAD RES 2 ACTIVE (PAGE 670) is activated

Note: All controllers cooperating together in Power management must have the same load reserve set selected.

Relative power management

The power management based on relative load reserves perfectly fits to those applications with such load portions connected to the group at once are much lower than the gen-set nominal power. This mode helps to achieve the maximal lifetime of the gen-sets, as they can be operated within optimal load range. The maximal size of the load connected at once depends on number of actually working gen-sets. The more gen-sets are connected to the bus bar the bigger load portion can be connected at once.

The relative power management guarantees that the engines are not continuously loaded more than to a certain level. This mode is active when **#Power Management Mode (page 333)** is set to REL [%] mode.



Image 5.22 Power management based on relative load reserve



Example: An example of relative power management is shown on the figure below. There are three gen-sets with following choice of setpoints:

Gen-set	Nominal power	Power management	#Power management mode	Priority	#Priority Auto Swap	#Starting Rel Load Reserve X	#Stopping Rel Load Reserve X
Gen-set #1	200 kW	ENABLED	REL (%)	1	DISABLED	35 %	40 %
Gen-set #2	500 kW	ENABLED	REL (%)	2	DISABLED	35 %	40 %
Gen-set #3	1 000 kW	ENABLED	REL (%)	3	DISABLED	35 %	40 %



Image 5.23 Relative power management example



As it is shown on both figures above, the additional gen-set is added once the actual load reserve is below the level given by the appropriate setpoint of load reserve. The additional gen-set is removed once the actual load reserve is above the level set by appropriate setpoint of load reserve.

The green dashed line depicts the value of load at which the additional gen-set is requested to start. This value of the load value is linked with the setpoint **#Starting Rel Load Reserve 1 (page 336)** (or other selected reserve set) in following way:

(100 % -**#Starting Rel Load Reserve 1 (page 336)** (or other selected reserve set)) * Sum of Nominal power = Value of load when additional gen-set requested to start in kW (in % of nominal power), e.g.: (100 % - 35 %) * 700 kW = 455 kW (65 % of nominal power).

The red dashed line depicts the value of load at which the additional gen-set is requested to stop. This value of the load value is linked with the setpoint **#Stopping Rel Load Reserve 1 (page 337)** (or other selected reserve set) in following way:

(100 % - **#Stopping Rel Load Reserve 1 (page 337)** (or other selected reserve set)) * Sum of Nominal power = Value of load when additional gen-set requested to stop in kW (in % of nominal power), e.g.: (100 % - 40 %) * 700 kW = 420 kW (60 % of nominal power).

There are 2 sets of setpoint for starting and stopping gen-sets in relative power management.

- #Starting Rel Load Reserve 1 (page 336) and #Stopping Rel Load Reserve 1 (page 337)
- #Starting Rel Load Reserve 2 (page 338) and #Stopping Rel Load Reserve 2 (page 339) considered if binary input LOAD RES 2 ACTIVE (PAGE 670) is activated

Note: All controllers cooperating together in Power management must have the same load reserve set selected.

Priorities

The priority of the gen-set within the group is given by the setpoint **Priority (page 333)**. Lower number represents "higher" priority, i.e. a gen-set with lower number starts before another one with higher number. In other words, the setpoint **Priority (page 333)** means order in which gen-sets are started and connected to the bus. An example is shown on the figure below. There are four gen-sets with following choice of setpoints:

Gen-set	Nominal power	Power management	#Power management mode	Priority	#Priority Auto Swap	#Starting Load Reserve X	#Stopping Load Reserve X
Gen-set #1	200 kW	ENABLED	ABS (kW)	4	DISABLED	50 kW	70 kW
Gen-set #2	200 kW	ENABLED	ABS (kW)	3	DISABLED	50 kW	70 kW
Gen-set #3	200 kW	ENABLED	ABS (kW)	2	DISABLED	50 kW	70 kW
Gen-set #4	200 kW	ENABLED	ABS (kW)	1	DISABLED	50 kW	70 kW





Image 5.24 Example of priorities in power management

By choosing the setpoint **Priority (page 333)** = 1, the gen-set #4 is running all the time in the example shown on the figure above (AUTO mode selected, Power management enabled and LBI **REMOTE START/STOP (PAGE 677)** activated).

The LBI TOP PRIORITY (PAGE 680) can be used to force priority 0 into the setpoint Priority (page 333). Priority 0 is the "highest" one, which means the gen-set will be running all the time while the power management is switched on.

If more than one gen-set have the same priority, they will act as "one big" gen-set. There are methods of automatic optimization of the priorities to achieve specific behavior of the group such as equalizing engine hours of the gen-sets or selection of optimal gen-sets to run according to their size and current load demand.

Priority auto swap

As stated in the chapter **Priorities (page 89)**, the operator is able to select the order of gen-set starting. There is also the option of automatic priority selection. The controllers are sharing data concerning the running hours and all important information relevant to the actual load. Thanks to the Automatic priority swapping function the controllers choose the gen-set(s) to be running with consideration of their running hours and the actual load.



The running hours equalization function keeps a constant maximal difference of gen-set's running hours. The efficient function keeps running only the gen-sets with suitable nominal power to avoid inefficient fuel consumption or gen-set overload.

Note: The Automatic priority swapping function does not change the setpoint **Priority (page 333)**. The function sets the order of gen-sets by virtual values "engine priority".

Run hours equalization

The gen-sets engine priorities are automatically swapped to balance engine running hours. In other words, the controllers compare running hours of each gen-set and select gen-set(s) to run in order to maintain constant maximal difference of running hours. Up to 32 controllers are supported. This function is activated via setpoint **#Priority Auto Swap (page 334)** = RUN HOURS.

The value of running hours which is used in run hours equalization is calculated by following formula:

RHE = Running Hours (page 585) - Run Hours Base (page 342)

RHE is considered value for running hours equalization, **Running Hours (page 585)** is a cumulative sum of run hours available in statistic values of the controller, **Run Hours Base (page 342)** is a setpoint. This setpoint may be used in the case of gen-sets with different runs hours are intended to be set at the same initial point (e.g. a new gen-set and a used gen-set after retrofit maintenance inspection).

The Running hours equalization function compares RHE value of each controller in the group. Once the difference between RHE of individual controllers is higher than **#Run Hours Max Difference (page 342)** (i.e. **#Run Hours Max Difference (page 342)** + 1), the gen-set(s) with the lowest RHE is/are started.

Example: The system structure and its settings is shown on the figure below.



Image 5.25 Example of the system

3 cases are considered:

- Case #1: 2 gen-gets available
- Case #2: 3 gen-gets available with same initial RHE.
- Case #3: 3 gen-gets available with different initial RHE.

Case #1:

Gen-set 1 running hours = 250 -> running hours considered in RHE = 100 (150 - Run Hours Base (page 342))



Gen-set 2 running hours = 450 -> running hours considered in RHE = 200 (250 - Run Hours Base (page 342))

Both gen-sets have the same nominal power of 700 kW. Originally, priority of gen-sets was G1 = 2, G2 = 1. Load demand in this example is constant and it is 500 kW (i.e. only one engine is running at any time). In this case, the controllers set the engine priority of the gen-set 1 to 1 because it has the lowest considered RHE and the difference between RHE2 (i.e. considered RHE of gen-set 2) and RHE1 is higher than **#Run Hours Max Difference (page 342)** that is set to 10h.

	Run hours	#RunHoursBase	RHE
Gen-set #1	250	150	100
Gen-set #2	450	250	200

The gen-set 1 runs for 100 hours to equalize the RHE of both gen-sets. The gen-set 1 keeps running until the difference between RHE1 and RHE2 exceeds **#Run Hours Max Difference (page 342)** (i.e. 10h). The gen-set 1 runs 100 + **#Run Hours Max Difference (page 342)** + 1 = 100 + 10 + 1 = 111 hours. After 111 hours the gen-sets 2 has the lowest RHE and the difference between RHE1 and RHE2 is higher than **#Run Hours Max Difference (page 342)** + 1 = nound runs to equalize the RHE of both gen-sets and then additional **#Run Hours Max Difference (page 342)** + 1 hours (i.e. 11 + 10 + 1 = 22 hours). The evolution of RHE1 and RHE2 is shown on the figure below.



Image 5.26 Run hours equalization - case #1

Step	0	1	2	3	4	5
RHE1	100	211	211	233	233	255
RHE2	200	200	222	222	244	244
Run G1 (ΔRHE1)	0	111	0	22	0	22
Run G2 (ΔRHE2)	0	0	22	0	22	0

From the example of the case #1, it can be concluded that the gen-sets are swapped after the duration determined by following formula:

SwapTime = Second lowest considered running hours – Current lowest considered running hours + **#Run** Hours Max Difference (page 342) +1

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Case #2:

- Gen-set 1 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)
- Gen-set 2 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)
- Gen-set 3 running hours = 0 -> running hours considered in RHE = 0 (0-RunHoursBase)

Each gen-set has the same RHE = 0 h. By applying the SwapTime formula, we get the run time of gen-set 1 before next swapping:

SwapTimeG1 = 0 - 0 + 10 + 1 = 11

Similar way, we get the run time of gen-set 2 before next swapping:

SwapTimeG2 = 11 - 11 + 10 + 1 = 11

Finally, we get the run time of gen-set 3 before next swapping:

SwapTimeG2 = 11 - 0 + 10 + 1 = 22

Please refer to figure below to understand the evolution of RHE of gen-sets in this particular case.



Image 5.27 Run hours equalization - case #2

step	0	1	2	3	4	5	6	7	8	9	10	11	12	13
RHE1	0	11	11	11	11	33	33	33	33	55	55	55	55	77
RHE2	0	0	11	11	22	22	33	33	44	44	55	55	66	66
RHE3	0	0	0	22	22	22	22	44	44	44	44	66	66	66
Run G1 (ΔRHE1)	0	11	0	0	0	22	0	0	0	22	0	0	0	22
Run G2 (ΔRHE2)	0	0	11	0	11	0	11	0	11	0	11	0	11	0
Run G3 (ΔRHE3)	0	0	0	22	0	0	0	22	0	0	0	22	0	0

Case #3:

- Gen-set 1 running hours = 250 -> running hours considered in RHE = 100 (150-RunHoursBase)
- Gen-set 2 running hours = 450 -> running hours considered in RHE = 200 (250-RunHoursBase)
- Gen-set 3 running hours = 750 -> running hours considered in RHE = 250 (500-RunHoursBase)

The gen-set 1 has the lowest RHE1 = 100 h. By applying the SwapTime formula, we get the run time of gen-set 2 before next swapping:

SwapTimeG1 = 200 - 100 + 10 + 1 = 111

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Till the step 5, the evolution of the gen-set swapping is the same as in the case #1, just gen-set 1 and gen-set 2 involve. In the step 6 the gen-set 2 can run only 17 hours (previously 22 hours) because the gen-set 3 involves. The evolution of RHE1, RHE2 and RHE3 is shown on the figure below.



Image 5.28 Run hours equalization - case #3

step	0	1	2	3	4	5	6	7	8	9	10	11	12	13
RHE1	100	211	211	232	233	255	255	255	272	272	272	288	288	288
RHE2	200	200	222	222	244	244	261	261	261	277	277	277	294	294
RHE3	250	250	250	250	250	250	250	266	266	266	283	283	283	299
Run G1 (ΔRHE1)	0	111	0	22	0	22	0	0	17	0	0	16	0	0
Run G2 (ΔRHE2)	0	0	22	0	22	0	17	0	0	16	0	0	17	0
Run G3 (ΔRHE3)	0	0	0	0	0	0	0	16	0	0	17	0	0	16

Note: Setting **#Run Hours Max Difference (page 342)** = 5 does not mean that gen-sets swap every 5 hours. The Swap time is determined by the formula stated above. Please read the entire chapter Running hours equalization for better understanding.

Note: In the case **#Run Hours Max Difference (page 342)** is set to 0 and all gen-set in the group are at the same initial point (RHE are equal), the gen-set swapping happens every hour.

Efficiency

The gen-sets engine priorities are automatically swapped to best fit to the actual load demand (load demand swap - LDS). Also engine running hours are taken to the calculation (run hours equalization - RHE). This function is activated via setpoint **#Priority Auto Swap (page 334)** = Efficiency.

Algorithm of function:

- ▶ In the first step, the gen-sets are sorted according to their nominal power.
- ▶ In the second step, the gen-sets with the same nominal power are sorted according to their RHE
- The gen-set(s) with nominal power which fits the most actual load demand are chosen. From those with same nominal power, the gen-set(s) with lowest RHE are chosen. Selection formula:



- #Power Management Mode (page 333) = ABS (kW)
 - Nominal power of gen-set > actual load demand + #Starting Load Reserve 1 (page 335)
- #Power Management Mode (page 333) = REL (%)
 - Nominal power of gen-set > (actual load demand × 100)/(100 #Starting Rel Load Reserve 1 (page 336))
- If two or more gen-sets are available for taking over the load always the one with the lowest CAN address is chosen.
- If load demand is higher than nominal power of the biggest gen-set, this one is fixed and the whole process repeats from point the third bullet.
- **Example:** The system structure and its settings is shown on the figure below.



Image 5.29 Example of the system

Following table provide an example of gen-set selection in function of system load evolution. The table is an example of Efficiency priority optimization function (**#Power Management Mode (page 333)** = ABS (kW) and **#Starting Load Reserve 1 (page 335)** = 20 kW).

System Load [kW]	Running gen-sets		Description	Total Running power within PM [kW]	Relative load of gen-sets [%]
40		5		100	40
60		5		100	60
80	5 2 [0h]	2 start 5 stop	LDS Swap	300	26
100	2 [10h]			200	50
120	2 [20h]			200	60
120	2 [30h] 3 [10h]	3 start 2 stop	RHE Swap	400	30
120	3 [20h]			200	60
140	3 [30h]			200	70
180	3 [40h] 1	1 start 3 stop	LDS Swap	500	36



System Load [kW]	Running gen-sets		Description	Total Running power within PM [kW]	Relative load of gen-sets [%]
200	1			300	67
240		1		300	80
280	1 5	5 start	Gen#5 joins (LDS)	400	70
340		1 5		400	85
380	1 5 4 [20h]	4 start 5 stop	LDS + RHE Swap	600	63
400		1 4		500	80
440		1 4		500	88
480	1 4 5	5 start	Gen#5 joins (LDS)	600	80
540		1 4 5		600	90
580	1 4 5 2 [30h]	2 start 5 stop	LDS Swap	800	73
600		1 4 2		700	86
640		1 4 2		700	91
680	1 4 2 5	5 start	Gen#5 joins (LDS)	800	85
740		1 4 2 5		800	93
780	1 4 2 5	3 start 5 stop	LDS Swap	1000	78



System Load [kW]	Running gen-sets	Description	Total Running power within PM [kW]	Relative load of gen-sets [%]
	3 [40h]			
800	1 4 2 3		900	89
840	1 4 2 3		900	93
880	1 4 2 5 start 3 5	Gen#5 joins (LDS)	1000	88
940	1 4 2 3 5		1000	94

Minimal running power

Minimum Running Power function is used to adjust a minimum value of the sum of nominal power of all running gen-sets. If the function is active, then the gen-sets would not be stopped, although the reserve for stop is fulfilled. Function is activated via logical binary input **Min Run Power Active (page 673)**.





Image 5.30 Minimal running power

Setpoint **#Min Run Power (page 339)** is adjusted to 400 kW. Once the **MIN RUN POWER ACTIVE (PAGE 673)** is activated, the available nominal running power has to be equal or higher to 400 kW. Even if the load reserve is big enough to stop the gen-set #2 (nominal power 500 kW), the gen-set keeps running as at least 400 kW has to be available. The gen-set#1 (nominal power 200 kW) is not enough.

5.3.11 Control groups

The physical group of the gen-sets (i.e. the site) can be separated into smaller logical groups, which can work independently even if they are interconnected by the CAN2 bus. The logical groups are intended to reflect the real topology of the site when the site is divided into smaller gen-set groups separated from each other by bus-tie breakers. If the bus-tie breakers are closed the sub-groups have to work as one large group and if the bus-tie breakers are open, the sub-groups have to work independently.

- The group which the particular controller belongs to is adjusted by the setpoint Control Group (page 344). Use the defaulf setting 1 with all controllers, if there is no bus-tie breaker.
- The information which groups are currently linked together is being distributed via the CAN. Each controller can provide information about one BTB breaker. The breaker position is detected by the input function *GroupLink* (i.e. this input is to be connected to the breaker feedback).



- The two groups which are connected together by the BTB, are defined with parameters Group Link L (page 344) and Group Link R (page 345).
- Controller sends via CAN2 bus information that controllers from groups Group Link L and Group Link R are linked together, if the Group link function (signal associated with the function) is active. It sends information that the groups are separated, if the Group link function is not active.

Note: The "group link" function is independent on the group, where the controller itself belongs to. The controller can provide "group link" information about any two groups and it may not belong to one of the groups.

All gensets/controllers in linked groups cooperate with each other and perform load sharing, VAr sharing and power management together. These functionalities are performed independently in each group, when the groups are separated.

Example:

4 gen-sets separated by a BTB breaker into two groups of 2. The BTB position is detected by the controllers 2 and 3. The reason, why there are 2 controllers used for detection of the BTB position, is to have a backup source of the group link information, if the primary source (controller) is switched off.



Image 5.31 Example of control groups

Once the BTB breaker is closed, the control groups 2 and 3 become new group 2+3. Power management, load sharing and VAr sharing are performed within newly established group 2+3. Merging of the groups may result with a genset stopping, if power management evaluates that available Actual Reserve is high enough to stop a genset.

5.3.12 Distributed power management signals

Sharing of multiple Logical Binary Input (LBI) functions is critical for power management system operation, because several power management functionality require simultaneous activation of LBI functions in controllers, which are involved in power management operation. It can be done either automatically using CAN2 bus link between controllers or using dedicated LBI functions.

These LBI functions are shared automatically:



- System Start/Stop
- Min Run Power Act
- Load Res 2 Active
- MCB Feedback

These rules applies to the automatic sharing of the selected signals:

- 1. LBI state is automatically shared via CAN2 bus, if corresponding LBI function is configured in a controller. **Example:** Logical input Remote Start/Stop is configured with a controller. State of the signal is automatically transmitted to other controllers via CAN2 bus as System Start/Stop.
- 2. LBI state received from CAN2 bus is automatically used, if corresponding LBI function is not configured in a controller.

Example: LBI Remote Start/Stop is not configured with a controller, but automatically shared System Start/Stop is received from CAN2 bus. Controller follows state of the shared LBI signal then.



LBI state received from CAN2 bus is not used, if corresponding LBI function is configured in a controller.
 Example: LBI Remote Start/Stop is configured with a controller. Controller follows only state of signal linked with the Remote Start/Stop function. The function is not activated by a shared System Start/Stop signal.

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4. LBI function state transmitted via CAN2 bus is used only by controllers, which are in the same group as controller, which is source of the shared signal. Signal coming from controller in a different group is accepted only if the "source controller" group is linked with the "receiving controller" group.





5. LBI function can be configured with multiple controllers, which transmit through CAN2 bus state of the function. OR function applies to the function evaluation in controllers, in which the function is not configured. It means that function is activated by shared signal coming from any controller (rule 4. applies).

5.3.13 Regulation loops

Regulation loops overview

Regulation loops overview

Loop type	Related applications	Related setpoints
Frequency	MINT, SPtM, MCB, MGCB	Frequency Gain (page 347), Frequency Int (page 348)
Load sharing	MINT	Load Sharing Gain (page 349), Load Sharing Int (page 349)
Load	MINT, SPtM, MCB, MGCB	Load Gain (page 348), Load Int (page 349)
Voltage	MINT, SPtM, MCB, MGCB	Voltage Gain (page 356), Voltage Int (page 356)



Loop type	Related applications	Related setpoints
VAr sharing	MINT	VAr Sharing Gain (page 357), VAr Sharing Int (page 357)
PF control	MINT, SPtM, MCB, MGCB	PF Gain (page 356), PF Int (page 357)
Angle regulation	MINT, SPtM, MCB, MGCB	Angle Gain (page 348)

Speed, Frequency, Load sharing, Load regulation loops have one common output = Speed request. The value of this output is always composed from the contribution of each of the regulation loops.

Voltage, PF, VAr sharing have one common output = Voltage request. The value of this output is always composed from the contribution of each of the regulation loop.

Each of the regulation loops is active in some certain time during the process, which is given by the state of the automat. If no regulation loop is active the speed governor output is kept on the level given by setpoint **Speed Governor Bias (page 346)** or **Voltage Regulator Bias (page 354)** in case of voltage regulator output.

Note: All regulation loops are PID, but only PI components are visible as setpoints.

MINT regulation loops

Loop type	Description
Frequency	The frequency loop is active in the first phase of synchronization when the generator frequency is regulated to match the mains/bus frequency.
Load sharing	The load sharing loop is active in multiple-island operation.
Load	The load regulation loop is active when single gen-set is running in parallel with mains and during load transfers from mains to generator or vice versa. This regulation loop is also active when multiple gen-sets are running in parallel with Mains.
Voltage	The voltage regulation loop gets active after Minimal Stabilization Time (page 278) . The loop is deactivated at the beginning of cooling sequence.
VAr sharing	The VAr sharing loop is active in multiple-island operation.
PF control	The PF control loop is active when single gen-set is running in parallel with mains and during load transfers from mains to generator or vice versa. This regulation loop is also active when multiple gen-sets are running in parallel with Mains.
Angle regulation	The differential angle control loop is active during the synchronization when phase match type of synchronization is used.

SPtM regulation loop

Loop type	Description
Frequency	The frequency regulation loop gets active after Minimal Stabilization Time (page 278) . The loop is deactivated at the beginning of cooling sequence. Loop is not active in parallel operation. In parallel operation PF control loop is used.
Load	The load regulation loop is active when gen-set is running in parallel with mains and during load transfers from mains to generator or vice versa.
Voltage	The voltage regulation loop gets active after Minimal Stabilization Time (page 278) . The loop is deactivated at the beginning of cooling sequence. Loop is not active in parallel operation. In parallel operation PF control loop is used.
PF control	The PF control loop is active when gen-set is running in parallel with mains and during



Loop type	Description		
	load transfers from mains to generator or vice versa.		
Angle regulation	The differential angle control loop is active during the synchronization when phase match type of synchronization is used.		

Adjustment of regulation loops

The regulation loops have two adjustable factors: P-factor and I-factor (except angle regulation loop, which has P-factor only). The P-factor (gain) influences the stability and overshoot of the regulation loop and the I-factor (int) influences the steady-state error as well as the settling time. See the picture below for typical responses of a PI regulation loop.



Image 5.32 Typical responses of PI regulator

For manual tuning of a control loop use following method:

- Set both the I-factor and P-factor to 0.
- Increase the P-factor slightly until the system starts to oscillate.
- Adjust the P-factor back to approx. one half of the value where the oscillations started.
- Increase the I-factor slightly to achieve optimal resulting response.

IMPORTANT: Be ready to press emergency stop button in case the regulation loop would start to behave unacceptable while it is being adjusted.

5.3.14 Speed/Load control

The speed control output is used to control the speed or the power of the engine. The frequency regulation, load regulation and load sharing are realized through the speed control. The speed request is internal value of the regulator. This value is transformed to range -10 .. 10 V based on setpoints **Speed Governor Low Limit (page 346)** and **Speed Governor High Limit (page 346)**. This value of speed request is then transformed to request which comes out of the controller. There are several ways how to send this request to gen-set:

- Analog output (speed governor output)
- ECU speed control
- Binary pulse control



Speed control outputs

Analog Output (speed governor output)

The speed regulator of the engine is controlled by the analog signal from controller. Please see the chapter **Speed governor interface (page 49)** for more information about speed governor.

The direction of speed regulation required by Speed regulator of the engine is given by the setpoint **Speed Regulator Character (page 345)**. A full range change of the speed governor output (from **Speed Governor Low Limit (page 346)** to **Speed Governor High Limit (page 346)**) should cause 5-10% change of the engine speed (**Speed Governor Low Limit (page 346)** ~ 95% **Nominal RPM (page 248)**, **Speed Governor Bias** (page 346) ~ 100% **Nominal RPM (page 248)**, **Speed Governor High Limit (page 346)** ~ 105% **Nominal RPM (page 248)**).

IMPORTANT: Speed governor has to be adjusted for optimum performance before Speed/Load control adjusting. Check generator phase sequence before the first GCB connection.



Image 5.33 Example of speed governor curve

ECU speed control

In case that ECU with speed control support is configured, then the speed is controlled via ECU.

Binary pulse control

The internal speed request is transformed to Up/Down pulse control. These pulses get out of the controller via binary outputs SPEED UP (PAGE 736) and SPEED DOWN (PAGE 736). Length of pulses SPEED UP (PAGE 736) and SPEED DOWN (PAGE 736) depends on the difference of actual RPM and requested RPM (actual power and requested power, actual frequency and requested frequency) and on the parameter **Tau Speed Governor Actuator (page 347)**. **Tau Speed Governor Actuator (page 347)** defines the pulse duration which is needed for the speed controller to travel from minimal position to the maximal position. The Maximum length of pulses is limited to 5 s, the minimal length of pulses is limited to 150 ms and minimal length between the pulses is 200 ms.

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Speed/Load control adjustment

Synchronization adjustment

- Start the engine in MAN Mode.
- Set the engine RPM by speed trim on the speed governor or by Speed Governor Bias (page 346), Speed Governor Low Limit (page 346) and Speed Governor High Limit (page 346) to achieve frequency according to setpoint Nominal Frequency (page 247).
- ► To start the synchronization press GCB ON/OFF button. GCB LED starts to flash to indicate synchronization. To stop synchronization press again GCB ON/OFF.
- Adjust Frequency Gain (page 347) to unstable speed control and decrease value by 30 % to insure stable performance.
- Adjust Frequency Int (page 348) to stable (fast and smooth) slip control. Synchroscope movement on the controller measure screen should slow down and stop (in any position, because Angle Gain (page 348) control is off).
- Set Angle Gain (page 348). Synchroscope on the controller measure screen should move slowly and stop in "up" position. Set Angle Gain (page 348) to unstable value (synchroscope swings) and decrease value by 30 % to insure stable performance.

Load control adjustment

IMPORTANT: Prior to Speed/Load control adjustment, the Voltage/PF control has to be adjusted.

MINT application

Load control loop is active in parallel to mains mode only (MCB feedback closed). Switch off other engines while adjusting.

- 1. Set #System BaseLoad (page 235) setpoint to 30 % of one gen-set.
- 2. Set Load Gain (page 348) to the same value as Angle Gain (page 348). Set Load Int (page 349) to zero.
- 3. Start the gen-set in MAN Mode, press GCB ON/OFF button to synchronize and close gen-set to mains.
- 4. When GCB is closed, gen-set load slowly increases to **#System BaseLoad (page 235)** value. Check that gen-set power is positive (CT polarity).
- Increase Load Int (page 349) to unstable load control and decrease value by 30 % to insure stable performance. When Load Int (page 349) factor is set to zero gen-set load can differ from required #System BaseLoad (page 235).
- To adjust and optimize Load Int (page 349) change #System BaseLoad (page 235) several times between 30 and 70 % of Nominal Power (page 242). Usually setting Load Int (page 349) to 100 % gives optimal performance.
- 7. When gen-set is running under full load check if
 - a. Speed governor output voltage value is not limited (it does not reach Speed Governor Low Limit (page 346) or Speed Governor High Limit (page 346))
 - b. Speed governor actuator is not mechanically limited or operates in a small section of the throttle range.

SPtM application

Load control loop is active in parallel to mains mode only (MCB feedback closed).

 Set Load Control PTM (page 230) = BASELOAD, set Baseload (page 233) setpoint to 30 % Nominal Power (page 242) of gen-set.



- 2. Set Load Gain (page 348) to the same value as Angle Gain (page 348). Set Load Int (page 349) to zero.
- 3. Start the gen-set in MAN Mode, press GCB ON/OFF button to synchronize and close gen-set to mains.
- 4. When GCB is closed, gen-set load slowly increases to **Baseload (page 233)** value. Check that gen-set power is positive (CT polarity).
- 5. Increase Load Gain (page 348) to unstable load control and decrease value by 30 % to insure stable performance. When Load Int (page 349) factor is set to zero gen-set load can differ from required Baseload (page 233).
- 6. To adjust and optimize Load Int (page 349) change Baseload (page 233) several times between 30 and 70 % of Nominal Power (page 242). Usually setting Load Int (page 349) to 100% gives optimal performance.
- 7. When gen-set is running under full load check if
 - a. Speed governor output voltage value is not limited (it does not reach **Speed Governor Low Limit** (page 346) or **Speed Governor High Limit** (page 346))
 - b. Speed governor actuator is not mechanically limited or operates in a small section of the throttle range.

5.3.15 Voltage/PF control

The voltage control output is used to control the voltage or the power factor of the engine. The voltage regulation, PF regulation and VAr sharing are realized through the voltage control. The voltage request is internal value of the regulator. This value is transformed to range -10 .. 10 V based on setpoints **Voltage Regulator Low Limit (page 355)** limit and **Voltage Regulator High Limit (page 355)**. This value of voltage request is then transformed to request which comes out of the controller. There are several ways how to send this request to gen-set:

- Analog output (integrated AVR interface)
- Binary pulse control

Voltage control outputs

Analog output (integrated AVR interface)

The voltage regulator of the engine is controlled by the analog signal from controller. Please see the chapter **AVR Interface (page 49)** for more information about AVR.

The direction of speed regulation required by Speed regulator of the engine is given by the setpoint Voltage Regulator Character (page 354). A full range change of the AVR output (from Voltage Regulator Low Limit (page 355) to Voltage Regulator High Limit (page 355)) should cause 5-10% change of the voltage (Voltage Regulator Low Limit (page 355) ~ 95% Nominal Voltage Ph-N (page 246), Voltage Regulator Bias (page 354) ~ 100% Nominal Voltage Ph-N (page 246), Voltage Regulator High Limit (page 355) ~ 105% Nominal Voltage Ph-N (page 246)).

Binary pulse control

The internal voltage request is transformed to Up/Down pulse control. These pulses get out of the controller via binary outputs AVR UP (PAGE 706) and AVR DOWN (PAGE 706). Length of pulses AVR UP (PAGE 706) and AVR DOWN (PAGE 706) depends on the difference of actual voltage and requested voltage (actual reactive power and requested reacted power, actual PF and requested PF) and on the parameter **Tau Voltage Governor** Actuator (page 355). Tau Voltage Governor Actuator (page 355) defines the pulse duration which is needed for the voltage controller to travel from minimal position to the maximal position. The Maximum length of pulses is limited to 5s, the minimal length of pulses is limited to 150 ms and minimal length between the pulses is 200 ms.

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Voltage/PF control adjustment

Voltage adjustment

- Set Voltage Gain (page 356), Voltage Int (page 356) to zero and Voltage Regulator Bias (page 354) to 50%.
- Start the gen-set in MAN Mode to without load.
- Adjust generator voltage to Nominal Voltage Ph-N (page 246) by change of Voltage Regulator Bias (page 354).
- Change Voltage Regulator Bias (page 354) to 0% and 100% to check generator voltage control range (typically ± 10 % of Nominal Voltage Ph-N (page 246)).
- Set Voltage Regulator Bias (page 354) to again reach Nominal Voltage Ph-N (page 246) on the generator.
- When gen-set is running unloaded increase carefully Voltage Gain (page 356) to unstable point and then decrease value by 30 % to insure stable performance.
- Adjust Voltage Int (page 356) (usually setting to 100% gives optimal performance).

PF adjustment

MINT application

Power factor control loop is active in parallel to mains mode only (MCB feedback closed). Switch off other engines while adjusting.

- Set the same values to PF Gain (page 356) and PF Int (page 357) as in the chapter Voltage adjustment (page 108) for parameters Voltage Gain (page 356) and Voltage Int (page 356).
- Set #System BaseLoad (page 235) = 30 % of Nominal Power (page 242) and #System Power Factor (page 236) = 1.0.
- Start and synchronize the gen-set in MAN Mode by pressing GCB ON/OFF.
- When running in parallel to mains loaded on 30%, increase slowly PF Gain (page 356) to unstable point and then decrease the value by 30 % to insure stable performance.
- Adjust PF Int (page 357) (usually setting to 100% gives optimal performance).

Note: To judge optimal adjusting of the power factor induce generator power jumps by **Voltage Regulator Bias** (page 354) change or by **#System BaseLoad** (page 235) change.

SPtM application

Power factor control loop is active in parallel to mains mode only (MCB feedback closed).

- Set the same values to PF Gain (page 356) and PF Int (page 357) as in the chapter Voltage adjustment (page 108) for parameters Voltage Gain (page 356) and Voltage Int (page 356).
- Set Baseload (page 233) = 30 % of Nominal Power (page 242) and Base Power Factor (page 233) = 1.0.
- Start and synchronize the gen-set in MAN Mode by pressing GCB ON/OFF.
- When running in parallel to mains loaded on 30%, increase slowly PF Gain (page 356) to unstable point and then decrease the value by 30 % to insure stable performance.
- Adjust **PF Int (page 357)** (usually setting to 100% gives optimal performance).

Note: To judge optimal adjusting of the power factor induce generator power jumps by **Voltage Regulator Bias** (page 354) change or by **Baseload** (page 233) change.


5.3.16 Gen-set operation states

Engine state machine

Init	Autotest during controller power on.
InitAutotest during controller power on.Not readyGen-set is not ready to start.ReadyGen-set is ready to run.PrestartPrestart sequence in process, PRESTART (PAPrestartPrestart sequence in process, PRESTART (PAPauseEngine is cranking, STARTER (PAGE 737) outpPausePause between start attempts.StartingStarting speed is reached and the Idle timer isRunningGen-set is running at nominal speed.Soft loadGen-set is running at nominal speed and GCESoft unidGen-set is cooling before stop.StopStop.StopStop.StuddownShut-down alarm activated.VentilGas engine - ventilation of unburned fuel when gas	Gen-set is not ready to start.
Not ready	Example: When shutdown alarm is active or unit is in OFF mode.
Ready	Gen-set is ready to run.
Droctart	Prestart sequence in process, PRESTART (PAGE 732) output is closed.
Flesiali	Example: Usually used for preheating or processes executed prior gen-set start.
Cranking	Engine is cranking, STARTER (PAGE 737) output is closed
Pause	Pause between start attempts.
Starting	Starting speed is reached and the Idle timer is running.
Running	Gen-set is running at nominal speed.
Soft load	Gen-set power is ramping up
Loaded	Gen-set is running at nominal speed and GCB CLOSE/OPEN (PAGE 716) is closed.
Soft unld	Gen-set power is ramping down
Cooling	Gen-set is cooling before stop.
Stop	Stop.
•	Example: Automatic or manual stop command was issued, engine is stopping.
Shutdown	Shut-down alarm activated.
Ventil	Gas engine - ventilation of unburned fuel when stop command comes during cranking with
SDV ontil	gas
Suvenui	Gas engine - ventilation of unburned rule after unsuccessful start attempt
EmergMan	EMERGENCY WAN (PAGE 665) gen-set operation.
	Example: Used for bypass the controller and engine manual start.

Engine started conditions

- Engine speed (RPM) > Starting RPM (page 273) or
- Oil pressure > Starting Oil Pressure (page 274) or
- Binary input OIL PRESSURE (PAGE 674) is in logical 0 or
- D+ terminal active (reached 80% of supply voltage) for minimum 1 s or
- Generator voltage > 25% of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246) (any phase)

Note: Any of these condition will disconnect starter of the engine, however for transition to next state RPM needs to be higher than **Starting RPM (page 273)**.

Engine running conditions

- Engine speed (RPM) > Starting RPM (page 273) or
- Oil pressure > Starting Oil Pressure (page 274) or

- Binary input OIL PRESSURE (PAGE 674) is in logical 0 or
- Generator voltage > 25% of Nominal Voltage Ph-N (page 246)

Still engine conditions

- Engine speed (RPM) < Starting RPM (page 273) or</p>
- Oil pressure < Starting Oil Pressure (page 274) or</p>
- Binary input OIL PRESSURE (PAGE 674) is in logical 1 or
- Generator voltage < 50 V (any phase)</p>

Note: When the engine was running before and all above conditions are fulfilled, additional 2 s delay is necessary to confirm "still engine".

When any engine running conditions are appeared on still engine than the Wrn Stop Fail (page 811) is activated with following delay:

- for generator voltage from 10 V to < 50 % of nominal voltage, Wrn Stop Fail has delay 1 s</p>
- ▶ for generator voltage > 50 % of nominal voltage, Wrn Stop Fail has delay 200 ms
- Oil pressure > Starting Oil Pressure (page 274), Wrn Stop Fail has delay 1 s
- Binary input OIL PRESSURE (PAGE 674) is in logical 0, Wrn Stop Fail has delay 1 s
- ▶ for detected RPM, there is no delay.

Stop engine conditions

If no engine running conditions are validated than the controller will wait extra 12 s before leaving the Machine state Stop and than it will release the **STOP SOLENOID** (PAGE **738**) output.



Image 5.34 Engine stops in Stop Time (page 281)

When the total time of stopping will exceed setpoint **Stop Time (page 281)** than the **Wrn Stop Fail (page 811)** and binary outputs are activated. The controller will continuously try to stop the engine.







Electric state machine

MainsOper	Mains is present and all its values are within limits.
Mansoper	Example: MCB is closed, GCB is opened
MainsFlt	Mains fails
lelOner	Island operation
IsiOper	Example: MCB is opened, GCB is closed
MainsRet	Mains recover
Synchro	Gen-set is synchronizing (MCB is closed, GCB is opened)
ParalOper	Gen-set is in parallel with mains (MCB is closed, GCB is closed)
BrksOff	GCB, MCB opened

5.3.17 Alarm management

The controller evaluates two levels of alarms. Level 1 – yellow alarm – is a pre-critical alarm that is only informative and does not take any action regarding gen-set control. Level 2 – red alarm – represents a critical situation, where an action must be taken to prevent damage of the gen-set or technology.

- One alarm of any type can be assigned to each binary input.
- Two alarms (one yellow and one red type) can be assigned to each analog input.
- There are also Built-in alarms (page 115) with fixed alarm types.
- Each alarm is written to the Alarmlist (page 115).
- Each alarm causes a record to be written into the history log.
- Each alarm activates the Alarm and Horn output.
- Each alarm can cause sending of a SMS message or an email.





Image 5.36 Analog input alarm evaluation principle

Alarm handling

There are three different alarm categories regarding the period when the alarms are evaluated. The category is selectable for alarms assigned to binary/analog inputs and fixed for built-in alarms. The categories are the following:

- > The alarm is evaluated all the time when the controller is switched on.
- The alarm is evaluated only when the engine is running. This type should be used for e.g. oil pressure. These alarms begin to be evaluated after the engine has been started with the delay given by the setpoint Protection Hold Off (page 279).
- The alarm is evaluated only when the generator is excited. These alarms begin to be evaluated after the engine has been started and Maximal Stabilization Time (page 279) has elapsed or the GCB has been closed. They remain evaluated until cooling has finished. Only Generator under/overvoltage and Generator under/overfrequency belong to this category. This category is not configurable to binary and analog input alarms.

If an alarm is being evaluated and the appropriate alarm condition is fulfilled, the delay of evaluation will start to run. The delay is adjustable by a setpoint (in the case of built-in alarms, analog input alarms) or is adjusted via configuration window in InteliConfig (in the case of binary input alarms). If the conditions persist, the alarm will activate. The alarm will not activate if the condition is dismissed while the delay is still running.

After pressing the Fault reset button or activating the binary input **FAULT RESET BUTTON (PAGE 665)**, all active alarms change to confirmed state. Confirmed alarms will disappear from the Alarmlist as soon as the respective condition dismisses. If the condition is dismissed before acknowledging the alarm, the alarm will remain in the Alarmlist as Inactive.

Note: The input **SD OVERRIDE (PAGE 680)** can be used for temporary disabling of red alarms to shutdown the engine. This input may be used in situations where providing the power is extremely important – e.g. if the genset drives pumps for fire extinguishers (sprinklers).

Alarm states

An alarm can have following states:

- Active alarm: the alarm condition persists, alarm delay has elapsed.
- Inactive alarm: the alarm condition has disappeared, but the alarm has not been confirmed.
- Confirmed alarm: the alarm condition persists, but the alarm has already been confirmed.

Alarm types - Level 1

The level 1 alarm indicates that a value or parameter is out of normal limits, but has still not reached critical level. This alarm does not cause any actions regarding the gen-set control.

Warning (Wrn)

The alarm appears in the Alarmlist and is recorded into the history log. Activates the output AL COMMON WRN (PAGE 687) as well as the standard alarm outputs (HORN (PAGE 722) and ALARM (PAGE 695)).

Alarm indication (AL Indic)

The event is only indicated in the Alarmlist. It disappears for the alarmist automatically as soon as the cause disappears. Standard alarm outputs (HORN (PAGE 722) and ALARM (PAGE 695)) are not activated.

History record only (HistRecOnl)

The event is recorded into the history. Standard alarm outputs (HORN (PAGE 722) and ALARM (PAGE 695)) are not activated.

Alarm types - Level 2

The level 2 level alarm indicates that a critical level of the respective value or parameter has been reached.

Note: It is not possible to start the engine if any red level protection is active or not confirmed.

IMPORTANT: The gen-set can start by itself after acknowledging the alarms if there is no longer an active red alarm and the controller is in AUTO or TEST mode!

Shutdown (Sd)

The alarm appears in the alarmlist and is recorded into the history log. It causes immediate stop of the Gen-set without unloading and cooling phase. Also GCB breaker is open. The gen-set cannot be started again while there is a shutdown alarm in the alarmlist. Activates the output **AL COMMON SDMPR (PAGE 687)** as well as the standard alarm outputs (HORN (PAGE 722) and **ALARM (PAGE 695)**).

Breaker open and cool down (BOC)

The event appears in the alarmlist and is recorded into the history log. It causes immediate opening of the GCB (without unloading) and then the standard stop sequence with cooling follows. The gen-set cannot be started again while there is a BOC alarm in the alarmlist. Activates the output **AL COMMON BOC (PAGE 686)** as well as the standard alarm outputs (HORN (PAGE 722) and **ALARM (PAGE 695)**).

Slow stop (Stp)

The alarm appears in the alarmlist and is recorded into the history log. It causes stop of the gen-set by the standard stop sequence, i.e. including unloading and cooling phase. The gen-set cannot be started again while there is a slow stop alarm in the alarmlist. Activates the output **AL COMMON STP (PAGE 687)** as well as the standard alarm outputs (HORN (PAGE 722) and **ALARM (PAGE 695)**).



Sensor fail detection (FLS)

If the measured resistance on an analog input exceeds the valid range, a sensor fail will be detected and a sensor fail message will appear in the **Alarmlist (page 115)**. The valid range is defined by the most-left (RL) and most-right (RH) points of the sensor characteristic ±12.5% from RH-RL.

Note: Sometimes there can be problem with lower limit of valid range which can be counted as negative number. In this case the lower limit is set as one half of the RL point of the sensor curve characteristic.



Image 5.37 Sensor fail detection principle

Remote alarm messaging

If communication plug-in module is connected to the controller, the controller can send SMS messages and emails at the moment when a new alarm appears in the Alarmlist (page 115) or new event is written in History log (page 118). The message will contain a copy of the Alarmlist (page 115) or reasons from History log (page 118). To enable this function, adjust setpoints Event Message (page 485), Wrn Message (page 485), BOC Message (page 485) and Sd Messages (page 486) to ON. Also enter a valid GSM phone number or email address to the setpoints Telephone Number 1 (page 486), Email Address 1 (page 481).

Terminal	Event SMS	Warning SMS	BOC SMS	Shutdown SMS	Event email	Warning email	BOC email	Shutdown email
CM-RS232-485	no	no	no	no	no	no	no	no
USB	no	no	no	no	no	no	no	no
Ethernet	no	no	no	no	yes	yes	yes	yes
CM-GPRS	yes	yes	yes	yes	yes*	yes*	yes*	yes*
CM-4G-GPS	yes	yes	yes	yes	yes*	yes*	yes*	yes*

The list of all supported terminals shows the table below:

Note: * Only with enabled Mode (page 479).



Alarmlist

Alarmlist is a container of active and inactive alarms. It will appear automatically on the controller display, if a new alarm occurs, or can be displayed manually from the display menu.

Active alarms are shown as inverted, not yet confirmed alarms are marked with asterisk before them.

Alarmlist contains three types of alarms:

- Controller built-in alarms
- User configured alarms on binary or analog inputs
- ECU alarms

Controller built-in alarms

An alarm message in the alarmlist begins with a prefix, which represents the alarm type (e.g. Wrn, Sd, BOC, Stp, MP, MPR). Then the alarm name follows. In some cases the prefix can be omitted.

User configured alarms

An alarm message in the alarmlist begins with a prefix, which represents the alarm type (e.g. Wrn, Sd, BOC, MP, MPR). Alarm type is selected by user during the configuration of binary or analog input as alarm. Then the alarm name follows. Name is adjusted by user during the configuration of binary or analog input as alarm.

ECU alarms

The ECU alarms are received from the ECU. The alarms are represented by the Diagnostic Trouble Code, which contains information about the subsystem where the alarm occurred, the alarm type and the alarm occurrence counter.

The most common fault codes are translated into text form. Other fault codes are displayed as a numeric code and the engine fault codes list must be used to determine the reason.

Built-in alarms

Events specification	Protection type	Description
Analog Input 1 Wrn	WRN	Value measured on analog input 1 is than Analog Protection 1 Wrn (page 366) setpoint.
Analog Input 1 Sd	SD	Value measured on analog input 1 is than Analog Protection 1 Sd (page 366) setpoint.
Analog Input 2 Wrn	WRN	Value measured on analog input 2 is than Analog Protection 2 Wrn (page 368) setpoint.
Analog Input 2 Sd	SD	Value measured on analog input 2 is than Analog Protection 2 Sd (page 369) setpoint.
Analog Input 3 Wrn	WRN	Value measured on analog input 3 is than Analog Protection 3 Wrn (page 371) setpoint.
Analog Input 3 Sd	SD	Value measured on analog input 3 is than Analog Protection 3 Sd (page 372) setpoint.
Analog Input 4 Wrn	WRN	Value measured on analog input 4 is than Analog Protection 4 Wrn (page 374) setpoint.
Analog Input 4 Sd	SD	Value measured on analog input 4 is than Analog Protection 4



Events specification	Protection type	Description
		Sd (page 375) setpoint.
Wrn Battery Voltage	WRN	Battery voltage is out of limits given by Battery Undervoltage (page 301) and Battery Overvoltage (page 301) setpoints.
Binary input		Configurable Warning/BOC/Shutdown alarms on the binary inputs.
Sd Battery Flat	SD	If the controller switches off during starting sequence (STARTER (PAGE 737) output is active) it doesn't try to start again and activates this protection (controller assumes bad battery condition).
Sd Start Fail	SD	Gen-set start failed. All crank attempts were tried without success.
Parameters Fail	NONE	Wrong check-sum of parameters. Happens typically after downloading new firmware or changing of the parameter. The controller stays in INIT mode. Check all parameters, change value of at least one parameter.
Sd Gen Lx >V	20	
BOC Gen Lx <v< td=""><td>50</td><td>The generator voltage is out of limits given by Gen <v and="" boc="" gen<="" td=""></v></td></v<>	50	The generator voltage is out of limits given by Gen <v and="" boc="" gen<="" td=""></v>
(where x=1,2,3)	BOC	>v Su selpoints.
BOC Gen V Unbalance	BOC	The generator voltage is unbalanced more than the value of Voltage Unbalance BOC (page 309) setpoint.
BOC Gen >, <frequency< td=""><td>BOC</td><td>The generator frequency is out of limits given by Generator Overfrequency BOC (page 310) and Generator Underfrequency BOC (page 311) setpoints.</td></frequency<>	BOC	The generator frequency is out of limits given by Generator Overfrequency BOC (page 310) and Generator Underfrequency BOC (page 311) setpoints.
BOC Current Unbalance	BOC	The generator current is unbalanced more than the value of Current Unbalance BOC (page 307) setpoint.
BOC Current IDMT	BOC	Generator current exceeds the limit for IDMT protection given by Nominal Current (page 243) and IDMT Overcurrent Delay (page 306) setpoints.
BOC Overload	BOC	The load is greater than the value given by Overload BOC (page 304) setpoint.
Sd Earth Fault	SD	This alarm is activated when Earth Fault value exceeds Earth Fault Sd (page 491) limit for at least Earth Fault Delay (page 490) period.
Sd Overspeed	SD	The protection comes active if the speed is greater than Overspeed Sd (page 285) setpoint.
Sd Underspeed	SD	During starting of the engine when the RPM reach the value of Starting RPM (page 273) setpoint the starter is switched off and the speed of the engine can drop under Starting RPM (page 273) again. Then the Underspeed protection becomes active. Protection evaluation starts 5 seconds after reaching Starting RPM (page 273) .
Emergency Stop	SD	If the input Emergency Stop is opened shutdown is immediately activated.
GCB Fail	SD	Failure of generator circuit breaker.
MCB Fail	WRN	Failure of mains circuit breaker.



Events specification	Protection type	Description
Sd RPM Measurement Fail	SD	Failure of magnetic pick-up sensor for speed measurement. This alarm appears, if starter was disengaged for other reason than overcrossing Starting RPM (page 273) (like oil pressure or D+) and at the end of timer Maximum Cranking Time (page 272) there are no RPMs > Starting RPM (page 273) detected.
Wm Stop Fail	WRN	Gen-set stop failed. See description at Gen-set Operation States chapter.
Wrn Maintenance 1	WRN	The period for servicing is set by the Maintenance Timer 1 (page 302) setpoint. The protection comes if counter reaches zero.
Wrn Maintenance 2	WRN	The period for servicing is set by the Maintenance Timer 2 (page 303) setpoint. The protection comes if counter reaches zero.
Wrn Maintenance 3	WRN	The period for servicing is set by the Maintenance Timer 3 (page 303) setpoint. The protection comes if counter reaches zero.
Charge Alternator Fail	WRN	Failure of alternator for charging the battery.
Sd Override	WRN	The protection is active if the output Sd Override is closed.
Mains CCW Rot	WRN	Mains voltage phases are not wired correctly. MCB closing is prohibited by controller.
Generator CCW Rot	WRN	Genset voltage phases are not wired correctly. GCB closing is prohibited by controller.
Stp Synchronization Fail	STP	If the synchronization timeout gets elapsed (forward synchronization).
Wrn Reverse synchro Fail	WRN	If the synchronization timeout gets elapsed (reverse synchronization).
BOC Reverse Power	BOC	The reverse power is higher than limit adjusted via setpoint Reverse Power Level (page 312) .
BOC Excitation Loss	BOC	The reactive power is higher than limit adjusted via setpoint Excitation Loss Level (page 312).
Wrn Voltage Regulation Limit	WRN	The AVR output stays close to one of the limit values for more than 2 seconds.
Wrn Speed Regulation Limit	WRN	The speed governor output stays close to one of the limit values for more than 2 seconds.

Note: This table does not contain all alarms in controller. It is only list of the most common alarms.



5.3.18 History log

The history log is an area in the controller's non-volatile memory that records "snapshots" of the system at moments when important events occur. The history log is important especially for diagnostics of failures and problems. When the history file is full, the oldest records are removed.

Each record has the same structure and contains:

- The event which caused the record (e.g. "Overspeed alarm" or "GCB closed")
- The date and time when it was recorded
- All important data values like RPM, kW, voltages, etc. from the moment that the event occurred.

Record structure

Name	Abbreviation	Description
Number	No.	Row number (0 corresponds to the last record, -1 to the previous one, etc.)
Reason	Reason	Reason for history record (any event or alarm related to the gen-set
Time	Time	Time
Date	Date	Date
RPM	RPM	Engine rotations per minute
Power	Pwr	Generator active power
Reactive power	Q	Generator reactive power
Power Factor	PF	Generator power factor
Load Character	LChr	Generator load character
Generator Frequency	Gfrq	Generator Frequency
Generator Voltage	Vg1	Generator voltage Ph1
Generator Voltage	Vg2	Generator voltage Ph2
Generator Voltage	Vg3	Generator voltage Ph3
Generator Voltage	Vg12	Generator voltage Ph12
Generator Voltage	Vg23	Generator voltage Ph23
Generator Voltage	Vg31	Generator voltage Ph31
Generator Current	IL1	Generator current Ph1
Generator Current	IL2	Generator current Ph2
Generator Current	IL3	Generator current Ph3
Mains Frequency	Mfrq	Mains Frequency
Mains Voltage	Vm1	Mains voltage Ph1
Mains Voltage	Vm2	Mains voltage Ph2
Mains Voltage	Vm3	Mains voltage Ph3
Mains Voltage	Vm12	Mains voltage Ph12
Mains Voltage	Vm23	Mains voltage Ph23
Mains Voltage	Vm31	Mains voltage Ph31



Voltage Battery	VBat	Voltage of battery
Analog Input 1	Ain1	Analog input 1
Analog Input 2	Ain2	Analog input 2
Analog Input 3	Ain3	Analog input 3
Analog Input 4	Ain4	Analog input 4
Binary Inputs	BIN	Controller binary inputs
E-Stop	E-Stop	State of dedicated E-Stop input
Binary Outputs	BOUT	Controller binary outputs
Speed regulator	SRO	Speed regulator output
Voltage regulator	VRO	Voltage regulator output
Running nominal power	TRPN	Nominal power of all running gen-sets
Available nominal power	APN	Available nominal power of all gen-sets
Controller Mode	Mode	Controller mode

Note: When some setpoint is changed, in history log is written its number of communication object.

Note: Some additional columns can be added due to actual controller configuration (ECU, modules, etc.).

5.3.19 Breaker control

The following power switches are controlled by the controller:

▶ The master generator circuit breaker or contactor – MGCB

It is possible to use either a motorized circuit breaker or contactor. Below is a list of available control outputs that should fit all types of contactors or breakers. The following rules must be kept to when designing the wiring of power switches:

- The control outputs must be configured and wiring of the power switches must be provided in such a way, that the controller has full control over the breakers – i.e. the controller can open and close the breaker at any time.
- The breaker must respond within max. 2 seconds to a close and open command. Special attention should be paid to opening of motorized circuit breakers, as it could take more than 2 seconds on some types. In such cases it is necessary to use an undervoltage coil for fast opening.
- After opening the breaker, there is internal delay for another closing of breaker. Delay is 6 seconds 5 seconds for OFF coil and 1 second for UV coil. After these 6 seconds, breaker can be closed again. For opening of breaker there is no delay.



Breaker control outputs

Close/Open	An output for control of a contactor. Its state represents the breaker position requested by the controller. The breaker must react within 2 seconds to a close or open command, otherwise an alarm is issued.
ON coil	An output giving a 2 second pulse in the moment the breaker has to be closed. The output is intended for control of close coils of circuit breakers.
OFF coil	An output giving a pulse in the moment the breaker has to be opened. The pulse lasts until the feedback deactivates, but at least for 2 seconds. The output is intended for control of open coils of circuit breakers.
UV coil	The GCB UV coil output is active the whole time the gen-set is running (not in idle or cooling). The output is deactivated for at least 2 seconds in the moment the breaker has to be switched off. The output is intended for control of undervoltage coils of circuit breakers.



Image 5.38 Breaker control outputs

MCB special requirements

- If a contactor is used on the MCB position, it is recommended that the wiring be provided in such a way that the contactor will be normally closed and will open if the logical binary output MCB CLOSE/OPEN (PAGE 726) closes. This behavior is called "negative logic" and can be adjusted by the setpoint MCB Logic (page 323). The negative logic will prevent accidental opening of the MCB when the controller is switched off.
- If a contactor is used on the MCB position, it will open itself immediately after the mains have failed, because it will lose power for the coil. That is why the following adjustment is necessary to prevent triggering the Wrn MCB Fail (page 809) alarm: MCB Opens On (page 325) = Mains Fail, Mains < > Voltage Delay (page 321) ≤ 1.
- If a 230 V motor driven circuit breaker is used on the MCB position and an undervoltage coil is not fitted, it is not possible to open the breaker after the mains have failed, because there is no power for the motor drive until the gen-set is started and providing voltage. Adjusting the setpoint MCB Opens On (page 325) = Gen Run will prevent triggering the Wrn MCB Fail (page 809) alarm.



Breaker fail detection

Breaker fail detection is based on binary output breaker close/open comparing with binary input breaker feedback.

IMPORTANT: It is necessary to configure breaker feedback to use this function.

IMPORTANT: Also it is possible to use breakers without feedbacks. In this case there is no check of breaker real state.

There are three different time delays for breaker fail detection - see following diagrams.

IMPORTANT: When controller is synchronizing, there is only 2 seconds delay for breaker fail detection.

When binary output breaker close/open is in steady state and breaker feedback is changed the breaker fail is detected immediately (no delay).



Image 5.39 Breaker fail - breaker close/open in steady position - open



Image 5.40 Breaker fail - breaker close/open in steady position - close

When binary output breaker close/open opens there is 2 sec delay for breaker fail detection.





Image 5.41 Breaker fail - breaker close/open opens

When binary output breaker close/open closes there is 2 sec delay for breaker fail detection.





5.3.20 Exercise timer

The exercise (general-purpose) timer in controller intended for scheduling of any operations such as e.g. periodic tests of the gen-set, scheduled transfer of the load to the gen-set prior to an expected disconnection of the mains etc.

Related setpoints for timer 1 are:

- Timer 1 Function (page 428)
- Timer 1 Repetition (page 429)
- ▶ Timer 1 First Occur. Date (page 429)
- Timer 1 First Occur. Time (page 429)
- Timer 1 Duration (page 430)
- Timer 1 Repeated (page 430)
- Timer 1 Repeat Day (page 433)

- Timer 1 Day (page 432)
- Timer 1 Repeated Day In Week (page 433)
- Timer 1 Repeat Day In Month (page 433)
- Timer 1 Repeat Week In Month (page 434)
- Timer 1 Refresh Period (page 431)
- Timer 1 Weekends (page 432)



Related setpoints for timer 2 are:

- Timer 2 Function (page 435)
- Timer 2 Repetition (page 436)
- Timer 2 First Occur. Date (page 436)
- Timer 2 First Occur. Time (page 436)
- Timer 2 Duration (page 437)
- Timer 2 Repeated (page 437)
- Timer 2 Repeat Day (page 440)

Available modes of timer:

- Timer 2 Day (page 439)
- Timer 2 Repeated Day In Week (page 440)
- Timer 2 Repeat Day In Month (page 440)
- Timer 2 Repeat Week In Month (page 441)
- Timer 2 Refresh Period (page 438)
- Timer 2 Weekends (page 439)

Once	This is a single shot mode. The timer will be activated only once at preset date/time for preset duration.
Daily	The timer is activated every "x-th" day. The day period "x" is adjustable. Weekends can be excluded. E.g. the timer can be adjusted to every 2nd day excluding Saturdays and Sundays.
Weekly	The timer is activated every "x-th" week on selected weekdays. The week period "x" is adjustable. E.g. the timer can be adjusted to every 2nd week on Monday and Friday.
Monthly	The timer is activated every "x-th" month on the selected day. The requested day can be selected either as "y-th" day in the month or as "y-th" weekday in the month. E.g. the timer can be adjusted to every 1st month on 1st Tuesday.
Short period	The timer is repeated with adjusted period (hh:mm). The timer duration is included in the period.

Once mode

Set-up via InteliConfig

To set-up timer via InteliConfig go to the setpoint ribbon, setpoint group scheduler and setpoint Timer 1 Setup.

Note: First of all function of timer has to be adjusted via setpoint Timer 1 Function (page 428).



Timer 1 Setup				×	
Timer	O Off	Once	🔘 Repeat		- (Timer mode
First occurrence: Time: 0:00	G	1/1/2015 Duration:	0:00	iii O	Timer
			Ok 🙁	Cancel	

Image 5.43 Once mode - InteliConfig

In timer mode select Once. In timer settings adjust date and time of occurrence of timer. Also adjust the duration of timer.

Set-up via controller interface

In controller go to the Scheduler setpoint group. Select the function of timer via **Timer 1 Function (page 428)** setpoint. Than go to *Timer 1 Setup* and press enter button. In **Timer 1 Repetition (page 429)** setpoint select Once mode. Than adjust **Timer 1 First Occur. Date (page 429)**, **Timer 1 First Occur. Time (page 429)** and **Timer 1 Duration (page 430)**.

Note: Use left and right buttons to move between timer setpoints.

Daily mode

Set-up via InteliConfig

To set-up timer via InteliConfig go to the setpoint ribbon, setpoint group scheduler and setpoint *Timer 1 Setup*. *Note:* First of all function of timer has to be adjusted via setpoint *Timer 1 Function (page 428)*.

ComAp

Timer	O off	Opre	Popo		Timer m
miler	O OII	Office	• Kepea	it.	
First occurrence Time: 12:00	(L)	1/1/2016 Duration:	1:00	•	Timer
Repeating since	first occurrence		dav		x-th day repetiti
O weekly	Includ	ing * v	eekends		
o monthly					Behavior
Short period	i?				
]	



In timer mode select Repeat. In repetition type select Daily. In timer settings adjust date and time of first occurrence of timer. Also adjust the duration of each occurrence of timer. Than select the x-th day of repetition (**Timer 1 Refresh Period (page 431)**) and behavior of timer on weekends (**Timer 1 Weekends (page 432)**).

Example: On image example first start of timer will be 1/1/2016 at 12:00. Duration will be 1 hour. Timer will be again activated every 3rd day at 12:00 for 1 hour including weekends.

Set-up via controller interface

In controller go to the Scheduler setpoint group. Select the function of timer via Timer 1 Function (page 428) setpoint. Than go to *Timer 1 Setup* and press enter button. In Timer 1 Repetition (page 429) setpoint select Repeated mode. Than adjust Timer 1 First Occur. Date (page 429), Timer 1 First Occur. Time (page 429) and Timer 1 Duration (page 430). In setpoint Timer 1 Repeated (page 430) select Daily and adjust Timer 1 Refresh Period (page 431) (x-th day of repetition) and Timer 1 Weekends (page 432) (behavior of timer on weekends).

Note: Use left and right buttons to move between timer setpoints.

Weekly mode

Set-up via InteliConfig

To set-up timer via InteliConfig go to the setpoint ribbon, setpoint group scheduler and setpoint Timer 1 Setup.

Note: First of all function of timer has to be adjusted via setpoint Timer 1 Function (page 428).

ComAp

Timer	OOff	O Once	 Repeating 	it	Timern
First occurrence: Fime: 12:00	C	1/1/2016 Duration:	1:00		Time
Repeating since fir daily weekly monthly short period	st occurrence every Mond Wedn Friday Sunda	ay esday y	2 🗘 . week on Tuesday Thursday Saturday		Active c
		۲	Ok 🔕	Cancel	



In timer mode select Repeat. In repetition type select Weekly. In timer settings adjust date and time of first occurrence of timer. Also adjust the duration of each occurrence of timer. Than select the x-th week of repetition (Timer 1 Refresh Period (page 431)) and days when timer should be active (Timer 1 Day (page 432)).

Example: On image example first start of timer will be 1/1/2016 at 12:00. Duration will be 1 hour. Timer will be again activated every 2nd week on Monday, Wednesday and Friday at 12:00 for 1 hour.

Set-up via controller interface

In controller go to the Scheduler setpoint group. Select the function of timer via **Timer 1 Function (page 428)** setpoint. Than go to *Timer 1 Setup* and press enter button. In **Timer 1 Repetition (page 429)** setpoint select Repeated mode. Than adjust **Timer 1 First Occur. Date (page 429)**, **Timer 1 First Occur. Time (page 429)** and **Timer 1 Duration (page 430)**. In setpoint **Timer 1 Repeated (page 430)** select Weekly and adjust **Timer 1 Day (page 432)** (days when timer should be active) and **Timer 1 Refresh Period (page 431)** (x-th week of repetition).

Note: Use left and right buttons to move between timer setpoints.

Monthly mode

Set-up via InteliConfig

To set-up timer via InteliConfig go to the setpoint ribbon, setpoint group scheduler and setpoint Timer 1 Setup.

Note: First of all function of timer has to be adjusted via setpoint Timer 1 Function (page 428).

There are two types of monthly repetition. First of them is based on repeating one day in month.

Timer	Off	O Once	Repea	t	Limer mor
First occurrence: Time: 12:00	Ċ	1/1/2016 Duratio	on: 1:00		Timer settings
Repeating since fir daily weekly monthly short period	st occurrence on Mond Wedn Friday Sunda in every	2 ‡ . ay esday y	0 = , day Tuesday Thursday Saturday 2 \$, month		Type of monthly repetition Active day in week x-th mont of repetition
Repetition		۷) Ok 🛛	Cancel	

Image 5.46 Monthly mode - InteliConfig

In timer mode select Repeat. In repetition type select Monthly. In timer settings adjust date and time of first occurrence of timer. Also adjust the duration of each occurrence of timer. Than select the type of monthly repetition and the x-th day of repetition (**Timer 1 Repeat Day In Month (page 433)**). Than select the x-th month of repetition.

Example: On image example first start of timer will be 1/1/2016 at 12:00. Duration will be 1 hour. Timer will be again activated every 2nd day in 2nd month at 12:00 for 1 hour.

ComAp

Timer 1 Setup × Timer mode Off Timer Once Repeat 曲 1/1/2016 First occurrence: Timer settings 0 0 Time: 12:00 Duration: 1:00 Repeating since first occurrence Type of 2 🗘 . day daily on monthly on weekly repetition Monday Tuesday monthly Wednesday Thursday short period Friday Saturday Sunday 2 C . month in every x-th month of repetition 0 Ok 8 Cancel Repetition type

Second type of monthly repetition is based on repeating days in week in month.



In timer mode select Repeat. In repetition type select Monthly. In timer settings adjust date and time of first occurrence of timer. Also adjust the duration of each occurrence of timer. Than select the type of monthly repetition, the x-th week of repetition and days in week. Than select the x-th month of repetition.

Example: On image example first start of timer will be 1/1/2016 at 12:00. Duration will be 1 hour. Timer will be again activated every 2nd week in 2nd month on Monday, Wednesday and Friday at 12:00 for 1 hour.

Set-up via controller interface

There are two types of monthly repetition. First of them is based on repeating one day in month.

In controller go to the Scheduler setpoint group. Select the function of timer via **Timer 1 Function (page 428)** setpoint. Than go to *Timer 1 Setup* and press enter button. In **Timer 1 Repetition (page 429)** setpoint select Repeated mode. Than adjust **Timer 1 First Occur. Date (page 429)**, **Timer 1 First Occur. Time (page 429)** and **Timer 1 Duration (page 430)**. In setpoint **Timer 1 Repeated (page 430)** select Monthly and adjust type of monthly repetition via **Timer 1 Repeat Day (page 433)**, **Timer 1 Refresh Period (page 431)** (x-th month of repetition) and **Timer 1 Repeat Day In Month (page 433)** (concrete day in repeated months).

Second type of monthly repetition is based on repeating days in week in month.

In controller go to the Scheduler setpoint group. Select the function of timer via **Timer 1 Function (page 428)** setpoint. Than go to *Timer 1 Setup* and press enter button. In **Timer 1 Repetition (page 429)** setpoint select Repeated mode. Than adjust **Timer 1 First Occur. Date (page 429)**, **Timer 1 First Occur. Time (page 429)** and **Timer 1 Duration (page 430)**. In setpoint **Timer 1 Repeated (page 430)** select Monthly and adjust type of monthly repetition via **Timer 1 Repeated Day (page 433)**, **Timer 1 Refresh Period (page 431)** (x-th month of repetition), **Timer 1 Repeated Day In Week (page 433)** (days in week when timer is active) and **Timer 1 Repeat Week In Month (page 434)** (concrete week in repeated months).

Note: Use left and right buttons to move between timer setpoints.



Short period mode

Set-up via InteliConfig

To set-up timer via InteliConfig go to the setpoint ribbon, setpoint group scheduler and setpoint Timer 1 Setup.

Note: First of all function of timer has to be adjusted via setpoint Timer 1 Function (page 428).

Timer 1 Setup				×	
Timer	O Off	O Once	Repea	t	Timer mod
First occurrence: Time: 12:00	C	1/1/2016 Duration:	1:00	iii O	Timer settings
Repeating since fir daily weekly monthly short period	st occurrence	4:00	• hours		x-th interva of repetitio
		۲	Ok 🔕	Cancel	5
Repetition type					

Image 5.48 Short period mode - InteliConfig

In timer mode select Repeat. In repetition type select Short period. In timer settings adjust date and time of first occurrence of timer. Also adjust the duration of each occurrence of timer. Than select the interval of repetition (shorter than 1 day).

Example: On image example first start of timer will be 1/1/2016 at 12:00. Duration will be 1 hour. Timer will be again activated every 4th hour for 1 hour.

Set-up via controller interface

In controller go to the Scheduler setpoint group. Select the function of timer via Timer 1 Function (page 428) setpoint. Than go to *Timer 1 Setup* and press enter button. In Timer 1 Repetition (page 429) setpoint select Repeated mode. Than adjust Timer 1 First Occur. Date (page 429), Timer 1 First Occur. Time (page 429) and Timer 1 Duration (page 430). In setpoint Timer 1 Repeated (page 430) select Short Period and adjust Timer 1 Refresh Period (page 431) (interval of repetition).

Note: Use left and right buttons to move between timer setpoints.

5.3.21 Rental Timers

In controller are two timers which are designed like rental timer. Rental timers will stop gen-set after their elapse.

How to set-up rental timer

This is a short guide for settings of rental timers. Please see following few steps how to set up rental timers:

- Choose the type of rental timer
 - Rental Timer 1 (page 441) (based on engine running hours)
 - Rental Timer 2 (page 443) (based on date)
- Adjust the length of chosen timer
- Adjust the warning for user Rental Timer 1 Wrn (page 443) or Rental Timer 2 Wrn (page 445)(warning will be displayed in alarmlist before elapsing of rental timer)
- Adjust Rental Timer BOC (page 445) common for both timers (if engine is still running after rental timer counts down, this timer will starts count down and after elapse of timer the gen-set will be cooled down and stop)

5.3.22 Service timers

Running hours counters

Service timers are used as maintenance interval counters. Counters can be set by setpoints - Maintenance Timer 1 (page 302), Maintenance Timer 2 (page 303) and Maintenance Timer 3 (page 303). All of them work the same way - their values are decremented every hour when the gen-set is running.

Actual value of counters is located either as the same setpoints Maintenance Timer 1 (page 302), Maintenance Timer 2 (page 303) and Maintenance Timer 3 (page 303) or as values Maintenance 1 (page 583), Maintenance 2 (page 584) and Maintenance 3 (page 584).

When the value of counter reaches 0, the alarm Wrn Maintenance 1 (page 808) or Wrn Maintenance 2 (page 808) or Wrn Maintenance 3 (page 809) is active until the respective counter is readjusted back to nonzero value.

Unused counter has to be adjusted to maximal value 10000 (Disabled).

5.3.23 Analog switches

There are logical analog function dedicated for analog switches. Each analog switch has setpoints for level ON and level OFF and logical binary output.

Analog switch	Setpoints	Binary output
AIN SWITCH 04 (DAOE 764)	Analog Switch 1 On (page 367)	AIN SWITCHOL (DA OF 606)
AIN SWITCH UT (PAGE 764)	Analog Switch 1 Off (page 368)	AIN SWITCHUT (PAGE 090)
AIN SWITCH 02 (DAOE 764)	Analog Switch 2 On (page 370)	AIN SWITCHO2 (DAOE 606)
AIN SWITCH UZ (PAGE 764)	Analog Switch 2 Off (page 371)	AIN SWITCHUZ (PAGE 090)
AIN SMUTCH 02 (DACE 764)	Analog Switch 3 On (page 373)	AIN SWITCHOZ (DA OF 607)
AIN SWITCH US (PAGE 764)	Analog Switch 3 Off (page 374)	AIN SWITCHUS (PAGE 697)
AIN SMUTCH OA (DAGE 765)	Analog Switch 4 On (page 376)	AIN SWITCHOA (DAOE 607)
AIN SWITCH 04 (PAGE 705)	Analog Switch 4 Off (page 377)	AIN SWITCH04 (PAGE 097)
AIN SMUTCH OF (DAGE 765)	Analog Switch 5 On (page 379)	AIN SWITCHOE (DAOE 609)
AIN SWITCH US (PAGE 705)	Analog Switch 5 Off (page 380)	AIN SWITCHUS (PAGE 030)



Analog switch	Setpoints	Binary output
AIN SWITCH OF (DACE 765)	Analog Switch 6 On (page 382)	
AIN SWITCH 00 (PAGE 705)	Analog Switch 6 Off (page 383)	AIN SWITCHOO (PAGE 050)
AIN SWITCH 07 (DAGE 766)	Analog Switch 7 On (page 385)	
AIN SWITCH UT (PAGE 700)	Analog Switch 7 Off (page 386)	AIN SWITCHUT (PAGE 055)
AIN SWITCH 08 (PAGE 766)	Analog Switch 8 On (page 388)	
AIN OWITCH OU (FAGE 700)	Analog Switch 8 Off (page 389)	AIN OWITCHOO (FAGE 000)
AIN SWITCH 09 (PAGE 766)	Analog Switch 9 On (page 391)	AIN SWITCH09 (PAGE 700)
	Analog Switch 9 Off (page 392)	
AIN SWITCH 10 (PAGE 767)	Analog Switch 10 On (page 394)	AIN SWITCH10 (PAGE 700)
	Analog Switch 10 Off (page 395)	
AIN SWITCH 11 (PAGE 767)	Analog Switch 11 On (page 397)	AIN SWITCH11 (PAGE 701)
	Analog Switch 11 Off (page 398)	
AIN SWITCH 12 (PAGE 767)	Analog Switch 12 On (page 400)	AIN SWITCH12 (PAGE 701)
	Analog Switch 12 Off (page 401)	
AIN SWITCH 13 (PAGE 768)	Analog Switch 13 On (page 403)	AIN SWITCH13 (PAGE 702)
	Analog Switch 13 Off (page 404)	····· ····· (······ ····)
AIN SWITCH 14 (PAGE 768)	Analog Switch 14 On (page 406)	AIN SWITCH14 (PAGE 702)
	Analog Switch 14 Off (page 407)	
AIN SWITCH 15 (PAGE 768)	Analog Switch 15 On (page 409)	AIN SWITCH15 (PAGE 703)
	Analog Switch 15 Off (page 410)	
AIN SWITCH 16 (PAGE 769)	Analog Switch 16 On (page 412)	AIN SWITCH16 (PAGE 703)
	Analog Switch 16 Off (page 413)	. ,
AIN SWITCH 17 (PAGE 769)	Analog Switch 17 On (page 415)	AIN SWITCH17 (PAGE 704)
. ,	Analog Switch 17 Off (page 416)	. ,
AIN SWITCH 18 (PAGE 769)	Analog Switch 18 On (page 418)	AIN SWITCH18 (PAGE 704)
	Analog Switch 18 Off (page 419)	
AIN SWITCH 19 (PAGE 770)	Analog Switch 19 On (page 421)	AIN SWITCH19 (PAGE 705)
	Analog Switch 19 Off (page 422)	
AIN SWITCH 20 (PAGE 770)	Analog Switch 20 On (page 424)	AIN SWITCH20 (PAGE 705)
	Analog Switch 20 Off (page 425)	

The behavior of the switch depends on the adjustment of the setpoints.



Image 5.49 Principle of analog switch

5.3.24 Additional running engine indications

It is helpful to have information other than speed (RPM), whether the engine is rotating or not, especially if RPM is measured from the generator frequency instead of magnetic pickup. The generator frequency measurement can be unreliable at very low speeds and/or may have a delayed reaction to sudden and big changes (i.e. in the moment that the engine has just started...).

The following conditions are evaluated as additional running engine indication:

- Voltage on the D+ input is higher than 80% of battery voltage. Connect this input to the D+ (L) terminal of the charging alternator and enable the D+ function by the setpoint D+ Function. If D+ terminal is not available, leave the input unconnected and disable the function.
- The pickup is not used and frequency is not detected on the pickup input. Connect the pickup input to the W terminal of the charging alternator if you do not use pickup and the W terminal is available. If not, leave the input unconnected.
- Oil pressure > Starting Oil Pressure (page 274) setpoint. The oil pressure is evaluated from the analog input or from the ECU if an ECU is configured.
- Binary input OIL PRESSURE (PAGE 674) is in logical 0.
- At least one phase of generator voltage is >25% of nominal voltage.

These signals are used during start for powering down the starter motor even if still no RPM is measured and also during stop in order to evaluate if the engine is really stopped.

5.3.25 Voltage phase sequence detection

Controller detects phase sequence on both voltage terminals. This protection is important after controller installation to avoid wrong voltage phase connection. The phase sequence is adjusted via setpoint **Phase Rotation** (page 252). When the phases are connected in different order, following alarms are detected:

- Generator CCW Rotation (page 814)
- Bus CCW Rotation
- Mains CCW Rotation (page 815)

5.3.26 Sensor curves

Background of the sensor calibration

To correct measuring error of each analog input (pressure, temperature, level, etc.) calibrating constants should be set. Calibration is made by adding the value of setpoint CU AIN1 Calibration (page 451), or Description (page 452), or CU AIN3 Calibration (page 452), or CU AIN4 Calibration (page 453) directly to the calculated value at analog input.



Note: The calibration must be done at the operational point of the analog input (e.g. 80°C, 4.0Bar etc..)

Default sensor curves

There are 16 default resistive curves available. The following table provides information on minimum/maximum values of respective sensors. Actual values especially of temperature curves may differ. Meaning is to prolong curve to the lower temperature values, so the cold engine will not raise alarm fail sensor.

Curve	Min [Ohm]	Max [Ohm]	Units
VDO 10 Bar 0-2400ohm	0	2400	Bar
VDO40-120°C0-2400ohm	0	2400	°C
VDOLevel%0-2400ohm	0	2400	%
General line 1	0	1000	ohm
General line 2	0	1000	ohm
General line 3	0	1000	ohm
General line 4	0	1000	ohm
General line 5	0	1000	ohm
General line 6	0	1000	ohm
General line 7	0	1000	ohm
General line 8	0	1000	ohm
General line 9	0	1000	ohm
General line 10	0	1000	ohm
General line 11	0	1000	ohm
General line 12	0	1000	ohm
General line 13	0	1000	ohm

Note: Curves can be modified via InteliConfig. In InteliConfig are also prepared some standard curves.

IMPORTANT: For right behavior of function, curve for this analog input has to be in percentage.

Sensor curve HW configuration

InteliGen 500 analog inputs allows you to select Input HW type. Three HW configuration options are available:

- 🕨 0-15 kΩ
- ▶ 0-10 V
- 0-20 mA passive

Setup controller analog input in this way to use other than the default HW configuration (0-15 k Ω):

1. Start with a sensor configuration and select requested HW configuration

Configuration	S	etpoints	Con	troller	I/O <mark>S</mark>	enso	rs N			
Sensors	Add	line	Delete	e line	Open	n][Save			
StarterKit OilPress	HW	HW configuration								
StarterKit CoolTemp	0-1	0-10 V 👻								
StarterKit FuelLev	Sens Sta	Sensor Name StarterKit OilPress								
General line 1	Reso	Resolution Dim								
General line 2		0,1	•	Bar		v	0			
General line 3			0-10 V	/	1	Bar				
General line 4	0	0 0,000			0,0					
General line 5	1	1,000			10,0					

2. Use the adjusted sensor with an analog input and the requested HW configuration will be used with the analog input automatically. There is no need to use a jumper, configured Input HW type is used by controller automatically.

Configuration	Setpoints Controller L	/O Sensors	Modules	PLC Editor	Others			
Binary Inputs	Analog Input 1							
Binary Outputs	Function:							
Analog Inputs	History abbreviation:	OilP						
	Sensor:							
	Bargraph 0%:		0,0	÷				
	Bargraph 100%:		\$					
	Input HW type:	0-10 V						
	Protection type:							
	Oil Pressure Delay	3	s					
	Oil Pressure Sd	1,0	Bar					
	Oil Pressure Wrn	2,0						
	Protection active:	Under Limit						
	Engine running only:	\checkmark						



5.3.27 PLC

PLC Editor is powerful tool which helps you to create your own PLC scheme. It has graphical interface to have user interface easy to use.



Image 5.50 PLC Editor main page

List of available PLC blocks

PLC block	Number of blocks
OR/AND	32
XOR/RS	8
Comparator with hysteresis (Comp Hyst)	4
Comparator with delay (Comp Time)	4
Timer	1
Delay	8
Force history record (Force Hist)	4
Force protection (Force Prot)	4
Counter	1



Working with the editor

If the currently opened archive does not contain any PLC program, then an empty drawing is created automatically when you select the PLC Editor. The procedure of creation of a PLC drawing (program) contains following essential steps:

- Adjust the sheet to your needs. See Working with sheets (page 136) for more information.
- Add PLC blocks into the sheets. See Adding PLC blocks (page 136) for more information.
- Define inputs and outputs of the PLC program. See Define inputs and outputs (page 137) for more information.
- Create connections between inputs, blocks and outputs. See Creating wires (page 140) for more information.
- Adjust properties of the blocks. See List of PLC blocks (page 777) for more information about blocks.

Working with sheets

Drag the sheet edges to re-size the sheet according to your needs.



Image 5.51 Adjusting PLC sheet

Adding PLC blocks

Adding PLC block is simple and intuitive. Follow the procedure below to add PLC block.

- Select required block from the list of available PLC blocks at the left and drag it into the sheet.
- Double-click on the block and adjust properties of the block. See List of PLC blocks (page 777) for more information about blocks.

Connect the block inputs and outputs by drawing wires in the sheet. See Define inputs and outputs (page 137) for more information. It is also possible to connected inputs and outputs via properties of selected PLC block.

	Operations Ot	hers PLC																							
	PLC Blocks												Sł	eet 1	ł										
	Logical functions			-	4	4 4	4	4	¥ 4	4	4	4 (4)	4	4 4	- 4	4	4 4	- 4	4	4	4	4 4	. u		
	- I OR/AND	(0/16)																						1	
		(0/2)		- 4																				-	
		(0/2/		_																					
		÷		-																				-	
	Comp Hyst	(0/2)		-																					
)	🖵 🛐 Comp Time	10/2)																						-	
	Time functions																								_
	- Timer	(0/1)	_																					1	
	Delay	(0/2)				1 4																			
	FJ Others			1							S	aci	e fo	r bl		(S								L	
	- III Force Hist	(0/2)		-																				-	
	Territo Dent	10/21		_																				-	
	- m Foice Plot	(0721																						-	
		-		-																				-	-
				=: ₁																				1	
				4																					_
																								1	
				-																					
				-																				-	

Image 5.52 Adding PLC blocks

Note: To delete PLC block just click on it and press delete button. Also delete selection function can by used.

Note: To see context help for selected PLC block just press F1 button.

Define inputs and outputs

•															Shee	et 1												a series		
	11	71	a.	a.	12	12	13	а	12	10	βî.	73	a	i.	a.	a.	10	13	10	а	12	а	a.	а	а	a	a	11		
	П																											11		
[Ш		
	11																											11		
1																												Ш		
																												11		
																												Ш		
	Π																											П		
	11																											Ш		
	П																											П		
Innute														al o		-												Ш	Output	
inputs	11												14		U.	3												11	Quipuis	8-
																												IJ		
	11																											11		
	U																											IJ		
	11																											11		
	U																											Ш		
	11																											П		
	U																													
	Π																											11		
																												1		
	ΓL																											11		

Image	5.53	Blank	sheet	of	PLC	editor
-------	------	-------	-------	----	-----	--------



Inputs

Sheet inputs are located at the left side of a sheet. Follow the procedure below to add or edit an input.

- > Double-click on a free input position or existing input to add new input or edit the existing one.
- Select the source for the input.
 - If you create a binary input, you can select a source from following categories:
 - Bin. Values this category contains all binary values available in the controller as binary inputs, logical binary outputs etc.
 - PLC Outputs this category contains all PLC blocks binary outputs available in the controller.
 - If you create an analog input, you can select a source from following categories:
 - Ana. Values this category contains all analog values available in the controller as analog inputs, electrical values, values from ECU etc.
 - All Setpoints this category contains all setpoints of the controller except the dedicated PLC setpoints. Names, resolutions and dimensions of these setpoints can not be modified.
 - PLC Setpoints this category contains a group of setpoints which are dedicated for using in the PLC program. PLC setpoints can be renamed, their dimension, resolution and limits can be modified according to need of PLC blocks where they are used.

PLC Setpoint name:	Dimension:	Resolution:	Low limit:	High limit:	
	-	1 -	0	0 0	Apply



Select input				×	
Bin. Values Ana. Values	All Setpoints	PLC Setpoints			Inputs
Controller I/O				•	categories
Log Bout				*	Innuts
					subgroups
		(ж 🔕	Cancel	

Image 5.54 PLC inputs

Outputs

Sheet outputs are located at the right side of a sheet. Follow the procedure below to add or edit an input.

- Doubleclick on a free output position to add new sheet output.
- Doubleclick on an already created output to configure the output onto a controller output terminal or a logical binary input (first of all some PLC block output has to be connected to this output to enable configuration of output).



PLC Binary Outp	out			×	News
Name: PL	C-BOUT 1.1				output
Connected to:					
					connection o output
+ Connect	- Disconne	ct			Connect or disconnect PLC output to
Available physic	al outputs / logic	al inputs:			 selected physical
Output		Name	Used as (Source)		binary output
B01		Starter	Starter		orlogical binary input
BO2		Fuel Solenoid	Fuel Solenoid		
BO3		GCB Close/Open	GCB Close/Open		
BO4		MCB Close/Open	MCB Close/Open		
BO5		GCB OFF Coil	GCB OFF Coil		
BO6		GCB ON Coil	GCB ON Coil		
BO7		MCB OFF Coil	MCB OFF Coil		
BO8		MCB ON Coil	MCB ON Coil		
Logical inp	uts				
			Ø ок	🙁 Cancel	
Available outputs or input	physical logical ts	Current function of physical outputs or logical inputs	Current s physical c logical	ource of outputs or inputs	



IMPORTANT: It is necessary to click on Connect button after selecting the output. Otherwise PLC output is not connected to output.

Creating wires

Wires can be create between PLC inputs and PLC blocks and between PLC blocks and PLC outputs.

IMPORTANT: Keep the order of starting and finishing connection points. Wires between inputs and blocks have to start from inputs. Wires between blocks and outputs have to start from blocks.

Follow the procedure below to create wire.

- Locate the mouse pointer over the starting point of the wire. If the area under the mouse pointer is a connection point, the pointer will change the color (fill of pointer will be white).
- Press and hold the left mouse button and drag the wire to the destination of required connection point. If you point over a valid connection point, the connection point will be marked with a red circle.
- Release the left mouse button to create a wire between the two points. The wire is routed automatically.



Note: It is possible to make connection only between the outputs and inputs with the same type of value (binary or analog). Binary values are marker by black pointer, analog values are marked with green pointer.

Note: To delete wire just click on it and press delete button. Also delete selection function can by used.

PLC logic execution rules

The PLC program is executed every 100 ms. The blocks are executed in order according to block numbers (item numbers), which are indicated in each block. The block numbers are assigned automatically according to position on sheet.



Image 5.56 PLC execution logic

IMPORTANT: Please always check that the blocks are ordered correctly, especially if you use direct feedbacks from outputs to inputs within one sheet. Wrong order may lead to incorrect results!!!



Other functions

Consistency check

Use this function to check if all inputs and outputs of PLC block are connected.

Delete whole content of sheet

Use this function to delete the whole content of sheet (including blocks, wires, inputs, outputs, etc...).

Hints

Use this function to enable or disable quick hints for blocks (controller help is not affected by this function).

PLC monitor

PLC monitor is a powerful tool for monitoring your PLC. Just click on PLC monitor button on main InteliConfig page to see you PLC. Active inputs and outputs have blue color. Also wires with active signals have blue color.

IMPORTANT: It is not possible to edit PLC in PLC monitor tool.

5.3.28 Aftertreatment Suppot

Afertreatment support generally provides monitoring and control of aftertreatment system installed on generators engines. The requirements are defined as:

- Providing Aftertreatment status information by:
 - displaying universal lamps (icons)
 - displaying corresponding analog and binary values
- Control of Aftertreatment regeneration function by
 - transmitting commands to the ECU module

Providing Aftertreatment status information

Aftertreatment screen

This screen is available when ECU module which supports Aftertreatment is configured. Aftertreatment screen is automatically brought to the front once any of selected lamps gets active or when increases reported severity. Deactivating of the lamp will not trigger automatic changeover to the Aftertreatment screen. The screen is then shown until operator switch it to another one. Alarmlist screen has lower priority, so even new alarm appears, Aftertreatment screen is still displayed. To avoid displaying blank screen, inactive lamps are represented by "greyed-out" icons. For no active lamp the screen shows all greyed-out icons. Please see examples below:

ComAp

[13/13] After	treat	ment		DE 🔺
STOP		0	5	- 1 3>
43		4	2	R
##	% ##	Soot Load	d 	% ####
REG Force			-	
	(13/13) After	(13/13) Aftertreat	[13/13] Aftertreatment	(13/13) Aftertreatment

Image 5.57 Example of active Aftertreatment screen



Image 5.58 Example of inactive Aftertreatment screen

Universal lamps (icons)

Universal lamp icons are shown on the Aftertreatment screen. Based on specific value read in specific frame with specific SPN is every lamp icon can be either:

- shown
- hidden
- blinking slow (1 Hz)
- blinking fast (2 Hz)

Note: Lamp icon blinking is defined as displaying active lamp icon and inverse colored active lamp icon in required frequency.



Lamp name	Active icon	Inactive icon	Notes
Yellow warning lamp		•	Note: This value can light or blink on both frequencies.
Red stop lamp	STOP	STOP	Note: This value can light or blink on both frequencies.
Engine wait to start	00	00	
ATT filter lamp	- I :3•	-==:;;	Note: Indicates the Aftertreatment filter needs to be regenerated. This lamp also activates alarm ATT Filter Lamp (page 811).
High exhaust system temperature lamp	=32	<b `	Note: Indicates High exhaust system temperature. This lamp also activates alarm ATT HEST Lamp (page 812).
SCR error lamp	=====;	= -3,	Note: Indicates SCR system problems. This lamp also activates alarm ATT SCR Error Lamp (page 812).
DEF low level lamp		- <u>+</u> , , , , ,	Note: Indicates DEF fluid low level. This lamp also activates alarm ATT DEF Level Lamp (page 812) .
Regeneration inhibit lamp	- To	132°	Note: Indicates Aftertreatment regeneration is inhibited. This lamp also activates alarm ATT Inhibited Lamp (page 812) .


Analog values

Supported analog values:

- DPF Ash Load (page 559)
- DPF Soot Load (page 559)
- DEF Level (page 559)

Control of Aftertreatment regeneration function

User can force or inhibit regeneration process by activating appropriate binary inputs of the controller. Please see the list of binary inputs below:

- REGENERATION FORCE (PAGE 674)
- REGENERATION INHIB (PAGE 674)

5.3.29 Geo-fencing

Geo-fencing function is kind of protection that evaluates whether the actual GPS location is within predefined area and based on the evaluation takes an action (sends sms, stops engine, make history record etc.). Function is enabled by setpoint **Geo-Fencing (page 448)** or by logical binary input **GEO-FENCING ENABLED (PAGE 669)**.

Using InteliConfig, it is possible to set two concentric geo-circles within which the unit is allowed to be located. Each geo-circle is defined as circular geographic area with centre (common for both geo-circles) named Home Position adjusted via setpoints **Home Latitude (page 446)** and **Home Longitude (page 446)** and radius named Fence Radius adjusted via setpoints .**Fence Radius 1 (page 447)** and **Fence Radius 2 (page 447)**.

Protections can be different for both circles. Protection are adjusted via setpoints Fence 1 Protection (page 449) and Fence 2 Protection (page 450).

It is also possible to see the current position of the controller in WebSupervisor map view.

5.3.30 Mains decoupling protections

Vector shift

The vector shift function is the fast protection for mains decoupling. It monitors the Load angle of the generator and if it gets changed dramatically, the protection is issued. The Vector shift is evaluated from the Mains Voltage Measurement (Phase 1).

Protection is enabled via setpoint Vector Shift Protection (page 326). Limit of protection is adjusted via setpoint Vector Shift Limit (page 326). When protection is activated, the breaker is opened. Which breaker is opened is adjusted via setpoint Vector Shift CB Selector (page 328). Maximal value of vector shift is represented by value Max Vector ShiftMaxVectorS (page 575).

Note: VectorShift protection gets active (is unblocked) right 500 ms after the condition for activation of protection gets fulfilled = when Controller goes to parallel to mains operation (When Vector Shift Protection = PARALLEL ONLY) or when MCB gets closed (when Vector shift protection = ENABLED).

The settings can lead to these situations:



MCB status	GCB status	Vector Shift CB Selector	Vector Shift Protection	Action
1	1	MCB or GCB	Parallel or Enabled (No influence)	Opens MCB or GCB based on setpoint Vector Shift CB Selector.
0	1	No influence	No influence	No action (GCB stays alaways closed)
1	0	No influence	Parallel	No action MCB stays closed
1	0	GCB	Enabled	No action MCB stays closed
1	0	MCB	Enabled	MCB opens

If a vector shift is detected and consequently the MCB is opened, however mains voltage and frequency remain in limits, the MCB is then closed again (synchronized) after **Mains Return Delay (page 319)** as the mains is evaluated as healthy.

If a vector shift is detected and consequently the GCB is opened, however mains voltage and frequency remain in limits, the GCB is then closed again (synchronized) immediately (no delay).

ROCOF

The Rate of Change of Frequency function is the fast protection for mains decoupling. It monitors the change of frequency and if it gets changed dramatically, the protection is issued.

Protection is enabled via setpoint ROCOF Protection (page 327). Limit of protection is adjusted via setpoints ROCOF df/dt (page 328) and ROCOF Windows Length (page 327). When protection is activated, the breaker is opened. Which breaker is opened is adjusted via setpoint Vector Shift CB Selector (page 328).

5.3.31 Droop

IMPORTANT: Droop is relevant only for MINT application.

The DROOP is primarily intended for Multiple parallel operation in Island to ensure the load sharing and VAr sharing when intercontroller communication fails. The Active and Reactive power is not regulated based on data communicated between the units (isochronous regulation) but the speed request and voltage request is calculated from actual voltage and actual frequency of the system (the measured Voltage and frequency of whole system is always equal). Actually the speed request is correlative to active power and the voltage request is correlative to reactive power. The correlation is the decreasing function and it creates the negative feedback of regulation.

Function is activated via setpoint Load/Var Sharing Regulation Type (page 361). There are two droop modes - emergency droop and droop.



Frequency droop



Image 5.59 Frequency droop

Equation:

Required frequency = Nominal frequency - [(Nominal frequency * Frequency Droop Slope (page 362) / 100) * (Active power / Nominal power - Frequency Droop Offset (page 363) / 100)).

Voltage droop







Equation

Required voltage = Nominal voltage - [(Nominal voltage * Voltage Droop Slope (page 363) / 100) * (Reactive power / Nominal reactive power - Voltage Droop Offset (page 364) / 100))

Note: Nominal reactive power is not setpoint, but is calculated from Nominal power for PF = 0,8

Principle of droop operation

Connecting of the gen-set operating in droop to the common bus bar

- Start command is received start button in MAN mode or LBI REMOTE START/STOP (PAGE 677) in AUTO mode gets active
 - The gen-set operating in droop is not calculated in the load reserve.
 - LBI REMOTE START/STOP (PAGE 677) is not influenced by power management and gen-set starts if it gets active.
- Gen-set is starting voltage and speed regulation are set to Voltage Regulator Bias (page 354) and Speed Governor Bias (page 346) (droop regulation is not active when GCB is opened).
- Connecting to bus
 - Dead bus controller is prohibited to close it's GCB because of safety reasons (controller does not know about other controllers). Only controller with setpoint Dead Bus GCB Close Master (page 362) = ENABLED is allowed to close it's GCB to the dead bus. Otherwise it must be done manually in MAN mode.
 - Energized bus controller starts synchronization (standard isochronous regulation).
 - GCB closes when synchronized Now the droop regulation gets active

Disconnecting of loaded gen-set from common bus bar in droop

- Gen-set is operating in droop and is loaded. Stop command is received stop button in MAN mode or LBI REMOTE START/STOP (PAGE 677) in AUTO mode gets inactive.
- Controller starts soft unload of loaded gen-set
 - Soft unload can be disabled via LBI DROOP UNLOAD DISL (PAGE 664) in case when there is the last genset on the common bus bar and it is not possible to unload it. Then the GCB is opened immediately.
- GCB opens when the active power drops under Unload MGCB Open LevelGenerator Unload GCB Open Level (page 352), latest when timer Load Ramp (page 353) elapses.

Transition from droop to iscochronous regulations

- The speed request during the transition from droop (or emergency droop) to is ochronous regulation is changed smoothly (not in step). It prevents the system against overshoot of the frequency.
- Frequency is changed by 2 Hz per Load Ramp (page 353).

Forcing of the regulation to droop

Droop regulation can be forced by LBI FORCE DROOP OPER (PAGE 665).

Principle of emergency droop

When **Load/Var Sharing Regulation Type (page 361)** = Emrg Droop, Isonchronous regulation is used until the conditions for activation of emergency droop are fulfilled. After activation, emergency droop regulation is used until the conditions for deactivation are fulfilled.



Conditions for activation

- The number of controllers detected by the controller on can is lower than the number in the setpoint #Number Of Controller On CAN (page 364).
- #Emergency Droop On Delay (page 365) has count down.

Conditions for deactivation

- The number of controllers detected by the controller on can is equal or higher than the number in the setpoint #Number Of Controller On CAN (page 364).
- **#Emergency Droop Off Delay (page 365)** has count down.

5.3.32 Alternate configuration

In controller are 3 sets of configuration.

Configuration set 1	Configuration set 2	Configuration set 3
Nominal Power 1 (page 455) Nominal Power Split Phase 1 (page 455) Nominal RPM 1 (page 456) Nominal Frequency 1 (page 456)	Nominal Power 2 (page 459) Nominal Power Split Phase 2 (page 459) Nominal RPM 2 (page 460) Nominal Frequency 2 (page 460)	Nominal Power 3 (page 463) Nominal Power Split Phase 3 (page 463) Nominal RPM 3 (page 464) Nominal Frequency 3 (page
Nominal Voltage Ph-N 1 (page 457) Nominal Voltage Ph-Ph 1 (page 457)	Nominal Voltage Ph-N 2 (page 461) Nominal Voltage Ph-Ph 2 (page 461)	Nominal Voltage Ph-N 3 (page 465) Nominal Voltage Ph-Ph 3 (page
Nominal Current 1 (page 456) Connection Type 1 (page 453)	Nominal Current 2 (page 460) Connection type 2 (page 457)	465) Nominal Current 3 (page 464) Connection type 3 (page 461)

Configuration sets can be changed via logical binary input ALTERNATE CONFIG 2 (PAGE 615) and logical binary input ALTERNATE CONFIG 3 (PAGE 615).

IMPORTANT: Gen-set can not switch to the alternative setpoints when is running.



5.3.33 USB host

USB host is a function for programming of controller from USB Flash Drive. Following functions are supported:

- Firmware upload
- Configuration upload
- Firmware and configuration upload
- Configuration download



Image 5.61 USB host flowchart

Terminology:

- The Archive = the native file of InteliConfig, including the complete Configuration + History + Statistic + Values (in the time of download) + Alarm list.
- Configuration = the part of Archive, in the terms of Configuration + Setpoints + PLC + IO definitions + Languages.
- New configuration = the configuration created in InteliConfig for the purpose of uploading it into the controller using the USB memory stick. The new configuration is recognized due to it's name. The name has to contain the specific string ="InteliGen500-Genset name-M.N.P.B.aig3".
- Compatible firmware = the firmware version compatible with the configuration in the controller. The name of file including the firmware is "InteliGen500-M.N.P.B.bin".

Abbreviations:

- CU control unit
- FW firmware
- CFG configuration



Firmware upload

- Point 1 controller detects that USB Flash Drive has been inserted.
 - If the communication via USB B is running controller will not detect the USB memory key.
 - On the other hand if the USB memory key was detected, communication via USB B port is not possible.
- Point 2 controller is in OFF mode
 - All operations with USB memory key are possible only in OFF mode
- Point 3 Conditions for firmware upload with current configuration
 - The new firmware compatible with the version of the configuration in the controller has been detected (and there is no new configuration file).
 - Detection is based on name of firmware required name: "InteliGen500-M.N.P.B.bin"
 - There can be stored more firmwares on the USB Flash Drive. Controller automatically select the compatible firmware with highest version.
- Point 4 Pop-up message
 - Confirmation of firmware upload with current configuration
- Point 5 Firmware upload
 - Current archive is download to USB Flash Drive (Name = SN_YYMMDDHHMM).
 - New firmware is uploaded into the controller without the change of the configuration
 - History record "USB Flash Drive FW upgrade" is made
 - Confirming file (.txt) on USB Flash Drive is made (Name = SN_YYMMDDHHMM)
 - Content: Serial number, Year/Date/Time, Upgrade to the FW "Name of the new FW" successful.
 - Confirmation pop-up message: "FW upgrade success"

Configuration upload

- Point 1 controller detects that USB Flash Drive has been inserted.
 - If the communication via USB B is running controller will not detect the USB memory key.
 - On the other hand if the USB memory key was detected, communication via USB B port is not possible.
- Point 2 controller is in OFF mode
 - All operations with USB memory key are possible only in OFF mode
- Point 9 conditions for new configuration upload
 - The new configuration compatible with the version of the firmware in the controller has been detected (and there is no new firmware file).
 - Detection is based on name of configuration required name: "InteliGen500-Genset name-M.N.P.B.aig3"
 - There can be only one configuration file
- Point 10 Pop-up message
 - Confirmation of configuration upload with current firmware
- Point 11 Configuration upload
 - Current archive is download to USB key (Name = SN_YYMMDDHHMM).
 - New configuration is uploaded into the controller without the change of the firmware



- History record "USB key CFG upload" is made
- Confirming file (.txt) on USB key is made (Name = SN_YYMMDDHHMM)
 - Content: Serial number, Year/Date/Time, Upgrade to the FW "Name of the new CFG" successful.
- Confirmation pop-up message: "CFG upgrade success"

Firmware and configuration upload

- Point 1 controller detects that USB Flash Drive has been inserted.
 - If the communication via USB B is running controller will not detect the USB memory key.
 - On the other hand if the USB memory key was detected, communication via USB B port is not possible.
- Point 2 controller is in OFF mode
 - All operations with USB memory key are possible only in OFF mode
- Point 6 conditions for new firmware and configuration upload
 - The new configuration has been detected. Also there is firmware file compatible with detected new configuration
 - Detection is based on name of configuration required name: "InteliGen500-Genset name-M.N.P.B.aig3" and on name of firmware - required name: "InteliGen500-M.N.P.B.bin"
 - There can be only one configuration file
 - There can be stored more firmwares on the USB key. Controller automatically select the compatible firmware with highest version.
- Point 7 Pop-up message
 - Confirmation of configuration and firmware upload
- Point 8 Configuration and firmware upload
 - Current archive is download to USB key (Name = SN_YYMMDDHHMM).
 - New firmware is uploaded into the controller
 - New configuration is uploaded into the controller
 - History record "USB key FW and CFG upload" is made
 - Confirming file (.txt) on USB key is made (Name = SN_YYMMDDHHMM)
 - Content: Serial number, Year/Date/Time, Upgrade to the FW "Name of the new FW" successful, Upgrade to the FW "Name of the new CFG" successful.
 - Confirmation pop-up message: "FW and CFG upgrade success"

Configuration download

- Point 1 controller detects that USB Flash Drive has been inserted.
 - If the communication via USB B is running controller will not detect the USB memory key.
 - On the other hand if the USB memory key was detected, communication via USB B port is not possible.
- Point 2 controller is in OFF mode
 - All operations with USB memory key are possible only in OFF mode
- Points 3, 6, 9 conditions for configuration download
 - There is no firmware or configuration with required name

- Point 12 Pop-up message
 - Confirmation of configuration download
- Point 11 Configuration download
 - Current archive is download to USB key (Name = SN_YYMMDDHHMM).
 - History record "USB key Archive download" is made
 - Confirmation pop-up message: "Archive download successful"

5.3.34 E-Stop

Binary outputs for the control of some essential functions are internally wired as "safe", it means, that their deactivation is directly bind with the dedicated Input E-STOP (not evaluated as the LBI in the controller). This BO are fully configurable and are used e.g. for the Starter and Fuel control.

- > The emergency stop circuit must be secured.
- ▶ No accidental activation on the PCB, circuit must disable the operation of the emergency stop.
- The power supply of the associated binary outputs (BIN1 and BIN2) is supplied by the E-STOP input, not by the + battery voltage.

Note: There is no difference int the way of configuration of all binary outputs. Binary outputs BO1 (Starter), BO2 (Fuel Solenoid) are intended for these functions (not dedicated).

There is a measuring of E-STOP input voltage analogically and setting the binary value (representing emergency stop input level) based on comparison of the measured voltage to two analog levels, which are derived from the controller supply voltage (battery voltage) perceptually.



Image 5.62 SW principle of E-STOP

- If the input voltage of E-stop is higher than high comparison level (for ex. higher than 80% of the supply voltage), then E-stop is not activated.
- If the input voltage of E-stop is lower than low comparison level (for ex. lower than 60% of the supply voltage), then E-stop is activated.

If the input voltage of E-stop is located somewhere between low and high comparison levels (for ex. between 60 and 80 % of the supply voltage, then E-stop binary value will stay on its previous state (means E-stop binary value will not change).

Visualization on CU screen

- 1 E-STOP has voltage state is OK
- 0 E-STOP has no voltage protection is active

More information about connection see E-Stop on page 40.

5.3.35 ECU Frequency selection

Setpoint *ECU Freq Select* is no longer in use. However **ECU Frequency Select (page 562)** value was kept and the value can be calculated from **Nominal Frequency (page 247)** setpoint. Sequence for frequency change is executed automatically (engine must be in still condition and ECU is powered on – ECU Power Relay is not configured) in following 9 steps:

- 1. Starting of the engine is blocked (state: Not Ready)
- 2. Wait 100 ms
- 3. ECU Stop Pulse is set for 1000 ms (standard Stop Pulse duration)
- 4. Wait 3000 ms
- 5. Frequency selection is changed to a new value
- 6. Wait 2000 ms
- 7. ECU Stop Pulse is set for 1000 ms (standard Stop Pulse duration)
- 8. Wait 2000 ms
- 9. Come back from start blocking state

This sequence does not control LBO ECU POWER RELAY (PAGE 712) anyhow.

Note: If LBO **ECU POWER RELAY (PAGE 712)** is used, this change can be make only in prestart phase. So prestart has to be set up for enough long time.

5.3.36 Mains import measurement

This functionality is applicable on SPTM application. This function is for gen-sets which are not equipped by the mains import measurement. Then the soft transfer of the load in the direction Mains to Generator (**Transfer Mains To Gen Bus (page 351)**) can't be driven by the mains import measurement (mains unload level - **Mains Unload MCB Open Window (page 353)**), but the load transfer duration must be defines by some certain time interval (**Close Transfer Max Duration (page 350)**).

Note: For situations when mains current is not measured by Mains CT (Mains Import Measurement = None or Analog Input), PF is limited to Base Power Factor value even though PF Control PTM = PF Imp/Exp.

5.3.37 Load shedding

The Load shedding is controlled disconnection of less important load groups (circuits) when the object consumption is too high. There are two functions of the load shedding:

To avoid loss of power at the fundamental loads in island mode, when the object consumption is getting near to the maximum power of the gen-sets.

All Load shedding outputs are activated (closed) to trip the unessential load when gen-set goes to island:

- When GCB is closed after mains fail and gen-set starts in AUT mode.
- When MCB opens from parallel to mains operation in AUT mode.
- Before MCB is opened in MAN mode by button.



How the Load shedding controls the Load shedding outputs

The load shedding function is active in all controller modes except OFF.

Load shedding has three steps and each step is linked with its own binary output, LOAD SHEDDING STAGE 1 (PAGE 725), LOAD SHEDDING STAGE 2 (PAGE 725) and LOAD SHEDDING STAGE 3 (PAGE 725)

The Load shedding outputs can be activated one by one in the direction 1, 2, 3. The condition for activation are defined by setpoints Load Shedding Level (page 330) and Load Shedding Delay (page 330).

The Load shedding outputs are deactivated one by one according to the conditions given by the setpoints Load Reconnection Level (page 330), Load Reconnection Delay (page 331), Auto Load Reconnection (page 331).

For manual reconnection of the load is desired the **Auto Load Reconnection (page 331)** setpoint needs to be disabled and the **MANUAL LOAD RECONNECTION (PAGE 671)** digital input needs to be configured.







Image 5.64 Load reconnection





Image 5.65 Load manual reconnection

5.3.38 Peak shaving

Peak shaving is applicable on SPtM application only. The function compares the mains import with some certain limit and start the Gen-set when the load excised this limit to decrease the mains import for some certain time.

The Peak shaving function is active only in AUT mode in Parallel to Mains operation. Peak shaving is based on active power only. If load consumption increases over **Peak Shaving Start Level (page 240)** and for period longer than **Peak Shaving Start/Stop Delay (page 241)** the Gen-set is started. If load consumption decreases below **Peak Shaving Stop Level (page 240)** and period longer than **Peak Shaving Stop Level (page 240)** and period longer than **Peak Shaving Start/Stop Delay (page 240)** and period longer than **Peak Shaving Stop Level (page 240)** and period longer than **Peak Shaving Start/Stop Delay (page 240)** and period longer than **Peak Shaving Start/Stop Delay (page 241)** the Gen-set is stopped. The activation of the function is indicated by LBO:**PEAK SHAVING ACTIVE (PAGE 731)**.





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6.1 Graphical User Interface

6.1.1 GUI overview

Front panel

Front panel of the unit uses hardware buttons for configuring, moving, scrolling, commands and other functions.

Inteli Gen 500					ComAp
	MAN	[1/9] Home	Power Factor	0.95	
▲ •• •••			Gen Frequency Gen Voltage Fuel Level	50.4 Hz 248 V 59 %	
	0	kW 250	Oil Pressure Coolant Temp RPM	4.4 Bar 73 ℃ 1510 RPM	•
	奔 ~~	₩-\- 6	Running MainsOper No Timer	0 s	
	Open MCB	Close GCB			
STATUS					0

Image 6.1 : Front panel overview

Navigation buttons

Arrow buttons on the front panel are mainly used for navigation inside the entire graphical user interface. In addition the arrows left and right are used for changing the controller mode if the actual position is any metering screen.



Arrow left and right



Image 6.2 : Arrow left and right

The buttons are used for :

- Changing the controller mode (only on metering screens)
- Movement between history columns
- Movement in the dialogs

Arrow up and down



Image 6.3 : Arrow up and down

The buttons are used for :

- Cyclical movement between the metering Screens
- Movement in the dialogs
- Changing the value in the dialogs
- Movement in menus
- Listing on pages

Enter



Image 6.4 : Enter button

The button is used for :

- Confirming the values
- Confirming the selections
- Confirming the listing options

Menu



Image 6.5 : Menu button

The button is used for :



- Escape function
- Step back function
- Cyclical change of the page (from any metering screen)

Function buttons

Function buttons are dedicated for the performing of the concrete function. By pressing the button the controller action or controller command is performed (see bellow).



Image 6.6 : Function buttons (Start, Stop, Alarm/Horn reset, Horn reset)

- **Start** : starting of the Gen-set
- **Stop** : stoping of the Gen-set
- > Alarm/Horn reset : resets the horn and confirms all the alarms in the alarmlist
- Horn reset : resets only the horn

User buttons



Image 6.7 : User button

User button is dedicated for predefined user function.

- Performing the controller command
- Jump to the specific page or metering screen
- special function on the pages

Special and button combination

In this manual the shortcut is a term for the combination of the buttons or long press of the button.



Image 6.8 : Shortcut (jump to the administration)

- **Enter + Menu** : performs the jump to the administration. Enter button has to be pressed first.
- Long press of the arrow up or down button
 - in the menus : performs the cyclical listing
 - in the dialog : velocity of the changing value is increased based on special algorithm



Status LED

There is one multicolor (RGB) LED on the front panel of the unit. The specified color and flashing function describes the actual state of the unit.



Image 6.9 : Status LED

- LED intensity is directly connected with the actual setting of the backlight intensity in Administration menu "Settings" accessible by shortcut Enter + Menu
 - the intensity respects the value of the Manual or External brigness control
- > The flashing of the status LED and indicative Alarm icon in the top statusbar have the same period
- Meaning of the status LED colors is described below

Color and flashing function meaning :

- Red is flashing
 - Active unconfirmed level2 (shutdown) alarm
 - Inactive unconfirmed level2 (shutdown) alarm
 - Lost of internal communication line
 - Controller unit in init state
- Red lights
 - Active confirmed level2 (shutdown) alarm
 - Integrated color display unit in init state
 - Integrated color display unit booting procedure
- Cyan lights
 - temperature inside the housing exceeded the 85°C (185°F)
- Yellow lights
 - Active unconfirmed level1 (warning) alarm
 - Inactive unconfirmed level1 (warning) alarm
 - Active confirmed level1 (warning) alarm
 - Active unconfirmed fail sensor alarm
 - Inactive unconfirmed fail sensor alarm
 - Active confirmed fail sensor alarm
- Green lights
 - unit is running correctly without any errors or alarms

Color state priority :

- 1. Red is flashing
- 2. Red lights
- 3. Cyan lights



- 4. Yellow lights
- 5. Green lights

Pages

There are several screens called pages in the graphical user interface (GUI), which are accessible by pressing the Menu button or concrete user button in the bottom status bar. Each page has a different function and different structure. Pages are described in special chapters in this manual.

The actual GUI consists of 6 different pages :

- Metering screen
- Alarmlist
- Setpoints
- History
- Trends
- Administration
 - Page administration is accessible only by pressing the combination of the Enter and Menu buttons from the only Metering screen.

Screens

Each type of controller has special set of screens stored in the controller configuration. The description of the each metering screens is by default predefined by ComAp. Scrolling between the screens is performed using the arrow up and down buttons.

Special screens

There are 2 special screens stored in the unit :

- Init screen
 - displayed during the booting procedure and in Administration menu
 - dedicated for specific user logo (by default predefined by ComAp)
- Service screen
 - displayed in Administration menu
 - dedicated for useful technical information (by default predefined by ComAp)

Note: More information about Init and Service screen modification is described in concrete chapter of this manual.

Dialogs

Values and parameters and other can be set in the controller via dialogs. There are several dialogs in the GUI. Dialogs for numbers, texts and lists.

Dialog Value

The dialog value is dedicated for number setting. When the dialog is active the buttons arrow up and down are used for number selection. Enter button confirms the option. Menu button cancels the dialog without saving.

Setpoints >> Process Control						
Ap Loa PF	Baseload			kW		
Ba				100		
Ba	Value Range:		0	200		
Im	Original:			100		
Im	Default:			100		
СВ						
Ma						
Pe						
Ope	n MCB Open GCB	A	Ū	A		

Image 6.10 : Dialog Value overview

Dialog Value Extended

The dialog value extended is dedicated for number setting with combination with one or more string value. When the dialog is active the buttons arrow up and down are used for number/item selection. Enter button confirms the option. Menu button cancels the dialog without saving.

No Ge	Backlight Timeout	min	
No		Disabled	
Ge No Co Po	Value Range:	Disabled; 1 255	
	Original:	Disabled	
	Default:	Disabled	
a			
lo Ph			
pe	n MCB Close GCB		

Image 6.11 : Dialog Value Extended overview

Dialog String List

The dialog string list is dedicated for list item selection. When the dialog is active the buttons arrow up and down are used for item selection. Enter button confirms the option. Menu button cancels the dialog without saving.

Setp	etpoints >> Process Control						
Ap Loa	PF Co	ntrol PTM					
PF			Base PF				
Ba	PF Imp/Exp						
Im							
Im							
СВ	_						
Реа							
Ope	n MCB	Open GCB	A	Ū	A		

Image 6.12 : Dialog String List overview

Dialog Text

The dialog text is dedicated for text inserting or modification. When the dialog is active the buttons arrow up and down are used for letter selection. Arrows left and right are used for moving between the letters in the text. Letter DEL deletes actual selected letter (using move to left or right). Insert letter inserts the letter to the actual position (using move to left or right) Enter button confirms the text modification. Menu button cancels the dialog without saving.



Image 6.13 : Dialog Text overview

Note: Enter button is used for dialog confirmation and saving the entire text to the configuration and because of this the DEL and INS letter is inserted using the left or right arrow button.

Dialog IP address

The dialog IP address is dedicated for IP address insertion. When the dialog is active the buttons arrow up and down are used for number selection. Arrows left and right are used for moving between the IP cells. Enter button confirms the option. Menu button cancels the dialog without saving.



Setpoints >> E	Ethernet					
IP Address M	IP Address Mode Manual					
IP Address		1	92.168.1.254			
Subnet Mask	(2	55.255.255.0			
Ga DN IP Add DN IP Air	lress	192 . 168.001.254				
Air AirGate Data Port 23						
AirGate Signa	alling Port	6127				
Event Messa	ge		Enabled			
Open MCB	Open GCB	A	U	A		

Image 6.14 : Dialog IP address overview

Dialog Message

The dialog message has informal character about the result of any action. Enter or Menu button cancels the dialog without saving. There is no need to confirm the selection.



Image 6.15 : Dialog Message overview

Dialog Progress

The dialog progress has informal character about the result of any action. The progress bar and percents are also displayed during the action performing. Enter or Menu button cancels the dialog without saving. There is no need to confirm the selection.



Ехро	ort/Impo	ort			
Im Ex		Ex	port Archi	ve	
Ope	n MCB	Close GCB	A	3	A

Image 6.16 : Dialog Progress overview

Dialog Date

The dialog date is dedicated for date setting. When the dialog is active the buttons arrow up and down are used for number selection. Arrows left and right are used for moving between the date cells. Enter button confirms the option. Menu button cancels the dialog without saving.

Setpoints >> Scheduler						
Time			16:36:45			
Date			31/03/2000			
Time Stamp	Period		60 I	min		
Tin Date			DD.MM.YY			
Rei Rei			31.03	3.00		
Rental Timer 2 Wrn 01/01/2015						
Rental Time	er BOC		24	h		
Open MCB	Close GCB	A	Ū	A		

Image 6.17 : Dialog Date overview

Dialog Time

The dialog time is dedicated for date setting. When the dialog is active the buttons arrow up and down are used for number selection. Arrows left and right are used for moving between the time cells. Enter button confirms the option. Menu button cancels the dialog without saving. Menu button cancels the dialog without saving.



Setpoints >> Scheduler				
Time	16:36:26			
Date	31/03/2000			
Time Stamp Period	60 min			
Tin Tin Tin	HH:MM:SS			
Rei	16:36:26			
Rental Timer 2 Wrn	01/01/2015			
Rental Timer BOC	24 n			
Open MCB Close GCB	A 3 A			

Image 6.18 : Dialog Time overview

Dialog Password

The dialog password is dedicated for password insertion. When the dialog is active the buttons arrow up and down are used for number selection. Enter button confirms the option. Menu button cancels the dialog without saving.

Access Rights 0 1 2 3	Setpoints >>	Password			DI 🔺 💄	
Pas Enter Password Ch Ch Change Password 3	Access Rights 0 1 2					
Change Password 3	Pas En Ch Ch	r Password	k	0	008	
	Change Pa	ssword 3	•	5		

Image 6.19 : Dialog Password overview

Dialog Password Change

The dialog password change is dedicated for password change. When the dialog is active the buttons arrow up and down are used for number selection. Enter button confirms the first option and the same password must be inserted again. Enter button after insertion the second cell performs the password change (in case the password are same). Menu button cancels the dialog without saving.



Setpo	oints >> Pa	ssword			C# 💄
Acc	Change	e Passwo	rd 1		3
Das	New Pas	sword			
Pas	h			0	000
En	Confirm	New Passwo	ord		
Ch	~			#	###
Ch	3) <u>I</u>				46
Oper	n MCB	Logout	A	0	A

Image 6.20 : Dialog Password Change overview

Dialog Timer

The dialog timer is dedicated for timer setting. When the dialog is active the buttons arrow left and right are used for the line option selection. Enter button confirms the actual option in the line and the next option can be performed. Enter button on the last line confirms all the option in dialog and save the timer settings to the controller. Menu button cancels the dialog without saving.

Setpoints >> Scheduler							
Tin Da Tin #Si Tin Tin Tin Re Re Re Re Re	Once	🔿 Repeato	ed				
Open MCB	Close GCB	A	U	A			

Image 6.21 : Dialog Timer (Off) overview

Setpoints >> Scheduler	0
Tin Da Tin #Si Off Once Repeated	i
Tin Tin First Occur. [DD/MM/YYYY]	00.00.00
Tin Rei Time [HH:MM:SS]	00:00:00
Re Duration [HH:MM]	00:00
Rei	
Open MCB Close GCB	3

Image 6.22 : Dialog Timer (Once) overview

Note: The user must be logged in with respective rights to be able to change password for respective rights.





Image 6.23 : Dialog Timer (Repeated) overview

Status bars

Bottom status bar

The bottom status bar is used for the user button functions. There are several status bars in the GUI. Bottom status bar consists of 5 areas (user buttons) dedicated for emitting the command to the controller unit (e.g. GCB open, GCB close, etc.), jump to the specified page (e.g. alarmlist, history) or special functions on some pages.

$\pi \bullet \bullet$	- → →	No Ti	mer	0 s
Open MCB	Close GCB	A	Ū	A
1	2	3	4	5

Image 6.24 : Example (bottom status bar on Home metering screen)

- 1. User button 1 emitting the command to the controller or link to page in GUI or special function
- 2. User button 2 emitting the command to the controller or link to page in GUI or special function
- 3. User button 3 emitting the command to the controller or link to page in GUI or special function
- 4. User button 4 emitting the command to the controller or link to page in GUI or special function
- 5. User button 5 emitting the command to the controller or link to page in GUI or special function

Note: The button press is visually indicated by black frame around the button area. The indication does not mean that requested command is performed, it is only press indication.

Note: Concrete status bar views for concrete page are described in specific chapters in this manual.

Top status bar

The top status bar can NOT be adjusted. Information in the top status bar is fixed and controlled by ComAp.



Image 6.25 Top Status Bar description



MAN	[1/9] Home	[1/9] Home				
OFF	MAN	N A	UTO	TEST		
0	kW 25	Gen N Gen N Fuel I Oil Pr 50 Coola RPM	requency /oltage Level ressure ant Temp	0.0 HZ 0 V 59 % 4.4 Bar 73 °C 0 RPM		
キー	₩ ->-	G Read Main Stop	y sOper Valve	43 s		
Open MCB	Close GCB	A	U	A		

Image 6.26 : Top Status Bar - Mode selector dialog

- Mode selector Mode selector is dedicated for the controller mode selection. Using arrow left and right the controller mode is changed (only on the metering screens). The choice must be always confirmed by enter button. There is 5s timer for the automatic mode selector dialog cancellation. The mode selector dialog can be also canceled by menu button.
- 2. **Page title** Each page and each metering screen has its own title. The first number in square brackets describes the actual metering screen position. The second number describes the total available number of metering screens.
- 3. Trending The icon is active when the trending is running. Icon is inactive when the trending is stopped.
- 4. **USB Stick** The icon is active if the USB stick is plugged in the display unit. Icon is inactive if there is no USB stick plugged in.
- 5. Access Lock Access lock icon is active if the display is locked for security reasons. Icon is inactive if the controller unit is not locked.
- 6. **PC connection** PC connection icon is active if the unit established connection to the PC using the USB cable. Icon is inactive if there is not established connection to the PC.
- 7. Alarm indication The alarm icon is flashing red if there is at least one unconfirmed alarm (shutdown or warning) in the alarmlist. The icon lights red if there is at least one confirmed active alarm and no unconfirmed alarm in the alarmlist. The icon is inactive if the alarmlist is empty.
- 8. **User** The user icon lights green if the user is logged in to the controller. The icon is inactive if the user is logged out.

6.1.2 Metering screens

Metering screens are dedicated for important controller values and setpoints.

InteliGen 500 controller screens

InteliGen 500 metering screens are predefined by Comap and covers all the application types.

- the movement between the metering screens is done using the arrow up and down buttons in the front panel
- the entire screens and instruments on the screens are dynamically displayed or hidden based on the following state of the controller unit :

- Application type
- Wiring controller settings
- Connected PlugIn modules
- Configured CAN modules
- Aftertreatment ECU list settings
- ▶ The following structure is predefined in the InteliGen 500 controller archive by default :
- 1. Home
- 2. Power
- 3. Generator
- 4. Mains
- 5. Bus
- 6. Synchro
- 7. Power Management
- 8. Analog inputs
- 9. Binary Inputs | Outputs
- 10. Statistics
- 11. Ethernet
- 12. Aftertreatment
- 13. CM-4G-GPS
- 14. CM-GPRS
- 15. EM-BIO8-EFCP-A
- 16. EM-BIO8-EFCP-B
- 17. CAN modules
- 18. ECU modules
- 19. Virtual modules

Note: Some of the screens are added automatically If external modules, ECU modules and others are added using InteliConfig software. The screens are automatically removed if the respective module is removed from the configuration.

MAN	[1/9] Home		DB	MAN	[2/9] Power		DB	MAN	[3/9] Generator		0
Ger	kW 250	Power Factor Gen Frequency Gen Voltage Fuel Level Oil Pressure Coolant Temp	0.85 50.4 Hz 248 V 59 % 4.4 Bar 73 °C	LOAD Load kW Load PF MAINS	● kW 0.00	GENSET Generator kW 25 Power Factor	G 77 kW 0.85 C	Gen V Ph-N	248 0	Gen V Ph-Ph	v 0 0 0
	77	RPM	1510 RPM	Mains Impo Mains PF	ort kW 0 kW 0.00	0.84 C Generator kVAr -16	-48 kVAr	Gen I	A 125	Gen Frequency	Hz
#-	₩-\- G	Running MainsOper No Timer	0 s	养 ~~	₩-\- (6)	Generator kVA 31	93 kVA		0	THD % L1 Voltage 27.1 Current ####	
Open MCB	Close GCB	A (3)	A	Open MCB	Close GCB	0	A	Open MCB	Close GCB	A (3)	A





Image 6.27 : InteliGen 500 metering screens overview

6.1.3 Alarmlist

The alarmlist page is intended for displaying the controller alarms. If any of the following type of the controller alarm occurs The alarmlist page is displayed and also the alarm button in the Top status bar starts flashing RED, even if it is not the shutdown alarm. The Automatic jump to the Alarmlist page is performed only in case the actual GUI position is the Home metering screen. The alarm icon in the top status bar is informative icon where the display unit informs the user that there is any alarm stored in the controller unit. Pressing the User button 3 opens the alarmlist page. The alarmlist page is displayed until the alarmlist contains at least one unconfirmed alarm.

There are 4 different types of controller alarms :

- Warning (often also known as 1st level alarm) represented by the YELLOW colour. These types of alarms inform the user that something is wrong and need to be checked and confirmed.
- Shutdown (often also known as 2nd level alarm) represented by the RED colour. These types of alarms protects the GenSet or Engine during the wrong state.
- ECU alarm represented by the BLUE colour. This type of alarm comes from the connected external ECU units.
- Sensor fail alarm represented by the WHITE colour. A special kind of alarm that appears if any connected sensor emits the wrong state.



	Alarmlist 1/				
	01 * Sd G	CB Fail			
1	02 * Wrn	Override All Sd			
2					
3					
4					
	Open MCB	Open GCB	(?)	0	A

Image 6.28 : Alarmlist Page

- 1. Alarm item number displays the number of the concrete alarm.
- 2. Alarm item star describes if the alarm is CONFIRMED or NOT COFIRMED. The confirmation action is performed by the Alarm reset button in the front panel
 - a. Star is displayed alarm is NOT CONFIRMED
 - b. Star is not displayed alarm is CONFIRMED (using alarm reset button)
- 3. Alarm description The short description of the alarm
- 4. Alarm coloring There are specified the color and asterix combination
 - level 1 (warning) alarm
 - Active/unconfirmed : * / yellow background / dark text (asterix active)
 - Active/confirmed : yellow background / dark text (asterix inactive)
 - Inactive/unconfirmed : * / dark background / yellow text / asterix active
 - level 2 (shutdown) alarm
 - Active/unconfirmed : * / red background / white text (asterix active)
 - Active/confirmed : red background / white text (asterix inactive)
 - Inactive/unconfirmed : * / dark background / red text (asterix active)
 - sensor fail alarm
 - Active/unconfirmed : * / white background / dark text (asterix active)
 - Active/confirmed : white background / dark text (asterix inactive)
 - Inactive/unconfirmed : * / dark background / white text (asterix active)
 - ECU alarm
 - Active/unconfirmed : * / blue background / white text (asterix active)
 - Active/confirmed : blue background / white text (asterix inactive)
 - Inactive/unconfirmed : * / dark background / blue text (asterix active)
- 5. **Topstatus bar Alarmlist icon** The alarm icon is fashing red if there is at least one unconfirmed alarm (shutdown or warning) in the alarmlist. The icon lights red if there is at least one confirmed active alarm and no unconfirmed alarm in the alarmlist. The icon is inactive if the alarmlist is empty. This is information that something is wrong and need to be checked and resolved.



Note: The Alarmlist displays maximum 8 alarm items at the same time. If there is more than 8 alarms in the alarmlist it is possible to list in the page to another alarm items by arrow up and down buttons.

Note: The alarmlist page is automatically displayed and backlight is turned on if the new alarm appears (only in case the actual GUI position is the Home metering screen).

IMPORTANT: InteliGen 500 controller displays maximum 16 alarms.

IMPORTANT: Alarm reset button confirms all the unconfirmed alarms stored in controller.

IMPORTANT: If the actual GUI position is Alarmlist page and there is at least one uncofirmed alarm in the Alarmlist the jump to the home metering screen and backlight timeout are ignored.

6.1.4 Setpoints

The setpoint page is intended for setting the controller values. Each type of controller has specific setpoints to be set. The setpoints also depend on the type of application like SPtM and MINT. Availability of the setpoint item also depends on configuration level settings in Administration page. Setpoint is set in 2 steps.

▶ 1st step - Setpoint group is selected using buttons arrow up and down and confirmed using enter button



Image 6.29 : Setpoints Page overview

- 1. **Setpoints group** the column setpoint group displays the available groups based on the controller, application type and configuration level settings. Respective setpoint group is selected using enter button.
- Available setpoints in actually selected group each setpoint group contains specific setpoints. The informative column Setpoint name displays the available set of setpoints to be set in each Setpoint group. This column is only informative and can NOT be set using the arrow left and right. The setpoint setting is done using the 2nd step - see below.
- 2nd step Setpoint item is selected using the buttons arrow up and down and the dialog for value setting is called using the enter button. The dialogs are described in the chapter Dialogs.



Setpoints >> Process Control						
Application Mode Select Load Control PTM PF Control PTM	SPTM Baseload Base PF					
Baseload	100 kW					
Base Power Factor Import Load Import PF Import/Export Limitation CB Control In MAN Mode Mains Import Measurement Peak Shaving	1.00 0 kW 1.00 Disabled Full Ctrl None Disabled					
Open MCB Open GCB						

Image 6.30 : Group Setpoints Page

- 1. **Setpoint name** Setpoint is set using the enter button. Specific dialog is displayed and the value can be set. There are several types of dialogs (text, numeric, stringlist) and the type of called dialog depends on the setpoint type. The dialogs are described in the chapter Dialogs.
- 2. Actual value Informative actual value for specific setpoint is displayed. Value range, original value and default value for the selected setpoint are displayed inside the dialog.



Password screen

The group Password is not setpoint group. This Password item is manually placed to the first group position on the program code level just for this controller unit.



Image 6.31 : Main Setpoints Page

1. **Password item -** the item dedicated for the password settings, login and logout.



Image 6.32 : Setpoints Password Page

- 1. Logged Access Level Info the information about actually logged in access rights.
 - a. 0 user has access rights 0, which means logged-out
 - b. 0,1 user has access rights 0 + 1 access rights
 - c. 0,1,2 user has access rights 0 + 1 + 2 access rights
 - d. 0,1,2,3 user has access rights 0 + 1 + 2 + 3, which means administrator rights
- 2. **Password Actions -** the list of available password actions.
 - a. Enter Password calls the dialog for password insert
 - b. Change Password calls the dialog for password change of respective access rights
- 3. Logout Button is active in case of any user is logged in. The button is inactive if any user is logged out this is indicated by green light of 0 access level.



6.1.5 History

The history page displays the records of the important moments in the controller history.

There are 2 types of history records :

- Event records are also known as standard history records. This type of record appears in case the controller event has been made. The time stamp history also belongs in the event history. The time record is stored for a specified period of time.
- System records are also known as text history record. These type of records are generated during the user login/off, controller programming or other system actions.

Histor	y 1							
No.	Reason	Date	Time	RPN				
0.	Sd GCB Fail	25/02/2000	00:33:23		3			
-1.	SetpointChange	25/02/2000	00:30:44	T=USB (
-2.	Ready	25/02/2000	00:27:23					
-3.	Wrn Override All Sd	25/02/2000	00:27:21		2			
-4.	Gen-set Stop	25/02/2000	00:27:19					
-5.	Loaded	25/02/2000	00:27:18					
-6.	Soft Load	25/02/2000	00:27:12					
-7.	Sd GCB Fail	25/02/2000	00:27:12					
1st Row/Col 1x A 🛞 🔺								
4								

Image 6.33 : History page overview

- 1. **Fixed column** has a different shade of colour. Fixed column is always merged and anchored on the left side of the history page.
- 2. **Event history record** this type of record appears in case the controller event has been made. The time stamp history also belongs in the event history. The time record is stored for a specified period of time. Pressing the enter button the dialog with detailed information for selected record is displayed.
- 3. **System history record** this type of record appears in case the controller system action has been made. The time stamp history also belongs in the event history. The time record is stored for a specified period of time. Pressing the enter button the dialog with detailed information for selected record is displayed.
- 4. **Jump to first row and column** the jump to the first row and first column is performed if the button is pressed.
- 5. Listing mode by pressing this button the listing mode is changed. There are available 3 modes : listing by 1 item, listing by 1 page, listing by 10 page. The mode is useful if the history is full of records. Listing mode is also automatically changed if the listing buttons arrow up and down are pressed for longer time. Original mode is set when the listing buttons are released.

Hist	ory			
Nc	Fls Fuel Level		RPN	
-	Date	12/03/2000		
	Time	02:15:51	ID (
-	RPM	0	BU	
	Generator kW	0	DC	
	Generator kVAr	0		
	Generator Power Factor	0.00		
	Generator Load Character			
-	Generator Frequency 0.0			
	Generator Voltage L1-N	0		
1st F	ow/Col 1x 🔺	(?)	ł	

Image 6.34 : History page - Item detail dialog

Note: Pressing the enter button on the actually selected row the dialog with detailed information for selected record is displayed.

IMPORTANT: Each controller unit supports the specific number of history records. E.g. controller InteliGen 500 supports 500 history records. Default configuration consists of 33 columns. Maximal column amount is approximately 100 columns based on the type of the observed value.

6.1.6 Administration

back to Graphical User Interface

Init screen

The init screen is the special screen (bitmap) defined and stored in the controller. The init screen is displayed during the booting procedure. The init screen is also accessible from administration as a first list item. The purpose of the init screen is to allow the user to create and show his own initial logo screen during the booting procedure. The init screen logo can be uploaded using the InteliConfig. By default the init screen is predefined by ComAp.



Image 6.35 : Init screen overview



Controller Info

Controller info page is dedicated for important information about the entire unit. These information is useful mainly for issue troubleshooting.

Controller info page is divided into 3 main blocks of information :

- Integrated Color Display unit
- Controller unit
- Configuration

ControllerIn	fo			-√ □∎		
Name		Value	Value			
ICD HW vers	ion	1.0.0.9	000			
ICD SW versi	on	1.0.0.9	1.0.0.900			
ICD bootload	ler version	0.0.0.0	0.0.0.0			
ID String		Inteli	InteliGen-500-1.0.0.20			
Software ver	rsion	1.0.0.2	1.0.0.20			
Serial numbe	er	FF1103	FF110339			
Controller ty	pe (HW)	21	21			
Application t	type (HW)	2	2			
Open MCB	Close GCB	A	Ū	A		

Image 6.36 : Administration Page - Controller Info

Note: Similar values with similar structure can be displayed using InteliConfig PC tool.



Modules Info

Modules info page is dedicated for important information about the connected modules information. The page Modules Info displays the information from the following type of connected modules :

- Plug-In modules
- CAN peripheral extension modules

Modules Info				-∿ ⊡∎
Module name	3	HW ver.	SW ver.	Address
			1	
Open MCB	Close GCB	A	U	

Image 6.37 : Administration Page - Modules Info

Note: The availability of the connected module depends on the type of controller unit.

Settings

Settings $ vert$		3	
Backlight Timeout [min]		Disabled	1
Brightness control		Manual	2
Brightness intensity [%]		60	3
	8⁼:	25.5°C	4
Open MCB Close GCB	\odot	A	

Image 6.38 : Administration Page - Settings

1. **Backlight Time** - if the cell area is pressed the dialog for time settings is displayed. The user is able to set the period from 1 up to 241 minutes. There is also the option to set NO Timeout which means the display unit is backlighted forever.

2. Brightness Control :

- a. Manual (by default) the value of the backlight is set manually using the value dialog (point 3)
- b. External the value of the backlight is given by the Analog Input settings in InteliConfig and connected value of resistor, voltage or current (based on the type of the selected sensor).


- 3. **Brightness intensity** the value is selected using the value dialog. Note the value is applied immediately during the change of the value.
- 4. Internal Temperature information- gives the actual inside temperature of the unit. There is implemented automatic mechanism for lowering the backlight intensity based the internal derating backlight curve. If the inside temperature exceeds 35 °C the area behind the temperature lights yellow. The yellow color indicates that the display backlight curve is applied and automatically starts derate the backlight intensity. The backlight intensity returns to normal when the temperature is decreased bellow 35 °C. This feature saves the lifetime of the internal components.

IMPORTANT: It is strongly recommended to use backlight on the standard level max. 60%. Maximal backlight intensity level of 100% is suitable only for application with higher amount of the ambient light. Be aware that higher intensity level means higher surface front glass temperature and lower lifetime.

IMPORTANT: It is strongly recommended to use Backlight Time (timer) set on the reasonable amount of time (approximately 30 minutes) during the normal running genset or engine phase. It is because of saving lifetime of the display unit. The display unit is still running if the backlight is off. For switching on the LCD backlight the simple pressing any button is necessary.

Languages



Image 6.39 : Administration Page - Languages

- Language settings the list of languages stored in the controller configuration is displayed in the list of possible languages.
- The integrated color display unit can display the following languages
 - English
 - Chinese
- The integrated color display unit can partially display the following languages
 - Bulgarian, Taiwan, Czech, German, Greek, Spanish, Finnish, French, Hungarian, Icelandic, Italian, Japanese, Korean, Dutch - Netherlands, Norwegian, Polish, Roman, Russian, Croatian, Slovak, Swedish, Turkish, Ukrainian, Slovenian, Estonian, Latvian, Lithunian, Vietnamese, Italian, Portuguese, Bosnian



IMPORTANT: Even the language is configured in InteliConfig the specific language is unavailable if the language is available in configuration (but empty) or the language is not supported by integrated color display unit.

Note: The flag is not displayed if the language is supported but the flag icon does not exist in the integrated color display unit.

Confiuration level

Configuratio	n Level			-∿ ⊡∎
Standard				
Advanced				
				1
Open MCB	Close GCB	A	Ū	A

Image 6.40 : Administration Page - Configuration Level

- Standard Limited amount of settings are available for configuration. The description which settings are available in chapters concerning to controller functions.
- Advanced Set by factory default. All the settings are available for configuration. Be aware that only experiences users should perform the settings of extended functions.

Note: By default the Advanced settings is selected which means all the setpoints are available by default. To restrict the availability the Standard setting must be performed. The advanced and standard category are set in InteliConfig PC application.



Export / Import

Export/Import		-∿ ⊡∎
Import Package		
Export Archive		
Open MCB Close GCB	3	A

Image 6.41 : Administration Page - Export & Import

- Import Package is dedicated for integrated color display unit firmware updated, controller firmware update, controller archive update. Extension modules firmware update is not supported.
 - If the USB stick is not connected the import function is not available and visually indicated as a greyed text.
 - File packages used for firmware import can be prepared only in InteliConfig PC application **only**.
 - The files (*.pcg3) prepared in InteliConfig (for import) must be stored in the root of USB stick folder the only root folder is supported for import.
 - Import function is always protected by Administrator (level 3 access rights) password. Until the correct password is not inserted the import function is unavailable. Be aware that there is implemented algorithm to have password protected against the brute force attempts.

Expo	ort/Impo	ort			CI8					
Import Package										
Exp	ort Arch	ive								
	Ente	r Password	1							
				(0000					
Ope	n MCB	Close GCB	A	0	A					

- The message dialog (Controller unit is not ready) is displayed if the controller is not in state ready for programming (e.g. genset running)
- **Export Archive** is dedicated for the entire archive export.
 - If the USB stick is not connected the export function is not available and visually indicated as a greyed text.
 - The archive files (*.aig3) is exported to the fixed directory in the USB stick (root:/IG500/Archive. The directory structure is automatically created if does not exist.



- Export function is not protected by password.
- The message dialog (Controller unit is not ready) is displayed if the controller is not in state ready for archive export (e.g. genset running)
- Waiting dialog is displayed during the export process.
- The message dialog is displayed after archive proccess.
 - Archive Export Successful if successfully exported.
 - Archive Export Failed if any error occurs during the export proccess.
- Integrated color display unit is restarted after export proccess.

Note: Once the USB stick is inserted to the display unit the directory and its subdirecotries are created automatically if does not exist.

IMPORTANT: Requested files to be imported must be saved in the root directory on a USB Stick.

Imported File selection

Import Pack	age			0: 💄
ICD-1.0.0.17	/.pcg3			
Open MCB	Close GCB	A	Ū	A

Image 6.42 : Administration Page - Export & Import - File selection

- File selection is available if the conditions above (in section Import Package) is fulfilled
 - Only files with pcg3 extension is displayed.
 - Maximum 100 files (*.pcg3) in root is displayed.
 - The message dialog (Package Incompatible) is displayed if the incompatible pcg3 file is used
 - The message dialog (Invalid File) is displayed if the pcg3 file is invalid or corrupted



Import proccess

Import Package		08 💄
Name	Actual	Package
HMI Logo	N/A	N/A
HMI Fonts	1.0.0.0	1.0.0.0
HMI Images	1.0.0.5	1.0.0.5
HMI Firmware	1.0.0.900	1.0.0.17 🔥
HMI Service screen	N/A	N/A
A	Ü	A

Image 6.43 : Administration Page - Export & Import - Import process

- Import process is available if the correct and compatible file is selected conditions above (in section Import Package) is fulfilled
 - The import process is not allowed if at least one file in the package is not compatible with each other the Import button is not displayed.
 - When the Import process is started it is not possible to interrupt it.
 - Bar Message is displayed
 - Package Import Successful (green colored) if success
 - Package Import Failed (red colored) if any error during the process
 - the user is informed about the actual item progress
 - Main and the file has been imported correctly
 - • - the file import is under progress
 - A the file is incompatible
 - The device is rebooted after import process.

IMPORTANT: Integrated color display unit firmware is updated in two steps. Firstly the firmware is uploaded to the internal memory (indicated by icon \checkmark). The second step is the firmware update from internal memory. The firmware is updated immediately after reboot using bootloader (Indicated by progress bars and messages in limited GUI). After all the unit is automatically started with new firmware.

IMPORTANT: Only in some special cases the import process using USB stick must be performed twice. This situation is always described in New Feature List with more detailed information.

IMPORTANT: Only FAT16 and FAT32 file system on USB stick are supported.

Note: If the USB stick is plugged in the Import/Export page is automatically displayed.

Note: If the import process fails try the import process again.



Service screen

The service screen is the special screen (bitmap) defined and stored in the controller. The service screen is also accessible from administration as a last list item. The purpose of the service screen is to allow the site administrator to put into the display (resp. controller) important data for technical support. The status screen can be uploaded using the InteliConfig. By default the service screen is predefined by ComAp.



Image 6.44 : Service screen overview



6.1.7 Trends



Image 6.45 : Trends page overview

The Trends page is divided on to 3 main blocks :

- Main Trends Window is intended to display all trends. The view and chart movement is fully automatic.
- **Channel panel** displays the actual values and sample period.
- **Function buttons** is intended for start, stop and settings of the trends.



Image 6.46 : Trends page description

- 1. X axis -X axis displays the time stamps. The view of X axis is fully automatic.
- 2. **Y axis** If the default range is not suitable for the displaying of the value it can be adjusted in settings option. See bellow for more information.
- 3. Grid the grid is displayed behind the trends charts. The grid is fully automatic.
- 4. **Trend line** each channel have different colour for better value identification. The color of the trend line match to the Value color in channel panel.
- 5. Actual period Actual period settings. The period can be adjusted in settings option.
- 6. Actual channel value panels display the values of the newest (actual) sample.



- 7. Trend Icon (Top Status bar) if the trends are running the informative icon is shown in the top status bar
- 8. **Start / Stop button** the button is dedicated for manual start and stop of the trends. It is possible to setup the automatic start of trending based on the trigger. There are 2 trigers : Return to Home metering screen and the specified bit of the available binary value.
- 9. Channel settings button There are some settings available for the trends. See more information bellow.



Trends settings

Trends settings page is dedicated for the available trends settings. The navigation in trends settings page is done by buttons arrow up, arrow down, arrow left, arrow right, enter, user button 1 and 2.



Image 6.47 : Trends page settings overview

- 1. **Channel value** the channel value menu appears if the enter button is pressed just on the position. Inside the channel value menu the the requested channel value can be selected. The value availability depends on the type of configuration stored in the controller.
- 2. Low limit value the low limit value is intended for changing the low border of the value range. For the best view of the displayed trends it is highly recommended to set this limit to the minimum expected value with some reserve.
- 3. **High limit value** the high limit value is intended for changing the low border of the value range. For the best view of the displayed trends it is highly recommneded to set this limit to the maximum expected value with some reserve.
- 4. Quick channel removal pressing the enter button on the trash bin icon the actual channel is not configured.
- 5. Period section is dedicated for setting of the sample time period.
- 6. Run the section is intended for the selection of the run mode
 - a. once trending only until the trend chart window is full
 - b. circular cyclic mode (trending is repeated continuously) be aware the samples are stored only in internal temporar memory, the trend chart starts moving when the trend chart window is full, the oldest samples are trashed out
- 7. Start option The start of trends are triggered by the start option. There are 3 start options.
 - a. Binary state the trigger is the bit of the selected binary value. Manual start and stop is still active.
 - b. Manual (by default) the triger is the start button called by user.
 - c. Home the trigger is the return to the Home metering screen from any GUI position. Manual start and stop is still active.
- 8. Bit of binary value selection If the start option is set to Binary state then the field for the bit of the concrete binary value is activated.
- 9. Acknowlegment button Pressing the user button 1 (Confirm) the settings are saved.
- 10. **Cancel button** Pressing the user button 2 (Cancel) the settings are canceled and the main trends page is displayed without any change of the trends configuration.



Note: To get the best view of the displayed trends it is recommended to manually set the typical value range for each channel.

IMPORTANT: If the trending is started and the changes have been made in the settings the trending is restarted based on the new settings.

IMPORTANT: Be aware the samples are stored only in internal temporar memory. Trend chart starts moving when the trend chart window is full, the oldest samples are trashed out.

IMPORTANT: There is no option to store the trends to the external memories like USB stick, etc.

6.2 Quick help

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6.2.1 Logging in/off to the Controller

The user is able to log in/off to/from the controller via the menu Passwords in Setpoint page.

Setpoints				Setpoints >>	Password					□ 🔺
Password Process Control Pasic Settings	Password e Password 1 e Password 2		Access Right	ts		0	1	2	3	
Communication Settings Ethernet	Change	e Password 3		Password A						
Engine Settings	Engine Settings					Enter Password				
Generator Settings Protections Mains Settings Load Shedding				Change Pas Change Pas Change Pas	ssword 1 ssword 2 ssword 3					
Speed/Load Control Voltage/PF Control		5		Open MCB	Logout	٨	5			

Image 6.48 : Password menu

- 1. Current Access Rights are shown on the top of the page.
- 2. Press the button on item Enter Password, the Password dialog will appear.
- 3. Insert the correct password. If the password is not correct, the user is informed about it. Be aware there is a brute force algorithm protection implemented.
- 4. The icon (user) in the top status bar turns green when the user is logged in.

Setpoints >>	Password			DI 🔺 💄				
Access Rights 0 1 2								
Pas En Ch Ch	r Passwor	d	C	0008				
Change Pa	ssword 3							
Open MCB	Logout	A	Ö	A				

Image 6.49 : Password dialog



Note: Each Access Rights password can be changed by inserting old password and new password.

IMPORTANT: If the setpoint is protected by password the password dialog appears when the attempt to password change is performed.

IMPORTANT: Be aware there is a brute force algorithm protection implemented. If the brute force protection is active then the user is informed by Invalid Password message even the password is inserted correctly.

6.2.2 Important values

The important controllers values and system buttons are displayed by default and accessible from the Home, Power and Synchro metering screens. The breaker status, controller status and system timer are also displayed on the Home metering screen.

101/11	[1/9] Home		DB	MAN	[2/9] Power		OB	MAN	[5/9] Synchrosco	pe	08
Ger	kW 250	Power Factor Gen Frequency Gen Voltage Fuel Level Oil Pressure Coolant Temp RPM	0.85 50.4 Hz 248 V 59 % 4.4 Bar 73 ℃ 1510 RPM	LOAD Load kW Load PF MAINS Mains Impo Mains PF	0 kW 0.00 作 rt kW 0 kW 0.00	GENSET Generator kW 25 Power Factor 0.84 C Generator kVAr	(G) 77 kW 0.85 C -48 kVAr	-90°≎ -1	° ±10° →+90° 68.3°	Slip Frequency Generator Voltage Mains Voltage Speed Reg Output Voltage Reg Output	0.22 Hz 248 V 232 V 0.000 V 0.000 V
₩	₩ - \ 6	Running MainsOper No Timer	0 s	*	₩ ->- G	Generator kVA 31	93 kVA	奔	₩ -> G	Running MainsOper No Timer	0 s

Image 6.50 : Important values

6.2.3 Gen-set mode change



Image 6.51 : Genset mode change

- 1. Press the button arrow left or right in any metering screen
- 2. Change the controller mode using button arrow left or right and confirm the selection using enter button.
- 3. If all the controller conditions are fulfilled the GenSet mode is changed.

IMPORTANT: If the controller mode setpoint is protected by password the password dialog appears when the attempt to confirm the selection is performed.

6.2.4 Password change

The password change can be performed using the Password menu in Setpoint page.



Setpoints			DB	Setpoints >>	Password				C	⊃∎ 🔺
Password Process Control Pacie Settings	Enter Pa Change	assword Password 1		Access Rights 0 1						3
Communication Settings Ethernet	Change	Password 3								
Engine Settings				Enter Password						
Generator Settings				Change Pas	ssword 1					
Mains Settings				Change Pas	ssword 2					
Load Shedding		Change Pas	ssword 3							
Voltage/PF Control										
Open MCB Open GCB	A	U		Open MCB	Logout	A	Ū		A	

Image 6.52 : Password menu

- 1. Choose the item for which access right you want to change password.
- 2. Using password change dialog enter correct old and new requested password and confirm the choice.
- 3. The password for respective Access Rights level is changed.

6.2.5 Display brightness settings

The display brightness setting is adjustable using the Administration Menu - InteliVision Settings.

Disabled
Manual
60
<i>I</i> [™] : 25.5°C
<u>م</u>

Image 6.53 : Display brightness settings

Backlight Timeout - can be set at a range of 1 to 254 minutes or Disabled. Disabled means the backlight never shuts down.

Brightness control

- 1. If the manual mode is chosen the user is responsible for his own backlight intensity.
- 2. If the External mode is chosen the display unit expects the external resistor (potentiometer) on its Analog input. The type of sensor can be set in InteliConfig

Brightness intensity - The backlight intensity can be adjusted using the value dialog from 1 up to 100%. It is not possible to set 0 to avoid total shutdown of backlight intensity.

IMPORTANT: It is strongly recommended to use maximum backlight if it is really needed. The temperature of the LCD grows linearly with the set of LCD backlight intensity. The product lifetime is temperature dependent. In general it means higher temperature lower lifetime.

IMPORTANT: It is strongly recommended to set the Backlight Timeout to reasonable time (e.g 5 minutes). If the backlight is off then any button press switch on the backlight again.



6.2.6 State messages

State message	Description
Running	Indication of correctly running controller.
Initialize control unit	Controller unit initialization is under progress. The message is displayed during the booting procedure.
Control unit is programmed	The controller upgrade process is under progress.
Configuration Reading	Controller configuration reading is in progress. Text disappears when controller is detected.
Detecting main CU failed	Internal communication error.
Unsupported configuration format	Configuration version is not supported
Unsupported screen format	Screens template has unsupported screen format. Screens template is missing in configuration.
Control unit firmware is corrupted	Controller unit is not in valid state.
Wrong configuration content	Content of the configuration in controller unit does not match to configuration.

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6.3 Custom configuration

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6.3.1 Init or Service screen logo customization

There is a possibility to change the init or service screen logo.



Image 6.54 : Default init and service screen logos

- 1. Make your own starting logo.
- 2. The image resolution is 800 x 480 pixels. Target image format is *.png, *.jpg or *.bmp.
- 3. Open InteliConfig PC application and connect to the controller where you want to change the logo (init, service or both at the same time).



4. Click to the tab Tools - USB Flash Export - Exporting Manager

Home	Cont	тоі	Tools											
Create clone	Save M clone C Cloning	anage Iones	Firmware upgrade •	Set statistic	Change password	Change access code Security	Password Reset	Export to CSV	Generate Cfg image (COM)	Generate o image (MOD Data	Cfg BUS) SN a export	Generate IMP MIB table +	USB Flash export +	Reset from init st
				4	nteliGer SN: FF11	n 500 0339				OF	F I	MAN	AUTO	TEST
	Export	ing man	ager										×	
	Genera	əl		-	-		÷1.					6		
	Splash	screen			Controll	ents	Na OR Co	ime	ofiguration	Ve	rsion	Compatibility	_	
	Service	e screen			CONTOIN	er coningurati		nuolei ci	lingulation	1.	5.0.700	2		
				\square	Controlle	er Firmware	Int	teliGen500	-GC (1.0.0.22)	1.0	0.0.22	5		$\mathbf{\nabla}$
					Internal	Display	Di Di Di	splay firmy splay grap splay fonts	vare nic data	1.0 1.0 1.0	0.0.21 0.0.5 0.0.0	3-5	· · · · ·	
											0	ок	Cancel	0,0 Hz PF
					L1-N L	2-N L3-N	11-12	2 12-13	L3-L1	11 12	L3	L1-N	1 L2-N L3-N	0 L1-L2 L2
					Oil Pressure									10

- 5. Prepare the package with the requested logos (Init, Service, or both). It is possible to prepare the package only with the logos.
- 6. Confirm your choice and save the package file in the root directory of your USB stick.
- 7. Insert the USB stick into the controller unit.
- 8. Administration Import/Export screen is automatically displayed when the USB stick is inserted. Or if the USB stick is already inserted use Enter + Menu button combination from metering screen, select the Import/Export item.
- 9. Select Import package. Insert the administrator (Access Rights level 3) password if not logged in.
- 10. Press user button 1 (Import)
- 11. The new logo(s) is(are) being imported to the Controller unit.
- 12. The device is rebooted and new logos imported.
- 13. Remove the USB Stick.

ComAp >

7 Communication

7.1 PC	 5
7.2 Connection to 3rd party systems	 2

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7.1 PC

7.1.1 Direct communication	
7.1.2 Remote communication	

7.1.1 Direct communication

A RS232, USB, RS485 or ethernet interface can be used for direct cable connection to a PC.

Connection via RS232

A plug-in communication module CM-RS232-485 is necessary for communication via RS232 connection.

The module is plugged into the slot located on the rear side of the controller. To find more information about installation of the modules **see Plug-in module installation on page 50**.

RS232 interface uses **COM1 Mode (page 466)** port of the controller. Use a cross-wired serial communication cable with DB9 female connectors and signals Rx, Tx, GND.

Note: Also USB-RS232 convertor can be used.



Image 7.1 Cross-wired RS232 cable is used



Image 7.2 Cross-wired RS232 cable and USB is used



Connection via RS485

Plug-in module CM-RS232-485 or on board RS485 connector can be used for communication via RS485 connection.

A plug-in communication module CM-RS232-485 is necessary for communication via RS485 connection.

The module is plugged into the slot located on the rear side of the controller. To find more information about installation of the modules **see Plug-in module installation on page 50**.

RS485 interface uses COM2 Mode (page 467) port of the controller.

Note: Also USB-RS485 convertor can be used.



Image 7.3 Built-in RS485 is used



Image 7.4 Plug-in module CM RS232-485 is used

Connection via Ethernet

This connection type is used for communication with the controller from InteliConfig or any other PC tool. Eight remote clients can be connected at the same time (six direct IP clients and two AirGate clients).

To connect your PC tool to the controller use the INTERNET connection type and just put the Ethernet IP address into the gen-set address box in the PC tool.



Image 7.5 Ethernet cable is used

Connection via USB

USB interface uses HID profile.





Image 7.6 Shielded USB type A cable is used

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7.1.2 Remote communication

A PC can be connected to the controller also remotely via CM-4G-GPSCM-GPRS or the built-in ethernet interface.

IMPORTANT: Factory default password and access code are "0". It is necessary to change them to avoid Default Credentials (page 795) or Default Credentials (page 820) alarm.

Ethernet LAN connection

Direct IP LAN connection is intended to be used if the Ethernet module is reachable from the client computer by specifying the IP address at which the module can be contacted.

If direct IP connection is to be used within a local network the Ethernet must have static IP address in the respective local network.



Image 7.7 Ethernet LAN connection

Setting-up static IP address

There are two basic ways to get the static IP address.

First way is to switch the Ethernet to manual IP address mode. Adjust the setpoint IP Address Mode (page 255) to FIXED. In that case all setpoints of IP settings (IP Address (page 256), Subnet Mask (page 256), Gateway IP (page 257), DNS IP Address 1 (page 258) and DNS IP Address 2 (page 258)) have to be adjusted manually. If this method is used several basic rules should be kept to avoid conflicts with the remaining network infrastructure:



- The static IP used in the controller must be selected in accordance with the local network in which Ethernet is connected.
- The static IP used in the controller must be excluded from the pool of addresses which is assigned by DHCP server, which is in charge of the respective local network.
- ▶ The local infrastructure must generally allow using devices with manually assigned IP addresses.
- There must not be any other device using the same static IP address. This can be tested from a computer connected to the same network using "ping <required_ip_address>" command issued from the command line. The IP address is not occupied if there is not any response to the ping command.

Note: The list above contains only basic rules. Other specific restrictions/rules may take place depending on the local network security policy, technology used, topology etc.

Next way is to switch the Ethernet to automatic IP address mode. Adjust the setpoint **IP Address Mode (page 255)** to AUTOMATIC. In that case all IP settings are assigned by DHCP server. Then configure the DHCP server to assign always the same IP address (i.e. static IP address) to the particular Ethernet according to it's MAC address.

Internet connection

Public static IP

If public static IP connection is to be used from the Internet, the IP address, which is entered into the client computer, must be static and public in scope of the Internet.

If Ethernet is connected to Internet via a local ethernet network then in most cases port forwarding must be created from the public IP address of the network gateway to the local IP address of Ethernet at the port specified for ComAp protocol. Different port numbers can be used to create multiple port forwarding rules in the same local network.



AirGate

This connection type is intended for remote connection from InteliConfig, or any other ComAp PC tool over the Internet in situations, where obtaining fixed public IP address is not possible. Two remote clients can be connected at the same time.



This connection type is active if AirGate connection is enabled. Setpoint **AirGate Address (page 260)** must contain AirGate server address. It can be entered in text form as well as numeric form. There is a public AirGate server available at address "airgate.comap.cz".

Once the controller is attached to the Internet and the AirGate server address is properly adjusted then the controller registers automatically to the server and an identification string AirGate ID is given to a controller, which is visible at the controller screen.

To connect your PC tool to the controller use the AirGate connection, put the the same AirGate address as in the controller into the AIRGATE ADDRESS field and use the AirGate ID displayed on the controller.

SMS

Event SMS

The InteliGen 500 controller equipped with the CM-GPRS or CM-4G-GPS communication module is able to send Event SMS according to the setting of setpoint:

Event Message (page 485)

Note: Firstly setpoint Telephone Number 1 (page 486) has to be adjusted.

The following events can be received by mobile phone:

- Engine Start/Stop
 - Manual Start/Stop
 - Remote Start/Stop
- Load on Gen-set

Message structure:

- Genset Name (hh:mm:ss dd.mm.yyyy)
- hh:mm:ss Load on Genset

Alarm SMS

The InteliGen 500 controller equipped with the CM-GPRS or CM-4G-GPS communication module is able to send Alarm SMS according to the setting of setpoints:

- Wrn Message (page 485)
- BOC Message (page 485)
- Sd Messages (page 486)

Note: Firstly setpoint Telephone Number 1 (page 486) has to be adjusted.

Message structure:

- Gen-set Name
- AL=(Alarm 1, Alarm 2, Alarm x)

Note: Asterisk means that alarm is unconfirmed and exclamation mark means that alarm is active.



SMS commands

To control the gen-set equipped with InteliGen 500 controller and CM-GPRS or CM-4G-GPS communication module (or modem) via SMS requests, send an SMS in the structure of:

#xxxx, yyyy, zzzz, etc.

SMS send to the telephone number of the SIM card in your CM-GPRS module (or modem). Where the "#" mark means the controller access code, "xxxx" means the Command 1, "yyyy" is Command 2, "zzzz" is Command 3, etc.

Note: Access code is set up via InteliConfig.

IMPORTANT: If wrong controller access code is set, then only help command is working.

start	Start the engine in MAN mode.
stop	Stop the engine in MAN mode.
fault reset	Acknowledging alarms and deactivating the horn output.
gcb close	Closing GCB in MAN and TEST mode.
gcb open	Opening GCB in MAN and TEST mode.
off	Switching to OFF mode.
man	Switching to MAN mode.
auto	Switching to AUTO mode.
status	Get status information from controller unit.
help	Get a list of available SMS requests.

Note: Between commands are internal delays adjusted due to system requirements.

Example: When the controller, in AUTO mode, with a controller name of "InteliGen 500-Test", with the CM-GPRS module and access code "0" receives the SMS:

0 man, start, gcb close, gcb open, stop, auto

Controller mode will be changed to MANUAL mode. The engine will be started and GCB will close. Then GCB will open, the engine will stop and it will go into AUTO mode again.

The controller will send back the SMS (controller will respond to SMS after every command has been finished, not sooner.):

#InteliGen 500-Test: <OK>,<OK>,<OK>,<OK>,<OK>,

The value <OK> or <ERROR> means if the command has been performed succesfuly or not.

Emails

Event Email

The InteliGen 500 controller equipped with the Ethernet communication module is able to send Event Email according to the setting of setpoint:

Event Message (page 485)

Note: Firstly setpoints Email Address 1 (page 481) and SMTP Sender Address (page 266) (for Ethernet) have to be adjusted.

Note: #Summer Time Mode (page 426) and Time Zone (page 484) have to be adjusted for correct time in emails.



Message structure:

Controller

Name: XXX

Serial number: XXX

SW branch: XXX

SW version: XXX

Application: XXX

Appl. version: XXX

Date: dd/mm/yyyy

Time: hh:mm:ss

Alarm list

Alarm 1

Alarm 2

Alarm 3

Events

hh:mm:ss Event 1 hh:mm:ss Event 2 hh:mm:ss Event 3

Alarm Email

The InteliGen 500 controller equipped with the Ethernet communication module is able to send Alarm Emails according to the setting of setpoints:

- Wrn Message (page 485)
- BOC Message (page 485)
- Sd Messages (page 486)

Note: Firstly setpoints Email Address 1 (page 481) and SMTP Sender Address (page 266) (for Ethernet) have to be adjusted.

Note: #Summer Time Mode (page 426) and **Time Zone (page 484)** have to be adjusted for correct time in emails.



Message structure:

Controller

Name: XXX

Serial number: XXX

SW branch: XXX

SW version: XXX

Application: XXX

Appl. version: XXX

Date: dd/mm/yyyy

Time: hh:mm:ss

Alarm list

Alarm 1

Alarm 2

Alarm 3

History events

0 dd/mm/yyyy hh:mm:ss.0 Event 1

-1 dd/mm/yyyy hh:mm:ss.0 Event 2

-2 dd/mm/yyyy hh:mm:ss.0 Event 3

Note: Asterisk means that alarm is unconfirmed and exclamation mark means that alarm is active.

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7.2 Connection to 3rd party systems

7.2.1 SNMP	
7.2.2 MODBUS-RTU, MODBUS/TCP	

O back to Communication

7.2.1 SNMP

SNMP is an UDP-based client-server protocol used for providing data and events into a supervisory system (building management system). The controller plays the role of a "SNMP Agent" while the supervisory system plays the role of a "SNMP Manager".

- Ethernet module is required for SNMP function
- Supported versions SNMP v1 and SNMP v2c

The SNMP Agent function is to be enabled by the setpoint **SNMP Agent (page 267)** in the Ethernet setpoint group. The setpoints **SNMP RD Community String (page 267)** and **SNMP WR Community String (page 267)** in the same group can be used to customize the "community strings" for the read and write operations



which have function like "passwords". All requests sent from the SNMP Manager have to contain community string which match with the community string adjusted in the controller otherwise the controller refuses the operation.

MIB table

The "MIB table" (Management Information Base) is a table which gives to the Manager description of all objects provided by the Agent.

- ▶ The MIB table is specific for each controller type and configuration
- > The MIB table is to be exported from the controller configuration using InteliConfig
- Controllers with identical firmware and configuration share also identical MIB table, however if the configuration and/or firmware is not identical the MIB table is different and must be exported separately for each controller.

The root node of the MIB table of InteliGen controller is enterprises.comapProjekt.il, which is 1.3.6.1.4.1.28634.14. Under this node there are following sub-nodes :

- Notifications group (SMI v2 only) contains definitions of all notification-type objects that the Agent may send to the Manager.
- GroupRdFix contains read-only objects that exist in all controller regardless of the firmware version/type and configuration.
- GroupRdCfg contains read-only objects that depend on the firmware version/type and configuration.
- GroupWrFix contains read-write objects that exist in all controller regardless of the firmware version/type and configuration.
- GroupWrCfg contains read-write objects that depend on the firmware version/type and configuration.
- GroupW contains write-only objects.
- NotificationData group contains objects that are accessible only as bindings of the notification messages.

SMI version

In InteliConfig the MIB table may be exported in two different formats – SMI v1 and SMI v2. The format which shall be used for export depends on the SNMP Manager and SMI version that it does support.

Typically, SMI v1 is used for SNMP v1 and vice versa, but it is not a rule and SMI v2 may be also used for SNMP v1.

SNMP reserved objects

Name	OID	Access	Data type	Meaning
pfActionArgument	groupWrFix.24550	read,write	Gauge32	Writing: command argument Reading: command return value
pfActionCommand	groupW.24551	write	Integer32	Command code 1)
pfPassword	groupW.24524	write	Integer32	Password

1) For list of commands, arguments and description of the procedure of invoking commands see the description of the MODBUS protocol.



SNMP notifications

Except the request-response communication model, in which the communication is controlled by the Manager, there are also messages that the Agent sends without any requests. These messages are called "Notifications" and inform the Manager about significant events occurred in the Agent.

The controller can send notifications to two different SNMP Managers (two different IP addresses). The addresses are to be adjusted in the Ethernet setpoint group by the setpoints **SNMP Traps IP Address 1 (page 268)** and **SNMP Traps IP Address 2 (page 268)**. If the Manager address is not adjusted the particular notification channel is off. The controller will send the notifications in format adjusted by the setpoint **SNMP Traps IP Address 2** (page 268).

- Each notification (kind of event) is identified by an unique identifier (Trap ID in SNMPv1 or Notification OID in SNMPv2). This unique identifier gives the specific meaning to the notification message, e.g. Protection 1. level Fuel Level alarm activated.
- All possible notifications and their identifiers are listed in the MIB table.
- > The notification message also contains controller name, serial number and textual description of the event.

Operational events

This events are used for SNMP traps. See the list below:

- Start commands of gen-set
 - Start button
 - Remote start
- Stop commands of gen-set
 - Stop button
 - Remote stop
- Breaker record
 - Load on gen-set

7.2.2 MODBUS-RTU, MODBUS/TCP

MODBUS protocol is used for integration of the controller into a building management system or for remote monitoring via 3rd party monitoring tools.

- MODBUS-RTU can be used with serial interfaces (via on board RS485 connector or via CM-RS232-485 communication module). The MODBUS-RTU server must be activated by switching the setpoint RS485 Mode (page 253) or COM2 Mode (page 467) to the Modbus position. The serial speed for MODBUS-RTU communication is to be adjusted by the setpoint RS485 MODBUS Speed (page 254) or COM2 MODBUS Communication Speed (page 468).
- MODBUS/TCP can be used with the built-in ethernet interface. Up to 3 clients can be connected simultaneously. The MODBUS/TCP server must be activated by the setpoint MODBUS Server (page 269).

MODBUS, MODBUS/TCP protocol can be used simultaneously with direct Ethernet connection and the SNMP agent.



IMPORTANT: Do not write setpoint repeatedly(e.g. power control form a PLC repeated writing of baseload setpoint via Modbus). The setpoints are stored in EEPROM memory. which can be overwritten up to 10⁵ times without risk of damage or data loss, but may become damaged, when the allowed number of writing cycles is exceeded!

Address space

The object address space is separated into several areas as described in the table below. The actual mapping of specific controller data objects to specific MODBUS addresses, which depends on configuration, can be exported into a text file from the appropriate controller archive using InteliConfig. There are several special registers with fixed meaning (reserved registers) which are listed in a separate table in this chapter.

MODBUS address	Meaning	Access	MODICON object type	MODBUS function
00000999	Binary objects	Read only	Discrete Inputs	Read: 01, 02
1000 2999	Values	Read only	Input Registers	Read: 03, 04
30003999	Setpoints	Read/Write	Holding Registers	Read: 03, 04 Write: 06, 16
4200 7167	Reserved registers	Read/Write, depends on each specific register	Input Registers Holding Registers	Read: 03, 04 Write: 06, 16

Configurable part of the map

The contents of the configurable part of the map is specified in the configuration table. It can be changed by the customer as well as exported in a human-readable format using the configuration tool.

Discrete inputs

The discrete inputs are read-only objects located in the address range 0-999. The source ComAp objects for discrete inputs can be:

- Single bit of any value of any binary type.
- Protection (e.g. 2nd-level protection of the state "xyz"). The input is high if the protection is active regardless of if it is configured or not.

Input registers

The input registers are read-only numeric values located in the address range 1000-2999. The source ComAp objects can be:

Any controller value of any data type. The mapping of the particular data type into registers is described in Mapping data types to registers (page 206).

Holding registers

The holding registers are read-write numeric values located in the address range 3000-3999. The source ComAp objects can be:

Any controller setpoint of a primitive data type. The mapping of the particular data type into registers is described in Mapping data types to registers (page 206).

Default contents of the configurable part

The default map of MODBUS objects contain following items. This map expects the PC tool does have the function allowing the user to modify the map.



Object type	Starting object address	Controller object
Discrete inputs	0000	Physical binary inputs CU + configured* modules Logical binary outputs Protections on binary inputs CU + configured* modules Protections on analog inputs CU + configured* modules All Built-in fixed protections
Input registers	1000	All configured* visible values
Holding registers	3000	None

*Present in the default configuration.

IMPORTANT: The default map of a particular firmware branch and application must not change when a new version of the firmware is created. If new objects are added they must be added to free positions so, that the previous content is not affected.

IMPORTANT: The default map of a particular firmware branch must not contain different values in different applications at the same MODBUS address. It means if a ComAp object does not make sense in some application type the respective MODBUS address must be left unassigned.

Mapping data types to registers

As there are multiple data types in the controller but only one data type in MODBUS (the register, which is 2 byte long), a mapping table is necessary to compose and decompose the MODBUS messages correctly.

Data type	Meaning	Number of registers	Data maping
Integer8	1-byte signed integer	1	MSB = sign extension
Integero	1-byte signed integer		LSB = value
Linsigned8	1-byte unsigned integer	1	MSB = 0
Unsignedo	1-byte unsigned integer	I	LSB = value
Intogor16	2 byte signed integer	1	MSB = value, MSB
Integer to	2-byte signed integer	I	LSB = value, LSB
Lingianod16	2 byte uppigped integer	1	MSB = value, MSB
Unsigned to	2-byte unsigned integer		LSB = value, LSB
	4-byte signed integer	2	MSB1 = value, byte 3 (MSB)
Integer32			LSB1 = value, byte 2
			MSB2 = value, byte 1
			LSB2 = value, byte 0 (LSB)
		2	MSB1 = value, byte 3 (MSB)
Lingian d22	4-byte unsigned integer		LSB1 = value, byte 2
Unsigned 52			MSB2 = value, byte 1
			LSB2 = value, byte 0 (LSB)
Dipon (9			MSB = 0
Difiaryö	o-bit binary value		LSB = value, bits 0-7



Data type	Meaning	Number of registers	Data maping
Binan/16	16 hit hingny value	1	MSB = value, bits 8-15
Dinary 10			LSB = value, bits 0-7
			MSB1 = value, bits 24-31
Binan/32	32-hit hinany value	n	LSB1 = value, bits 16-23
Diriary 52	SZ-bit binary value	2	MSB2 = value, bits 8-15
			LSB2 = value, bits 0-7
Char	1-byte ASCII character	1	MSB = 0
			LSB = ASCII value of the character
Strl ist	Index into a list of strings	1	MSB = 0
Ottelst	index into a list of strings		LSB = index into the list
			MSB1 = ASCII value of the 1. character
	Zona tamain ata di atain a af		LSB1 = ASCII value of the 2. character
ShortStr	Zero-terminated string of max 15 ASCII characters	8	MSB2 = ASCII value of the 3. character
			LSB2 = ASCII value of the 4. character
			MSB1 = ASCII value of the 1. character
	Zero-terminated string of		LSB1 = ASCII value of the 2. character
LongStr		16	MSB2 = ASCII value of the 3. character
	max 31 ASCII characters.		LSB2 = ASCII value of the 4. character
			MSB1 = BCD (dd)
Dete	Data (dd mm yw)	0	LSB1 = BCD (mm)
Dale	Jale (dd-mm-yy)		MSB2 = BCD (yy)
			LSB2 = 0
			MSB1 = BCD (hh)
Time			LSB1 = BCD (mm)
TIME		2	MSB2 = BCD (ss)
			LSB2 = 0
			MSB1 = reserved for future use
			LSB1 = reserved for future use
			MSB2 = Alarm level *)
			LSB2 = Alarm status **)
Alarm	An item of the Alarmlist	27	MSB3 = alarm string ***)
			LSB3 = alarm string
			MSB4 = alarm string
			LSB5 = alarm string



*) 1 .. level 1 (yellow), 2 .. level 2 (red), 3 .. sensor fail

- **) Bit0 alarm is active, Bit1 alarm is confirmed
- ***) String encoding is UTF-8

Error codes (exception codes)

Exception code is returned by the controller (server) if the query sent from the client could not be completed successfuly.

The controller responds with the error codes in as follows:

- 01 Ilegal function is returned if an incompatible type of operation is applied for a specific object, e.g. if function 03 is applied to a binary object.
- 02 illegal address is returned if the client tries to perform an operation with a object address that is not related to any existing object or that is located inside an object which is composed by multiple addresses (registers).
- 04 device error is returned in all other errorneous situations. More detailed specification of the problem can be consequently obtained by reading the registers 4205 – 4206.

Reserved registers

There are several registers with specific meaning. These registers are available in all controllers regardless of the configuration.

Register addresses	Number of registers	Access	Data type	Meaning
4200 - 4201	2	read/write	Time	RTC Time in BCD code
4202 - 4203	2	read/write	Date	RTC Date in BCD code
4204	1	read/write	Index of the language that is used for teUnsigned8data provided by MODBUS (e.g. alarm messages).	
4205 - 4206	2	read	Last application error. To be read after device returns the exception code 04. contains specific information about th	
4207 - 4208	2	read/write	Unsigned32	Writing:command argument Reading: command return value
4209	1	write	Unsigned16 Command code	
4010	1	-	- Not implemented	
4211	1	write	Unsigned16	Password
4212 - 4213	2	read	Unsigned32	Communication status
4214	1	read	Unsigned8	Number of items in the Alarmlist
4215 - 4241	27	read	Alarm	1. record in alarm list
4242 - 4268	27	read	Alarm 2. record in alarm list	
4269 - 4295	27	read	Alarm	3. record in alarm list
4296 - 4322	27	read	Alarm	4. record in alarm list
4323 - 4349	27	read	Alarm	5. record in alarm list



Register addresses	Number of registers	Access	Data type	Meaning
4350 - 4376	27	read	Alarm	6. record in alarm list
4377 - 4403	27	read	Alarm	7. record in alarm list
4404 - 4430	27	read	Alarm	8. record in alarm list
4431 - 4457	27	read	Alarm	9. record in alarm list
4458 - 4484	27	read	Alarm	10. record in alarm list
4485 - 4511	27	read	Alarm	11. record in alarm list
4512 - 4538	27	read	Alarm 12. record in alarm list	
4539 - 4565	27	read	Alarm	13. record in alarm list
4566 - 4592	27	read	Alarm	14. record in alarm list
4593 - 4619	27	read	Alarm	15. record in alarm list
4620 - 4646	27	read	Alarm	16. record in alarm list

List of commands and arguments

"Commands" are used to invoke a specific action in the controller via the communication channel. The list of available actions is in the table below. The general procedure of writing a command via MODBUS is as follows:

- (Optional) Write required level of password into the register 44212 (register address 4211). Use function 6. If the password is required or not depends on configuration of access rules. It can be adjusted/modified by InteliConfig.
- Write the command argument into the registers 44208-44209 (register addresses 4207-4208). Use function 16.
- 3. Write the command code into the register 44210 (register address 4209). Use function 6.
- 4. (Optional) Read the command return value from the registers 44208-44209 (register addresses 4207-4208). Use function 3.
- 5. If the command was executed the return value is as listed in the table. If the command was accepted but there was an error during execution the return value indicates the reason:
 - a. 0x0000001 invalid argument
 - b. 0x0000002 command refused (e.g. controller not in MAN, breaker can not be closed in the specific situation etc.)

Action	Command code	Argument	Return value
Engine start *)	0x01	0x01FE0000	0x000001FF
Engine stop *)	0x01	0x02FD0000	0x000002FE
Fault reset *)	0x01	0x08F70000	0x00008F8
Horn reset *)	0x01	0x04FB0000	0x000004FC
GCB toggle *)	0x02	0x11EE0000	0x000011EF
GCB on	0x02	0x11EF0000	0x000011F0
GCB off	0x02	0x11F00000	0x000011F1
MCB toggle *)	0x02	0x12ED0000	0x000012EE
MCB on	0x02	0x12EE0000	0x000012EF
MCB off	0x02	0x12EF0000	0x000012F0



*) This action is an equivalent of pressing the front panel button

MODBUS examples

Modbus RTU examples

- Reading of Battery voltage
 - Export table of values from InteliConfig

Table: Values									
Allowed MODB	US function	s: 03, 04							
Register(s)	Com.Obj.	Name	Dimension	Туре	Len	Dec	Min	Max	Group
01053	8213	BatteryVoltage	ν	Integer	2	1	0	400	Controller I/O

Request: (Numbers in I	Hex)						
01	03	04	1D	00	01	15	3C
Controller address	Modbus function	Registe 041D _{he}	er address _x = 1053_{dec}	Number o	f registers	CI	RC

Response: (Numbers in Hex)										
01	03	02	00	F0	B8	00				
Controller address	Modbus function	Length of data 02 _{hex} = 2 bytes read	[00F0 _{he}	Data _x = 240 _{dec}	CF	RC				

We read value 240 from register 01053. From table of modbus registers we get dimension of read value and "Dec". Dec=1 means shift one decimal place to the right. So battery voltage is **24.0 V**.



Reading Nominal power

• Export table of values from InteliConfig

Table: Values									
Allowed MODBUS functions: 03, 04									
Register(s)	Com.Obj.	Name	Dimension	Туре	Len	Dec	Min	Max	Group
01228	9018	Nominal Power	kW	Integer	2	0	0	32767	Generator

Request: (Numbers in H	lex)						
01	03	04	CC	00	01	45	05
Controller address	Modbus function	Registe 04CC _{he}	er address _x = 1228_{dec}	Number of registers		CI	RC

Response: (Numbers in Hex)										
01	03	02	00	C8	B9	D2				
Controller address Modbus function		Length of data 02 _{hex} = 2 bytes read] 00C8 _{he}	Data = 200 _ _{dec}	CI	RC				

Read nominal power is 200 kW.

Reading all binary inputs as modbus register

Table: Values									
Allowed MODBUS functions: 03, 04									
Register(s)	Com.Obj.	Name	Dimension	Туре	Len	Dec	Min	Max	Group
01068	8235	Binary Inputs		Binary#2	2	0	-	-	Controller I/O

Request: (Numbers in H	Hex)						
01	03	04	2C	00	01	44	F3
Controller address	Modbus function	Registe 042C _{hex}	er address _x = 1068_{dec}	Number o	f registers	с	RC

Response: (Numbers in Hex)										
01	03	02	00	12	38	49				
Controller address	Modbus function	Length of data 02 _{hex} = 2 bytes read	E 0012 _{hex} =	0ata 00010010 _{bin}	С	RC				

Binary inputs is 00010010. It means Binary input 2 and binary input 5 are active.

Note: You can use modbus function 4 insted of 3, rest of data remain same (CRC differs).



Reading binary inputs as coil status.

Table: Binaries	Table: Binaries								
Allowed MODBUS functions: 01, 02									
Addresses Modbus Addr. Prot. Addr.	Source = Value = State	C.O.# State <i>#</i>	Name of Value Name of State	Bit #	Bit Name Activated by protection(s):	Group			
00000	Value	8235	Binary Inputs	1	GCB Feedback	Controller I/O			
00001	Value	8235	Binary Inputs	2	MCB Feedback	Controller I/O			
00002	Value	8235	Binary Inputs	3	Emergency Stop	Controller I/O			

We will read state of MCB Feedback binary input.

Request: (Numbers in Hex)										
01	01	00	01	00	01	AC	0A			
Controller address	Modbus function	Registe 0001 _{hex}	er address _c = 0001 _{dec}	Number o	f registers	CF	RC			

Response: (Numbers in Hex)									
01	01	01	01	90	48				
Controller address	Modbus function	Length of data 01 _{hex} = 1 byte read	Data 01 _{hex} = active	С	RC				

The readed data is 01, it means this binary input is active.

Note: You can use modbus function 2 insted of 1, rest of data remains same (CRC differs).



Starting the engine

Before starting engine you may need to write password. Depends on your settings in controller.

Table Reserved registers (page 208)

Register addresses	Number of registers	Access	Data type	Meaning
4207 - 4208	2	read/write	Unsigned32	Writing:command argument Reading: command return value
4209	1	write	Unsigned16	Command code

Table List of commands and arguments (page 209)

Action	Command code	Argument	Return value
Engine start	0x01	0x01FE0000	0x000001FF
Engine stop	0x01	0x02FD0000	0x000002FE

Request 1/2: (Numbers in Hex)								
01	10	10	6F	00	03	06		
Controller address	Modbus function $10_{hex} = 16_{dec}$	Register address 106F _{hex} = 4207 _{dec}		Number of registers		Data length in bytes		

Request 2/2: (Numbers in Hex)									
01	FE	00	00	00	01	68	0B		
Argument			Comma	nd code	CI	RC			

Note: Command and argument may be written as one "packet" (function 16) or you can split it and write argument (function 16) and after that write command code (function 6).



Password

This password is the same as in InteliConfig or directly in controller.

Table Reserved registers (page 208)

Register addresses	Number of registers	Access	Data type	Meaning
4211	1	write	Unsigned16	Password

Note: Default password is "0".

In this example the password is "1234".

Request: (Numbers in Hex)										
01	06	10	73	04	D2	7C	D1			
Controller address	Modbus function	Register address 1073 _{hex} = 4211 _{dec}		Pa: 04D2 _{he}	ssword _x = 1234 _{dec}	CF	RC			

Response for success: (Numbers in Hex)										
01	06	10	73	00	00	7C	D1			
Controller address	Modbus function	Register address 1073 _{hex} = 4211 _{dec}		Allwa	ays zero.	CF	RC			

Response	Response for bad password: (Numbers in Hex)								
01	86	04	43	A3					
Controller	Modbus exception	04 – device error	CRC						
address	for function 6.	see Error codes (exception codes) on page 208		0					



Nominal Power – writing

Table: Setpo	Table: Setpoints								
Allowed MODBUS functions: 03, 04, 06, 16									
Register(s)	Com.Obj.	Name Dimension Type Len Dec Min Max Group							
03008	8276	Nominal Power	kW	Unsigned	2	0	1	5000	Basic Settings

Request: (Numbers in Hex)										
01	06	0B	C0	00	64	8A	39			
Controller address	Modbus function	Register address 0BC0 _{hex} = 3008 _{dec}		۲ 0064 _{he}	Data _x = 100 _{dec}	CF	RC			

Response: (Numbers in Hex)										
01	06	0B	C0	00	00	8B	D2			
Controller address	Modbus function	Register address 0BC0 _{hex} = 3008 _{dec}		Allwa	ays zero	C	RC			

Writen setpoint nominal power is 100 kW.

CRC calculation

The check field allows the receiver to check the validity of the message. The check field value is the Cyclical Redundancy Check (CRC) based on the polynomial $x^{16}+x^{15}+x^2+1$. CRC is counted from all message bytes preceding the check field.

Online CRC calculator: http://www.lammertbies.nl/comm/info/crc-calculation.html Use CRC-16 (Modbus) Write LSB first.

For writing nominal power 100 kW the CRC is calculated from this data: $01060BC00064_{hex}$



Modbus TCP examples

- Reading of Battery voltage
 - Export table of values from InteliConfig

Table: Values									
Allowed MODBUS functions: 03, 04									
Register(s)	Com.Obj.	Name	Dimension	Туре	Len	Dec	Min	Max	Group
01053	8213	BatteryVoltage	v	Integer	2	1	0	400	Controller I/O

Request: (Numbers in Hex)											
00	00	00	00	00	06	01	03	04	1D	00	01
transaction identifier (usually 0)		protocol identifier (usually 0)		Length of data bytes following		Controller address	Modbus Regist function 041D _{he}		gister address D _{hex} = 1053 _{dec}	Num regis	per of ters

Request: (Numbers in Hex)											
00	00	00	00	00	06	01	03	04	1D	00	01
transaction identifier (usually 0)		protocol identifier (usually 0)		Length of data bytes following		Controller address	Modbus function	Register address 041D _{hex} = 1053 _{dec}		Number of registers	

Response: (Numbers in Hex)											
00	00	00 00		00 05		01	03	02	00	F0	
transaction identifier (usually 0)		protocol identifier (usually 0)		Length of data bytes following		Controller address	Modbus function	Length of data 02 _{hex} = 2 bytes read	C 00F0 _{he}	Data _x = 240 _{dec}	

We read value 240 from register 01053. From table of modbus registers we get dimension of read value and "Dec". Dec=1 means shift one decimal place to the right. So battery voltage is **24.0 V**.

O back to Connection to 3rd party systems


8 Technical data

Power supply

Power supply range	8-36 V DC
Power consumption	320 mA / 8 V DC
	210 mA / 12 V DC
	120 mA / 24 V DC
	90 mA / 36 V DC
Power terminal fusing	Max. 4 A
	E-Stop max.1.2 A
E-Stop power terminal fusing	1.2 A
Max. Power Dissipation	9 W

D+

Max. excitation current	250 mA
Charging fail threshold	80 % of Usupply

Operating conditions

Operating temperature	-20 °C to +70 °C
Storage temperature	-30 °C to +80 °C
Protection degree (front panel)	IP 65
Operating humidity	95 % w/o condensation
Vibratian	5-25 Hz, ± 1.6 mm
VIDFALION	25-100 Hz, a = 4 g
Shocks	a = 500 m/s ²
Surrounding air temperature rating 70°C	
Suitable for pollution degree 2	
Heat radiation	9 W

Voltage measurement

Measurement inputs	3ph-n Gen voltage , 3ph-n Mains
Measurement range	277 V ph-n
Max. allowed voltage	350 V ph-n
Accuracy	1 %
Frequency range	40-70 Hz (accuracy 0.1 Hz)
Input impedance	0.72 MΩph-ph , 0.36 MΩph-n

Display

Туре	Build-in monochromatic 3.2"
Resolution	800 × 480 px

E-Stop

Physically disconnects binary outputs 1 & 2 from power	
Dedicated terminal for E-Stop input	
•	

Binary inputs

Number	8, non-isolated
Close/Open indication	0-2 V DC close contact
	0-50 V DC Open contact



Binary outputs

	6 low current output, non-isolated
Supplied by power terminal	BO 3-8 = 0.5 A
	switching to positive supply terminal
Supplied by E-Stop power terminal	2 high current output, non-isolated
	BO 1, 2 = 4 A
	switching to positive supply terminal

Analog inputs

Number	4, switchable (R/U/I)	
Туре	Resistive	
Resistive Senso Accura	Range	0-2 500 Ω 0-15 000 Ω with limited accuracy
	Sensor current	10mA @ 100 Ω
	Accuracy	$0-250~\Omega;2\%$ from measured value and +/- 5 Ω $250-15000~\Omega;4\%$ from measured value
Voltage	Range	0-10 V
	Max. voltage	12,5 V
	Input impedance	40 kΩ
	Accuracy	1% from measured value and +/-0,1 V
Current Ra Current Inp Ac	Range	0-20 mA
	Max. current	25 mA
	Input impedance	150 Ω
	Accuracy	1% from measured value and +/-0,2 mA

Voltage regulator output

Protection	Isolated
Туре	max±10 V DC

Speed governor output

Output type	± 10 VDC or 5 V @ 500 Hz PWM selectable by jumper
Protection	Non-isolated

Magnetic pickup

	4 Vpk-pk to 50 Vpk-pk in range 4 Hz to 1 kHz
Voltage input range	6 Vpk-pk to 50 Vpk-pk in range 1 kHz to 5 kHz
	10 Vpk-pk to 50 Vpk-pk in range 4 Hz to 10 kHz
Frequency input range	4 Hz to 10 kHz
Frequency measurement tolerance	0.2 % from range 10 kHz

Communications

USB port	Non-isolated
CAN 1 + CAN 2	250 / 50 kbps, isolated, nominal impedance 120 Ω

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9.1.1 Setpoints

What setpoints are:

Setpoints are analog, binary or special data objects which are used for adjusting the controller to the specific environment. Setpoints are organized into groups according to their meaning. Setpoints can be adjusted from the controller front panel, PC, MODBUS, etc.

All setpoints can be protected by a password against unauthorized changes. Password protection can be assigned to the setpoints during the configuration procedure.

IMPORTANT: Do not write setpoints repeatedly (e.g. power control from a PLC by repeated writing of baseload setpoint via Modbus). The setpoints are stored in EEPROM memory, which can be overwritten up to 10⁵ times without risk of damage or data loss, but it may become damaged, when the allowed number of writing cycles is exceeded.

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List of setpoints

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Group: Process Control

Subgroup: Application Selector

Application Mode Select

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	SPtM / MINT [-]		
Default value	MINT	Alternative config	NO
Step	[-]		
Comm object	12157	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			
This setpoint defines the controller application. The change of this setpoint is accepted in OFF mode only = It is not possible to change the setpoint while			

the controller is not set to OFF mode.

SPtM	Single parallel to mains application. The controller controls two breakers – a mains breaker and a generator breaker. Feedback from both breakers is required.
MINT	Multiple island-parallel application without mains and multiple parallel application with mains. The controller controls one breaker only, the generator breaker. Feedback from the generator breaker is required. For parallel to mains operation also mains breaker feedback is required.



Subgroup: Load Control

Load Control PTM

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	Baseload / Import/Export [-]		
Default value	Baseload	Alternative config	NO
Step	[-]		
Comm object	8638	Related applications	MINT, SPtM
Config level	Standard		,
Setpoint visibility	Always		
Description			
This setpoint adjust t	the type of load control.		
Gen-set produces amount of the power given by setpoint Baseload (page 233). The rest of power is supplied from the mains or exported to the mains (depends on proportions of load and Baseload (page 233) setpoint). Even in baseload control mode can be the Import/Export limited. This function can be activated by setpoint Import/Export Limitation (page 235) = Enabled. Then the request for the power of the genset operating in baseload can be limited to prevent the Import/Export go below the limit given by setpoint Import Load (page 234).BaseloadExample: Baseload = 1000 kW, load = 700 kW, Import load = 100. Then the Baseload request will be limited to 600 kW to prevent the Import power go below 100 kWExample: Baseload = 1000 kW, load = 700 kW, Import load = -100. Then the Baseload request will be limited to 800 kW to prevent the Import power go below -100 kW (actually it is limitation of the export).			to the mains (depends on nt). Even in baseload control in can be activated by setpoint then the request for the power of event the Import/Export go below W, Import load = 100. Then the prevent the Import power go W, Import load = -100. Then the prevent the Import power go export).

Gen-set produces the certain amount of power to keep constant import/export from
the mains regardless the demand of the load. The requested import/export is given byImp/Expsetpoint Import Load (page 234). If the value of the setpoint is >0 the power is
imported from the mains, if setpoint value is <0, then the power is exported to the
mains.

Note: In both modes, the lower level of the power is always limited by the setpoint **Minimal Power PTM** (page 305). If the requested load (given by the active load control mode, e.g. Baseload, Import/Export) is below this limit the requested load is limited to the level adjusted by this setpoint.



PF Control PTM

Set	point group	Process Control	Related FW	1.0.0
Rai	ge [units] Base PF/ PF Import/Export [-]			
Def	ault value	Base PF Alternative config NO		NO
Ste	р	[-]		
Со	mm object	n object 10120 Related applications SPtM		SPtM
Co	Config level Standard			
Set	point visibility	Always		
Des	scription			
This	s setpoint adjust t	the type of power factor c	ontrol.	
Base PF		The power factor on the gen-set is kept on the level given by the setpoint Base Power Factor (page 233) regardless the load demand. The rest of demanded reactive power is supplied from the mains. Values >1 means that capacitive reactive power is supposed to be imported from mains, values <1 means that inductive reactive power is imported from the mains. Gen-sets are controlled to keep the constant level of the power factor. The level is adjusted by setpoint #System Power Factor (page 236) .		
	PF Imp/Exp	Gen-set produces the certain amount of reactive power to keep constant PF imported from the mains regardless the demand of the load. The requested power factor import is given by setpoint Import PF (page 234) . Values >1 means that the gen-set is pushing the capacitive power to the system (sytem Gen-set - Load-Mains), values <1 means that the gen-set is pushing the inductive power to the system.		



#System Load Control PTM

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	Baseload / Loadsharing [-]		
Default value	Baseload	Alternative config	NO
Step	[-]		
Comm object	8774	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

Load control mode in parallel to mains operation of the whole group of gen-sets.

Baseload	The total power of the group is controlled to constant level given by the setpoint #System BaseLoad (page 235) . Each loaded gen-set takes equal part (relative to their nominal power) from this requested value. The load is regulated locally in each controller by Load control regulation loop, load-sharing is not active. The setpoint #System BaseLoad (page 235) is also used for determining which gen-sets have to run or not.
Loadsharing	Gen-sets load is controlled by MainsCompact controller to share the total load (given by the setpoint #System BaseLoad (page 235)) with other loaded gen-sets in such a way, that all loaded gen-sets will be loaded at the same level (relative to gen-set nominal power). Load-sharing regulation loop is active.

Note: The Loadsharing mode shall be used in case a MainsCompact controller is present in the system. In systems without MainsCompact the setpoint must be in the Baseload position.

Note: The power factor (PF) is regulated to constant level given by the setpoint **#System PF Control PTM (page 233)** in parallel to mains operation and does not depend on active load control mode.



#System PF Control PTM

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	Base PF / Var Sharing [-]		
Default value	Base PF	Alternative config	NO
Step	[-]		
Comm object	8779	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
Power factor control mode in parallel to mains operation of the whole group of gen-sets.			

Base PF	Gensets PF is controlled by their PF control loops to provide constant power factor adjusted by setpoint #System Power Factor (page 236) . InteliMains doesn't play active role in PF control in parallel to mains operation.
Var Sharing	Gensets PF is controlled by InteliMains through the VAr sharing line.

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Baseload

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	0 Nominal Power (page 242) [kW]		
Default value	100 kW	Alternative config	NO
Step	1 kW		
Comm object	8639	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Required gen-set load in parallel to mains operation.			

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Base Power Factor

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	0,60 1,20 [-]		
Default value	1,00 [-]	Alternative config	NO
Step	0,01 [-]		
Comm object	8640	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Required gen-set power factor when the gen-set is running in parallel to the mains.			



Import Load

Setpoint group	Process Control Related FW 1.0.0			
Range [units]	-32 000 32 000 [kW]			
Default value	0 kW	Alternative config	NO	
Step	1 kW			
Comm object	8641	Related applications	SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Defines maximal lim	it of load for import/export.	Behavior of setpoint deper	nds on setpoint Load Control	

PTM (page 230).

Baseload	Setpoint adjust the maximal value of import/export. Also Import/Export Limitation (page 235) setpoint has to be set to Enabled.
Import/Export	Setpoint adjust requested value of constant import/export.

If the value of the setpoint is >0 the power is imported from the mains, if the setpoint value is <0, then the power is exported to the mains.

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Import PF

Set	point group	Process Control Related FW 1.0.0		
Rar	nge [units]	0,60 1,20 [-]		
Def	ault value	1,00 [-] Alternative config NO		
Ste	р	0,01 [-]		
Со	mm object	8642	Related applications	SPtM
Со	Config level Standard			
Set	Setpoint visibility Always			
Des	scription			
Def Coi	ines maximal lim ntrol PTM (page	it of power factor for import 231) .	export. Behavior of setpo	int depends on setpoint PF
	Baseload	Setpoint adjust the maximal value of import. Also Import/Export Limitation (page 235) setpoint has to be set to Enabled.		
	Import/Export	Setpoint adjust requested value of constant import.		



Import/Export Limitation

Setpoint group	Process Control	Related FW	1.0.0	
Range [units]	ENABLED / DISABLED [-]			
Default value	Disabled Alternative config NO			
Step	[-]			
Comm object	9592	Related applications	SPtM	
Config level	Standard			
Setpoint visibility	Always			

Description

Enable or disable limitation for import/export. If function is enabled, then the request for the power of the gen set is limited to prevent the Import/Export go below the limits. Limits are adjusted via setpoints Import Load (page 234) and Import PF (page 234).

Example: Baseload = 1000 kW, load = 700 kW, Import load = 100 kW. Then the Baseload request will be limited to 600 kW to prevent the Import power go below 100 kW.

Example: Baseload = 1000 kW, load = 700 kW, Import load = -100 kW. Then the Baseload request will be limited to 800 kW to prewent the Import power go below -100 kW (actually it is limitation of the export).

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#System BaseLoad

Setpoint group	Process Control	Related FW	1.0.0
Range [units]	032000 [kW]		
Default value	1 000 kW	Alternative config	NO
Step	1 kW		
Comm object	8775	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
Required total load o	of the gen-set group in paral	llel to mains operation in ba	aseload mode (setpoint #System

Load Control PTM (page 232) = Baseload).



#System Power Factor

Setpoint group	Process Control	Related FW	1.0.0	
Range [units]	0,60 1,20 [-]			
Default value	1,00 [-]	Alternative config	NO	
Step	0,01 [-]			
Comm object	8776	Related applications	MINT	
Config level	Standard	Standard		
Setpoint visibility	Always	Always		
Description				
Required gen-set por regulated locally in e	wer factor when the group ach controller by PF contro	of gen-sets is running para ol regulation loop, VARsha	llel to the mains. The PF is ring is not active.	



Subgroup: Neutral Contactor

#Neutral Contactor Control

etpoint group	Process Control	Related FW	1.0.0		
ange [units]	Each / Common [-]				
efault value	Each	Alternative config	NO		
ер	[-]				
omm object	9890	Related applications	MINT, SPtM		
onfig level	Standard	Standard			
etpoint visibi	lity Always	Always			
escription					
etpoint change Intactor contro	es behavior of binary output I.	NCB CLOSE/OPEN (PAGE 7	30) which is used for neutral		
	The EACH option should pole GCB must be used in The output is alwa	be used if each gen-set has i n this case. ys opened while the gen-set vs opened while the MCB is	t's own neutral contactor. Four- is not running closed		
Each	 While the gen-set voltage in at least the generator volta While the gen-set the output is given one gen-set conner the gen-set with low 	 While the gen-set is running and GCB is open, the output closes when generator voltage in at least one phase exceeds 85% of the nominal voltage. It opens when the generator voltage in all phases drops below 50% of the nominal voltage While the gen-set is running, MCB is open and GCB is closed, then the position of the output is given by an internal algorithm, which ensures, that always exactly one gen-set connected to the bus has the neutral contactor closed. It is always the gen set with lowest CAN address 			
Common	 The COMMON option show whole site. The NCB CLO together and the combiner used in this case. The output is alware. The output is alware. The output is alware. While the gen-set one phase exceed voltage in all phase least one gen-set in the set. 	ould be used if there is one co DSE/OPEN (PAGE 730) output ad signal is used to control the hys opened while the gen-set hys opened while the MCB is is running the output closes w as 85% of the nominal voltage es drops below 50% of the no in the site is running and havi	ommon neutral contactor for the s from all controllers are combined e breaker. Three-pole GCB must be is not running closed when generator voltage in at least e. It opens when the generator ominal voltage. That means if at ng proper voltage, the neutral		



Subgroup: Process Limitation

CB Control In MAN Mode

Setpoint group)	Process Control	Related FW	1.0.0		
Rai	nge [units]		Full Ctrl / Aut Trans / IsInd Disl [-]				
Default value			Full Ctrl	Alternative config	NO		
Step			[-]	(-)			
Со	mm object		14962	Related applications	SPtM		
Со	nfig level		Standard				
Set	point visibi	lity	Always				
Des	scription						
The	behavior of	trans	sition of load in MAN mode	is adjusted via this setpoir	nt.		
	Full Ctrl	No evo	limitation of CB control in N ke the synchronization and	MAN mode (operator can c d consequential operation i	lose any breaker manually or n parallel to mains)		
	Aut Trans	Ope cor set (pas Col pus It is Sol	whete the synchronization and consequential operation in parallel to mains) erator can control both MCB or GCB breaker. However once transition is evoked the itroller performs the automatic transfer of the load (depends on adjustment of points Transfer BusGen To Mains (page 352) and Transfer Mains To Gen Bus ge 351)). ntroller performs synchronisation accross MCB, if GCB is closed and MCB button is inded. Load transfer is done after synchronisation and GCB is opened automatically. ntroller performs synchronisation accross GCB, if MCB is closed and GCB button is shed. Load transfer is done after synchronisation and MCB is opened automatically. also possible to open currently closed breaker and keep the load non-energized. en it is possible to close MCB or GCB MGCB to energize the load from a healthy with mains and setting is changed to Aut Trans. It is necessary to push MCB or GCB button to open a breaker. Note: Open transfer is performed, if the Open option is selected with Transfer				
	IsInd Disl	Bel	BusGen To Mains (page 352) or Transfer Mains To Gen Bus (page 351) ehaves like the full manual control but the Island operation is disabled. Example: When MCB opened and GCB pressed, controller don't go to island Example: In parallel operation when MCB button pressed, MCB is not opened				



Subgroup: Mains Import Measurement

Mains Import Measurement

· · · · · · · · · · · · · · · · · · ·					
Setpoint group	Process Control	Related FW	1.0.0		
Range [units]	None/Mains CT/Analog Input [-]				
Default value	Mains CT	Alternative config	NO		
Step	[-]				
Comm object	10599	Related applications	SPtM		
Config level	Advanced				
Setpoint visibility	Visible only in SPtM mode Always				
Description					
Defines source value of the Maine Import I/M (near 574)					

Defines source value of the Mains Import kW (page 574).

None	The Mains import is not measured and the duration of the load transfer in direction Mains to Generator is given exactly by the setpoint Speed/Load Control / Close Transfer Max Duration (page 350).
Mains CT	The Mains Import kW (page 574) value is measured via Mains CTs. The load transfer in direction Mains to Generator is considered to be finished when the mains is unloaded under certain level.
Analog Input	The Mains Import kW (page 574) value is measured via analog input, accordingly LAI: MAINS IMPORT MEASUREMENT (PAGE 773) . The load transfer in direction Mains to Generator is considered to be finished when the mains is unloaded under certain level.

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Subgroup: Peak Shaving

Peak Shaving

Setpoint group			Process Control	Related FW	1.0.0		
Range [units]			Enabled / Disabled [-]				
Default value			Disable	Alternative config	NO		
Step			[-]	[-]			
Comm object			11601	Related applications	SPtM		
Config level			Advanced				
Set	point visibil	ity	Always				
Des	scription						
The	behavior of	oeak	shaving functions				
	Enabled	The cor	Peak Shaving function is active and the start command is activated when the ditions for Peaks Shaving activation were fulfilled.				
Disabled The Peak Shaving function is BLOCK even the conditions for Peaks Shavin			e Peak Shaving function is en the conditions for Peaks	BLOCKED and the start c Shaving activation were f	ommand can not be activated ulfilled.		



Peak Shaving Start Level

Setpoint group	Process Control	Related FW	1.0.0		
Range [units]	Peak Shaving Stop Level (page 240) 32000 [kW]				
Default value	1000 kW	Alternative config	NO		
Step	1 kW				
Comm object	8643	Related applications	SPtM		
Config level	Advanced				
Setpoint visibility	Visible only if Peak Shaving (page 239) = enabled				
Description					

This setpoint starts genset, when the value of the load consumption Load kW exceeds the value given by this setpoint for the time of **Peak Shaving Start/Stop Delay (page 241)**.

The gen-set is synchronized to the Mains (kept in the parallel to the Mains) and the genset power is controlled according to the settings in the Group Process Control/Load Control.

The gen-set stays running until the conditions for Peak Shaving run are active. Conditions of deactivation are given by the setpoint **Peak Shaving Stop Level (page 240)** and **Peak Shaving Start/Stop Delay (page 241)**.

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Peak Shaving Stop Level

Setpoint group	Process Control	Related FW	1.0.0		
Range [units]	0 Peak Shaving Start Level (page 240) [kW]				
Default value	900 kW	Alternative config	NO		
Step	1 kW				
Comm object	8644	Related applications	SPtM		
Config level	Advanced				
Setpoint visibility	Visible only if Peak Shaving (page 239) = enabled				
Description					
This aptraint stops gon act, of the load approximation Load kW/ degreeses under the value given by this					

This setpoint stops gen-set, of the load consumption Load kW decreases under the value given by this setpoint for the time of **Peak Shaving Start/Stop Delay (page 241)**.



Peak Shaving Start/Stop Delay

Setpoint group	Process Control	Related FW	1.0.0			
Range [units]	0600[s]					
Default value	600 s	Alternative config	NO			
Step	1s					
Comm object	9989	Related applications	SPtM			
Config level	Advanced					
Setpoint visibility	Visible only if Peak Shaving (page 239) = enabled					
Description						
Defines of the delay	of activation or deactivatio	n of the Peak Shaving. Sta	arts when:			
The value of t	The value of the load consumption Load kW exceeds the value given by the setpoint Peak Shaving					
Start Level (page 240).						
The value of the load consumption Load kW decreases under the value given by the setpoint Peak						
Shaving Stop Level (page 240)						



Group: Basic settings

Subgroup: Name

Gen-Set Controller Name

Setpoint group	Basic settings	Related FW	1.0.0			
Range [units]	0 15 characters [-]					
Default value	InteliGen	Alternative config	NO			
Step	[-]					
Comm object	8637	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Always					
Description						
User defined name, used for the controller identification at remote phone or mobile connection. Gen-Set Name is maximally 15 characters long and can be entered using InteliConfig or from controller's						

configuration menu.

Note: If the Gen-Set Name is "TurboRunHours", the running hours will be counted faster - 1 minute in real will represent 1 hour.

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Subgroup: Power settings

Nominal Power

Setpoint group	Basic settings	Related FW	1.0.0			
Range [units]	15000 [kW]					
Default value	200 kW	Alternative config	Yes			
Step	1 kW					
Comm object	8276	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Always					
Description						
Naminal news of the gap set. Concreter Overland ROC (name 204) protection is based on this setucint						

Nominal power of the gen-set. Generator **Overload BOC (page 304)** protection is based on this setpoint.

Note: This setpoint is used when setpoint **Connection type (page 244)** is adjusted to Monophase or Splitphase or 3Ph3Wire or High Leg D or 3Ph4Wire or when Autodetect detects connection type as 3Ph3Wire or High Leg D or 3Ph4Wire.

Note: To lock this setpoint against editing you also have to lock setpoint Nominal Power 1 (page 455), Nominal Power 2 (page 459) and Nominal Power 3 (page 463).



Nominal Power Split Phase

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	15000 [kW]				
Default value	200 kW	Alternative config	Yes		
Step	1 kW				
Comm object	9977	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Conditioned by the setpoi	nt Connection type (pag	e 244)		
Description					

Nominal power of the gen-set for detected split-phase or mono phase connection. Generator **Overload BOC** (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint **Connection type (page 244)** is adjusted to Autodetect and Autodetect detects connection type as Monophase or Splitphase.

Note: To lock this setpoint against editing you also have to lock setpoint Nominal Power Split Phase 1 (page 455), Nominal Power Split Phase 2 (page 459) and Nominal Power Split Phase 3 (page 463).

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Subgroup: Current settings

Nominal Current

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	1 10 000 [A]				
Default value	350 A	Alternative config	YES		
Step	1A				
Comm object	8275	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Conditioned by the setpo	int Connection type (pag	e 244).		
Description					
It is current limit for mains current protections and means maximal continuous mains current. Nominal Current can be different from mains rated current value.					

Note: To lock this setpoint against editing you also have to lock setpoint **Nominal Current 1** (page 456), Nominal Current 2 (page 460) and Nominal Current 3 (page 464).



CT Ratio

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	1 5 000 [A/5A]				
Default value	2 000 A/5A	Alternative config	NO		
Step	1 A/5A				
Comm object	8274	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	etpoint visibility Always				
Description					
Gen-set Mains import current transformers ratio.					
Note: Generator Mains currents and power measurement is suppressed if current level is below 1%					

CT range.

O back to List of setpoints

Mains Import CT Ratio

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	1 2 000 [A/5A]				
Default value	500 A/5A	Alternative config	NO		
Step	1 A/5A				
Comm object	8566	Related applications	SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Mains current transformers ratio.					
Note: Generator currents and power measurement is suppressed if current level is below 1% of CT range.					

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Subgroup: Voltage settings

Connection type

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	Mono Phase / SplitPhase / 3Ph3Wire / High Leg D / 3Ph4Wire / Autodetect [-]			
Default value	3Ph4Wire	Alternative config	YES	
Step	[-]			
Comm object	11628	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Connection type:				



Mono Phase	Single phase voltage measurement L1-N			
	1x CT (Current Transformer)			
Split Phase	Double Delta connection			
	Split Phase			
	Two phase voltage measurement L	1,L2 with 180° phase shift		
	2x CT (Current Transformer)			
3Ph3Wire	Ungrounded Delta connection			
	Open Delta			
	Ungrounded Wye			
	Corner-Grounded Delta			
	Split Phase Delta			
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift		
	No neutral is available 3x CT (Curre	ent Transformer)		
High Leg D	High Leg Delta connection			
	Three phase voltage measurement L1,L2,L3			
	3x CT (Current Transformer)			
3Ph4Wire	Grounded Star (Grounded Wye) connection – 3PY			
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift		
	3x CT (Current Transformer)			
Autodetect	High Leg Delta	L1>=100V; L1<=140V		
		L2>=140V		
	or	L3>=100V; L3<=140V		
	3PH3Wire or 3Ph4Wire	11 >= 100)/		
	or			
		23 - 1000		
	Split Phase	L1>=100V		
		L2 <= 20V		
	Ŭ.	L3>=100V		
	Mono Phase	11>=100V		
		12 <= 20 V		
	or	$13 \le 20 \text{V}$		
	Voltage Autodetect shutdown			
	- onage Autodeteet shaldown			
Note: To lock this setpoint against editing you also have to lock setpoint Connection Type 1 (page 152). On prostion type 2 (none 157) and Oppmention type 2 (none 157).				
453), Connectio	on type 2 (page 457) and Connection ty	pe 3 (page 461).		



Nominal Voltage Ph-N

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	80 20 000 [V]			
Default value	231 V	Alternative config	YES	
Step	1 V			
Comm object	8277	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Connection type (page 244).			
Description				
Nominal voltage (phase to neutral).				

Note: To lock this setpoint against editing you also have to lock setpoint Nominal Voltage Ph-N 1 (page 457), Nominal Voltage Ph-N 2 (page 461) and Nominal Voltage Ph-N 3 (page 465).

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Nominal Voltage Ph-Ph

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	80 40 000 [V]			
Default value	400 V	Alternative config	YES	
Step	1 V			
Comm object	11657	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Connection type (page 244).			
Description				
Nominal system voltage (phase to phase).				

Note: To lock this setpoint against editing you also have to lock setpoint Nominal Voltage Ph-Ph 1 (page 457), Nominal Voltage Ph-Ph 2 (page 461) and Nominal Voltage Ph-Ph 3 (page 465).

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Gen Mains VT Ratio

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	0,1500,0 [V/V]			
Default value	1,0 V/V	Alternative config	NO	
Step	0,1 V/V			
Comm object	9579	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Generator Mains voltage potential transformers ratio. If no PTs are used, adjust the setpoint to 1.				



Mains/Bus VT Ratio

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	0,1500,0 [V/V]			
Default value	1,0 V/V	Alternative config	NO	
Step	0,1 V/V			
Comm object	9580	Related applications	SPtM	
Config level	Advanced			
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)			
Description				
Mains/Bus voltage potential transformers ratio. If no PTs are used, adjust the setpoint to 1.				

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Subgroup: Frequency settings

Nominal Frequency

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	45 65 [Hz]			
Default value	50 Hz	Alternative config	YES	
Step	1 Hz			
Comm object	8278	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Nominal system frequency (usually 50 or 60 Hz).				
Note: To lock this setpoint against editing you also have to lock setpoint Nominal Frequency 1 (page				

456), Nominal Frequency 2 (page 460) and Nominal Frequency 3 (page 464).



Gear Teeth

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	FGen->RPM / 1 500 [-]			
Default value	120	Alternative config	NO	
Step	1			
Comm object	8252	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				

Number of teeth on the engine flywheel where the pick-up is installed. Set to zero if no pick-up is used and the Engine speed will be counted from the generator frequency.

Note: If no pickup is used, the D+ or W terminal should be used to prevent possible overcranking, which can occur if at least 25% of nominal generator voltage is not present immediately after exceeding firing speed.

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Nominal RPM

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	1004000 [RPM]				
Default value	1 500 RPM	Alternative config	YES		
Step	1 RPM				
Comm object	8253	Related applications	MINT, SPtM		
Config level	Advanced	Advanced			
Setpoint visibility	Always				
Description					
Nominal engine speed (RPM - revolutions per minute).					
Note: To lock this setpoint against editing you also have to lock setpoint Nominal RPM 1 (page 456).					

Nominal RPM 2 (page 460) and Nominal RPM 3 (page 464).



Subgroup: Controller settings

Controller mode

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	OFF / MAN / AUTO[-]			
Default value	OFF	Alternative config	NO	
Step	[-]			
Comm object	8315	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				

This setpoint can be used for changing the Controller mode remotely, e.g. via MODBUS. Use the mode selector on the main screen for changing the mode from the front panel. Use mode selector in the control window for changing the mode from InteliConfig.

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Power On Mode

Set	point group	Basic settings		Related FW	1.0.0	
Rar	nge [units]	Previous / OFF [-]	Previous / OFF [-]			
Def	ault value	Previous	Previous Alternative config NO			
Ste	р	[-]	[-]			
Со	nm object	13000	13000 Related applications MINT, SPtM			
Со	nfig level	Advanced	Advanced			
Set	point visibili	t y Always				
Des	scription					
This setpoint adjusts controller mode after power on of controller.						
	Previous	When controller is po	hen controller is power on, than is switched into last mode before power off.			
	OFF	When controller is po	hen controller is power on, than is switched into OFF mode.			

Note: Remote modes - In case that some LBI remote mode is activated during power on of controller than this LBI has higher priority than this setpoint - controller mode is forced into mode selected via LBI. After deactivation of LBI, controller is switched into value selected via setpoint Power On Mode



Reset To Manual

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	Disabled / Enabled [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	9983	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			
If this function is enabled, the controller will ewitch automatically to MAN mode when there is a red clarm in			

If this function is enabled, the controller will switch automatically to MAN mode when there is a red alarm in the alarm list and fault reset button is pressed. This is a safety function that prevents the gen-set starting again automatically in specific cases when fault reset button is pressed.

Example: Controller is in AUTO mode and there is red inactive unconfirmed alarm and fault reset button is pressed, controller will start automatically.

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Backlight Timeout

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	Disabled / 1 255 [min]		
Default value	Disabled	Alternative config	NO
Step	1 min		
Comm object	10121	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			
The diaplay healtlight is switched off when this timer avaged. When extraint is adjusted to dischold then the			

The display backlight is switched off when this timer exceed. When setpoint is adjusted to disabled then the display will be backlighted all the time.



Horn Timeout

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	Disabled / 1 599 [s]			
Default value	10 s	Alternative config	NO	
Step	1s			
Comm object	8264	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Setting of horn behavior.				
Disabled Dis	bled Disabling the Horn sounding function			
1 599 [s] Tir thi	meout for HORN (PAGE 722) binary output. The HORN (PAGE 722) output is opened when is timeout elapsed.			
Note: Horn timeout starts again from the beginning if a new alarm appears before previous Horn timeout has elapsed.				

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Main Screen

Setpoint grou	ıp	Basic settings Related FW 1.0.0			
Range [units]]	PwrFactor/ATT/Run Hours [-]			
Default value		PwrFactor Alternative config NO			
Step		F			
Comm object	t	13346 Related applications MINT, SPtM			
Config level		Advanced			
Setpoint visit	bility	Always			
Description					
Setpoint adjust value which is shown on main screen.					
PwrFactor:	Value of power factor is shown on main screen.				
ATT:	This option is for Tier IV Final support. In this case value of DEF Level is shown on main screen.				
Run Hours:	Value of running hours will be shown on main screen.				



Subgroup: Phase rotation

Phase Rotation

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	Clockwise / CounterCCW [-]		
Default value	Clockwise	Alternative config	NO
Step	[-]		
Comm object	15122	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	All the time		
Description			
This setpoint adjust the phase sequence of voltage terminals.			

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Group: Communication Settings

Subgroup: Controller CAN Address

Controller Address

Setpoint group	Communication Settings	Related FW	1.0.0
Range [units]	132[-]		
Default value	1	Alternative config	NO
Step	1		
Comm object	24537	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Controller identification number. It is possible to set controller address different from the default value (1) so that more controllers can be interconnected (via RS485) and accessed e.g. from MODBUS terminal.			

Note: When opening connection to the controller it's address has to correspond with the setting in PC tool.


Subgroup: RS485 Settings

RS485 Mode

Set	point group	Communication Settings	Related FW	1.0.0		
Range [units]		Direct / MODBUS [-]	irect / MODBUS [-]			
Default value		Direct	Alternative config	NO		
Step		H				
Comm object		24134	Related applications	MINT, SPtM		
Config level		Standard				
Set	point visibility	Always				
Des	scription					
Communication protoc		ocol switch for on-board R	S485.			
Direct I		InteliConfig commu	InteliConfig communication protocol via serial cable.			
MODBUS		MODBUS protocol	MODBUS protocol.			

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RS485 Communication Speed

Setpoint group	Communication Settings	Related FW	1.0.0		
Range [units]	9600 / 19200 / 38400 / 57600 / 115200 [bps]				
Default value	57600 bps	Alternative config	NO		
Step	[-]				
Comm object	24135	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
If the direct mode is selected on on-board RS485, the direct communication speed of controller part of line can be adjusted here. Speed of second part of line has to be adjusted to the same value.					

Note: Winscope supports only 19200, 38400, 57600 speeds.



RS485 MODBUS Speed

Setpoint group	Communication Settings	Related FW	1.0.0		
Range [units]	9600 / 19200 / 38400 / 57600 / 115200 [bps]				
Default value	9600 bps	Alternative config	NO		
Step	[-]				
Comm object	24141	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint COM1 Mode (page 466)				
Description					
If the MODBUS mode is selected on COM1 channel, the MODBUS communication speed can be adjusted here.					

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Group: Ethernet

Subgroup: NTP Settings

NTP Clock Synchronization

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0		
Range [units]	DISABLED / ENABLED [-]				
Default value	DISABLED	Alternative config	NO		
Step	[-]				
Comm object	24075	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)				
Description					
This setpoint is used to enable/disable controller time synchronization with exact time from an NTP server.					
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.					



NTP Server

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	[-]				
Default value	pool.ntp.org	Alternative config	NO		
Step	[-]				
Comm object	24074	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed				
Description					
NTP server address.					

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Subgroup: TCP/IP Settings

IP Address Mode

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	FIXED / AUTOMATIC [-]			
Default value	AUTOMATIC	Alternative config	NO	
Step	[-]			
Comm object	24259	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is	installed		
Description				
The setpoint is used	to select the method how t	he ethernet connection is a	adjusted.	
DISABLED: T	D: The Ethernet connection is fixed by means of the setpoints <u>IP Addr</u> , <u>NetMask</u> , <u>GateIP</u> , DNS IP Address.			
T ori W ENABLED: T ori su th	his method should be used for a classic Ethernet or internet connection. When this type connection opens, the controller is specified by its IP address. This means that it ould be inconvenient if the IP address were not fixed (static). The Ethernet connection setting is obtained automatically from the DHCP server . The obtained settings are then copied to the related setpoints. If the process of obtaining the ettings from the DHCP server is not successful, the value 000.000.000.000 is copied to be setpoint IP address and the module continues to try to obtain the settings.			



IP Address

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	Valid IP address [-]			
Default value	192.168.1.254	Alternative config	NO	
Step	[-]			
Comm object	24376	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint IP Address Mode (page 255)			
Description				

The setpoint is used to select the method how the IP Address is adjusted.

If **IP Address Mode (page 255)** is FIXED this setpoint is used to adjust the IP address of the ethernet interface of the controller. Ask your IT specialist for help with this setting.

If **IP Address Mode (page 255)** is AUTOMATIC this setpoint is inactive. The IP address is assigned by the DHCP server.

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Subnet Mask

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	Valid IP address [-]			
Default value	255.255.255.0	Alternative config	NO	
Step	[-]			
Comm object	24375	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint IP Address Mode (page 255)			
Description				

The setpoint is used to select the method how the Subnet Mask is adjusted.

If **IP Address Mode (page 255)** is FIXED this setpoint is used to adjust the Subnet Mask. Ask your IT specialist for help with this setting.

If **IP Address Mode (page 255)** is AUTOMATIC this setpoint is inactive. The Subnet Mask is assigned by the DHCP server.



Gateway IP

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	Valid IP address [-]			
Default value	192.168.1.1	Alternative config	NO	
Step	[-]			
Comm object	24373	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint IP Address Mode (page 255)			

Description

The setpoint is used to select the method how the Gateway IP is adjusted.

If **IP Address Mode (page 255)** is DISABLE this setpoint is used to adjust the IP address of the gateway of the network segment where the controller is connected.

If **IP Address Mode (page 255)** is ENABLED this setpoint is used to display the gateway IP address which has been assigned by the DHCP server.

A gateway is a device which connects the respective segment with the other segments and/or Internet.

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DNS Mode

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	Automatic / Manual [-]			
Default value	Automatic	Alternative config		
Step	[-]			
Comm object	24101	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility				
Description				

This setpoint enables to enter DNS server addresses manually, even with the **IP Address Mode (page 255)** set to Automatic.

Automatic DNS server addresses automatically obtained from a DHCP server are used

DNS IP Address 1 (page 258) and DNS IP Address 2 (page 258) can be adjusted manually.

Manual Use this option to resolve e.g. internet access policy related issue, if local DNS server addresses automatically obtained from a DHCP server do not work



DNS IP Address 1

Setpoint group	Ethernet	Related FW	1.0.0			
Range [units]	Valid IP address [-]					
Default value	8.8.8.8	Alternative config	NO			
Step	[-]					
Comm object	24362	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Only if relevant module is installed					
Description						
The setpoint is used to select the method how the DNS Address 1 is adjusted						

If **IP Address Mode (page 255)** is FIXED this setpoint is used to adjust the domain name server (DNS), which is needed to translate domain names in email addresses and server names into correct IP addresses.

If **IP Address Mode (page 255)** is AUTOMATIC this setpoint is inactive. The DNS server IP address is assigned by the DHCP server.

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DNS IP Address 2

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	Valid IP address [-]			
Default value	8.8.8.8	Alternative config	NO	
Step	[-]			
Comm object	24331	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				

The setpoint is used to select the method how the DNS Address 2 is adjusted.

If **IP Address Mode (page 255)** is FIXED this setpoint is used to adjust the domain name server (DNS), which is needed to translate domain names in email addresses and server names into correct IP addresses.

If **IP Address Mode (page 255)** is AUTOMATIC this setpoint is inactive. The DNS server IP address is assigned by the DHCP server.



IP Firewall

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	ENABLED / DISABLED	ENABLED / DISABLED [-]			
Default value	DISABLED	Alternative config			
Step	[-]				
Comm object	24092	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility					
Description					
This setpoints en	ables to switch on the built	-in Firewall functionality.			
DISABLED	The firewall function is switched off				
ENABLED	The firewall function is switched on, use InteliConfig to setup the firewall rules (configuration card Others - Firewall)				

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Subgroup: AirGate Settings

AirGate Connection

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	DISABLED / ENABLED	DISABLED / ENABLED [-]			
Default value	ENABLED	Alternative config	NO		
Step	[-]				
Comm object	24365	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Only if relevant module is	Only if relevant module is installed			
Description					
This setpoint selects the Ethernet connection mode.					
DISABLED: T th fr y	This is a standard mode in which the controller listens to the incoming traffic and answers the TCP/IP queries addressed to it. This mode requires the controller to be accessible from the remote device (PC), i.e. it must be accessible at a public and static IP address if you want to connect to it from the internet.				
ENABLED T	is mode enables the AirGate service. The AirGate server address is adjusted by the tooint AirGate Address (page 260) . Also the standard TCP/IP is enabled.				



AirGate Address

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	[-]			
Default value	airgate.comap.cz	Alternative config	NO	
Step	[-]			
Comm object	24364	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)			
Description				

This setpoint is used for entering the domain name or IP address of the AirGate server. Use the free AirGate server provided by ComAp at airgate.comap.cz.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.

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AirGate Data Port

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	0 65535 [-]				
Default value	23	Alternative config			
Step	1				
Comm object	24096	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility					
Description	Description				
This port is used for TCP data communication with the AirGate server.					
Note: Use port 21, 23 or 6127 for standard ComAp AirGate service.					



AirGate Signalling Port

Setpoi	int group	Ethernet	Related FW	1.0.0	
Range	[units]	065535 [-]			
Defaul	t value	6127	Alternative config		
Step		[-]			
Comm	n object	24358	Related applications	MINT, SPtM	
Config	g level	Standard			
Setpoi	int visibility				
Descri	Description				
Thi	This port is used for UDP signalling communication with the AirGate server.				
	Note: Use port 6127 for standard ComAp AirGate service.				

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Subgroup: Messages Settings

Event Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]	ON / OFF [-]		
Default value	ON	Alternative config	NO	
Step	[-]			
Comm object	10926	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
This setpoint enables or disables Event Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				



Wrn Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]			
Default value	ON	Alternative config	NO	
Step	[-]			
Comm object	8482	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
This setpoint enables or disables Wrn Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				

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BOC Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]			
Default value	ON	Alternative config	NO	
Step	[·]			
Comm object	10566	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
This setpoint enables or disables BOC Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				

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Sd Messages

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]			
Default value	ON	Alternative config	NO	
Step	F			
Comm object	8484	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
This setpoint enables or disables Sd Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				



Time Zone

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	GMT-12:00 GMT+13:00 [hours]			
Default value	GMT+1:00 hour	Alternative config	NO	
Step	[-]			
Comm object	24366	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				

This setpoint is used to select the time zone where the controller is located. See your computer time zone setting (click on the time indicator located in the rightmost position of the Windows task bar) if you are not sure about your time zone.

Note: If the time zone is not selected properly the active e-mails may contain incorrect information about sending time, which may result in confusion when the respective problem actually occurred.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.

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E-mail/SMS Language

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0		
Range [units]	[-]				
Default value	English	Alternative config	NO		
Step	[-]				
Comm object	24299	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed				
Description	Description				
Use this setpoint to set the language of SMS and e-mail.					
Note: Numbers correspond with languages in language list.					
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules					



Subgroup: E-mail Settings

Email Address 1

Setpoint group	Ethernet	Related FW	1.0.0	
Range [units]	063 characters [-]	063 characters [-]		
Default value	[-]	Alternative config	NO	
Step	H			
Comm object	24298	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.				
Note: This setpo	pint is common for Etherner	t, CM-GPRS and CM-4G-0	GPS modules.	

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Email Address 2

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24297	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet. CM-GPRS and CM-4G-GPS modules.			

O back to List of setpoints

Email Address 3

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	H		
Comm object	24145	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			



Email Address 4

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	H		
Comm object	24144	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

O back to List of setpoints

SMTP UserName

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	F		
Comm object	24370	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Use this setpoint to enter the username for the SMTP server. Leave the setpoint blank if the SMTP server			

does not require authentication.

O back to List of setpoints

SMTP User Password

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	015 characters [-]		
Default value	[-]	Alternative config	NO
Step	F		
Comm object	24369	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Use this setpoint to enter the password for the SMTP server. Leave the setpoint blank if the SMTP server			

does not require authentication.



SMTP Server Address

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	airgate.comap.cz:9925	Alternative config	NO
Step	H		
Comm object	24368	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint is used for entering the domain name (e.g. smtp.yourprovider.com) or IP address (e.g.			

74.125.39.109) or number of port (with colon like a first mark) of the SMTP server. Ask your internet provider or IT manager for this information.

O back to List of setpoints

SMTP Sender Address

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[·]		
Comm object	24367	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter an existing email address into this setpoint. This address will be used as sender address in active emails that will be sent from the controller.

Note: It is not needed to enter an existing email address, nevertheless valid email format needs to be followed.

IMPORTANT: This item is obligatory when emails are configured.



Subgroup: SNMP Settings

SNMP Agent

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	DISABLED / ENABLED [-]		
Default value	DISABLED	Alternative config	NO
Step	F		
Comm object	24336	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enable or disable SNMP v1 Agent.			

O back to List of setpoints

SNMP RD Community String

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	public	Alternative config	NO
Step	[-]		
Comm object	24335	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint SNMP Agent (page 267)		
Description			
SNMP Community String only for reading.			

O back to List of setpoints

SNMP WR Community String

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	private	Alternative config	NO
Step	H		
Comm object	24334	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint SNMP Agent (page 267)		
Description			
SNMP Community String for writing and reading.			



SNMP Traps IP Address 1

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	Valid IP address [-]		
Default value	DISABLED	Alternative config	NO
Step	[-]		
Comm object	24294	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
IP address 1 for receiving SNMP Traps. Leave this setpoint blank if SNMP traps should not be send.			

O back to List of setpoints

SNMP Traps IP Address 2

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	Valid IP address [-]		
Default value	DISABLED	Alternative config	NO
Step	[-]		
Comm object	24293	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
IP address 2 for receiving SNMP Traps. Leave this setpoint blank if SNMP traps should not be send.			

O back to List of setpoints

SNMP Trap Format

Setpoint group E		Etherr	net	Related FW	1.0.0	
Range [units]		v1 Tra	ap / v2 Notific / v2 In	ıform [-]		
Default value v2 li		v2 Info	orm	Alternative config		
Ste	р	[-]				
Comm object 241		24136	i	Related applications	MINT, SPtM	
Config level		Stand	itandard			
Set	point visibility					
Des	scription					
This setpoint enables to select format of the SNMP trap messages.						
v1 Trap		SNMPv1 trap format is used				
	v2 Notific		SNMPv2c Notification format is used			
	v2 Inform		SNMPv2c Inform format is used			



Subgroup: MODBUS Settings

MODBUS Server

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	DISABLED / ENABLED [-]				
Default value	Disabled	Alternative config	NO		
Step	[-]				
Comm object	24337	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed				
Description					
Enable or disable MODBUS communication via ethernet interface.					

O back to List of setpoints

MODBUS Client Inactivity Timeout

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	065535[s]				
Default value	60 s	Alternative config			
Step	1s				
Comm object	24097	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility					
Description					
Modbus connection (TCP socket) is closed by controller, if a Modbus client does not communicate for this time.					

O back to List of setpoints

Subgroup: ComAp Client Settings

Direct Connection

Setpoint group	Ethernet	Related FW	1.0.0		
Range [units]	ge [units] Disabled / Enabled [-]				
Default value	Enabled	Alternative config			
Step	[-]				
Comm object	24099	Related applications	MINT, SPtM		
Config level	evel Standard				
Setpoint visibility					
Description					
Use this to enable/disable direct connection of a ComAp client (e.g. InteliConfig) to the IP address of the controller.					
Note: For Direct connection the controller IP address must be reachable from the client			chable from the client IP address.		



Direct Connection Port

Setpoint group	Ethernet	Related FW	1.0.0			
Range [units]	0 65535 [-]					
Default value	23	Alternative config				
Step	[-]					
Comm object	24374	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Setpoint visibility					
Description						
This port is used to li	This port is used to listen for an incoming TCP connection if Direct Connection is ENABLED.					

O back to List of setpoints

ComAp Client Inactivity Timeout

Setpoint group	Ethernet	Related FW	1.0.0			
Range [units]	065535 [s]					
Default value	60 s	Alternative config				
Step	1s					
Comm object	24098	Related applications	MINT, SPtM			
Config level	Standard	Standard				
Setpoint visibility						
Description						
Connection (TCP socket) is closed by controller, if a client (e.g. InteliConfig) does not communicate for this time. This timeout applies to both direct and AirGate connection.						

O back to List of setpoints

Group: Engine settings

Subgroup: Starting



Fuel Solenoid

Setpoint group		Engine settings	Related FW	1.0.0	
Range [units]		Diesel / Gas [-]			
Default value		Diesel	Alternative config	NO	
Step		[-]			
Comm object		9100	Related applications	MINT, SPtM	
Config lev	/el	Advanced			
Setpoint v	/isibility	Always			
Descriptio	on				
Determine	s behavior	of the Binary output FUEL	Solenoid (page 715)		
Diesel:	Output cl	oses before binary output STARTER (PAGE 737). Lead of output is adjusted via setpoint			
Fuel Sol		enoid Lead (page 276). The output opens if Emergency Stop comes or gen-set is			
stopped		and in pause between repeated starts.			
Gas: Output cl value). C		oses together with binary output IGNITION (PAGE 723) if RPM is over the 30 RPM (fixed output opens after stop command or in pause between repeated start.			

O back to List of setpoints

Cranking Attempts

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	1 10 [-]				
Default value	3	Alternative config	NO		
Step	1				
Comm object	8255	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Maximal number of cranking attempts.					



Maximum Cranking Time

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	1 255 [s]				
Default value	5 s	Alternative config	NO		
Step	1s				
Comm object	8256	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Always				
Description					
Maximum time limit of cranking time					

Maximum time limit of cranking time.

IMPORTANT: There is a protection against broken pinion on starter. In case that there are no RPM after 5 seconds of starting, cranking is interrupted and cranking fail pause follows.

O back to List of setpoints

Cranking Fail Pause

Setpoint group	Engine settings	Related FW	1.0.0			
Range [units]	560[s]	560 [s]				
Default value	8 s	Alternative config	NO			
Step	1s					
Comm object	8257	Related applications	MINT, SPtM			
Config level	Advanced	Advanced				
Setpoint visibility	Always					
Description						
Pause between Cranking Attempts (page 271) . PRESTART (PAGE 732) output is active in this pause until Cranking Fail Pause elapses.						



Prestart Time

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0600[s]		
Default value	2 s	Alternative config	NO
Step	1 s		
Comm object	8394	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
B • <i>A</i>			

Description

Time of closing of the **PRESTART** (PAGE 732) output prior to the engine start. Set to zero if you want to leave the output **PRESTART** (PAGE 732) open.



O back to List of setpoints

Starting RPM

Setpoint group	Engine settings	Related FW	1.0.0			
Range [units]	550 [%]					
Default value	25%	Alternative config	NO			
Step	1 % of Nominal RPM (page 248)					
Comm object	8254	Related applications	MINT, SPtM			
Config level	Advanced					
Setpoint visibility	Always	Always				
Description						
This setpoint defines the "firing" speed level as percent value of the Nominal RPM (page 248) . If this level is exceeded the engine is considered as started.						



Starting Oil Pressure

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	0,0 10,0 [bar]				
Default value	4,5 bar	Alternative config	NO		
Step	0,1 bar				
Comm object	9681	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Oil pressure limit for starting. The controller will stop cranking (STARTER (PAGE 737) goes OFF) if the oil pressure rises above this limit.					

IMPORTANT: Value from analog input has higher priority than value from ECU.

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D+Function

Setpoint g	roup	Engine sett	tings	Related FW		1.0.0
Range [uni	its]	Enabled / C	ChargeFail / Dis	abled [-]		
Default val	ue	Disabled		Alternative config	3	NO
Step		[-]				
Comm obj	ect	9683		Related application	ons	MINT, SPtM
Config leve	el	Standard				
Setpoint vi	sibility	Always				
Description	n					
Behavior of	D+ terminal.					
Enabled	The dete	D+ terminal is ection.	s used for both t	unctions – "running e	engine"	detection and charge fail
ChargeFail	The	D+ terminal is	s used for charg	e fail detection only		
Disabled	The	D+ terminal is	s not used.			
Perecent of Battery Voltage						
	 	Cranking	Starting	Runni	ing	
			Idle Time	Minimal Stabili	ization Time	
100 % — 80 % —						
						Alternator Voltage
0% —						D+
	Prestart Time	Maximum Cranking Time				-
	l Start	I Starting RPM			I	- ïme
			Image 9.2	D+ Function 1		





O back to List of setpoints

Glow Plugs Time

Setpoint group	Engine settings	Related FW	1.0.0			
Range [units]	0 Prestart Time (page	0 Prestart Time (page 273) [s]				
Default value	0 s	Alternative config	NO			
Step	1s					
Comm object	14412	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Always					
Description						
This setpoint defines the time before starting when logical binary output GLOW PLUGS (PAGE 720) will be close.						



Subgroup: Starting Timers

Fuel Solenoid Lead

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	0,0 25,0 [s]			
Default value	0,5 s	Alternative config	NO	
Step	0,1 s			
Comm object	10525	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			

Description

Delay between FUEL SOLENOID (PAGE 715) and STARTER (PAGE 737) logical binary inputs.FUEL SOLENOID (PAGE 715) is closed before STARTER (PAGE 737). Lead time is adjusted via this setpoint.



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Idle Time

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	0600[s]				
Default value	12 s	Alternative config	NO		
Step	1 s				
Comm object	9097	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Idle Time delay starts when RPM exceeds Starting RPM (page 273) . Start fail is detected when during Idle state RPM decreases below 2 RPM.					

The output IDLE/NOMINAL (PAGE 723) remains inactive during the idle period. Binary output Idle/Nominal opens during Cooling period again. This output can be used for switching the governor between idle and nominal speed.





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Minimal Stabilization Time

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	1 Maximal Stabilization Time (page 279) [s]			
Default value	2 s	Alternative config	NO	
Step	1s			
Comm object	8259	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				

Description

When the gen-set has been started and the idle timer has elapsed, the controller will wait for a period adjusted by this setpoint before closing GCB, even if the generator voltage and frequency are already in limits.



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Maximal Stabilization Time

Sotpoint group	Engine settings	Polatod EW	100		
Selpoint group	Engine settings		1.0.0		
Range [units]	Minimal Stabilization Time (page 278) 300 [s]				
Default value	10 s	Alternative config	NO		
Step	1 s				
Comm object	8313	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Always				

Description

When the gen-set has been started and the idle timer has elapsed, the generator voltage and frequency must get within limits within this period of time, otherwise an appropriate shutdown alarm (generator voltage and/or frequency) is issued.



O back to List of setpoints

Protection Hold Off

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	0,0300,0 [s]				
Default value	5,0 s	Alternative config	YES		
Step	0,1 s				
Comm object	10023	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Always				
Description					
During the start of the gen-set, some engine protections have to be blocked (e.g. Oil pressure). The protections are unblocked after the Protect Hold Off. The time starts after reaching Starting RPM.					



Sd Ventilation Time

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	060[s]				
Default value	5 s	Alternative config	NO		
Step	1s				
Comm object	9695	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Always				
Description					
In case Fuel Solenoid (page 271) is set to GAS, the Sd Ventilation Time adjusts the time of the starter to be switched on for engine pre-ventilation in the case of a first start attempt after shutdown or controller					

switch-on.

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Subgroup: Stopping

Cooling Speed

Se	tpoint group	Engine settings	Related FW	1.0.0			
Ra	nge [units]	Idle / Nominal [-]					
De	fault value	Nominal	Alternative config	NO			
Ste	эр	[-]					
Co	omm object	10046	Related applications	MINT, SPtM			
Co	onfig level	Advanced					
Se	tpoint visibilit	y Always					
De	scription						
Se	lects the function	on of the binary output IDLE/	NOMINAL (PAGE 723) during	g engine cooling state.			
ld	e C	Cooling is executed at Idle sp	beed and generator protection	ons are switched off.			
No	ominal C	Cooling is executed at Nomir	nal speed and generator pro	tections are active.			
	Note: When ECU is connected the predefined value 900 RPM for Idle speed is requested.						
	Note: Binary output IDLE/NOMINAL (PAGE 723) must be configured and connected to speed governor. Engine Idle speed must be adjusted on speed governor.						



Subgroup: Stopping Timers

Cooling Time

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	03600[s]				
Default value	30 s	Alternative config	NO		
Step	1s				
Comm object	8258	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Runtime of the unloa	ded gen-set to cool the en	gine before stop.			

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Stop Time

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0600[s]		
Default value	60 s	Alternative config	NO
Step	1s		
Comm object	9815	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		

Description

Under normal conditions the engine must certainly stop within this period after the FUEL SOLENOID (PAGE 715) has been de-energized and the STOP SOLENOID (PAGE 738) energized. The Stop Solenoid output is deactivated 12 s after last running engine indication went off.







O back to List of setpoints

After Cooling Time

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	03600[s]		
Default value	180 s	Alternative config	NO
Step	1s		
Comm object	8662	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Runtime of engine after cooling pump. Binary output Cooling pump is closed when the engine starts and opens AfterCool time delayed after gen-set stops.			

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Subgroup: Power switch

Power Switch On

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	032000 [kW]		
Default value	100 kW	Alternative config	NO
Step	1 kW		
Comm object	11658	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if the logical binary output POWER SWITCH (PAGE 732) is configured.		
Description			
Threshold level for switching the binary output POWER SWITCH (PAGE 732) on.			





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Power Switch Off

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0 32 000 [kW]		
Default value	50 kW	Alternative config	NO
Step	1 kW		
Comm object	11659	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if the logical bi	nary output Power Switch	I (PAGE 732) is configured.

ComAp >



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Subgroup: Engine Protections

Overspeed Sd

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	50200[%]		
Default value	115%	Alternative config	NO
Step	1 % of Nominal RPM (page 248)		
Comm object	8263	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for over speed protection. Relative to the nominal speed.			



Starting Overspeed Sd

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	100200 [%]		
Default value	115 %	Alternative config	NO
Step	1 %		
Comm object	11033	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

The rise up threshold for overspeed protection. The time for which this level is accepted is defined as **Starting Overspeed Time (page 287)**. This period starts to be counted once the RPM exceeds the value **Starting RPM (page 273)**. The threshold **Overspeed Sd (page 285)** starts to be valid once this period elapsed.

The type of reaction of the overspeed protection within the **Starting Overspeed Time (page 287)** is defined by the setpoint **Starting Overspeed Protection (page 287)**, so it is either considered as Sd Overspeed or unsuccessful start attempt. Then the next start attempt is enabled once the engine was stopped. History record Starting Overspeed should be written in this case.



Image 9.15 Staring speed overshoot > Ovespeed Sd





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Starting Overspeed Time

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0255[s]		
Default value	5 s	Alternative config	NO
Step	1s		
Comm object	14108	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Time when Starting Overspeed Sd (page 286) level is used for overspeed protection. This time starts			

countdown when starting RPM are reached.

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Starting Overspeed Protection

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	OverSpd Sd / NextStartAt [-]		
Default value	OverSpd Sd	Alternative config	NO
Step	[-]		
Comm object	15808	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Time of protection of the overspeed in Starting Overspeed Time (page 287)			

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Oil Pressure Wrn

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	12895	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input OIL PRESSURE (PAGE 774) is configured		
Description			
Warning or history threshold level for OIL PRESSURE (PAGE 774).			



Oil Pressure Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	12779 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input OIL PRESSURE (PAGE 774) is configured			
Description				
Shutdown threshold level for OIL PRESSURE (PAGE 774).				

O back to List of setpoints

Oil Pressure Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0 900 [s]		
Default value	3 s	Alternative config	NO
Step	1s		
Comm object	14341	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input OIL PRESSURE (PAGE 774) is configured or logical binary input OIL PRESSURE (PAGE 674) is configured		
Description			
Delay for OIL PRESSURE (PAGE 774).			

O back to List of setpoints

ECU Oil Pressure Wrn

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is defined by ECU sensor curve		
Default value	the value is defined by ECU sensor curve	Alternative config	YES
Step	the step is defined by ECU sensor curve		
Comm object	14426Related applicationsMINT, SPtM		
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Warning threshold level for Oil pressure which is send from ECU.			


ECU Oil Pressure Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by ECU sensor curve			
Default value	the value is defined by ECU sensor curve	Alternative config	NO	
Step	the step is defined by ECU sensor curve			
Comm object	14425	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if ECU is configured			
Description				
Shutdown threshold level for Oil pressure which is send from ECU.				

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ECU Oil Pressure Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900[s]		
Default value	3 s	Alternative config	NO
Step	1s		
Comm object	14427	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Delay for Oil pressure which is send from ECU.			

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Coolant Temperature Wrn

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	12896	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input COOLANT TEMP (PAGE 771) is configured			
Description				
Warning or history threshold level for COOLANT TEMP (PAGE 771).				



Coolant Temperature Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	12780	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input COOLANT TEMP (PAGE 771) is configured			
Description				
Shutdown or BOC threshold level for COOLANT TEMP (PAGE 771).				

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Coolant Temperature Delay

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	5 s	Alternative config	NO	
Step	1s			
Comm object	14342	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input COOLANT TEMP (PAGE 771) is configured or logical binary input COOLANT TEMP (PAGE 664) is configured			
Description				
Delay for COOLANT TEMP (PAGE 771).				

O back to List of setpoints

ECU Coolant Temperature Wrn

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is defined by ECU sensor curve		
Default value	the value is defined by ECU sensor curve	Alternative config	NO
Step	the step is defined by ECU sensor curve		
Comm object	14429 Related applications MINT, SPtM		
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Warning threshold level for Coolant temperature which is send from ECU.			



ECU Coolant Temperature Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by ECU sensor curve			
Default value	the value is defined by ECU sensor curve	Alternative config	NO	
Step	the step is defined by ECU sensor curve			
Comm object	14428	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if ECU is configured			
Description				
Shutdown or BOC threshold level for Coolant temperature which is send from ECU.				

O back to List of setpoints

ECU Coolant Temperature Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900 [s]		
Default value	5 s	Alternative config	NO
Step	1s		
Comm object	14430	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Delay for Coolant temperature which is send from ECU.			

O back to List of setpoints

Oil Temp Wrn

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	15747	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input OIL TEMP (PAGE 775) is configured			
Description				
Warning or history threshold level for OIL TEMP (PAGE 775).				



Oil Temp Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	15748	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input OIL TEMP (PAGE 775) is configured			
Description				
Shutdown threshold level for OIL TEMP (PAGE 775).				

O back to List of setpoints

Oil Temp Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900[s]		
Default value	3 s	Alternative config	NO
Step	1s		
Comm object	15749	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input OIL TEMP (PAGE 775) is configured		
Description			
Delay for OIL TEMP (PAGE 775).			

O back to List of setpoints

ECU Oil Temp Wrn

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is defined by ECU sensor curve		
Default value	the value is defined by ECU sensor curve	Alternative config	NO
Step	the step is defined by ECU sensor curve		
Comm object	15637	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Warning threshold level for Oil temperature which is send from ECU.			



ECU Oil Temp Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by ECU sensor curve			
Default value	the value is defined by ECU sensor curve	Alternative config	NO	
Step	the step is defined by ECU sensor curve			
Comm object	15636	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if ECU is configured			
Description				
Shutdown threshold level for Oil temperature which is send from ECU.				

O back to List of setpoints

ECU Oil Temp Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900[s]		
Default value	3 s	Alternative config	NO
Step	1s		
Comm object	15638	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Delay for Oil temperature which is send from ECU.			



Temperature Switch On

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is define by sens	or curve (analog or ECU)		
Default value	the value is defined by sensor curve (analog or ECU)	Alternative config	NO	
Step	the step is defined by sensor curve (analog or ECU)			
Comm object	8688	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output TEMPERATURE SWITCH (PAGE 740) is configured.			
Description				
Threshold level for switching the binary output TEMPERATURE SWITCH (PAGE 740) on.				
Note: Value from analog input has higher priority than ECU.				





Temperature Switch Off

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is define by sensor curve (analog or ECU)		
Default value	the value is defined by sensor curve (analog or ECU)	Alternative config	NO
Step	the step is defined by sens	or curve (analog or ECU)	
Comm object	8689	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output TEMPERATURE SWITCH (PAGE 740) is configured.		

Description

Threshold level for switching the binary output TEMPERATURE SWITCH (PAGE 740) off.

Note: Value from analog input has higher priority than ECU.



O back to List of setpoints

Coolant Temperature Low Wrn

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	YES	
Step	the step is defined by analog sensor curve			
Comm object	9684	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Visible only if the logical analog input COOLANT TEMP (PAGE 771) is configured			
Description				
Threshold level for lower limit of COOLANT TEMP (PAGE 771).				



Coolant Temperature Low Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900[s]		
Default value	5 s	Alternative config	YES
Step	1s		
Comm object	10270	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if the logical analog input COOLANT TEMP (PAGE 771) is configured		
Description			
Delay for Coolant Temperature Low Wrn (page 295).			

O back to List of setpoints

Fuel Level Wrn

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	12897	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input FUEL LEVEL (PAGE 772) is configured			
Description				
Warning or history threshold level for FUEL LEVEL (PAGE 772).				

O back to List of setpoints

Fuel Level Sd

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	12898	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input FUEL LEVEL (PAGE 772) is configured			
Description				
Shutdown or BOC threshold level for FUEL LEVEL (PAGE 772).				



Fuel Level Delay

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	10 s	Alternative config	NO	
Step	1s			
Comm object	14343	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Visible only if the logical analog input FUEL LEVEL (PAGE 772) is configured or logical binary input FUEL LEVEL (PAGE 667) is configured			
Description				
Delay for FUEL LEVEL (PAGE 772).				

O back to List of setpoints

ECU Fuel Level Wrn

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	the range is defined by E0	the range is defined by ECU sensor curve		
Default value	the value is defined by ECU sensor curve	Alternative config	NO	
Step	the step is defined by ECU sensor curve			
Comm object	14432	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if ECU is configured			
Description				
Warning threshold level for Fuel level which is send from ECU.				

O back to List of setpoints

ECU Fuel Level Sd

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	the range is defined by ECU sensor curve		
Default value	the value is defined by ECU sensor curve	Alternative config	NO
Step	the step is defined by ECU sensor curve		
Comm object	14431	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configured		
Description			
Shutdown or BOC threshold level for Fuel level which is send from ECU.			



ECU Fuel Level Delay

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0900[s]		
Default value	10 s	Alternative config	NO
Step	1s		
Comm object	14433	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if ECU is configuredd		
Description			
Delay for Fuel level which is send from ECU.			

O back to List of setpoints

Fuel Tank Volume

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0 10 000 [I]		
Default value	2001	Alternative config	YES
Step	11		
Comm object	11103	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if the logical analog input FUEL LEVEL (PAGE 772) is or ECU is configured		
Description			
Define a capacity of gen-set fuel tank.			

O back to List of setpoints

Maximal Fuel Drop

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	Disabled / 1 50 [%/h]			
Default value	25 %/h	Alternative config	NO	
Step	1%/h			
Comm object	12373	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Setpoint indicates the maximum allowable drop of fuel in fuel tank per running hour. When the engine is not				

running the maximal allowed fuel drop-off is preset to 5% of total tank volume per hour.



Maximal Fuel Drop Delay

Setpoint group	Engine settings	Related FW	1.0.0		
Range [units]	0600[s]				
Default value	5 s	Alternative config	NO		
Step	S				
Comm object	14683	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Always	Always			
Description					
When the value of fuel drop per hour is higher than Maximal Fuel Drop (page 298) this delay stars count down. After count down of this delay alarm Wrn Fuel Theft (page 803) is activated.					

• back to List of setpoints

Fuel Pump On

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	0Fuel Pump Off (page 300) [%]		
Default value	20 %	Alternative config	NO
Step	1 %		
Comm object	10100	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if the logical binary output FUEL PUMP (PAGE 715) is configured and logical binary input FUEL PUMP ON/OFF (PAGE 667) isn't configured		

Description

Threshold level for switching the binary output FUEL PUMP (PAGE 715) on.



Image 9.19 Fuel Pump On

IMPORTANT: When binary input FUEL PUMP ON/OFF (PAGE 667) is configured then binary output FUEL PUMP (PAGE 715) is control by this binary input. Setpoints Fuel Pump On and Fuel Pump Off (page 300) are not evaluated!

Note: Value from analog input has higher priority than ECU.

Note: This setpoint is visible only if the logical binary output FUEL PUMP (PAGE 715) is configured.



Fuel Pump Off

Setpoint group	t group Engine settings Related FW 1.0.0		1.0.0		
Range [units]	Fuel Pump On (page 299) 100 [%]				
Default value	90 %	Alternative config	NO		
Step	1 %				
Comm object	10101	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Visible only if the logical binary output FUEL PUMP (PAGE 715) is configured and logical binary input FUEL PUMP ON/OFF (PAGE 667) isn't configured				
Description					
Threshold level for switchi	ng the binary output FUEL P	UMP (PAGE 715) off.	Fuel pump output		
Image 9.20 Fuel Pump Off IMPORTANT: When binary input FUEL PUMP ON/OFF (PAGE 667) is configured then binary output FUEL PUMP (PAGE 715) is control by this binary input. Setpoints Fuel Pump On (page 299) and Fuel Pump Off are not evaluated!					
Note: Value from anal	Note: Value from analog input has higher priority than ECU.				
Note: This setpoint is	visible only if the logical bin	ary output FUEL PUMP (PAG	E 715) is configured.		



Transfer Wrn Delay

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	Disabled / 1 60 [s]			
Default value	30 s	Alternative config	YES	
Step	1s			
Comm object	10685	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Visible only if the logical binary output FUEL PUMP (PAGE 715) is configured			
Description				
If the controller does not see the fuel increase during fuel transfer within this time alarm Wrn Fuel Transfer Failed (page 818) will be displayed and the FUEL PUMP (PAGE 715) will be turned off. Alarm Wrn Fuel Transfer Failed (page 818) will be displayed but this alarm becomes immediately inactive and it will be				

possible to delete this message by the Fault reset button. If the fault is deleted the controller will initiate the transfer again.

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Subgroup: Battery Protections

Battery Undervoltage

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	8,0 V Battery Overvoltage (page 301) [V]			
Default value	18,0 V	Alternative config	NO	
Step	0,1 V			
Comm object	8387	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Warning threshold for low battery voltage.				

O back to List of setpoints

Battery Overvoltage

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	Battery Undervoltage (page 301) 40,0 [V]			
Default value	36,0 V	Alternative config	NO	
Step	0,1 V			
Comm object	9587	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Warning threshold for high battery voltage.				



Battery <> Voltage Delay

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	0600[s]			
Default value	5 s	Alternative config	NO	
Step	1s			
Comm object	8383	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Delay for Battery Undervoltage (page 301) and Battery Overvoltage (page 301) protection.				

O back to List of setpoints

Battery Charger Fail Delay

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	0 15 [min]			
Default value	5 min	Alternative config	NO	
Step	1 min			
Comm object	11374	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Conditioned with LBI BATTERY CHARGER (PAGE 616)			
Description				
Delay for LBI BATTERY CHARGER (PAGE 616).				

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Subgroup: Maintenance

Maintenance Timer 1

Setpoint group	Engine settings	Related FW	1.0.0
Range [units]	-10 000 9 999 [h] / Disabled		
Default value	1 000 h	Alternative config	NO
Step	1 h		
Comm object	10528	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

Maintenance timer 1 counts down when engine is running. If reaches zero, an alarm appears, but the timer still counting down into negative values. When the value 10000 is set, than the Maintenance function is disabled and counter does not count. Counter value disappear from controllers statistics.



Maintenance Timer 2

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	-10 000 9 999 [h] / Disabled			
Default value	1 000 h	Alternative config	NO	
Step	1 h			
Comm object	10529	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Maintenance timer 2 counts down when engine is running. If reaches zero, an alarm appears, but the timer				

still counting down into negative values. When the value 10000 is set, than the Maintenance function is disabled and counter does not count. Counter value disappear from controllers statistics.

O back to List of setpoints

Maintenance Timer 3

Setpoint group	Engine settings	Related FW	1.0.0	
Range [units]	-10 000 9 999 [h] / Disabled			
Default value	1 000 h Alternative config NO			
Step	1 h			
Comm object	10530	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Maintenance timer 3 counts down when engine is running. If reaches zero, an alarm appears, but the timer				

still counting down into negative values. When the value 10000 is set, than the Maintenance function is disabled and counter does not count. Counter value disappear from controllers statistics.



Group: Generator settingsMains Settings

Subgroup: Overload Protection

Overload BOC

Setpoint group	Generator settings	Related FW	1.0.0			
Range [units]	Overload Wrn (page 30	Overload Wrn (page 304) 200 [%]				
Default value	120 % Alternative config NO					
Step	1 % of Nominal Power (page 242)					
Comm object	8280	Related applications	MINT, SPtM			
Config level	Standard	Standard				
Setpoint visibility	Always					
Description						
Threshold level for generator overload (in % of Nominal power) protection. Protection is BOC (Breaker Open and gen-set Cooldown).						

Note: When there is no control of breakers, the type of protection is Sd not BOC.

O back to List of setpoints

Overload Wrn

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	0 Overload BOC (page 304) [%]			
Default value	120 %	Alternative config	NO	
Step	1 % of Nominal Power (page 242)			
Comm object	9685	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Threshold level for generator overload (in % of Nominal power) protection. This is only warning.				

O back to List of setpoints

Overload Delay

Setpoint group	Generator settings	Related FW	1.0.0		
Range [units]	0,0 600,0 [s]				
Default value	5,0 s	Alternative config	NO		
Step	0,1 s				
Comm object	8281	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Delay for Overload BOC (page 304)Overload BOC (page 304) and Overload Wrn (page 304) protection.					



Subgroup: Underload Protection

Minimal Power PTM

Setpoint group	Generator settings	Related FW	1.0.0		
Range [units]	0 100 [%]				
Default value	5 %	Alternative config	NO		
Step	1 % of Nominal Power (page 242)				
Comm object	9241	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Minimal power of the gen-set. Value of this setpoint is used in Load Control PTM (page 230).					

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Subgroup: Current Protection

Short Circuit BOC

Setpoint group	Generator settings	Related FW	1.0.0		
Range [units]	100 500 [%]				
Default value	250 %	Alternative config	NO		
Step	1 % of Nominal Current (page 243)				
Comm object	8282	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
BOC occurs when generator current reaches this preset threshold.					
Note: When there is no control of breakers, the type of protection is Sd not BOC.					

O back to List of setpoints

Short Circuit BOC MPR Delay

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	0,00 10,00 [s]			
Default value	0,04 s	Alternative config	YES	
Step	0,01 s			
Comm object	9991	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Delay for Short Circuit BOC (page 305) protection.				



IDMT Overcurrent Delay

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	1,0600,0[s]		
Default value	4,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8283	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

IDMT curve shape selection. IDMT Overcurrent Delay is a reaction time of IDMT protection for 200% overcurrent I $_{gen}$ =2*Nominal Current (page 243)

IDMT is "very inverse" over current protection. Reaction time is not constant but depends on over current level according to the following formula:

Reaction ??? time = Overcurrent IDMT??? Delay* Nominal??? ??? Current

Note: Reaction time is limited to 3600 s = 60 minutes. IDMT protection is not active for Reaction time values longer than 60 minutes.

 \mathbf{I}_{gen} is maximal value of all measured phases of generator Mains current.

Table 9.1 EXAMPLE of Reaction time for different over current levels

	Overcurrent IDMT Delay	Overcurrent		
		≤ 100 %	101 %	110 %
Reaction time	0,2 s	No action	20 s	2 s
	2 s	No action	200 s	20 s
	20 s	No action	2000 s	200 s





Current Unbalance BOC

Setpoint group	Generator settings	Related FW	1.0.0		
Range [units]	1 200 [%] of Nominal C	1 200 [%] of Nominal Current (page 243)			
Default value	50 %	50 % Alternative config NO			
Step	1 % of Nominal Current (page 243)				
Comm object	8284	Related applications	MINT, SPtM		
Config level	Advanced				
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)				
Description					
Threshold for generator current asymmetry (unbalance).					
Protection is BOC (Breaker Open and genset Cooldown).					
Note: When there is no control of breakers, the type of protection is Sd not BOC.					

O back to List of setpoints

Current Unbalance BOC Delay

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	0,0 600,0 [s]			
Default value	5,0 s	Alternative config	NO	
Step	0,1 s			
Comm object	8285	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)			
Description				
Delay for Current Unbalance BOC (page 307) protection.				

O back to List of setpoints

Subgroup: Voltage Protection

Generator Overvoltage Sd

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	Generator Overvoltage Wrn (page 308) 200 [%]			
Default value	110 %	Alternative config	NO	
Step	1 % of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246)			
Comm object	8291	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Threshold for generator overvoltage protection. All three phases are checked. Maximum out of three is used.				
Note: Phase to phase and phase to neutral voltages are used for this protection.				



Generator Overvoltage Wrn

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	Generator Undervoltage Wrn (page 309) Generator Overvoltage Sd (page 307) [%]		
Default value	110 %	Alternative config	NO
Step	1 % of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246)		
Comm object	9686	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for generator overvoltage protection. All three phases are checked. Maximum out of three is used.			
Note: Phase to p	Note: Phase to phase and phase to neutral voltages are used for this protection.		

O back to List of setpoints

Generator Undervoltage BOC

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	0 Generator Undervol	0Generator Undervoltage Wrn (page 309) [%]		
Default value	70 %	Alternative config	NO	
Step	1 % of Nominal Voltage	1 % of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246)		
Comm object	8293	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
Threshold for gener	Threshold for generator undervoltage protection. All three phases are checked. Minimum out of three is used.			
Note: Phase to phase and phase to neutral voltages are used for this protection.				
Note: When there is no control of breakers, the type of protection is Sd not BOC.				



Generator Undervoltage Wrn

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	Generator Undervoltage BOC (page 308) Generator Overvoltage Wrn (page 308) [%]		
Default value	70 %	Alternative config	NO
Step	1 % of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246)		
Comm object	9687	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for generator undervoltage protection. All three phases are checked. Minimum out of three is used.			

Note: Phase to phase and phase to neutral voltages are used for this protection.

O back to List of setpoints

Generator <> Voltage Delay

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0,0600,0[s]		
Default value	3,0 s	Alternative config	NO
Step	0,1 s		
Comm object	9103	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Delay for Generator Overvoltage Sd (page 307), Generator Overvoltage Wrn (page 308), Generator Undervoltage BOC (page 308) and Generator Undervoltage Wrn (page 309) protection.			

O back to List of setpoints

Voltage Unbalance BOC

Setpoint group	Generator settingsBus Settings	Related FW	1.0.0
Range [units]	1 200 [%] of Nominal Voltage Ph-Ph (page 246)		
Default value	10 %	Alternative config	NO
Step	1 % of Nominal Voltage Ph-Ph (page 246)		
Comm object	8288	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)		
Description			
Threshold for generator voltage unbalance alarm.			
Note: When there is no control of breakers, the type of protection is Sd not BOC.			



Bus Voltage Unbalance BOC Delay

Setpoint group	Generator settingsBus Settings	Related FW	1.0.0
Range [units]	0,0 600,0 [s]		
Default value	3,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8289	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)		
Description			
Delay for Voltage Unbalance BOC (page 309) protection.			

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Subgroup: Frequency Protection

Generator Overfrequency BOC

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	Generator Overfrequency Wrn (page 310) 200,0 [%]		
Default value	110,0 %	Alternative config	NO
Step	0,1 % of Nominal Frequency (page 247)		
Comm object	8296	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for generator phase L1 overfrequency.			
Note: When there is no control of breakers, the type of protection is Sd not BOC.			

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Generator Overfrequency Wrn

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	Generator Underfrequency Wrn (page 311) Generator Overfrequency BOC (page 310) [%]		
Default value	110,0 %	Alternative config	NO
Step	0,1 % of Nominal Frequency (page 247)		
Comm object	9688	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for generator phase L1 overfrequency.			



Generator Underfrequency BOC

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0,0 Generator Underfrequency Wrn (page 311) [%]		
Default value	85,0 %	Alternative config	NO
Step	0,1 % of Nominal Frequency (page 247)		
Comm object	8298	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Threshold for generator phase L1 underfrequency.			
Note: When there is no control of breakers, the type of protection is Sd not BOC.			

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Generator Underfrequency Wrn

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	Generator Underfrequency BOC (page 311) Generator Overfrequency Wrn (page 310) [%]			
Default value	85,0 %	Alternative config	NO	
Step	0,1 % of Nominal Frequency (page 247)			
Comm object	9689	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
Threshold for generator phase L1 underfrequency.				

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Generator <> Frequency Delay

Setpoint group	Generator settings	Related FW	1.0.0	
Range [units]	0,0600,0[s]			
Default value	3,0 s	Alternative config	NO	
Step	0,1 s			
Comm object	8297	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Delay for Generator Overfrequency BOC (page 310), Generator Overfrequency Wrn (page 310), Generator Underfrequency Wrn (page 311) and Generator Underfrequency BOC (page 311) protection.				



Subgroup: Reverse Power Protection

Reverse Power Level

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0 50 [%]		
Default value	10 %	Alternative config	NO
Step	1 % of Nominal Power (page 242)		
Comm object	8486	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Reverse Power Protection (page 317).		
Description			
Level for generator Reverse Power Protection (page 317).			

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Reverse Power Delay

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0,0600[s]		
Default value	5,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8552	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Reverse Power Protection (page 317).		
Description			
Delay for generator Reverse Power Protection (page 317).			

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Subgroup: Excitation Loss Protection

Excitation Loss Level

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0 150 [%]		
Default value	30 %	Alternative config	NO
Step	1 % of Nominal Power (page 242)		
Comm object	12486	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Excitation Loss Protection (page 318).		
Description			
Level for generator Excitation Loss Protection (page 318).			



Excitation Loss Delay

Setpoint group	Generator settings	Related FW	1.0.0
Range [units]	0,0 600,0 [s]		
Default value	5,0 s	Alternative config	NO
Step	0,1 s		
Comm object	12487	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Excitation Loss Protection (page 318).		
Description			
Delay for generator Excitation Loss Protection (page 318).			

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Group: Protections

Subgroup: Overload Protection

Overload Protection

Set	point group	Protections	Related FW	1.0.0
Rar	nge [units]	Enabled/Disabled/ExtDisable [-]		
Def	ault value	Enabled	Alternative config	NO
Ste	р	[-]	[-]	
Со	nm object	15664	Related applications	MINT, SPtM
Со	nfig level	Advanced	Advanced	
Set	point visibility	ility Always		
Des	Description			
This	This setpoint adjusts the behavior of generator Overload protection.			
	Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Overload BOC (page 304), Overload Wrn (page 304) and Overload Delay (page 304).		
	Disabled:	Protection is disabled.		
	ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)		



Subgroup: Current Protection

IDMT Overcurrent Protection

Set	point group	Protections	Related FW	1.0.0	
Rai	nge [units]	Enabled / Disabled / ExtD	Enabled / Disabled / ExtDisable[-]		
Def	ault value	Enabled Alternative config NO		NO	
Ste	р	[-]			
Со	mm object	15666	15666 Related applications MINT, SPtM		
Co	nfig level	Advanced	Advanced		
Set	etpoint visibility Always				
Des	Description				
This setpoint adjusts the behavior of generator IDMT Overcurrent protection.			on.		
	Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoint IDMT Overcurrent Delay (page 306).			
	Disabled:	Protection is disabled.			
	ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE [PAGE 666]			

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Current Unbalance Protection

Set	point group	Protections	Related FW	1.0.0	
Rar	nge [units]	Enabled / Disabled / ExtE	Enabled / Disabled / ExtDisable[-]		
Def	ault value	Enabled	Enabled Alternative config NO		
Ste	р	[-]			
Со	nm object	15667	Related applications	MINT, SPtM	
Со	nfig level	Advanced	Advanced		
Set	point visibility	/ Always			
Des	escription				
This	This setpoint adjusts the behavior of generator Current Unbalance protection.				
	Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Current Unbalance BOC (page 307) and Current Unbalance BOC Delay (page 307).			
	Disabled:	Protection is disabled.			
	ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)			



Subgroup: Voltage Protection

Generator <> Voltage Protection

Protections	Related FW	1.0.0
Enabled / Disabled / ExtDisable [-]		
Enabled	Alternative config	NO
[-]		
15668	Related applications	MINT, SPtM
Advanced		
Always		
	Protections Enabled / Disabled / Ext Enabled [-] 15668 Advanced Always	ProtectionsRelated FWEnabled / Disabled / ExtSable [-]EnabledAlternative config[-]Felated applicationsAdvancedAlways

Description

This setpoint adjusts the behavior of generator Generator <> Voltage protection. GCB closing is blocked, if the protection is disabled!

Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Generator Overvoltage Sd (page 307), Generator Overvoltage Wrn (page 308), Generator Undervoltage BOC (page 308), Generator Undervoltage Wrn (page 309) and Generator <> Voltage Delay (page 309).
Disabled:	Protection is disabled.
ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)

GCB closing, generator voltage regulation and synchronization are disabled (blocked), if the parameter is set to Disabled. It is blocked as well, if the parameter is set to ExtDisable and LB IFORCE PROTECTION DISABLE (PAGE 666) is active.

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Voltage Unbalance Protection

Setpoint group	Protections	Related FW	1.0.0
Range [units]	Enabled / Disabled / ExtD)isable [-]	
Default value	Enabled	Alternative config	NO
Step	[-]		
Comm object	15669	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			
This set point adjusts the behavior of generator Voltage Linhalance protection			

etpoint adjusts the behavior of generator Voltage Unbalance protection.

Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Voltage Unbalance BOC (page 309) and Bus Voltage Unbalance BOC Delay (page 310).
Disabled:	Protection is disabled.
ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)



Subgroup: Frequency Protection

Generator Frequency Protection

	-		
Setpoint group	Protections	Related FW	1.0.0
Range [units]	Enabled / Disabled / ExtDisable [-]		
Default value	Enabled	Alternative config	NO
Step	[-]		
Comm object	15670	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			

Description

This setpoint adjusts the behavior of generator Generator Frequency protection. GCB closing is blocked, if the protection is disabled!.

Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Generator Overfrequency BOC (page 310), Generator Overfrequency Wrn (page 310), Generator Underfrequency BOC (page 311), Generator Underfrequency Wrn (page 311), and Generator <> Frequency Delay (page 311).
Disabled:	Protection is disabled.
ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)

GCB closing, generator frequency regulation and synchronization are disabled (blocked), if the parameter is set to Disabled. It is blocked as well, if the parameter is set to ExtDisable and LBI FORCE PROTECTION DISABLE (PAGE 666) is active.



Subgroup: Reverse Power Protection

Reverse Power Protection

Setpoint group	Protections	Related FW	1.0.0
Range [units]	Enabled / Disabled / ExtDisable [-]		
Default value	Enabled	Alternative config	NO
Step	[-]		
Comm object	13230	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Decembration			

Description

The protection of the generator against the reverse (negative) active power. Protection gets active when the level of active power [kW] gets under limit given by setpoint **Reverse Power Level (page 312)** for time longer than the value of setpoint **Reverse Power Delay (page 312)**.

This setpoint adjusts behavior of generator Reverse power protection.

Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Reverse Power Level (page 312), Reverse Power Delay (page 312)
Disabled:	Protection is disabled.
ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)



Subgroup: Excitation Loss Protection

Excitation Loss Protection

Setpoint group	Protections	Related FW	1.0.0
Range [units]	Enabled / Disabled / ExtDisable [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	13269	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		

Description

The protection protect the generator against negative value of reactive power. Protection gets active when the level of reactive power [kVAr] gets under limit given by setpoint **Excitation Loss Level (page 312)** for time longer than the value of setpoint **Excitation Loss Delay (page 313)**.

Enabled:	Protection is enabled. Behavior of protection is adjusted via setpoints Excitation Loss Level (page 312), Excitation Loss Delay (page 313)
Disabled:	Protection is disabled.
ExtDisable:	Protection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE (PAGE 666)

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Subgroup: Speed Protection

Underspeed Protection

Set	point group	Protections	Related FW	1.0.0	
Rar	nge [units]	Enabled / Disabled / ExtD	Enabled / Disabled / ExtDisable [-]		
Def	ault value	Enabled	Enabled Alternative config NO		
Ste	р	[-]			
Cor	nm object	15671	Related applications	MINT, SPtM	
Cor	nfig level	Advanced	Advanced		
Set	point visibility	Always			
Des	Description				
This	This setpoint adjusts the behavior of generator Underspeed protection.				
	Enabled:	Protection is enabled.	otection is enabled.		
	Disabled:	Protection is disabled.	rotection is disabled.		
	ExtDisable:	rotection is enabled or disabled by the state of LBI FORCE PROTECTION DISABLE AGE 666)			



Group: Mains settings

Subgroup: AMF Timers

Emergency Start Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	06000 [s]		
Default value	5 s	Alternative config	NO
Step	1s		
Comm object	8301	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoir	nt Application Mode Selec	ct (page 229)
Description			
Starter Output	Emergency Start Delay Vains failure	Prestart Time	Mains Voltage

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Mains Return Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	13600[s]		
Default value	20 s	Alternative config	NO
Step	1s		
Comm object	8302	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
This setpoint adjust the delay, how long mains has to be returned after mains fail to start load transfer to mains.			



MCB Close Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	0,0600,0[s]		
Default value	1,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8389	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Delay after mains returns to MCB closing, if the gen-set is not running(e.g. is in start-up procedure)			

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AMF Start

Setpoint group	Process ControlMains settings	Related FW	1.0.0
Range [units]	ENABLED / DISABLED	[-]	
Default value	ENABLED	Alternative config	NO
Step	[-]		
Comm object	9238	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Use this setpoint to enable or disable the AMF operation (page 77).			

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Subgroup: Mains Voltage Limits

Mains Overvoltage

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Mains Undervoltage (page 321) 150 [%]		
Default value	110 %	Alternative config	NO
Step	1 % of Nominal Voltage Ph-Ph (page 246)		
Comm object	8305	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Threshold for mains overvoltage. All three phases are checked. Maximum out of three is used.			



Mains Undervoltage

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	50 Mains Overvoltage (page 320) [%]		
Default value	60 %	Alternative config	YES
Step	1 % of Nominal Voltage Ph-Ph (page 246)		
Comm object	8307	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Threshold for mains undervoltage. All three phases are checked. Minimum voltage out of three phases is used.			

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Mains < > Voltage Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	0,0 600,0 [s]		
Default value	2,0 s	Alternative config	YES
Step	0,1 s		
Comm object	8306	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Delay for Mains Undervoltage (page 321) and Mains Overvoltage (page 320) protection.			

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Mains Voltage Unbalance

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	1 150 [%] of Nominal Voltage Ph-Ph (page 246)		
Default value	10 %	Alternative config	NO
Step	1 % of Nominal Voltage Ph-Ph (page 246)		
Comm object	8446	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Threshold for mains voltage unbalance.			



Mains Voltage Unbalance Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	0,0 600,0 [s]		
Default value	2,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8447	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Delay for Mains Voltage Unbalance (page 321) protection.			

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Subgroup: Mains Frequency Limits

Mains Overfrequency

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Mains Underfrequency (page 322) 150 [%]		
Default value	102,0 %	Alternative config	NO
Step	1,0 % of Nominal Frequency (page 247)		
Comm object	8310	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Threshold for mains overfrequency.			

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Mains Underfrequency

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	50 Mains Overfrequency (page 322) [%]		
Default value	98,0 %	Alternative config	NO
Step	1,0 % of Nominal Frequency (page 247)		
Comm object	8312	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Threshold for mains underfrequency.			

•



Mains < > Frequency Delay

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	0,0 600,0 [s]		
Default value	0,5 s	Alternative config	NO
Step	0,1 s		
Comm object	8311	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Delay for Mains Underfrequency (page 322) and Mains Overfrequency (page 322) protection.			

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Subgroup: MCB Control

MCB Logic

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Close On / Close Off [-]		
Default value	Close Off	Alternative config	NO
Step	[-]		
Comm object	8444	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	ity Conditioned by the setpoint Application Mode Select (page 229)		
Description			
The set point influences the	ne behavior of the output MC	B CLOSE/OPEN (PAGE 726).
Close On When the output	t MCB CLOSE/OPEN (PAGE	726) is closed – MCB shou	ld be closed.
Close Off When the output	IT MCB CLOSE/OPEN (PAGE	726) is closed – MCB shou	ld be opened.
Binary output MCB Close /Open			
	Mains ok	Mains failure Mains	s ok
	► 	► <	Controller is on
Close			Controller is off
Open-			
			→
			Time
Image 9.23 MCB Logic 1			





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Subgroup: AMF Settings

Return From Island

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Manual / Auto [-]		
Default value	Auto	Alternative config	NO
Step	[-]		
Comm object	9590	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Application Mode Select (page 229)		
Description			
Setpoint adjust the behavior of closing MCB when the mains returns.			
Manual	When Return From Island = MANUAL and there is a Mains Fail, gen-set is started and take the load. After mains return the load have to manually transfer to mains. Also in Alarmlist will be displayed Manual Restore (page 815) alarm.		
	Note: Select MANUAL in case you need to manually control the moment when the load is transferred back to the mains.		
Auto	No automatic mode change is performed.		


MCB Opens On

Setpoint group	Mains settings	Mains settings Related FW 1.0.0	
Range [units]	Mains Fail / Gen Run [-]		
Default value	Gen Run	Alternative config	NO
Step	[-]		
Comm object	9850	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoi	int Application Mode Sel	ect (page 229)
Description			
Setpoint adjust the l	pehavior of opening MCB in	AUTO mode when there is	s mains fail.
Mains Fail The co	mmand to open the MCB is	given immediately after m	ains fail condition is evaluated.
If the mains will return into parameters after MCB was opened and before GCB is closed, timer MCB Close Delay (page 320) is applied before MCB closing. Gen Run MCB will be opened when engine will be running and it will be possible to transfer load from			
Mains to gen-set (after stabilisation phase).			
Note: This optic coil.	Note: This option should be used for MCBs using 230V control and not equipped with the undervoltage coil.		ot equipped with the undervoltage



Subgroup: Mains Decoupling Protection

Vector Shift Protection

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Enabled / Parallel Only / Disabled [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	10551	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint selects the function of the built-in vector shift protection.

Disabled	The vector shift protection is disabled.
Parallel Only	The vector shift protection is enabled only while the gen-set is running parallel to the mains, i.e. the both MCB and GCB MGCB are closed.
Enabled	The vector shift protection is active always while the MCB is closed, regardless of the GCB MGCB position.

Note: The vectorshift protection is recorded into the history file, however it is not indicated in the Alarm list. When it occurs the controller opens either MCB or GCB MGCB depending on the setpoint **Vector Shift CB Selector (page 328)**. If the MCB is not controlled in the particular application then GCB MGCB is opened.

Note: If a vector shift is detected and consequently the MCB is opened, however mains voltage and frequency remain in limits, the MCB is then reclosed again after **Mains Return Delay (page 319)**, as the mains is evaluated as healthy.

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Vector Shift Limit

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	1 45 [°]		
Default value	10 °	Alternative config	NO
Step	1 °		
Comm object	9843	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts the threshold level for the vector shift protection.

Note: To adjust this setpoint properly, check the value **Max Vector ShiftMaxVectorS (page 575)**. The value is available in InteliConfig, contains the maximal measured vector shift value since the gen-set has been synchronized to the mains and after opening of GCB or MCB it is "frozen". In normal conditions the value should not be higher than 3 ° and the most common setting of the threshold is about 7 °.



ROCOF Protection

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	Enabled / Parallel Only / Disabled [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	9840	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint selects the function of the built-in ROCOF protection.

Disabled	The ROCOF protection is disabled.
Parallel Only	The ROCOF protection is enabled only while the gen-set is running parallel to the mains, i.e. the both MCB and GCB MGCB are closed.
Enabled	The ROCOF protection is active always while the MCB is closed, regardless of the GCB MGCB position.

Note: The ROCOF protection is recorded into the history file, however it is not indicated in the Alarm list. When it occurs the controller opens either MCB or GCB MGCB depending on the setpoint **Vector Shift CB Selector (page 328)**. If the MCB is not controlled in the particular application then GCB MGCB is opened.

Note: If a ROCOF is detected and consequently the MCB is opened, however mains voltage and frequency remain in limits, the MCB is then reclosed again after **Mains Return Delay (page 319)**, as the mains is evaluated as healthy.

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ROCOF Windows Length

Setpoint group	Mains settings	Related FW	1.0.0
Range [units]	3 30 [-]		
Default value	5	Alternative config	NO
Step	1 [-]		
Comm object	9990	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts the averaging level for the **ROCOF Protection (page 327)**. It defines number of periods of the mains voltage in which the ROCOF protection is evaluated. The higher length of ROCOF window means less sensitive protection for short oscillations of the frequency to both directions from the nominal value. Also delay of evaluation is higher.



ROCOF df/dt

Setpoint group	Mains settings	Related FW	1.0.0	
Range [units]	0,110,0 [Hz/s]			
Default value	1,0 Hz/s	Alternative config	NO	
Step	0,1 Hz/s			
Comm object	9844	Related applications	SPtM	
Config level	Standard			
Setpoint visibility	Always	Always		
Description				
This setpoint adjusts the trip level for ROCOF Protection (page 327) (Rate Of Change Of Frequency).				

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Vector Shift CB Selector

Setpoint group	Mains settings	Related FW	1.0.0	
Range [units]	MCB / GCB MGCB [-]			
Default value	MCB	Alternative config	NO	
Step	[-]			
Comm object	10552	Related applications	SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
This setpoint selects which breaker will be opened when the Vector Shift Protection (page 326) or ROCOF Protection (page 327) protection is detected.				
Note: If the GCB MGCB is selected and a mains failure occurs the GCB MGCB will be opened immediately when the vectorshift or ROCOF is detected, however also MCB will be opened				

consequently due to other mains protection as underfrequency or undervoltage.



Group: Load Shedding

Load Shedding Active

Set	point group	Load Shedding Related FW 1.0.0		1.0.0
Rar	nge [units]	Disabled / Island only / ISL+Trip paral / All the time [-]		
Def	ault value	Disabled Alternative config NO		
Ste	р	[-]		
Со	mm object	11001	Related applications	MINT, SPtM
Со	nfig level	Advanced		
Set	point visibility	Visible always		
Des	scription			
This	s setpoint is used	l for adjustment when the lo	bad shedding function is ac	ctive.
	Disabled	The Load shedding function	on is disabled. All the outpu	uts are open.
	Island only	 In Island operation (e.g. MCB is open and (M)GCB is closed) Load shedding outputs are controlled by load shedding function. Load shedding outputs are activated/Deactivated one by one in island operation All Loadshedding outputs are tripped once the genset comes into the island operation from "NO LOAD" operation (MCB and (M)GCB were opened -> Genset started and (M)GCB closed) 		s closed) Load shedding outputs ated one by one in island e genset comes into the island and (M)GCB were opened ->
	ISL+Trip paral	 I This setting adjusts the same behavior as ISLAND ONLY but in addition to it all load shedding outputs are closed when gen-set group goes from parallel operation ino the island operation. Load shedding outputs are activated/Deactivated one by one in island operation. All Loadshedding outputs are tripped at once when the genset comes into the island operation from "NO LOAD" operation (MCB and (M)GCB were opened > Genset started and (M)GCB closed). All Loadshedding outputs are tripped at once when the genset comes from Parallel operation (MCB, (M)GCB closed) to island operation (MCB opens, (M)GCB stays closed). This scenario is also valid when Test On Load is taken. 		ONLY but in addition to it all load es from parallel operation ino the ated one by one in island when the genset comes into the MCB and (M)GCB were opened - when the genset comes from island operation (MCB opens, valid when Test On Load is
	All the time	 Load shedding Outputs are controlled by the load shedding function regardless of breaker positions. Loadshedding is active in island operation, in parallel operation too. All Loadshedding outputs are never tripped at once. 		



Load Shedding Level

Setpoint group	Load Shedding	Related FW	1.0.0	
Range [units]	Load Reconnection Level	Load Reconnection Level 200 [%] of Nominal Power (page 242)		
Default value	80 %	Alternative config	NO	
Step	1 %			
Comm object	8884	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Visible only if Load Shed	Visible only if Load Shedding Active (page 329) is disabled		
Description				
This setpoint is used to proceeds the next Load shedding stage. When gen-set load exceeds this level for more than Load Shedding Delay (page 330) time				

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Load Shedding Delay

Setpoint group	Load Shedding	Related FW	1.0.0
Range [units]	0,0600,0 [s]		
Default value	10 s	Alternative config	NO
Step	1s		
Comm object	8887	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if Load Shedding Active (page 329) is disabled		
Description			
This setpoint is used to proceeds the next Load shedding stage. When gen-set load exceeds this level for			

more than Load Shedding Level (page 330) time

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Load Reconnection Level

Setpoint group	Load Shedding	Related FW	1.0.0
Range [units]	0Load Shedding Level (page 330)		
Default value	20 %	Alternative config	NO
Step	1 %		
Comm object	8890	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if Load Shedding Active (page 329) is disabled		
Description			
This setpoint is used to proceeds the next Load shedding stage. When gen-set load exceeds this level for more than Load Shedding Delay (page 330) time			



Load Reconnection Delay

Setpoint group	Load Shedding	Related FW	1.0.0
Range [units]	0600 [s]		
Default value	10 s	Alternative config	NO
Step	1s		
Comm object	8893	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Visible only if Load Shedding Active (page 329) is disabled		
Description			
This setpoint is used to proceeds the lower Load shedding stage. When gen-set load drops under Load Reconnection Level (page 330) for more than this delay time. The binary output for higher stage is opened.			

Automatic load reconnection works only when Auto Load Reconnection (page 331) = Enabled

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Auto Load Reconnection

Setpoint gro	oup	Load Shedding	Related FW	1.0.0
Range [units	5]	Disabled / Enabled [-]		
Default value	e	Enabled	Alternative config	NO
Step		[-]		
Comm object	ct	9649	Related applications	MINT, SPtM
Config level		Advanced		
Setpoint visi	ibility	Visible only if Load Shedding Active (page 329) is disabled		
Description	Description			
Switch between manual and automatic reconnection of shedded load				
Disabled	Rising edge on binary input MANUAL LD RECON resets controller to the lower stage, but only Disabled if the load is under the Load Reconnection Level (page 330). Load Reconnection Delay (page 331) is not taken into account in this case.			
Enabled	Load reconnection is automatic depend on setpoints Load Reconnection Level (page 330) bled and Load Reconnection Delay (page 331). Binary input MANUAL LOAD RECONNECTION (PAGE 671) has no function.			



Group: Power Management

Subgroup: Power Management Control

Power	Management
-------	------------

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	Enabled / Disabled [-]		
Default value	Enabled	Alternative config	NO
Step	[-]		
Comm object	8551	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to enable or disable the Power management (nage 79) function in the particular			

This setpoint is used to enable or disable the **Power management (page 79)** function in the particular controller. It performs automatic load dependent starts and stops or load demand swap. If the function is disabled the gen-set's nominal power is not part of the power management calculation and the start and stop of the gen-set is performed only according to the position of the binary input **REMOTE START/STOP (PAGE 677)** i.e. if the input is active the gen-set is running and vice versa.

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Power Management Delay

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	03600 [s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	12488	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		

Description

Setpoint defines delay of the **Power management (page 79)**. When **REMOTE START/STOP (PAGE 677)** signal is activated and the gen-sets should start, all the engines (where **Power Management (page 332)** is enabled) are started and stay running for time period specified by this parameter. After this period elapses, only the gen-set(s) needed according to the Power Management calculation stay running and the rest is stopped.

Example: This delay is useful, when you need to start gen-sets to an unknown load. Setting for example 360s (6 minutes) and activating **REMOTE START/STOP (PAGE 677)** will force all gen-sets to start and run for 6 minutes despite of the power management setting.

Note: By setting "0" the Power Management function is enabled immediately.



#Power Management Mode

Set	point group		Power Management	Related FW	1.0.0
Range [units]			ABS [kW] / REL [%]		
Default value			ABS	Alternative config	NO
Step [-]					
Со	mm object		9874 Related applications MINT		
Со	Config level Standard				
Set	Setpoint visibility Always				
Des	Description				
This setpoint is used to select the Power management (page 79) mode.					
	ABS [kW] The power management is based on actual active power and gen-set nominal power. The reserves are calculated and adjusted in kW.		er and gen-set nominal power.		
	REL[%]	L[%] The power management is based on the relative load, i.e. ratio active power to nominal			

power. The reserves are calculated and adjusted in %.

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Priority

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	1 32 [-]		
Default value	1	Alternative config	NO
Step	1		
Comm object	8488	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts the priority of the gen-set within the group. A lower number represents a "higher" priority, i.e. a gen-set with lower number will start before another one with higher number.

Note: If the binary input **Top Priority (page 680)** is active, the gen-set gets the highest priority (0) independent of the setpoint setting.

Note: If more than one gen-set have the same priority they will act as "one big" gen-set.

IMPORTANT: Value of the setpoint Priority is taken into account only for absolute mode of power management (#Power Management Mode (page 333) = ABS).



#Priority Auto Swap

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	Disabled / Run Hours Equal / Efficient [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	10593	Related applications	MINT,
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts priority auto swapping.

Disabled	Optimalization is disabled. Priorities are given directly by the values adjusted in the setpoints Priority (page 333) .	
Run Hours Equal	This method changes the priorities (not the setpoints itself) to equalize running hours of the gen-sets or to keep constant difference of running hours by the controller (adjusted via setpoint #Run Hours Max Difference (page 342)).	
	This method changes the priorities (not the setpoints itself) to optimize which gen- sets are running according to their capacities and actual load demand.	
Efficient	IMPORTANT: This priority swapping function is only for absolute mode of power management (#Power Management Mode (page 333) = ABS).	
	Optimal power band (number of running gen-sets) is calculated based on the nominal power of each gen-set, their Run Hours and requested Load reserve. For gen-sets with the same nominal power also run hour equalization is being performed.	

IMPORTANT: Binary input Top Priority (page 680) can be used only if #Priority Auto Swap = Disabled.

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#System Start Delay

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 600 [-]		
Default value	5	Alternative config	NO
Step	1		
Comm object	8549	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the delay of the system activation after the binary input REMOTE START/STOP (PAGE 677) has been activated.			



#System Stop Delay

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 600 [-]		
Default value	30	Alternative config	NO
Step	1		
Comm object	8550	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the delay of the system deactivation after the binary input REMOTE START/STOP (PAGE 677) has been deactivated.			

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Subgroup: Load Reserve Set 1

#Starting Load Reserve 1

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 #Stopping Load Reserve 1 (page 336) [kW]		
Default value	60 kW	Alternative config	NO
Step	1 kW		
Comm object	8489	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust the load reserve for start of next gen-set in absolute mode. i.e. **#Power Management Mode (page 333) =** ABS.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be deactivated, otherwise setpoints of Load Reserve Set 2 are used.

Note: See Power management (page 79) chapter for more information.



#Stopping Load Reserve 1

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	#Starting Load Reserve 1 (page 335) 32 000 [kW]		
Default value	110 kW	Alternative config	NO
Step	1 kW		
Comm object	8491	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust the load reserve for stop of next gen-set in absolute mode, i.e. #Power			

Management Mode (page 333) = ABS.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be deactivated, otherwise setpoints of Load Reserve Set 2 are used.

Note: See Power management (page 79) chapter for more information.

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#Starting Rel Load Reserve 1

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 #Stopping Rel Load Reserve 1 (page 337) [%]		
Default value	60 %	Alternative config	NO
Step	1 %		
Comm object	10648	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust the load reserve for start of next gen-set in relative mode. i.e. **#Power Management Mode (page 333)** = REL.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be deactivated, otherwise setpoints of Load Reserve Set 2 are used.

Note: See Power management (page 79) chapter for more information.



#Stopping Rel Load Reserve 1

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	#Starting Rel Load Reserve 1 (page 336) 110 [%]		
Default value	80 %	Alternative config	NO
Step	1 %		
Comm object	10652	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust the load reserve for stop of next gen-set in relative mode. i.e. #Power			

Management Mode (page 333) = REL.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be deactivated, otherwise setpoints of Load Reserve Set 2 are used.

Note: See Power management (page 79) chapter for more information.

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Subgroup: Load Reserve Set 2

#Starting Load Reserve 2

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 #Stopping Load Reserve 2 (page 338) [kW]		
Default value	410 kW	Alternative config	NO
Step	1 kW		
Comm object	8490	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust the load reserve for start of next gen-set in absolute mode. i.e. **#Power Management Mode (page 333) =** ABS.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be activated, otherwise setpoints of Load Reserve Set 1 are used.

Note: See Power management (page 79) chapter for more information.



#Stopping Load Reserve 2

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	#Starting Load Reserve 2 (page 337) 32 000 [kW]		
Default value	460 kW	Alternative config	NO
Step	1 kW		
Comm object	8633	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust the load reserve for stop of next gen-set in absolute mode. i.e. #Power			

Management Mode (page 333) = ABS.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be activated, otherwise setpoints of Load Reserve Set 1 are used.

Note: See Power management (page 79) chapter for more information.

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#Starting Rel Load Reserve 2

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 #Stopping Rel Load Reserve 2 (page 339) [%]		
Default value	60 %	Alternative config	NO
Step	1 %		
Comm object	10649	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust the load reserve for start of next gen-set in relative mode. i.e. **#Power** Management Mode (page 333) = REL.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be activated, otherwise setpoints of Load Reserve Set 1 are used.

Note: See Power management (page 79) chapter for more information.



#Stopping Rel Load Reserve 2

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	#Starting Rel Load Reserve 2 (page 338) 110 [%]		
Default value	80 %	Alternative config	NO
Step	1%		
Comm object	10653	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust the load reserve for stop of next gen-set in relative mode. i.e. #Power			

Management Mode (page 333) = REL.

IMPORTANT: Logical binary input LOAD RES 2 ACTIVE (PAGE 670) has to be activated, otherwise setpoints of Load Reserve Set 1 are used.

Note: See Power management (page 79) chapter for more information.

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Subgroup: Minimal Running Power

#Min Run Power

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	065 000 [kW]		
Default value	210 kw	Alternative config	NO
Step	1 kW		
Comm object	9584	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust certain minimum value of the sum of nominal power of all running gen-sets. If the function is active (by logical binary input **Min Run Power Active (page 673)**), then the gen-sets would not be stopped, although the reserve for stop is fulfilled, if the total remaining nominal power drops below this minimal value.

Note: Logical binary input **Min Run Power Active (page 673)**) needs to be activated on all gen-sets in the same time.



Subgroup: Start/Stop Timing

#Next Engine Start Delay

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	03600[s]			
Default value	5s	Alternative config	NO	
Step	1s			
Comm object	8492	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint adjusts	This setpoint adjusts the delay for starting the next gen-set after the reserve has dropped below the reserve			

This setpoint adjusts the delay for starting the next gen-set after the reserve has dropped below the reserve for start.

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#Next Engine Stop Delay

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	03 600 [s]			
Default value	20 s	Alternative config	NO	
Step	1s			
Comm object	8494	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint adjusts the delay for stopping the gen-set after the reserve has risen above the reserve for stop.				

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#Slow Stop Delay

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0600[s]		
Default value	60 s	Alternative config	NO
Step	1s		
Comm object	8495	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust how long the particular gen-set will suppress it's own Slow stop alarm to give chance to another gen-set to start and replace the defective one.			

Note: If there isn't any available gen-set to start, the alarm is not suppressed.



Subgroup: Over Load Next Start Protection

#Overload Next Start Protection

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	Enabled / Disabled [-]			
Default value	Enabled	Alternative config	NO	
Step	[-]			
Comm object	14942	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint is inter	ided for activation of the pro	otection against the overlo	ading of the system due to rapid	

change of the load. It makes the next gen-set (in priority order) to start when the load excises the value given by the setpoint **#Overload Next Start Level (page 341)** right after the delay **#Overload Next Start Delay** (page 341).

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#Overload Next Start Level

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	0 100 [%]			
Default value	80 %	Alternative config	NO	
Step	1 %			
Comm object	14941	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
Threshold level for #Overload Next Start Protection (page 341).				

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#Overload Next Start Delay

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	05[s]			
Default value	1s	Alternative config	NO	
Step	1s			
Comm object	8493	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always	Always		
Description				
Delay for #Overload Next Start Protection (page 341).				



Subgroup: Run Hours Equalization

Run Hours Base

Setpoint group	Power Management	Related FW	1.0.0		
Range [units]	0,0200000,0[h]	0,0 200000,0 [h]			
Default value	0,0 h	0,0 h Alternative config NO			
Step	0,1 h				
Comm object	10600	Related applications	MINT		
Config level	Standard	Standard			
Setpoint visibili	ty Always				
Description					
Running hours ba	se corrects actual Running I	nours differences between p	particular gen-sets.		
Example:					
Gen-set 1	Gen-set 1 actual Running hours = 1000 h.				
Gen-set 2	et 2 actual Running hours = 2000 h.				
Adjust this	Adjust this setpoint for Gen-set 1 = 1000 h and for Gen-set 2 = 2000 h to be on the same base for				
Running H	ng Hours Equalization.				

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#Run Hours Max Difference

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	0 65 000 [h]		
Default value	100 h	Alternative config	NO
Step	1 h		
Comm object	9919	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts the "dead-band" for the running hours equalization function (**#Priority Auto Swap** (page 334) = Run Hours Equal). The priorities are swapped when engine hours difference is higher than this dead-band.

Note: The system calculates with whole hours.

Example: The difference in engine running hours has to be 11.0 hours, if #Run Hours Max Difference is set to 10. The priorities shuffling is not done with the difference just 10.1 hours.



Subgroup: Efficient Mode

#Power Band Change Up Delay

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	03600[s]		
Default value	10 s	Alternative config	NO
Step	[s]		
Comm object	8896	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used for adjusting the delay of changing the power band if the load demand rose above the upper limit of the current power band. Setpoint is taken into account only if **#Priority Auto Swap (page 334)** = Efficient.

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#Power Band Change Down Delay

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	03600[s]			
Default value	10 s	Alternative config	NO	
Step	[s]			
Comm object	10795	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint is used for adjusting the delay of changing the power band if the load demand drops below the lower limit of the current power band. Setpoint is taken into account only if #Priority Auto Swap (page 334)				

= Efficient.



Subgroup: Group Settings

Control Group

Setpoint group	Power Management	Related FW	1.0.0
Range [units]	1,232[-]		
Default value	1s	Alternative config	NO
Step	1 s		
Comm object	10589	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint selects the control group (to get more information on this function please refer to the chapter **Control groups (page 98)** to which the particular gen-set belongs. If there aren't logical groups at the site, adjust the setpoint to 1.

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Group Link L

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	1,232[-]			
Default value	1s	Alternative config	NO	
Step	1s			
Comm object	10590	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				

If the input **GROUP LINK (PAGE 669)** of this particular controller is used to provide the "group link" information for two Control groups (to get more information refer to the chapter **Control groups (page 98)**), then this setpoint is used to select which group is located at the left side of the group link breaker (bus tie breaker). If this particular controller is not used for the group link function, adjust this setpoint to 1.



Group Link R

Setpoint group	Power Management	Related FW	1.0.0	
Range [units]	1,2 32 [-]			
Default value	1s	Alternative config	NO	
Step	1s			
Comm object	10591	Related applications	MINT	
Config level	Standard			
Setpoint visibility	Always			
Description				
If the input GROUP LINK (PAGE 669) of this particular controller is used to provide the "group link" information				

for two Control groups (to get more information refer to the chapter **Control groups (page 98)**), then this setpoint is used to select which group is located at the right side of the group link breaker (bus tie breaker). If this particular controller is not used for the group link function, adjust this setpoint to 1.

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Group: Speed/Load ControlLoad Control

Subgroup: Speed Control

Speed Regulator Character

Set	point group) (Speed/Load Control	Related FW	1.0.0	
Rar	nge [units]		Positive / Negative [-]			
Def	ault value		Positive	Alternative config	NO	
Ste	р		[-]			
Cor	nm object	9	9054	Related applications	MINT, SPtM	
Cor	nfig level		Standard			
Set	point visibi	lity	Always			
Des	scription					
This setpoint selects the characteristic of the speed governor output of the controller. Adjust it according to the behavior of the remote speed input of the governor.						
	Positive	Raisi	ng the voltage on the governor remote speed input causes engine speed to rise.			

Negative Raising the voltage on the governor remote speed input causes engine speed to go down.



Speed Governor Bias

Setpoint group	Speed/Load Control	Related FW	1.0.0	
Range [units]	-10,00 10,00 [V]			
Default value	0,00 V	Alternative config	NO	
Step	0,01 V			
Comm object	8656	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				

This setpoint adjusts the initial voltage level for the speed governor output, which is present on the output, if no speed or power regulation loop is active.

Note: To make a fine adjustment, start the gen-set in MAN mode, leave it running unloaded and then make fine adjustment of this setpoint to achieve nominal engine speed.

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Speed Governor Low Limit

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	-10,00 10,00 [V]		
Default value	0,00 V	Alternative config	NO
Step	0,01 V		
Comm object	10115	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Lower limit of the speed governor output. Use this setpoint to adjust the governor output range according to			

your governor type.

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Speed Governor High Limit

Setpoint group	Speed/Load Control	Related FW	1.0.0	
Range [units]	-10,00 10,00 [V]			
Default value	0,00 V	Alternative config	NO	
Step	0,01 V			
Comm object	10559	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Upper limit of the speed governor output. Use this setpoint to adjust the governor output range according to your governor type.				



Speed Governor PWM Rate

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	500 2 900 [Hz]		
Default value	500 Hz	Alternative config	NO
Step	1 Hz		
Comm object	10911	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the frequency of the speed governor PWM output.			

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Tau Speed Governor Actuator

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	1,0300,0[s]		
Default value	10,0 s	Alternative config	NO
Step	0,1 s		
Comm object	10784	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint is used to adjust the transformation ratio of the speed governor output to the pulses at the binary outputs SPEED UP (PAGE 736) and SPEED DOWN (PAGE 736) . Adjust the setpoint to the pulse duration which is needed for the speed control device to travel from minimal position to the maximal position.			

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Subgroup: Regulation Loops

Frequency Gain

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0,0 200,0 [%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8715	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the frequency control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			



Frequency Int

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	8716	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the frequency control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

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Angle Gain

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0,0200,0 [%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8718	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This sotroint is used for adjusting of the gain factor (P factor) of the phase angle P control loop			

This setpoint is used for adjusting of the gain factor (P-factor) of the phase angle P-control loop.

Note: During synchronization, first the frequency loop is started to match the generator frequency with the mains or bus and after that the phase angle loop is started to match the phase angle.

Note: See the chapter Regulation loops (page 102) for more information.

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Load Gain

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0,0 200,0 [%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8659	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the load control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			



Load Int

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	8713	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the load control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

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Load Sharing Gain

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0,0 200,0 [%]		
Default value	10,0 % Alternative config NO		
Step	0,1 %		
Comm object	8725	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the load sharing control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

O back to List of setpoints

Load Sharing Int

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	9035	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the load sharing control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			



Subgroup: Load Transfer

Close Transfer Max Duration

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0,1 Load Ramp (page 353) [s]		
Default value	5,0 s	Alternative config	NO
Step	0,1 s		
Comm object	8661	Related applications	SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
The time of parallel work of gen-set and mains in close transition.			

O back to List of setpoints

Open Transfer Min Break

Setpoint group	Speed/Load Control	Related FW	1.0.0	
Range [units]	0,1 600,0 [s]			
Default value	1,0 s	Alternative config	NO	
Step	0,1 s			
Comm object	8303	Related applications	SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always	Always		
Description				
Minimal duration of break in open transition when Transfer BusGen To Mains (page 352) or Transfer Mains To Gen Bus (page 351) is chosen as open transfer.				



Transfer Mains To Gen Bus

Set	point group	Speed/Load Control Related FW 1.0.0			
Ra	nge [units]	Open / Close Only / Close Primarily / Soft Transfer [-]			
Def	ault value	Soft Transfer Alternative config NO			
Ste	р	[-]			
Co	mm object	12969	Related applications	SPtM	
Co	nfig level	Standard			
Set	point visibility	Always			
Des	scription				
Thi	s setpoint defines	the type of transfer of load	from mains to generator b	ous.	
OpenTransfer of the load from mains to generator without parallel work and synchronization (one breaker opens and second is closed - checking feedb The setpoint Open Transfer Min Break (page 350) sets the minimal durat break.Close OnlyTransfer of the load from mains to generator with synchronization and parallel work is given by setpoint Close Transfer Max Duration (page 350) .			out parallel work and s closed - checking feedbacks). 50) sets the minimal duration of		
			synchronization and parallel nt Close Transfer Max and gen-set is stopped.		
	Close Primarily	Transfer of the load from mains to generator with synchronization and parallel work. The time of parallel work is given by setpoint Close Transfer Max Duration (page 350) .			
	Soft Transfer	er Transfer of the load from mains to generator with parallel work and soft loading of the gen-set. This function is proceeded like the closed transfer, but there is time limitation of loading of the gen-set adjusted via setpoint Load Ramp (page 353). The transfer is succeed only when the gen-set is fully loaded - mains is fully unloaded (level of load when mains is considered as unloaded is adjusted via setpoint Mains Unload MCB Open Window (page 353)).			

Note: Close transfer of load is also affected by setpoint Mains Import Measurement (page 239).



Transfer BusGen To Mains

Setpoint group Speed/Load Control		Speed/Load Control	Related FW	1.0.0
Rar	ange [units] Open / Close Only / Close Primarily / Soft Transfer [-]		-]	
Def	fault value	Soft Interchange Alternative config NO		
Ste	р	[-]		
Со	mm object	14688	Related applications	SPtM
Со	nfig level	Standard		
Set	point visibility	Always		
Des	scription			
This	s setpoint defines	the type of transfer of load	from generator to mains.	
OpenTransfer of the load from generator to mains without parallel w synchronization (one breaker opens and second is closed - ch The setpoint Open Transfer Min Break (page 350) sets the break.Close OnlyTransfer of the load from generator to mains with synchronization work. The time of parallel work is given by setpoint Close Transfer Duration (page 350) . In case of synchronization fail, MCB stays close and gen-set		out parallel work and s closed - checking feedbacks). 50) sets the minimal duration of		
		Transfer of the load fror work. The time of parall Duration (page 350) . In case of synchronizat	Transfer of the load from generator to mains with synchronization and parallel work. The time of parallel work is given by setpoint Close Transfer Max Duration (page 350) . In case of synchronization fail, MCB stays close and gen-set is stopped.	
	Close Primarily Transfer of the load from generator to mains with synchronization and parallel work. The time of parallel work is given by setpoint Close Transfer Max Duration (page 350) .			synchronization and parallel at Close Transfer Max
	Soft Transfer	Transfer of the load from generator to mains with parallel work and soft unloading of the gen-set. This function is proceeded like the closed transfer, but there is time limitation of unloading of the gen-set adjusted via setpoint Load Ramp (page 353). The transfer is succeed only when the gen-set is fully unloaded (level of load when gen-set is considered as unloaded is adjusted via setpoint Unload MGCB Open LevelGenerator Unload GCB Open Level (page 352)).		

O back to List of setpoints

Unload MGCB Open LevelGenerator Unload GCB Open Level

Setpoint group	Speed/Load Control	Related FW	1.0.0	
Range [units]	0 100 [%]			
Default value	10 %	Alternative config	NO	
Step	1 % of Nominal Power (page 242)			
Comm object	8547	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always	Always		
Description				
This setpoint adjusts the value of the power when the GCB MGCB is opened during unloading of the gen-set.				
<i>Note:</i> It is set usually higher than 0 to prevent the engine to go to reverse power.				



Mains Unload MCB Open Window

Setpoint group	Speed/Load Control	Related FW	1.0.0	
Range [units]	0 100 [%]			
Default value	10 %	Alternative config	NO	
Step	1 % of Nominal Power (page 242)			
Comm object	14694	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint adjusts the value which defines the level where the mains is considered as unloaded.				

Note: This setpoint is window. It means that when you adjust this setpoint to 10%, there is window from -10% to +10%. The reason is import/export function.

O back to List of setpoints

Load Ramp

Setpoint group	Speed/Load Control	Related FW	1.0.0
Range [units]	0600 [s]		
Default value	5 s	Alternative config	NO
Step	1s		
Comm object	8658	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
The max duration of soft transition(time for gen-set loading / unloading).			



Group: Voltage/PF Control

Subgroup: Voltage Control

Voltage Regulator Character

Setpoint group	Voltage/PF Control	Related FW	1.0.0	
Range [units]	Positive / Negative [-]			
Default value	Positive	Alternative config	NO	
Step	[-]			
Comm object	9055	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always	Always		
Description				
This setpoint selects the characteristic of the voltage governor output of the controller. Adjust it according to the behavior of the remote voltage input of the governor.				

Positive	Raising the voltage on the remote voltage adjustment input causes the generator voltage to raise.
Negative	Raising the voltage on the governor remote speed input causes engine speed to go down.

O back to List of setpoints

Voltage Regulator Bias

Setpoint group	Voltage/PF Control	Related FW	1.0.0		
Range [units]	-10,00 10,00 [V]				
Default value	0,00 V	Alternative config	NO		
Step	0,01 V				
Comm object	8500	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Always	Always			
Description					
This setpoint adjusts the initial level for the voltage governor output. This level is present on the output if no					

regulation loop is active.



Voltage Regulator Low Limit

Setpoint group	Voltage/PF Control	Related FW	1.0.0	
Range [units]	-10,00 10,00 [V]			
Default value	0,00 V	Alternative config	NO	
Step	0,01 V			
Comm object	14792	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
Lower limit of the voltage governor output. Use this setpoint to adjust the governor output range according to				

your governor type.

O back to List of setpoints

Voltage Regulator High Limit

Setpoint group	Voltage/PF Control	Related FW	1.0.0	
Range [units]	-10,00 10,00 [V]			
Default value	0,00 V	Alternative config	NO	
Step	0,01 V			
Comm object	14793	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
Upper limit of the voltage governor output. Use this setpoint to adjust the governor output range according to				

your governor type.

O back to List of setpoints

Tau Voltage Governor Actuator

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	1,0300,0 [s]		
Default value	10,0 s	Alternative config	NO
Step	0,1 s		
Comm object	10785	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint is used to adjust the transformation ratio of the voltage governor output to the pulses at the binary outputs **AVR UP (PAGE 706)** and **AVR DOWN (PAGE 706)**. Adjust the setpoint to the pulse duration which is needed for the voltage control device to travel from minimal position to the maximal position.



Subgroup: Regulation Loops

Voltage Gain

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0,0200,0[%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8501	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the voltage control PI loop.			

Note: See the chapter Regulation loops (page 102) for more information.

O back to List of setpoints

Voltage Int

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	8720	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the voltage control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

O back to List of setpoints

PF Gain

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0,0200,0[%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8503	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the PF control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			



PF Int

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	8721	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the PF control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

O back to List of setpoints

VAr Sharing Gain

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0,0200,0[%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8777	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the gain factor (P-factor) of the VAr sharing control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			

O back to List of setpoints

VAr Sharing Int

Setpoint group	Voltage/PF Control	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	50 %	Alternative config	NO
Step	1 %		
Comm object	9036	Related applications	MINT
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the relative integration factor (I-factor) of the VAr sharing control PI loop.			
Note: See the chapter Regulation loops (page 102) for more information.			



Group: Synchronisation

Synchronization Type

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	Phase Match / Slip Synchro [-]		
Default value	Phase Match	Alternative config	NO
Step	[-]		
Comm object	14802	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

This setpoint adjusts the type of synchronization.

Phase Match	This type of synchronization is based on voltage and phase shift match. Limits are adjusted via setpoints Voltage Window (page 359) and Phase Window (page 359) . When voltage and phase shift are match, Dwell Time (page 359) starts countdown. After that the command for breaker closing is activated.
Slip Synchro	This type of synchronization regulates the value of frequency to the value Mains/Bus frequency + Slip Frequency (page 360) (Mains frequency in SPtM, Bus frequency in MINT application). When this frequency is reached, Dwell Time (page 359) starts countdown. After that the command for breaker closing is activated. The closing breaker command is issued in advance due to latency of breakers (adjusted via setpoints GCB MGCB Latency (page 360) and MCB Latency (page 361)).
	Note: Condition of Voltage Window (page 359) has to be also fulfilled.

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Synchronization Timeout

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	OFF / 1 1800 [s]		
Default value	60 s	Alternative config	NO
Step	1s		
Comm object	8657	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the maximum duration of synchronizing.			

Note: If this setpoint is adjusted to OFF then automatic restart of synchronization occurs every 180s. This method helps to synchronize successfully even in difficult conditions.



Voltage Window

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	0,0 100,0 [%]		
Default value	10,0 %	Alternative config	NO
Step	0,1 %		
Comm object	8650	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts maximum difference between generator and mains/bus voltage in respective phases for synchronization.			

O back to List of setpoints

Phase Window

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	0 90 [°]		
Default value	10 °	Alternative config	NO
Step	1 °		
Comm object	8652	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
This setpoint adjusts the maximum absolute value of difference between actual phase angle between the generator and mains/bus voltages for synchronization.			

O back to List of setpoints

Dwell Time

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	0,025,0[s]		
Default value	0,3 s	Alternative config	NO
Step	0,1 s		
Comm object	8653	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
-			

The period of time that the phase angle difference must be within **Phase Window (page 359)** and voltage difference within **Voltage Window (page 359)** before the breaker is closed.



Slip Frequency

Setpoint group	Synchronisation	Related FW	1.0.0		
Range [units]	-0,50 0,50 [Hz]				
Default value	-0,25 Hz	Alternative config	NO		
Step	0,01 Hz				
Comm object	14798	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Slip frequency for slip synchronization (Synchronization Type (page 358) = Slip Synchro).					

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Slip Frequency Window

Setpoint group	Synchronisation	Related FW	1.0.0		
Range [units]	0,01 0,50 [Hz]				
Default value	0,15 Hz	Alternative config	NO		
Step	0,01 Hz				
Comm object	14799	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Window of slip frequency for slip synchronization (Synchronization Type (page 358) = Slip Synchro).					

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GCB MGCB Latency

Setpoint group	Synchronisation	Related FW	1.0.0		
Range [units]	201000 [ms]				
Default value	80 ms	Alternative config	NO		
Step	1 ms				
Comm object	14800	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Latency of GCB MGCB.					
IMPORTANT: This setpoint is enable, when Synchronization Type (page 358) has Split Synchro value					


MCB Latency

Setpoint group	Synchronisation	Related FW	1.0.0
Range [units]	201000 [ms]		
Default value	80 ms	Alternative config	NO
Step	1 ms		
Comm object	14801	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Latency of MCB.			
IMPORTANT: This setpoint is enable, when Synchronization Type (page 358) has Split			

Synchro value

O back to List of setpoints

Group: Droop Settings

Subgroup: Droop Settings

Load/Var Sharing Regulation Type

Setpoint group	Droop Settings	Related FW	1.0.0	
Range [units]	Isochronous / Droop / Emergency Droop [-]			
Default value	sonchronous Alternative config NO			
Step	[-]			
Comm object	13212	Related applications	MINT	
Config level	Advanced			
Setpoint visibility	Visible only if ECU is configured			
Description				

This setpoint adjusts how the active and reactive power is regulated. The droop is primarily intended for multiple parallel operation in island to ensure the load sharing and VAr sharing when intercontroller communication fails.

Isochronous	The active and reactive power is regulated based on data communicated between the controller units (intercontroller communication).
Droop	The active and reactive power is not regulated based on data communicated between the units but the speed request and voltage request is calculated from actual voltage and actual frequency of the system. The speed request is correlative to active power and the voltage request is correlative to reactive power.
Emrg Droop	Regulation of active and reactive power is based on standard isochronous regulation based on intercontroller communication but it can be conditionally turned to droop



Dead Bus GCB Close Master

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	Disabled / Enabled [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	13952	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			

This setpoint adjusts the behavior of GCB for droop regulation in AUTO mode. If the bus values are without the limits then the controller is prohibited to close it's GCB because of safety reasons.

Disabled	If the bus values are without the limits then the controller is prohibited to close it's GCB because of safety reasons. Closing of GCB can be done manually in MAN mode.
Enabled	If the bus values are without the limits, controller is allowed to close it's GCB to the dead bus.

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Subgroup: Frequency Droop

Frequency Droop Slope

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0,020,0[%]		
Default value	4,0 %	Alternative config	NO
Step	0,1 %		
Comm object	10032	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			
This setpoint defines the slope of the load droop correlation. The slope is set as a droop of frequency in percentages of the requested system frequency (Basic settings: Nominal Frequency (page 247)) on the			

percentages of the requested system frequency (Basic settings: Nominal Frequency (page 247)) on t range of the requested power from 0 to 100% of Basic settings: Nominal Power (page 242).



Frequency Droop Offset

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	100 %	Alternative config	NO
Step	1 %		
Comm object	13213	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			
This setpoint defines the value of requested power on the requested system frequency (Basic settings: Nominal Frequency (page 247)). Allows to shift the droop correlation line up or down.			

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Subgroup: Voltage Droop

Voltage Droop Slope

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0,020,0[%]		
Default value	4,0 %	Alternative config	NO
Step	0,1 %		
Comm object	10033	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			
This set point defines the slope of the V/Ar droop correlation. The slope is set as a droop of voltage in			

This setpoint defines the slope of the VAr droop correlation. The slope is set as a droop of voltage in percentages of the generator nominal voltage (Basic settings: **Nominal Voltage Ph-N (page 246)**) on the range of the requested reactive power from 0 to 100% of nominal reactive power (value of nominal reactive power is not given by setpoint but it is calculated from setpoint **Nominal Power (page 242)** whilst the PF=0,8).



Voltage Droop Offset

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0 100 [%]		
Default value	100 %	Alternative config	NO
Step	1 %		
Comm object	13214	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			
This setpoint defines the value of requested reactive power on the nominal voltage (Basic settings: Nominal Voltage Ph-N (page 246)). Allows to shift the droop correlation line up or down.			

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Subgroup: Emergency Droop Settings

#Number Of Controller On CAN

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	1 32 [-]		
Default value	1	Alternative config	NO
Step	1		
Comm object	13953	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			

This setpoint defines the minimum number of units supposed to be connected to CAN2. See values CAN16 and CAN32 for information about number of controllers on CAN2 bus. Controller counts itself as well, the number is always 1 or higher, it is never 0. If the number of controllers detected by the controller on CAN2 is lower than the number in this setpoint, the system falls in emergency droop, it means that regulations are switched to droop after delay defined by **#Emergency Droop On Delay (page 365)**. If the intercontroller communication recovers (the number of controllers detected on CAN2 gets equal or higher than value in this setpoint, then the system turns the regulations back to isochronous mode after delay defined by setpoint **#Emergency Droop Off Delay (page 365)**.

Note: This function is available only when Load/Var Sharing Regulation Type (page 361) = Emergency Droop.



#Emergency Droop On Delay

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0,010,0[s]		
Default value	10,0 s	Alternative config	NO
Step	0,1 s		
Comm object	13954	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			
This setpoint adjusts the delay for switching from isochronou regulation to droop regulation when number of			

controller detected by the controller on CAN2 is lower than the number in the setpoint **#Number Of Controller On CAN (page 364)**.

Note: This function is available only when Load/Var Sharing Regulation Type (page 361) = Emergency Droop.

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#Emergency Droop Off Delay

Setpoint group	Droop Settings	Related FW	1.0.0
Range [units]	0,010,0[s]		
Default value	10,0 s	Alternative config	NO
Step	0,1 s		
Comm object	13955	Related applications	MINT
Config level	Advanced		
Setpoint visibility	Always		
Description			

This setpoint adjusts the delay for switching from droop regulation to isochronous regulation when number of controller detected by the controller on CAN2 is equal or higher than the number in the setpoint **#Number Of Controller On CAN (page 364)**.

Note: This function is available only when Load/Var Sharing Regulation Type (page 361) = Emergency Droop.



Group: General Analog Inputs

General Analog Input 1

Analog Protection 1 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9259	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT01 (PAGE 744) is configured			
Description				
Warning or history threshold level for AIN PROT01 (PAGE 744).				
Note: These setpoints are used only if LAI AIN PROT01 (PAGE 744) is adjusted to required protection				

type. Otherwise these setpoints are useless.

O back to List of setpoints

Analog Protection 1 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0		
Range [units]	the range is defined by analog sensor curve				
Default value	the value is defined by analog sensor curve	Alternative config	NO		
Step	the step is defined by analog sensor curve				
Comm object	9260	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Visible only if the logical analog input AIN PROT01 (PAGE 744) is configured				
Description					
Shutdown or BOC threshold level for AIN PROT01 (PAGE 744).					
Note: These setpoints are used only if LAI AIN PROT01 (PAGE 744) is adjusted to required protection type. Otherwise these setpoints are useless.					



Analog Protection 1 Delay

Se	tpoint group	General Analog Inputs	Related FW	1.0.0		
Ra	nge [units]	0900[s]				
De	fault value	0 s Alternative config NO				
Ste	ep 🛛	1s				
Co	mm object	9261	Related applications	MINT, SPtM		
Co	nfig level	Standard				
Se	tpoint visibility	Visible only if the logical analog input AIN PROT01 (PAGE 744) is configured				
De	Description					
De	Delay for AIN PROT01 (PAGE 744).					
Note: These setpoints are used only if LAI AIN PROT01 (PAGE 744) is adjusted to required protection type. Otherwise these setpoints are useless.						

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Analog Switch 1 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	11407 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH01 (PAGE 696) is configured			
Description				

Description

Threshold level for switching the binary output **AIN SWITCH01 (PAGE 696)** on. The value is measured from **AIN SWITCH 01 (PAGE 764)** analog input.







Analog Switch 1 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analo	the step is defined by analog sensor curve		
Comm object	11410Related applicationsMINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH01 (PAGE 696) is configured			
Description				

Threshold level for switching the binary output **AIN SWITCH01** (PAGE 696) off. The value is measured from **AIN SWITCH 01** (PAGE 764) analog input.



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General Analog Input 2

Analog Protection 2 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9262	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT02 (PAGE 745) is configured			
Description				
Warning or history threshold level for AIN PROT02 (PAGE 745).				

Note: These setpoints are used only if LAI **AIN PROTO2** (PAGE **745**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 2 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9263	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT02 (PAGE 745) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT02 (PAGE 745).				

Note: These setpoints are used only if LAI **AIN PROTO2** (PAGE **745**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 2 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9264	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT02 (PAGE 745) is configured			
Description				
Delay for AIN PROT02 (PAGE 745).				
Note: These setpoints are used only if LAI AIN PROT02 (PAGE 745) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 2 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	11408	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch02	(PAGE 696) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 02 (PAGE 764) on. The value is measured from AIN SwITCH 02 (PAGE 764) analog input.				
Image 9.27 General analog input 2 switch				



Analog Switch 2 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	11411	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH02 (PAGE 696) is configured			
Description				

Threshold level for switching the binary output **AIN SWITCH 02 (PAGE 764)** off. The value is measured from **AIN SWITCH 02 (PAGE 764)** analog input.



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General Analog Input 3

Analog Protection 3 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9265	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT03 (PAGE 746) is configured			
Description				
Warning or history threshold level for AIN PROT03 (PAGE 746).				

Note: These setpoints are used only if LAI **AIN PROT03** (PAGE **746**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 3 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9266	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT03 (PAGE 746) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT03 (PAGE 746).				

Note: These setpoints are used only if LAI **AIN PROT03** (PAGE **746**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 3 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0		
Range [units]	0 900 [s]				
Default value	0 s	Alternative config	NO		
Step	1s				
Comm object	9267	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT03 (PAGE 746) is configured				
Description					
Delay for AIN PROT03 (PAGE 746).					
Note: These setpoints are used only if LAI AIN PROT03 (PAGE 746) is adjusted to required protection					

type. Otherwise these setpoints are useless.



Analog Switch 3 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	11409	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	inary output AIN Swiтсн03	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwiTcH 03 (PAGE 764) on. The value is measured from AIN SwiTcH 03 (PAGE 764) analog input. General Analog Switch Output Level On - Level Off Level O				
Image 9.29 General analog input 3 switch				



Analog Switch 3 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analo	og sensor curve		
Comm object	11412 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH03 (PAGE 697) is configured			
Description				

Threshold level for switching the binary output **AIN SWITCH 03 (PAGE 764)** off. The value is measured from **AIN SWITCH 03 (PAGE 764)** analog input.



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General Analog Input 4

Analog Protection 4 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9268	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT04 (PAGE 747) is configured			
Description				
Warning or history threshold level for AIN PROT04 (PAGE 747).				

Note: These setpoints are used only if LAI **AIN PROT04** (PAGE **747**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 4 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9269	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT04 (PAGE 747) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT04 (PAGE 747).				

Note: These setpoints are used only if LAI **AIN PROT04** (PAGE **747**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 4 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0		
Range [units]	0900[s]				
Default value	0 s	Alternative config	NO		
Step	1s				
Comm object	9270	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT04 (PAGE 747) is configured				
Description					
Delay for AIN PROT04 (PAGE 747).					
Note: These setpoints are used only if LAI AIN PROT04 (PAGE 747) is adjusted to required protection					

type. Otherwise these setpoints are useless.



Analog Switch 4 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14385	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwiTcH 04 (PAGE 765) on. The value is measured from AIN SwiTcH 04 (PAGE 765) analog input. General Analog Switch Output Level On > Level Off Level O				
Image 9.31 General analog input 4 switch				



Analog Switch 4 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14386	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured			
Description				
Threshold level for switching the binary output AIN SWITCH 04 (PAGE 765) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 5

Analog Protection 5 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9271	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT05 (PAGE 748) is configured			
Description				
Warning or history threshold level for AIN PROT05 (PAGE 748).				

Note: These setpoints are used only if LAI **AIN PROT05** (PAGE **748**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 5 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9272	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT05 (PAGE 748) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT05 (PAGE 748).				

Note: These setpoints are used only if LAI **AIN PROT05** (PAGE **748**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 5 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9273	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT05 (PAGE 748) is configured			
Description				
Delay for AIN PROT05 (PAGE 748).				
Note: These setpoints are used only if LAI AIN PROT05 (PAGE 748) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 5 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14963	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwiTCH 05 (PAGE 765) on. The value is measured from AIN SwiTCH 05 (PAGE 765) analog input. General Analog Switch Output Level On - Level Off Level On - Level Off Center Off Cente				
Image 9.33 General analog input 4 switch				



Analog Switch 5 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14979 Related applications MINT, SPtM		
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for quitching the hings, output AIN SWITCH OF (DAGE 765) off. The value is measured from			

Threshold level for switching the binary output **AIN SWITCH 05 (PAGE 765)** off. The value is measured from **AIN SWITCH 05 (PAGE 765)** analog input.



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General Analog Input 6

Analog Protection 6 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9274	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT06 (PAGE 749) is configured			
Description				
Warning or history threshold level for AIN PROT06 (PAGE 749).				

Note: These setpoints are used only if LAI **AIN PROTO6** (PAGE **749**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 6 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9275	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT06 (PAGE 749) is configured			
Description				
Shutdown or BOC threshold level for AIN PROTO6 (PAGE 749).				

Note: These setpoints are used only if LAI **AIN PROTO6** (PAGE **749**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 6 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9276	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT06 (PAGE 749) is configured			
Description				
Delay for AIN PROT06 (PAGE 749).				
Note: These setpoints are used only if LAI AIN PROT06 (PAGE 749) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 6 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14964	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SwiTcH 06 (PAGE 765) on. The value is measured from AIN SwiTcH 04 (PAGE 765) analog input.				
Image 9.35 General analog input 4 switch				



Analog Switch 6 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14980	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured			
Description				
Threshold level for switching the binary output AIN SWITCH 06 (PAGE 765) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 7

Analog Protection 7 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9277	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT07 (PAGE 750) is configured			
Description				
Warning or history threshold level for AIN PROT07 (PAGE 750).				

Note: These setpoints are used only if LAI **AIN PROTO7** (PAGE **750**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 7 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9278 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT07 (PAGE 750) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT07 (PAGE 750).				

Note: These setpoints are used only if LAI **AIN PROTO7** (PAGE **750**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 7 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900 [s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9279	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT07 (PAGE 750) is configured			
Description				
Delay for AIN PROT07 (PAGE 750).				
Note: These setpoints are used only if LAI AIN PROT07 (PAGE 750) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 7 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14965	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SwiTcH 07 (PAGE 766) on. The value is measured from AIN SwiTcH 04 (PAGE 765) analog input.				
Image 9.37 General analog input 4 switch				



Analog Switch 7 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14981	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured			
Description				
Threshold level for switching the binary output AIN SWITCH 07 (PAGE 766) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 8

Analog Protection 8 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9280	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT08 (PAGE 751) is configured			
Description				
Warning or history threshold level for AIN PROT08 (PAGE 751).				

Note: These setpoints are used only if LAI **AIN PROT08** (PAGE **751**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 8 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9281	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT08 (PAGE 751) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT08 (PAGE 751).			

Note: These setpoints are used only if LAI **AIN PROT08** (PAGE **751**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 8 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900[s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9282	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT08 (PAGE 751) is configured		
Description			
Delay for AIN PROT08 (PAGE 751).			
Note: These setpoints are used only if LAI AIN PROT08 (PAGE 751) is adjusted to required protection			

type. Otherwise these setpoints are useless.



Analog Switch 8 On

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by anal	og sensor curve	
Comm object	14966	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured
Description			
Description Threshold level for switching the binary output AIN SwiTCH 08 (PAGE 766) on. The value is measured from AIN SwiTCH 04 (PAGE 765) analog input. General Analog Switch Output Level On < Level Off Level O			
Image 9.39 General analog input 4 switch			



Analog Switch 8 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14982	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for switching the binary output AIN SWITCH 08 (PAGE 766) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.			



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General Analog Input 9

Analog Protection 9 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9283	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT09 (PAGE 752) is configured		
Description			
Warning or history threshold level for AIN PROT09 (PAGE 752).			

Note: These setpoints are used only if LAI **AIN PROT09** (PAGE **752**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 9 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9284	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT09 (PAGE 752) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT09 (PAGE 752).			

Note: These setpoints are used only if LAI **AIN PROT09** (PAGE **752**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 9 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900 [s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9285	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT09 (PAGE 752) is configured		
Description			
Delay for AIN PROT09 (PAGE 752).			
Note: These setpoints are used only if LAI AIN PROT09 (PAGE 752) is adjusted to required protection			

type. Otherwise these setpoints are useless.



Analog Switch 9 On

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by anal	og sensor curve	
Comm object	14967	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured
Description			
Threshold level for switching the binary output AIN SwITCH 09 (PAGE 766) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input.			
Image 9.41 General analog input 4 switch			



Analog Switch 9 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by ana	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	14983	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 09 (PAGE 766) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 10

Analog Protection 10 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9286	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT10 (PAGE 753) is configured		
Description			
Warning or history threshold level for AIN PROT10 (PAGE 753).			

Note: These setpoints are used only if LAI **AIN PROT10** (PAGE **753**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 10 Sd

General Analog Inputs	Related FW	1.0.0	
the range is defined by analog sensor curve			
the value is defined by analog sensor curve	Alternative config	NO	
the step is defined by analog sensor curve			
9287	Related applications	MINT, SPtM	
Standard			
Visible only if the logical analog input AIN PROT10 (PAGE 753) is configured			
Description			
Shutdown or BOC threshold level for AIN PROT10 (PAGE 753).			
	General Analog Inputs the range is defined by an the value is defined by analog sensor curve the step is defined by ana 9287 Standard Visible only if the logical a reshold level for AIN Pro	General Analog Inputs Related FW the range is defined by analog sensor curve sensor curve the step is defined by analog sensor curve Alternative config 9287 Related applications Standard Visible only if the logical analog input AIN PROT10 (PAGE 753).	

Note: These setpoints are used only if LAI **AIN PROT10** (PAGE **753**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 10 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900[s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9288	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT10 (PAGE 753) is configured		
Description			
Delay for AIN PROT10 (PAGE 753).			
Note: These setpoints are used only if LAI AIN PROT10 (PAGE 753) is adjusted to required protection			

type. Otherwise these setpoints are useless.



Analog Switch 10 On

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14968	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Description Threshold level for switching the binary output AIN SwITCH 10 (PAGE 767) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input. General Analog Switch Output Level On < Level Off Level On < Level Off Level On < Level Off Level O			
Image 9.43 General analog input 4 switch			



Analog Switch 10 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14984	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for switching the binary output AIN SWITCH 10 (PAGE 767) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.			



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General Analog Input 11

Analog Protection 11 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9289	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT11 (PAGE 754) is configured		
Description			
Warning or history threshold level for AIN PROT11 (PAGE 754).			

Note: These setpoints are used only if LAI **AIN PROT11** (PAGE **754**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 11 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9290	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT11 (PAGE 754) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT11 (PAGE 754).			

Note: These setpoints are used only if LAI **AIN PROT11** (PAGE **754**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 11 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900[s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9291	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT11 (PAGE 754) is configured		
Description			
Delay for AIN PROT11 (PAGE 754).			
Note: These setpoints are used only if LAI AIN PROT11 (PAGE 754) is adjusted to required protection			

type. Otherwise these setpoints are useless.


Analog Switch 11 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	14969	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SWITCH 11 (PAGE 767) on. The value is measured from AIN SWITCH 04 (PAGE 765) analog input. General Analog Switch Output Level On > Level Off Level On < Level Off Level O				
Image 0.45 Constal analog input 4 quitch				



Analog Switch 11 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14985	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 11 (PAGE 767) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 12

Analog Protection 12 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9292	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT12 (PAGE 755) is configured			
Description				
Warning or history threshold level for AIN PROT12 (PAGE 755).				

Note: These setpoints are used only if LAI **AIN PROT12** (PAGE **755**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 12 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9293 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT12 (PAGE 755) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT12 (PAGE 755).				

Note: These setpoints are used only if LAI **AIN PROT12** (PAGE **755**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 12 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9294	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT12 (PAGE 755) is configured			
Description				
Delay for AIN PROT12 (PAGE 755).				
Note: These setpoints are used only if LAI AIN PROT12 (PAGE 755) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 12 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14970	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 12 (PAGE 767) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input.				
Image 9.47 General analog input 4 switch				



Analog Switch 12 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analo	og sensor curve		
Comm object	14986	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 12 (PAGE 767) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				
	Level On > Level Off	Level On < Level Off		



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General Analog Input 13

Analog Protection 13 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9295 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT13 (PAGE 756) is configured			
Description				
Warning or history threshold level for AIN PROT13 (PAGE 756).				

Note: These setpoints are used only if LAI **AIN PROT13 (PAGE 756)** is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 13 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9296 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT13 (PAGE 756) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT13 (PAGE 756).				

Note: These setpoints are used only if LAI **AIN PROT13** (PAGE **756**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 13 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0		
Range [units]	0900[s]				
Default value	0 s	Alternative config	NO		
Step	1s				
Comm object	9297	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT13 (PAGE 756) is configured				
Description					
Delay for AIN PROT13 (PAGE 756).					
Note: These setpoints are used only if LAI AIN PROT13 (PAGE 756) is adjusted to required protection					

type. Otherwise these setpoints are useless.



Analog Switch 13 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14971	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN Switch 13 (PAGE 768) on. The value is measured from AIN Switch 04 (PAGE 765) analog input.				
Image 9.49 General analog input 4 switch				



Analog Switch 13 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14987	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured			
Description				
Threshold level for switching the binary output AIN SWITCH 13 (PAGE 768) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 14

Analog Protection 14 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9298	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT14 (PAGE 757) is configured		
Description			
Warning or history threshold level for AIN PROT14 (PAGE 757).			

Note: These setpoints are used only if LAI **AIN PROT14** (PAGE **757**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 14 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9299	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT14 (PAGE 757) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT14 (PAGE 757).			

Note: These setpoints are used only if LAI **AIN PROT14** (PAGE **757**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 14 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900[s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9300	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT14 (PAGE 757) is configured		
Description			
Delay for AIN PROT14 (PAGE 757).			
Note: These setpoints are used only if LAI AIN PROT14 (PAGE 757) is adjusted to required protection			

type. Otherwise these setpoints are useless.



Analog Switch 14 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14972	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SWITCH 14 (PAGE 768) on. The value is measured from AIN SWITCH 04 (PAGE 765) analog input. General Analog Switch Output off tevel On > Level Off tevel On < Level Off tevel Off te				
Image 9.51 General analog input 4 switch				



Analog Switch 14 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14988	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for switching the binary output AIN SWITCH 14 (PAGE 768) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.			



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General Analog Input 15

Analog Protection 15 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9301	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT15 (PAGE 758) is configured		
Description			
Warning or history threshold level for AIN PROT15 (PAGE 758).			

Note: These setpoints are used only if LAI **AIN PROT15** (PAGE **758**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 15 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9302	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT15 (PAGE 758) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT15 (PAGE 758).			

Note: These setpoints are used only if LAI **AIN PROT15** (PAGE **758**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 15 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	0900[s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	9303	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT15 (PAGE 758) is configured		
Description			
Delay for AIN PROT15 (PAGE 758).			
Note: These setpoints are used only if LAI AIN PROT15 (PAGE 758) is adjusted to required protection			

type. Otherwise these setpoints are useless.



Analog Switch 15 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14973	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwiTCH 15 (PAGE 768) on. The value is measured from AIN SwiTCH 04 (PAGE 765) analog input. General Analog Switch Output Level On > Level Off Level Off Level On > Level Off Level On > Level Off Level Off Level Off Level On > Level Off Level Off				
Image 9.53 General analog input 4 switch				



Analog Switch 15 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14989	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for switching the binary output AIN SWITCH 15 (PAGE 768) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.			



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General Analog Input 16

Analog Protection 16 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9304	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT16 (PAGE 759) is configured		
Description			
Warning or history threshold level for AIN PROT16 (PAGE 759).			

Note: These setpoints are used only if LAI **AIN PROT16** (PAGE **759**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 16 Sd

General Analog Inputs	Related FW	1.0.0	
the range is defined by analog sensor curve			
the value is defined by analog sensor curve	Alternative config	NO	
the step is defined by analog sensor curve			
9305	Related applications	MINT, SPtM	
Standard			
Visible only if the logical analog input AIN PROT16 (PAGE 759) is configured			
Description			
Shutdown or BOC threshold level for AIN PROT16 (PAGE 759).			
	General Analog Inputs the range is defined by an the value is defined by analog sensor curve the step is defined by ana 9305 Standard Visible only if the logical a reshold level for AIN Pro	General Analog Inputs Related FW the range is defined by analog sensor curve sensor curve the step is defined by analog sensor curve Alternative config 9305 Related applications Standard Visible only if the logical analog input AIN PROT16 (PAGE 759).	

Note: These setpoints are used only if LAI **AIN PROT16** (PAGE **759**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 16 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9306	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT16 (PAGE 759) is configured			
Description				
Delay for AIN PROT16 (PAGE 759).				
Note: These setpoints are used only if LAI AIN PROT16 (PAGE 759) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 16 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	14974	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwiTCH 16 (PAGE 769) on. The value is measured from AIN SwiTCH 04 (PAGE 765) analog input. General Analog Switch Output Level On > Level Off Level On < Level Off Level O				
Image 9.55 General analog input 4 switch				



Analog Switch 16 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14990	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 16 (PAGE 769) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 17

Analog Protection 17 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9307	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT17 (PAGE 760) is configured			
Description				
Warning or history threshold level for AIN PROT17 (PAGE 760).				

Note: These setpoints are used only if LAI **AIN PROT17** (PAGE **760**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 17 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9308 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT17 (PAGE 760) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT17 (PAGE 760).				

Note: These setpoints are used only if LAI **AIN PROT17** (PAGE **760**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 17 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0		
Range [units]	0900[s]				
Default value	0 s	Alternative config	NO		
Step	1s				
Comm object	9309	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT17 (PAGE 760) is configured				
Description					
Delay for AIN PROT17 (PAGE 760).					
Note: These setpoints are used only if LAI AIN PROT17 (PAGE 760) is adjusted to required protection					

type. Otherwise these setpoints are useless.



Analog Switch 17 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	14975	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 17 (PAGE 769) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input. General Analog Switch Output				
Image 9.57 General analog input 4 switch				



Analog Switch 17 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14991	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 17 (PAGE 769) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 18

Analog Protection 18 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9310 Related applications MINT, SPtM			
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT18 (PAGE 761) is configured			
Description				
Warning or history threshold level for AIN PROT18 (PAGE 761).				

Note: These setpoints are used only if LAI **AIN PROT18** (PAGE **761**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 18 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9311	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT18 (PAGE 761) is configured			
Description				
Shutdown or BOC threshold level for AIN PROT18 (PAGE 761).				

Note: These setpoints are used only if LAI **AIN PROT18** (PAGE **761**) is adjusted to required protection type. Otherwise these setpoints are useless.

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Analog Protection 18 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9312	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT18 (PAGE 761) is configured			
Description				
Delay for AIN PROT18 (PAGE 761).				
Note: These setpoints are used only if LAI AIN PROT18 (PAGE 761) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 18 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14976	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 18 (PAGE 769) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input. General Analog Switch Output Level On - Level Off Level				
Image 9.59 General analog input 4 switch				



Analog Switch 18 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by ana	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14992	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured			
Description				
Threshold level for switching the binary output AIN SWITCH 18 (PAGE 769) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				



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General Analog Input 19

Analog Protection 19 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9313	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT19 (PAGE 762) is configured			
Description				
Warning or history threshold level for AIN PROT19 (PAGE 762).				

Note: These setpoints are used only if LAI **AIN PROT19** (PAGE **762**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 19 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9314	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT19 (PAGE 762) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT19 (PAGE 762).			

Note: These setpoints are used only if LAI **AIN PROT19** (PAGE **762**) is adjusted to required protection type. Otherwise these setpoints are useless.

O back to List of setpoints

Analog Protection 19 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9315	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT19 (PAGE 762) is configured			
Description				
Delay for AIN PROT19 (PAGE 762).				
Note: These setpoints are used only if LAI AIN PROT19 (PAGE 762) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 19 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	14977	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 19 (PAGE 770) on. The value is measured from AIN SwITCH 04 (PAGE 765) analog input. General Analog Switch Output				
Image 9.61 General analog input 4 switch				



Analog Switch 19 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	14993	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical binary output AIN SWITCH04 (PAGE 697) is configured		
Description			
Threshold level for switching the binary output AIN SWITCH 19 (PAGE 770) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.			
General Analog			



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General Analog Input 20

Analog Protection 20 Wrn

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	9316	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT20 (PAGE 763) is configured			
Description				
Warning or history threshold level for AIN PROT20 (PAGE 763).				

Note: These setpoints are used only if LAI **AIN PROT20** (PAGE **763**) is adjusted to required protection type. Otherwise these setpoints are useless.



Analog Protection 20 Sd

Setpoint group	General Analog Inputs	Related FW	1.0.0
Range [units]	the range is defined by analog sensor curve		
Default value	the value is defined by analog sensor curve	Alternative config	NO
Step	the step is defined by analog sensor curve		
Comm object	9317	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Visible only if the logical analog input AIN PROT20 (PAGE 763) is configured		
Description			
Shutdown or BOC threshold level for AIN PROT20 (PAGE 763).			

Note: These setpoints are used only if LAI **AIN PROT20** (PAGE **763**) is adjusted to required protection type. Otherwise these setpoints are useless.

O back to List of setpoints

Analog Protection 20 Delay

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	0900[s]			
Default value	0 s	Alternative config	NO	
Step	1s			
Comm object	9318	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical analog input AIN PROT20 (PAGE 763) is configured			
Description				
Delay for AIN PROT20 (PAGE 763).				
Note: These setpoints are used only if LAI AIN PROT20 (PAGE 763) is adjusted to required protection				

type. Otherwise these setpoints are useless.



Analog Switch 20 On

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by analog	og sensor curve		
Comm object	14978	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Switch04	(PAGE 697) is configured	
Description				
Description Threshold level for switching the binary output AIN SwITCH 20 (PAGE 770) on. The value is measured from AIN SWITCH 04 (PAGE 765) analog input. General Analog Switch Output Level On < Level Off Level On < Level Off Level Off				
Image 9.63 General analog input 4 switch				



Analog Switch 20 Off

Setpoint group	General Analog Inputs	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	the value is defined by analog sensor curve	Alternative config	NO	
Step	the step is defined by anal	og sensor curve		
Comm object	14994	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Visible only if the logical bi	nary output AIN Swiтсн04	(PAGE 697) is configured	
Description				
Threshold level for switching the binary output AIN SWITCH 20 (PAGE 770) off. The value is measured from AIN SWITCH 04 (PAGE 765) analog input.				
General Analog Switch Output				
Leve	l Off Level On	Level On Level Off	Time	
Image 9.64 General analog input 4 switch				

O back to List of setpoints

Group: Scheduler

Subgroup: Time & Date

Time

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	HH:MM:SS [-]		
Default value	0:0:0	Alternative config	NO
Step	[-]		
Comm object	24554	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Real time clock adjustment.			



Date

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	DD/MM/YYYY [-]			
Default value	1.1.2015	Alternative config	NO	
Step	[·]			
Comm object	24553	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Always			
Description				
Actual date adjustment.				

O back to List of setpoints

Time Stamp Period

Setpoint group	Scheduler	Related FW	1.0.0		
Range [units]	0 240 [min]				
Default value	60 min Alternative config NO				
Step	1 min				
Comm object	8979	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description	Description				
Time interval for periodic history records.					
Note: History record is made only when engine is running.					

O back to List of setpoints

#Summer Time Mode

Setpoint group	Scheduler	Related FW	1.0.0		
Range [units]	Disabled / Winter / Summ	Disabled / Winter / Summer / Winter - S / Summer - S [-]			
Default value	Disabled	Alternative config	NO		
Step	[-]				
Comm object	8727	Related applications	MINT, SPtM		
Config level	Advanced	Advanced			
Setpoint visibility	Always	Always			
Description					
Behavior of switchi	ng between winter and sum	mer time.			
Disable A	utomatic switching betweer	tomatic switching between summer and wintertime is disabled.			
Winter A	utomatic switching betweer	tomatic switching between summer and wintertime is enabled and it is set to winter			
(Summer) (s	ummer) season.	mmer) season.			
Winter - S (Summer - S)	dification for southern hemisphere.				



Subgroup: Timer 1

Timer 1 Setup

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	10969	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Related setpoints for timer 1 are:				
Timer 1 Function (page 428)		Timer 1 Day (page 432)	

- Timer 1 Repetition (page 429)
- Timer 1 First Occur. Date (page 429)
- Timer 1 First Occur. Time (page 429)
- Timer 1 Duration (page 430)
- Timer 1 Repeated (page 430)
- Timer 1 Repeat Day (page 433)

- Timer 1 Repeated Day In Week (page 433)
- Timer 1 Repeat Day In Month (page 433)
- Timer 1 Repeat Week In Month (page 434)
- Timer 1 Refresh Period (page 431)
- Timer 1 Weekends (page 432)



Timer 1 Function

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	Disable / No Func / TEST / Test OnLd / MFail Blk / Mode OFF [-]		
Default value	Disable	Alternative config	NO
Step	[-]		
Comm object	15358	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
_			

Description

It is possible to choose from following timer functions. Binary output **EXERCISE TIMER 1 (PAGE 713)** is always activated when Timer is active regardless of chosen timer function. Timer functions require controller running in AUTO mode.

IMPORTANT: Binary output is activated always when timer should be activated e.g. even when controller is in different mode than AUTO.

Timer 1 has the highest priority. Timer 8 has the lowest priority. So if Timer 1 is configured for OFF mode and Timer 8 is over the same time configured for AUTO mode, controller will work in OFF mode.

Controller activates timer whenever it is powered up even in period, where timer should be already running.

Disable	The Timer is disabled.
No Func	There is no any other function, only binary output of timer is activated.
Auto Run	When this option is chosen then the binary output of timer is internally connected to the REMOTE START/STOP (PAGE 677) binary input.
TEST	When this option is chosen then the binary output of timer is internally connected to the binary input Remote TEST.
TEST OnLd	When this option is chosen then the binary output of timer is internally connected to the Remote TEST On Load binary input.
MFail Blk	When this option is chosen then the binary output of timer is internally connected to the Mains Fail Block binary input.
Mode OFF	When this option is chosen then the binary output of timer is internally connected to the Remote OFF binary input.



Timer 1 Repetition

Setpoint grou	ıp	Scheduler	Related FW	1.0.0	
Range [units]		Off / Once / Repeated [-]			
Default value		Off Alternative config NO			
Step		H			
Comm object	t	0 Related applications MINT, SPtM			
Config level		Standard			
Setpoint visit	oility	Conditioned by the setpoi	nt Timer 1 Function (pag	je 428)	
Description					
Defines repetit	tion of	Timer 1 Function (page	428).		
Off	Timer	1 Function (page 428) will not be activated.			
Once	Timer	¹ Function (page 428) will be activated only one time.			
Repeated	Timer 1 Function (page 428) will be repeatedly activated.				

O back to List of setpoints

Timer 1 First Occur. Date

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[DD/MM/YYYY]			
Default value	01/01/2000	Alternative config	NO	
Step	F			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Date of first occurrence of Timer 1 Function (page 428).				

O back to List of setpoints

Timer 1 First Occur. Time

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[HH:MM]			
Default value	00:00	Alternative config	NO	
Step	H			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Time of first occurrence of Timer 1 Function (page 428).				



Timer 1 Duration

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[HH:MM]			
Default value	00:00	Alternative config	NO	
Step	H			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Timer 1 Function (page 428) duration time.				

O back to List of setpoints

Timer 1 Repeated

Setpoint group		Scheduler	Related FW	1.0.0
Range [units]		Daily / Weekly / Monthly / Short Period [-]		
Default value		Daily Alternative config NO		
Step		[-]		
Comm object		0	Related applications	MINT, SPtM
Config level		Standard		
Setpoint visibili	ty	Conditioned by the setpoi	nt Timer 1 Function (pag	ge 428)
Description				
Repeated interva	l of '	Timer 1 Function (page	428).	
Daily T	Timer 1 Function (page 428) is repeated every day.			
Weekly T	imer 1 Function (page 428) is repeated every week in chosen days.			
Monthly T	Fimer 1 Function (page 428) is repeated in chosen day every month or in chosen days of			
C	hos	osen week of month		
Short Period T	Timer 1 Function (page 428) is repeated in adjusted period.			



Timer 1 Refresh Period

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpo	int Timer 1 Function (pag	je 428)	
Description				
Refresh period of Tir adjusted in Timer 1	ner 1 Function (page 428 Repeated (page 430).	Meaning of this setpoint	depends on type of repetition	
	Range [units]: 1 1000 [activated.	day]. This setpoint adjust t	hat every X day the timer will be	
Daily	Example: If you have daily repetition and you set this setpoint to 2, then every second day from first occurrence of Timer 1 Function (page 428) , the Timer 1 Function (page 428) will be activated.			
	Range [units]: 1 60 [we activated.	[units]: 1 60 [week]. This setpoint adjust that every X week the timer will be ed.		
Weekly Example: If you have weekly repetition and you set this setpoint to 2, the second week from first occurrence of Timer 1 Function (page 428), the Function (page 428) will be activated in selected days adjusted by Time (page 432)				
	Range [units]: 1 12 [mo activated.	onth]. This setpoint adjust t	hat every X month the timer will be	
Monthly Monthl		e monthly repetition and you set this setpoint to 2, then every rst occurrence of Timer 1 Function (page 428) , the Timer 1 will be activated in selected day of month adjusted by Timer nth (page 433) or in selected days of week of month Day (page 432) and Timer 1 Repeat Week In Month (page		
	Range [units]: [HH:MM]. This setpoint adjust that every X short period the timer will be activated.			
Short Period	Example: If you have every second minute Timer 1 Function (p	e short period repetition and from first occurrence of Tir age 428) will be activated.	you set this setpoint to 2, then ner 1 Function (page 428), the	



Timer 1 Weekends

Setpoint group	Scheduler	Related FW	1.0.0		
Range [units]	Including / Skip / Postpone [-]				
Default value	Including	Alternative config	NO		
Step	[-]				
Comm object	0	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibilit	y Conditioned by the setpo	Conditioned by the setpoint Timer 1 Function (page 428)			
Description					
Behavior of Timer 1 Function (page 428) on weekends.					
Including	mer 1 Function (page 428) counter is running on the weekends and Timer 1 unction (page 428) can be active.				
Skip	mer 1 Function (page 428) counter is running on the weekends but Timer 1 Function age 428) isn't active.				
Postpone	mer 1 Function (page 428) counter isn't running on the weekends and Timer 1 unction (page 428) isn't active. If the activation of timer is counted on the weekend, an timer will be activated after weekend. Another activation of timer is counted from riginal date of first occurrence date.				

O back to List of setpoints

Timer 1 Day

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Monday / Tuesday / Wednesday / Thursday / Friday / Saturday/ Sunday[-]			
Default value	All OFF	Alternative config	NO	
Step	[-]			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Use this setpoint to include or exclude individual days of week. To select the day use Up and Down buttons. To change the value of day use Enter button.				


Timer 1 Repeat Day

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Repeated Day / Repeated Day In Week [-]			
Default value	Repeated Day	Alternative config	NO	
Step	[-]	[-]		
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description	Description			
Use this setpoint to adjust behavior of monthly repetition of the Timer 1 Function (page 428).				
Repeated Day Repeated Day In W	Chose one day in month when Timer 1 Function (page 428) will be activated. Chose days in one week when Timer 1 Function (page 428) will be activated.			

O back to List of setpoints

Timer 1 Repeated Day In Week

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Monday / Tuesday / Wednesday / Thursday / Friday / Saturday/ Sunday[-]			
Default value	All OFF	Alternative config	NO	
Step	H			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Use this setpoint to select the day of week when timer will be activated.				
Note: More day can be selected. Timer will be activated on the day which happened like the first.				

• List of setpoints (page 222)

Timer 1 Repeat Day In Month

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	131 [day]			
Default value	0	Alternative config	NO	
Step	F			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
Use this setpoint to chose the day in month when the Timer 1 Function (page 428) will be activated.				



Timer 1 Repeat Week In Month

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	15[week]			
Default value	1 week	Alternative config	NO	
Step	1 week			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 1 Function (page 428)			
Description				
This setpoint adjust the week of month in which the Timer 1 Function (page 428) will be activated.				

O back to List of setpoints

Subgroup: Timer 2

Timer 2 Setup

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	10970	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Related setpoints for	timer 2 are:			
Timer 2 Fun	 Timer 2 Function (page 435) Timer 2 Day (page 439) 			
Timer 2 Rep	etition (page 436)	Timer 2 Repeating the second secon	Timer 2 Repeated Day In Week (page 440)	
Timer 2 Firs	t Occur. Date (page 436)	Timer 2 Repeating the second secon	at Day In Month (page 440)	
 Timer 2 First Occur. Time (page 436) Timer 2 Repeat Week In Month (page 44) 			at Week In Month (page 441)	
Timer 2 Duration (page 437)		Timer 2 Refres	Timer 2 Refresh Period (page 438)	
Timer 2 Repeated (page 437)		Timer 2 Week	Timer 2 Weekends (page 439)	
Timer 2 Repeat Day (page 440)				



Timer 2 Function

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	Disable / No Func / TEST / Test OnLd / MFail Blk / Mode OFF [-]		
Default value	No Func	Alternative config	NO
Step	[-]		
Comm object	15359	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		

Description

It is possible to choose from following Timer functions. Binary output **EXERCISE TIMER 2 (PAGE 714)** is always activated when Timer is active regardless of chosen timer function. Timer functions require controller running in AUTO mode.

IMPORTANT: Binary output is activated always when timer should be activated e.g. even when controller is in different mode than AUTO.

Timer 1 has the highest priority. Timer 8 has the lowest priority. So if Timer 1 is configured for OFF mode and Timer 8 is over the same time configured for AUTO mode, controller will work in OFF mode.

Controller activates timer whenever it is powered up even in period, where timer should be already running.

Disable	The Timer is disabled.
No Func	There is no any other function, only binary output of timer is activated.
Auto Run	When this option is chosen then the binary output of timer is internally connected to the REMOTE START/STOP (PAGE 677) binary input.
TEST	When this option is chosen then the binary output of timer is internally connected to the binary input Remote TEST.
TEST OnLd	When this option is chosen then the binary output of timer is internally connected to the Remote TEST On Load binary input.
MFail Blk	When this option is chosen then the binary output of timer is internally connected to the Mains Fail Block binary input.
Mode OFF	When this option is chosen then the binary output of timer is internally connected to the Remote OFF binary input.



Timer 2 Repetition

Setpoint grou	р	Scheduler	Related FW	1.0.0	
Range [units]		Off / Once / Repeated [-]			
Default value		Off Alternative config		NO	
Step		H			
Comm object		0 Related applications MINT, SPtM			
Config level		Standard			
Setpoint visib	ility	Conditioned by the setpoi	nt Timer 2 Function (pag	ge 435)	
Description					
Defines repetiti	ion of	Timer 2 Function (page	435).		
Off	Timer	2 Function (page 435) will not be activated.			
Once	Timer	² 2 Function (page 435) will be activated only one time.			
Repeated	Timer	r 2 Function (page 435) will be repeatedly activated.			

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Timer 2 First Occur. Date

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	[DD/MM/YYYY]		
Default value	01/01/2000	Alternative config	NO
Step	H		
Comm object	0	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)		
Description			
Date of first occurrence of Timer 2 Function (page 435).			

O back to List of setpoints

Timer 2 First Occur. Time

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	[HH:MM]		
Default value	00:00	Alternative config	NO
Step	H		
Comm object	0	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)		
Description			
Time of first occurrence of Timer 2 Function (page 435).			



Timer 2 Duration

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	[HH:MM]		
Default value	00:00	Alternative config	NO
Step	H		
Comm object	0	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)		
Description			
Timer 2 Function (page 435) duration time.			

O back to List of setpoints

Timer 2 Repeated

Setpoint group		Scheduler	Related FW	1.0.0
Range [units]		Daily / Weekly / Monthly / Short Period [-]		
Default value		Daily Alternative config NO		NO
Step		[-]		
Comm object		0	Related applications	MINT, SPtM
Config level		Standard		
Setpoint visibili	ity	Conditioned by the setpoint Timer 2 Function (page 435)		
Description				
Repeated interva	al of '	Timer 2 Function (page	435).	
Daily T	Timer 2 Function (page 435) is repeated every day.			
Weekly T	Timer 2 Function (page 435) is repeated every week in chosen days.			
Monthly T	Timer 2 Function (page 435) is repeated in chosen day every month or in chosen days of			
С	hosen week of month			
Short Period T	Timer 2 Function (page 435) is repeated in adjusted period.			

• List of setpoints (page 222)



Timer 2 Refresh Period

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	[-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpo	int Timer 2 Function (pag	je 435)	
Description				
Refresh period of Tin adjusted in Timer 2	ner 2 Function (page 43 Repeated (page 437).	5). Meaning of this setpoint	depends on type of repetition	
	Range [units]: 1 1000 [activated.	day]. This setpoint adjust t	hat every X day the timer will be	
Daily	Example: If you have daily repetition and you set this setpoint to 2, then every second day from first occurrence of Timer 2 Function (page 435) , the Timer 2 Function (page 435) will be activated.			
	Range [units]: 1 60 [we activated.	eek]. This setpoint adjust th	nat every X week the timer will be	
Weekly	Example: If you have weekly repetition and you set this setpoint to 2, then every second week from first occurrence of Timer 2 Function (page 435) , the Timer 2 Function (page 435) will be activated in selected days adjusted by Timer 2 Day (page 439).			
	 Range [units]: 1 12 [month]. This setpoint adjust that every X month the timer will be activated. Example: If you have monthly repetition and you set this setpoint to 2, then every second month from first occurrence of Timer 2 Function (page 435), the Timer 2 Function (page 435) will be activated in selected day of month adjusted by Timer 2 Repeat Day In Month (page 440) or in selected days of week of month adjusted by Timer 2 Day (page 439) and Timer 2 Repeat Week In Month (page 441). 			
Monthly				
	Range [units]: [HH:MM]. be activated.	This setpoint adjust that e	every X short period the timer will	
Short PeriodExample: If you have short period repetition and you set this setpoint to every second minute from first occurrence of Timer 2 Function (page Timer 2 Function (page 435) will be activated.				



Timer 2 Weekends

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Including / Skip / Postpor	ncluding / Skip / Postpone [-]		
Default value	Including	Alternative config	NO	
Step	[-]	[-]		
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibilit	y Conditioned by the setpo	Conditioned by the setpoint Timer 2 Function (page 435)		
Description				
Behavior of Time	2 Function (page 435) on v	veekends.		
Including	Timer 2 Function (page 435) counter is running on the weekends and Timer 2 Function (page 435) can be active.			
Skip	Timer 2 Function (page 43 (page 435) isn't active.	imer 2 Function (page 435) counter is running on the weekends but Timer 2 Function page 435) isn't active.		
Postpone	Timer 2 Function (page 435) counter isn't running on the weekends and Timer 2 Sunction (page 435) isn't active. If the activation of timer is counted on the weekend, than timer will be activated after weekend. Another activation of timer is counted from priginal date of first occurrence date.			

O back to List of setpoints

Timer 2 Day

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Monday / Tuesday / Wednesday / Thursday / Friday / Saturday/ Sunday[-]			
Default value	All OFF	Alternative config	NO	
Step	[-]			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)			
Description				
Use this setpoint to include or exclude individual days of week. To select the day use Up and Down buttons. To change the value of day use Enter button.				



Timer 2 Repeat Day

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Repeated Day / Repeated Day In Week [-]			
Default value	Repeated Day	Alternative config	NO	
Step	H			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)			
Description	Description			
Use this setpoint to adjust behavior of monthly repetition of the Timer 2 Function (page 435).				
Repeated Day Repeated Day In W	Chose one day in month when Timer 2 Function (page 435) will be activated. Chose days in one week when Timer 2 Function (page 435) will be activated.			

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Timer 2 Repeated Day In Week

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	Monday / Tuesday / Wednesday / Thursday / Friday / Saturday/ Sunday[-]			
Default value	All OFF	Alternative config	NO	
Step	F			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)			
Description				
Use this setpoint to select the day of week when timer will be activated.				
Note: More day can be selected. Timer will be activated on the day which happened like the first.				

• List of setpoints (page 222)

Timer 2 Repeat Day In Month

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	131 [day]			
Default value	0	Alternative config	NO	
Step	[-]			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)			
Description				
Use this setpoint to chose the day in month when the Timer 2 Function (page 435) will be activated.				



Timer 2 Repeat Week In Month

Setpoint group	Scheduler	Related FW	1.0.0	
Range [units]	15[week]			
Default value	1 week	Alternative config	NO	
Step	1 week			
Comm object	0	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Timer 2 Function (page 435)			
Description				
This setpoint adjust the week of month in which the Timer 2 Function (page 435) will be activated.				

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Subgroup: Rental Timers

Rental Timer 1

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	Disabled / 1 8 760 [h]		
Default value	Disabled	Alternative config	NO
Step	1 h		
Comm object	14326	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
-			

Description

Another engine start is not allowed when this timer elapsed. This timer is based on engine running hours. The alarm Rental Timer 1 Elapsed (page 798) will be recorded in alarm list and the binary output AL RENTAL TIMER 1 (PAGE 694) will close.

IMPORTANT: To reset Rental Timer 1 (page 441) we have to set up Rental Timer 1 (page 441) again. It means go to setpoint group Scheduler and to the setpoint Rental Timer 1 (page 441). Then press enter button , change the value if it is necessary and press enter button again.

When the **Rental Timer 1 (page 441)** elapsed during engine run the gen-set will not stop immediately. The adjustable **Rental Timer BOC (page 445)** timer will start in this moment. The engine will be cooled and stopped when the **Rental Timer BOC (page 445)** time elapsed.





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Rental Timer 1 Wrn

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	Disabled / 1 Rental Timer 1 (page 441) [h]		
Default value	Disabled	Alternative config	NO
Step	1 h		
Comm object	14332	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Rental Timer 1 (page 441)		
Description			

Alarm Wrn Rental Timer 1 (page 810) comes up after xx running hours from adjusting the Rental Timer 1 (page 441). Hours are adjusted by this setpoint.



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Rental Timer 2

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	[DD/MM/YYYY]		
Default value	01/01/2015	Alternative config	NO
Step	1 day		
Comm object	14367	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			

Another engine start is not allowed when this timer elapsed. This timer is based on date. At the midnight of the last day the alarm Rental Timer 2 Elapsed (page 799) will be recorded in alarm list and the binary output **AL RENTAL TIMER 2** (PAGE 694) will close.

IMPORTANT: To reset Rental Timer 2 (page 443) we have to set up Rental Timer 2 (page 443) again. It means go to setpoint group Scheduler and to the setpoint Rental Timer 2 (page 443). Then press enter button , change the value if it is necessary and press enter button again.

IMPORTANT: To disable Rental Timer 2 (page 443) set date to 01/01/2015.



When the **Rental Timer 2 (page 443)** elapsed during engine run the gen-set will not stop immediately. The adjustable **Rental Timer BOC (page 445)** timer will start in this moment. The engine will be cooled and stopped when the **Rental Timer BOC (page 445)** time elapsed.



The Running Hours Overrun counter will start increment when the engine is continue running after the **Rental Timer 2** (page 443) elapsed.

Note: There is no priority between Rental Timer 1 and Rental Timer 2. The sooner timer will activated the **Rental Timer BOC (page 445)** protection.



Rental Timer 2 Wrn

Setpoint group	Scheduler	Related FW	1.0.0
Range [units]	Disabled / 01/01/2015 Rental Timer 2 (page 443) [DD/MM/YYYY]		
Default value	01/01/2015	Alternative config	NO
Step	1 day		
Comm object	14368	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Conditioned by the setpoint Rental Timer 2 (page 443)		
Description			

Alarm Wrn Rental Timer 2 (page 810) comes up xx days before the Rental Timer 2 (page 443). Days are adjusted by this setpoint.



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Rental Timer BOC

Setpoint group	Scheduler	Related FW	1.0.0		
Range [units]	Disabled / 1 210 [h]				
Default value	24 h	Alternative config	NO		
Step	1h				
Comm object	14334	Related applications	MINT, SPtM		
Config level	Advanced	Advanced			
Setpoint visibility	Conditioned by the setpoints Rental Timer 1 (page 441) and Rental Timer 2 (page 443)				
Description					
This timer will start after Rental Timer 1 (page 441) or Rental Timer 2 (page 443) elapsed in case that the					

engine is still running. When this timer elapsed the engine is cooled and stopped.



Group: Geo-Fencing

Home Latitude

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	-90,000090,0000 [°]		
Default value	0,0000 °	Alternative config	NO
Step	0,0001 °		
Comm object	14606	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Description

This setpoint adjust latitude of "home" position. Home is position where gen-set should runs. Positions on north hemisphere have positive value, position on south hemisphere have negative value.

Note: This value with Home Longitude (page 446) are used for counting Fence Radius 1 (page 447) and Fence Radius 2 (page 447).

Note: This value can be also obtained automatically via logical binary input **GEO HOME POSITION (PAGE 668)**. In case of activation of this binary input for at least 2 seconds, setpoint will be adjusted automatically from actual coordinates from GPS signal.

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Home Longitude

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	-180,0000180,0000 [°]		
Default value	0,0000 °	Alternative config	NO
Step	0,0001 °		
Comm object	14607	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

This setpoint adjust longitude of "home" position. Home is position where gen-set should runs. Positions on east hemisphere have positive value, position on west hemisphere have negative value.

Note: This value with Home Latitude (page 446) are used for counting Fence Radius 1 (page 447) and Fence Radius 2 (page 447).

Note: This value can be also obtained automatically via logical binary input **GEO HOME POSITION (PAGE 668)**. In case of activation of this binary input for at least 2 seconds, setpoint will be adjusted automatically from actual coordinates from GPS signal.



Fence Radius 1

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	0,099,9 [km]		
Default value	0,0 km	Alternative config	NO
Step	0,1 km		
Comm object	11677	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Radius for circle area 1. When the gen-set leaves this area, Fence 1 Protection (page 449) is activated after Fence 1 Delay (page 447) .			

Note: The center of this circle area is defined by "Home" position - setpoints **Home Longitude** (page 446) and **Home Latitude** (page 446).

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Fence Radius 2

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	0,099,9 [km]		
Default value	0,0 km	Alternative config	NO
Step	0,1 km		
Comm object	14608	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Radius for circle area 2. When the gen-set leaves this area, Fence 2 Protection (page 450) is activated after Fence 2 Delay (page 448).

Note: The center of this circle area is defined by "Home" position - setpoints **Home Longitude (page 446)** and **Home Latitude (page 446)**.

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Fence 1 Delay

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	03600 [s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	11682	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Delay for Fence 1 Protection (page 449).			



Fence 2 Delay

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	03600 [s]		
Default value	0 s	Alternative config	NO
Step	1s		
Comm object	14609	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Delay for Fence 2 Protection (page 450).			

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Geo-Fencing

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	Disabled / Enabled / LBI Enable [-]		
Default value	Disabled	Alternative config	NO
Step	[-]		
Comm object	11681	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enable	s or disables geo-fencing fu	unction.	
Disabled	Fence 1 Protection (page 449) and Fence 2 Protection (page 450) are disabled.		
Enabled	Fence 1 Protection (page 449) and Fence 2 Protection (page 450) are enabled.		
LBI Enable	Fence 1 Protection (page 449) and Fence 2 Protection (page 450) are enabled only when logical binary input .GEO-FENCING ENABLED (PAGE 669) is active.		



Fence 1 Protection

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	HistRecOnl / Wrn / Sd / BOC[-]		
Default value	HistRecOnl	Alternative config	NO
Step	[-]		
Comm object	14610	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Protection type for geo-fencing 1 protection. Fence of circle area is adjusted by setpoint **Fence Radius 1** (page 447). Delay for protection is adjusted by setpoint **Fence 1 Delay (page 447)**.

Protection types

HistRecOnl	Position of gen-set is only measured and displayed on the LCD screen but not used for protection. History record is made if position is out of Fence Radius 1 (page 447) .
Wm	Position of gen-set is used for warning protection only. Protection is activated when position of the gen-set is out of Fence Radius 1 (page 447) .
Sd	Position of gen-set is used for shutdown protection. Protection is activated when position of the gen-set is out of Fence Radius 1 (page 447) .
BOC	Position of gen-set is used for BOC (Breaker Open and Cooling) protection. Protection is activated when position of the gen-set is out of Fence Radius 1 (page 447) .

Note: Protection is activated also when GPS signal is lost for Fence 1 Delay (page 447).



Fence 2 Protection

Setpoint group	Geo-Fencing	Related FW	1.0.0
Range [units]	HistRecOnl / Wrn / Sd / BOC[-]		
Default value	HistRecOnl	Alternative config	NO
Step	[-]		
Comm object	14611	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Protection type for geo-fencing 2 protection. Fence of circle area is adjusted by setpoint **Fence Radius 2** (page 447). Delay for protection is adjusted by setpoint **Fence 2 Delay (page 448)**.

Protection types

HistRecOnl	Position of gen-set is only measured and displayed on the LCD screen but not used for protection. History record is made if position is out of Fence Radius 2 (page 447) .
Wm	Position of gen-set is used for warning protection only. Protection is activated when position of the gen-set is out of Fence Radius 2 (page 447) .
Sd	Position of gen-set is used for shutdown protection. Protection is activated when position of the gen-set is out of Fence Radius 2 (page 447) .
BOC	Position of gen-set is used for BOC (Breaker Open and Cooling) protection. Protection is activated when position of the gen-set is out of Fence Radius 2 (page 447) .

Note: Protection is activated also when GPS signal is lost for Fence 2 Delay (page 448).

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Group: Plug-In Modules

Slot A

Setpoint group	Plug-In Modules	Related FW	1.0.0	
Range [units]	ENABLED / DISABLED	ENABLED / DISABLED [-]		
Default value	ENABLED	Alternative config	NO	
Step	F			
Comm object	24280	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint enable or disable module in slot A.				



Slot B

Setpoint group	Plug-In Modules	Related FW	1.0.0	
Range [units]	ENABLED / DISABLED [-]			
Default value	ENABLED	Alternative config	NO	
Step	[·]			
Comm object	24279	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
This setpoint enable or disable module in slot B.				

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Group: CU AIN Calibration

Subgroup: Analog Input 1

CU AIN1 Calibration

Setpoint group	CU AIN Calibration	Related FW	1.0.0		
Range [units]	the range is defined by an	the range is defined by analog sensor curve			
Default value	0 (number of decimal is given by sensor curve)	Alternative config	NO		
Step	the step is defined by analog sensor curve				
Comm object	8431	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always				
Description					
Calibrating constant to adjust the measured value of controller analog inputs. Physical dimension of calibrating constant is corresponding to Analog input.					

Note: Unit is adjusted via InteliConfig in configuration of analog input 1.



Subgroup: Analog Input 2

Set	point group	CU AIN Calibration	Related FW	1.0.0			
Ra	nge [units]	the range is defined by an	the range is defined by analog sensor curve				
De	ault value	0 (number of decimal is given by sensor curve)	Alternative config	NO			
Ste	р	the step is defined by analog sensor curve					
Co	mm object	8407	Related applications	MINT, SPtM			
Co	nfig level	Standard					
Set	point visibility	Always					
Description							
Calibrating constant to adjust the measured value of controller analog inputs. Physical dimension of calibrating constant is corresponding to Analog input.							
Note: Unit is adjusted via InteliConfig in configuration of analog input 2.							

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Subgroup: Analog Input 3

CU AIN3 Calibration

Setpoint group	CU AIN Calibration	Related FW	1.0.0	
Range [units]	the range is defined by analog sensor curve			
Default value	0 (number of decimal is given by sensor curve)	Alternative config	NO	
Step	the step is defined by analog sensor curve			
Comm object	8467	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Calibrating constant to adjust the measured value of controller analog inputs. Physical dimension of calibrating constant is corresponding to Analog input.				

Note: Unit is adjusted via InteliConfig in configuration of analog input 3.



Subgroup: Analog Input 4

CU AIN4 Calibration

Setpoint group	CU AIN Calibration	Related FW	1.0.0			
Range [units]	the range is defined by an	the range is defined by analog sensor curve				
Default value	0 (number of decimal is given by sensor curve)	Alternative config	NO			
Step	the step is defined by analog sensor curve					
Comm object	8793	Related applications	MINT, SPtM			
Config level	Standard					
Setpoint visibility	Always					
Description						
Calibrating constant to adjust the measured value of controller analog inputs. Physical dimension of calibrating constant is corresponding to Analog input.						
Note: Unit is adjusted via InteliConfig in configuration of analog input 4.						

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Group: Alternate Config

Subgroup: Basic settingsConfiguration 1

Connection Type 1

Set	etpoint group Basic settings Related FW 1.0.0			1.0.0	
Range [units]		Monophase / Splitphase / S	Monophase / Splitphase / 3Ph3Wire / High Leg D / 3Ph4Wire / Autodetect [-]		
Default value 3Ph4Wire Alternative config YES			YES		
Ste	р	[-]			
Co	mm object	12058	Related applications	MINT, SPtM	
Со	nfig level	Standard			
Set	point visibility	Always			
Des	scription				
Cor	nnection type:				
	MONOFILASE	1x CT (Current Transformer)	Single phase voltage measurement Link		
1x CT (Current Transformer)					
	Split Phase	Double Delta connection			
		Split Phase	Split Phase		
		Two phase voltage measure	ment L1,L2 with 180° phase	e shift	
		2x CT (Current Transformer))		
	3Ph3Wire Ungrounded Delta connection				
Open Delta Ungrounded Wye					
	Corner-Grounded Delta				



	Split Phase Delta		
	Three phase voltage measurement L1,L2,L3 with 120° phase shift		
	No neutral is available 3x CT (Curre	ent Transformer)	
igh Leg D	High Leg Delta connection		
	Three phase voltage measurement	L1,L2,L3	
	3x CT (Current Transformer)		
Ph4Wire	Grounded Star (Grounded Wye) co	nnection – 3PY	
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift	
	3x CT (Current Transformer)		
utodetect	High Leg Delta	L1>=100V; L1<=140V	
		L2>=140V	
	OF	L3>=100V; L3<=140V	
	3PH3Wire or 3Ph4Wire		
		$L_1 > -100V$	
	or	L2 >= 100V	
		L3 >= 100V	
	Split Phase	L1>=100V	
	or	L2 <= 20V	
	UI	L3>=100V	
	Mono Phase	11>=100\/	
		12 <= 20\/	
	or	13<= 201/	
	Voltage Autodetect shutdown		

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Nominal Power 1

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	1 5 000 [kW]			
Default value	200 kW	Alternative config	Yes	
Step	1 kW			
Comm object	12046	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Nominal power of the gen-set. Generator Overload BOC (page 304) protection is based on this setpoint.				

Note: This setpoint is used when setpoint **Connection type (page 244)** is adjusted to Monophase or Splitphase or 3Ph3Wire or High Leg D or 3Ph4Wire or when Autodetect detects connection type as 3Ph3Wire or High Leg D or 3Ph4Wire.

Note: This value is used when any other alternate configuration is not active.

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Nominal Power Split Phase 1

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	15000 [kW]		
Default value	200 kW	Alternative config	Yes
Step	1 kW		
Comm object	15771	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)		
Description			

Nominal power of the gen-set for detected split-phase or mono phase connection. Generator **Overload BOC** (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint *Connection type (page 244)* is adjusted to Autodetect and Autodetect detects connection type as Monophase or Splitphase.

Note: This value is used when any other alternate configuration is not active.



Nominal Current 1

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	1 10 000 [A]				
Default value	350 A	Alternative config	YES		
Step	1 A				
Comm object	12049	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Always	Always			
Description					
It is current limit for generator current protections and means maximal continuous generator current. Nominal Current can be different from generator rated current value.					

Note: This value is used when any other alternate configuration is not active.

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Nominal Frequency 1

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	4565 [Hz]			
Default value	50 Hz	Alternative config	YES	
Step	1 Hz			
Comm object	9913	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				
Nominal system frequency (usually 50 or 60 Hz).				
Note: This value is used when any other alternate configuration is not active.				

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Nominal RPM 1

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	1004000 [RPM]			
Default value	1 500 RPM Alternative config YES			
Step	1 RPM			
Comm object	9915	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Nominal engine speed (RPM - revolutions per minute).				
Note: This value is used when any other alternate configuration is not active.				



Nominal Voltage Ph-N 1

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	8020000 [V]				
Default value	231 V Alternative config YES				
Step	1V				
Comm object	12052	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Conditioned by the setpoi	Conditioned by the setpoint Connection Type 1 (page 453).			
Description					
Nominal system voltage (phase to neutral).					
Note: This value is used when any other alternate configuration is not active.					

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Nominal Voltage Ph-Ph 1

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	80 40000 [V]			
Default value	400 V Alternative config YES			
Step	1V			
Comm object	12055	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoi	nt Connection Type 1 (p	age 453).	
Description				
Nominal system voltage (phase to phase).				
Note: This value is used when any other alternate configuration is not active.				

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Connection type 2

Set	point group	Basic settings	Basic settings Related FW 1.0.0			
Range [units] Monophase / Splitphase / 3Ph3Wire / High Leg D / 3Ph4Wire /			h4Wire / Autodetect [-]			
Def	ault value	3Ph4Wire	3Ph4Wire Alternative config YES			
Ste	0	[-]	H			
Cor	nm object	12059	12059 Related applications MINT, SPtM			
Cor	nfig level	fig level Standard				
Set	point visibility	Always				
Des	cription					
Cor	nection type:					
	Mono Phase	Single phase voltage measurement L1-N				
		1x CT (Current Transformer)				
	Split Phase	Double Delta connection				



	Split Phase			
	Two phase voltage measurement L	1,L2 with 180° phase shift		
	2x CT (Current Transformer)			
3Ph3Wire	Ungrounded Delta connection			
	Open Delta			
	Ungrounded Wye			
	Corner-Grounded Delta			
	Split Phase Delta			
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift		
	No neutral is available 3x CT (Curre	ent Transformer)		
ligh Leg D	High Leg Delta connection			
	Three phase voltage measurement	L1,L2,L3		
	3x CT (Current Transformer)			
Ph4Wire	Grounded Star (Grounded Wye) co	nnection – 3PY		
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift		
	3x CT (Current Transformer)			
utodetect	High Leg Delta	L1 >=100V; L1 <=140V		
		L2>=140V		
	or	L3>=100V; L3<=140V		
	3PH3Wire or 3Ph4Wire			
		L1>=100V		
	or	L2>=100V		
		L3>=100V		
	Split Phase	L1 >=100V		
		L2 <= 20V		
	or	L3>=100V		
	Mono Phase	11>-1001/		
		L 2 = 100V		
	or	$LZ \leq 20V$		
		L3 <= 20V		



Nominal Power 2

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	1 5 000 [kW]			
Default value	200 kW	Alternative config	Yes	
Step	1 kW			
Comm object	12047	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always			
Description				

Nominal power of the gen-set. Generator Overload BOC (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint **Connection type (page 244)** is adjusted to Monophase or Splitphase or 3Ph3Wire or High Leg D or 3Ph4Wire or when Autodetect detects connection type as 3Ph3Wire or High Leg D or 3Ph4Wire.

Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.

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Nominal Power Split Phase 2

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	15000 [kW]		
Default value	200 kW	Alternative config	Yes
Step	1 kW		
Comm object	15772	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)		
Description			

Nominal power of the gen-set for detected split-phase or mono phase connection. Generator **Overload BOC** (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint *Connection type (page 244)* is adjusted to Autodetect and Autodetect detects connection type as Monophase or Splitphase.

Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.



Nominal Current 2

Setpoint group	Basic settings	Related FW	1.0.0			
Range [units]	1 10000 [A]					
Default value	350 A	Alternative config	YES			
Step	1A					
Comm object	12050	Related applications	MINT, SPtM			
Config level	Standard	Standard				
Setpoint visibility	Always					
Description						
It is current limit for generator current protections and means maximal continuous generator current. Nominal Current can be different from generator rated current value.						

Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.

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Nominal Frequency 2

Setpoint group	Basic settings	Related FW	1.0.0		
Range [units]	4565[Hz]				
Default value	50 Hz	Alternative config	YES		
Step	1 Hz				
Comm object	9914	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Always	Always			
Description					
Nominal system frequency (usually 50 or 60 Hz).					
Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.					

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Nominal RPM 2

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	1004000 [RPM]			
Default value	1 500 RPM Alternative config YES			
Step	1 RPM			
Comm object	9916	Related applications	MINT, SPtM	
Config level	Advanced			
Setpoint visibility	Always			
Description				
Nominal engine speed (RPM - revolutions per minute).				
Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.				



Nominal Voltage Ph-N 2

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	8020000 [V]			
Default value	231 V Alternative config YES			
Step	1V			
Comm object	12053	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Connection type 2 (page 457).			
Description				
Nominal system voltage (phase to neutral).				
Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.				

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Nominal Voltage Ph-Ph 2

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	80 40000 [V]			
Default value	400 V Alternative config YES			
Step	1 V			
Comm object	12056	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Conditioned by the setpoint Connection type 2 (page 457).			
Description				
Nominal system voltage (phase to phase).				
Note: This value is used when binary input ALTERNATE CONFIG 2 (PAGE 615) is active.				

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Connection type 3

Set	ooint group	Basic settings	Related FW	1.0.0		
Ran	ange [units] Monophase / Splitphase / 3Ph3Wire / High Leg D / 3Ph4Wire / Autodetec			n4Wire / Autodetect [-]		
Def	ault value	3Ph4Wire Alternative config YES				
Ste	0	[-]				
Cor	nm object	12060	12060 Related applications MINT, SPtM			
Cor	nfig level	vel Standard				
Set	ooint visibility	Always				
Des	cription					
Con	nection type:					
	Mono Phase	Single phase voltage measurement L1-N				
		1x CT (Current Transformer)				
	Split Phase	Double Delta connection				



	Split Phase		
	Two phase voltage measurement L	1,L2 with 180° phase shift	
	2x CT (Current Transformer)		
3Ph3Wire	Ungrounded Delta connection		
	Open Delta		
	Ungrounded Wye		
	Corner-Grounded Delta		
	Split Phase Delta		
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift	
	No neutral is available 3x CT (Curre	ent Transformer)	
ligh Leg D	High Leg Delta connection		
	Three phase voltage measurement	L1,L2,L3	
	3x CT (Current Transformer)		
3Ph4Wire	Grounded Star (Grounded Wye) co	nnection – 3PY	
	Three phase voltage measurement	L1,L2,L3 with 120° phase shift	
	3x CT (Current Transformer)		
Autodetect	High Leg Delta	L1>=100V; L1<=140V	
		L2>=140V	
	or	L3>=100V; L3<=140V	
	3PH3Wire or 3Ph4Wire		
		L1>=100V	
	or	L2>=100V	
		L3>=100V	
	Split Phase	L1>=100V	
		L2 <= 20V	
	or	L3>=100V	
	Mono Phase		
		L1 >=100V	
	or	L2 <= 20V	
		$1.3 \le 20 V$	



Nominal Power 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	15000 [kW]		
Default value	200 kW	Alternative config	Yes
Step	1 kW		
Comm object	12048	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			

Nominal power of the gen-set. Generator Overload BOC (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint **Connection type (page 244)** is adjusted to Monophase or Splitphase or 3Ph3Wire or High Leg D or 3Ph4Wire or when Autodetect detects connection type as 3Ph3Wire or High Leg D or 3Ph4Wire.

Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.

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Nominal Power Split Phase 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	1 5 000 [kW]		
Default value	200 kW	Alternative config	Yes
Step	1 kW		
Comm object	15773	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Connection type (page 244)		
Description			

Nominal power of the gen-set for detected split-phase or mono phase connection. Generator **Overload BOC** (page 304) protection is based on this setpoint.

Note: This setpoint is used when setpoint *Connection type (page 244)* is adjusted to Autodetect and Autodetect detects connection type as Monophase or Splitphase.

Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.



Nominal Current 3

Setpoint group	Basic settings	Related FW	1.0.0	
Range [units]	1 10 000 [A]			
Default value	350 A	Alternative config	YES	
Step	1 A			
Comm object	12051	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Always	Always		
Description				
It is current limit for generator current protections and means maximal continuous generator current. Nominal Current can be different from generator rated current value.				

Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.

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Nominal Frequency 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	4565 [Hz]		
Default value	50 Hz	Alternative config	YES
Step	1 Hz		
Comm object	15197	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Always		
Description			
Nominal system frequency (usually 50 or 60 Hz).			
Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.			

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Nominal RPM 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	1004 000 [RPM]		
Default value	1 500 RPM	Alternative config	YES
Step	1 RPM		
Comm object	15196	Related applications	MINT, SPtM
Config level	Advanced		
Setpoint visibility	Always		
Description			
Nominal engine speed (RPM - revolutions per minute).			
Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.			



Nominal Voltage Ph-N 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	80 20 000 [V]		
Default value	231 V	Alternative config	YES
Step	1 V		
Comm object	12054	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Connection type 3 (page 461).		
Description			
Nominal system voltage (phase to neutral).			
Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.			

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Nominal Voltage Ph-Ph 3

Setpoint group	Basic settings	Related FW	1.0.0
Range [units]	80 40 000 [V]		
Default value	400 V	Alternative config	YES
Step	1 V		
Comm object	12057	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Conditioned by the setpoint Connection type 3 (page 461).		
Description			
Nominal system voltage (phase to phase).			
Note: This value is used when binary input ALTERNATE CONFIG 3 (PAGE 615) is active.			



Group: CM-RS232-485

COM1 Mode

Setpoint group	CM-RS232-485	Related FW	1.0.0
Range [units]	Direct / MODBUS / DualSlave / Dual Master [-]		
Default value	Direct	Alternative config	NO
Step	[-]		
Comm object	24522	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Communication protocol switch for the COM1 channel.			
Direct MODBUS	InteliConfig communication protocol via serial cable. MODBUS protocol.		

O back to List of setpoints

COM1 Communication Speed

Setpoint group	CM-RS232-485	Related FW	1.0.0
Range [units]	9600 / 19200 / 38400 / 57600 / 115200[bps]		
Default value	57600 bps	Alternative config	NO
Step	[-]		
Comm object	24341	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint COM1 Mode (page 466)		
Description			
If the direct mode is selected on COM1 channel, the direct communication speed of controller part of line can			

be adjusted here. Speed of second part of line has to be adjusted to the same value.

Note: Winscope supports only 19200, 38400, 57600 speeds.

• List of setpoints (page 222)



COM1 MODBUS Communication Speed

Setpoint group	CM-RS232-485	Related FW	1.0.0
Range [units]	9600 / 19200 / 38400 / 57600 / 115200 [bps]		
Default value	9600 bps	Alternative config	NO
Step	[-]		
Comm object	24477	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint COM1 Mode (page 466)		
Description			

If the MODBUS mode is selected on COM1 channel, the MODBUS communication speed can be adjusted here.

• List of setpoints (page 222)

COM2 Mode

Setpoint group	CM-RS232-485	Related FW	1.0.0	
Range [units]	Direct / MODBUS / DualSlave / Dual Master [-]			
Default value	Direct	Alternative config	NO	
Step	[-]	[-]		
Comm object	24451	Related applications	MINT, SPtM	
Config level	Standard	Standard		
Setpoint visibility	Only if relevant module is installed			
Description				
Communication protocol switch for the COM2 channel.				
Direct MODBUS	InteliConfig communication protocol via serial cable. MODBUS protocol.			

O back to List of setpoints

COM2 Communication Speed

Setpoint group	CM-RS232-485	Related FW	1.0.0		
Range [units]	9600 / 19200 / 38400 / 57600 / 115200[bps]				
Default value	57600 bps	Alternative config	NO		
Step	[-]				
Comm object	24340	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint COM2 Mode (page 467)				
Description					
If the direct mode is selected on COM2 channel, the direct communication speed of controller part of line can be adjusted here. Speed of second part of line has to be adjusted to the same value.					

Note: Winscope supports only 19200, 38400, 57600 speeds.



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COM2 MODBUS Communication Speed

Setpoint group	CM-RS232-485	Related FW	1.0.0		
Range [units]	9600 / 19200 / 38400 / 57600 / 115200 [bps]				
Default value	9600 bps	Alternative config	NO		
Step	(-)				
Comm object	24420	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint COM2 Mode (page 467)				
Description					
If the MODBUS mode is selected on COM2 channel, the MODBUS communication speed can be adjusted here.					

• List of setpoints (page 222)

Group: CM-GPRS

Mode

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0		
Range [units]	Email+SMS / SMS Only [-]				
Default value	Email+SMS	Alternative config	NO		
Step	[-]				
Comm object	24315	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed				
Description					
This setpoint adjust the communication mode of module.					
Controller is connected to the Internet and is able to send e-mails as well as SMS. The					

Email+SMS controller is also accessible via AirGate. Internet-enabled SIM card must be used. Also APN Name (page 480) has to be adjusted.

SMS Only Only SMS are sent. Internet-enabled SIM card is not required.

IMPORTANT: When this setpoint is changed the controller has to be restarted to apply changes.

List of setpoints (page 222)


APN Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24363	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
APN (Access Point Name) of the GPRS/4G network, provided by GSM operator.			

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APN User Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	015 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24361	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
User name for the GPRS/4G Access Point if authentication is required. But mostly it is not required and			

should be left blank.

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APN User Password

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0	
Range [units]	015 characters [-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	24360	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)			
Description				
User password for the GPRS/4G Access Point if authentication is required. But mostly it is not required and should be left blank.				



Email Address 1

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24298	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Email Address 2

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	H		
Comm object	24297	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Email Address 3

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	H		
Comm object	24145	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			



Email Address 4

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24144	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpo	oint is common for Etherner	t, CM-GPRS and CM-4G-0	GPS modules.

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E-mail/SMS Language

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	[-]		
Default value	English	Alternative config	NO
Step	[-]		
Comm object	24299	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Use this setpoint to set the language of SMS and e-mail.			
Note: Numbers correspond with languages in language list.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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SMTP User Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[·]		
Comm object	24313	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
Use this setpoint to enter the username for the SMTP server. Leave the setpoint blank if the SMTP server does not require authentication.			



SMTP User Password

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	015 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24312	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
Use this setpoint to enter the password for the SMTP server. Leave the setpoint blank if the SMTP server			

does not require authentication.

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SMTP Server Address

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	airgate.comap.cz:9925	Alternative config	NO
Step	[-]		
Comm object	24311	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			

Description

This setpoint is used for entering the domain name (e.g. smtp.yourprovider.com) or IP address (e.g. 74.125.39.109) or number of port (with colon like a first mark) of the SMTP server. Ask your internet provider or IT manager for this information.

Note: You may use also any public SMTP server which does not require connection over SSL/TLS channels. If the device is connected to AirGate the AirGate SMTP server at "airgate.comap.cz" may be used. Ports 25 and 9925 are supported. After controller connects to AirGate for the first time (or with new public IP address), it may not be able to send emails for first 5-10 minutes.



SMTP Sender Address

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24310	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)		

Description

Enter an existing email address into this setpoint. This address will be used as sender address in active emails that will be sent from the controller.

Note: It is not needed to enter an existing email address, nevertheless valid email format needs to be followed.

IMPORTANT: This item is obligatory when emails are configured.

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Time Zone

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	GMT-12:00 GMT+13:00 [hours]		
Default value	GMT+1:00 hour	Alternative config	NO
Step	[-]		
Comm object	24366	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

This setpoint is used to select the time zone where the controller is located. See your computer time zone setting (click on the time indicator located in the rightmost position of the Windows task bar) if you are not sure about your time zone.

Note: If the time zone is not selected properly the active e-mails may contain incorrect information about sending time, which may result in confusion when the respective problem actually occurred.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.



Event Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	[·]		
Comm object	10926	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables Event Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Wrn Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	H		
Comm object	8482	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables Wrn Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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BOC Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	H		
Comm object	10566	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables BOC Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			



Sd Messages

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	F		
Comm object	8484	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables Sd Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Telephone Number 1

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	F		
Comm object	24296	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.



Telephone Number 2

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24295	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.

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Telephone Number 3

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24143	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.



Telephone Number 4

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	(-)		
Comm object	24142	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.

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DNS IP Address

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	Valid IP address [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24314	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
The setpoint is used to adjust the domain name server (DNS), which is needed to translate domain names in			

The setpoint is used to adjust the domain name server (DNS), which is needed to translate domain names in email addresses and server names into correct IP addresses.

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AirGate Connection

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0	
Range [units]	DISABLED / ENABLED [-]			
Default value	ENABLED	Alternative config	NO	
Step	[-]	[-]		
Comm object	24273	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)			
Description				
This setpoint enable or disable AirGate connection via CM-GPRS or via CM-4G-GPS.				
DISABLED: O	nly SMS are sent. Internet-enabled SIM card is not required. AirGate is not used.			
ENABLED TI	nis mode uses the "AirGate" service. Internet-enabled SIM card must be used. The rGate server address is adjusted by the setpoint AirGate Address (page 260) .			
IMPORTANT: When this setpoint is changed the controller has to be restarted to apply changes.				

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ComAp TCP Port

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	065 535[-]		
Default value	23	Alternative config	NO
Step	(-)		
Comm object	24374	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)		

Description

This setpoint is used to adjust the port number, which is used for Ethernet connection to a PC with any of ComAp PC program (i.e. InteliConfig). This setpoint should be adjusted to 23, which is the default port used by all ComAp PC programs. A different value should be used only in special situations as e.g. sharing one public IP address among many controllers or to overcome a firewall restrictions.

IMPORTANT: If AirGate is used, this setpoint has to be adjusted to 23.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.



Group: CM-4G-GPS

Mode

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0		
Range [units]	Email+SMS / SMS Only	Email+SMS / SMS Only [-]			
Default value	Email+SMS	Email+SMS Alternative config NO			
Step	[-]				
Comm object	24315	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibili	ty Only if relevant module is	installed			
Description					
This setpoint adju	ust the communication mode of	of module.			
Email+SMS	Controller is connected to the Internet and is able to send e-mails as well as SMS. The controller is also accessible via AirGate. Internet-enabled SIM card must be used. Also				
SMS Only	Only SMS are sent. Internet-e	y SMS are sent. Internet-enabled SIM card is not required.			
IMPORTANT: When this setpoint is changed the controller has to be restarted to apply changes.					

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Required Connection Type

Setpoint group	CM-4G-GPS	Related FW	1.0.0	
Range [units]	2G/3G/4G/Automatic [-]			
Default value	Automatic	Alternative config	NO	
Step	[-]			
Comm object	24132	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
This setpoint adjusts preferred connection type of CM-4G-GPS module.				



APN Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24363	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
APN (Access Point Name) of the GPRS/4G network, provided by GSM operator.			

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APN User Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	015 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24361	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
User name for the GPRS/4G Access Point if authentication is required. But mostly it is not required and			

should be left blank.

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APN User Password

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0	
Range [units]	015 characters [-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	24360	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)			
Description				
User password for the GPRS/4G Access Point if authentication is required. But mostly it is not required and should be left blank.				



Email Address 1

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24298	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Email Address 2

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24297	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Email Address 3

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24145	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			



Email Address 4

Setpoint group	Ethernet	Related FW	1.0.0
Range [units]	063 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24144	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
Enter in this setpoint a valid e-mail address where the alarm and event e-mails shall be sent.			
Note: This setpoint is common for Ethernet. CM-GPRS and CM-4G-GPS modules.			

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E-mail/SMS Language

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0		
Range [units]	[-]				
Default value	English	Alternative config	NO		
Step	[-]				
Comm object	24299	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant module is installed				
Description	Description				
Use this setpoint to set the language of SMS and e-mail.					
Note: Numbers correspond with languages in language list.					
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.					

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SMTP User Name

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0	
Range [units]	031 characters [-]			
Default value	[-]	Alternative config	NO	
Step	[-]			
Comm object	24313	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)			
Description				
Use this setpoint to enter the username for the SMTP server. Leave the setpoint blank if the SMTP server does not require authentication.				



SMTP User Password

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	015 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24312	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			
Use this setpoint to enter the password for the SMTP server. Leave the setpoint blank if the SMTP server			

does not require authentication.

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SMTP Server Address

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	airgate.comap.cz:9925	Alternative config	NO
Step	[-]		
Comm object	24311	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479)		
Description			

Description

This setpoint is used for entering the domain name (e.g. smtp.yourprovider.com) or IP address (e.g. 74.125.39.109) or number of port (with colon like a first mark) of the SMTP server. Ask your internet provider or IT manager for this information.

Note: You may use also any public SMTP server which does not require connection over SSL/TLS channels. If the device is connected to AirGate the AirGate SMTP server at "airgate.comap.cz" may be used. Ports 25 and 9925 are supported. After controller connects to AirGate for the first time (or with new public IP address), it may not be able to send emails for first 5-10 minutes.



SMTP Sender Address

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24310	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)		

Description

Enter an existing email address into this setpoint. This address will be used as sender address in active emails that will be sent from the controller.

Note: It is not needed to enter an existing email address, nevertheless valid email format needs to be followed.

IMPORTANT: This item is obligatory when emails are configured.

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Time Zone

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	GMT-12:00 GMT+13:00 [hours]		
Default value	GMT+1:00 hour	Alternative config	NO
Step	[-]		
Comm object	24366	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

This setpoint is used to select the time zone where the controller is located. See your computer time zone setting (click on the time indicator located in the rightmost position of the Windows task bar) if you are not sure about your time zone.

Note: If the time zone is not selected properly the active e-mails may contain incorrect information about sending time, which may result in confusion when the respective problem actually occurred.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.



Event Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	(-)		
Comm object	10926	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables Event Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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Wrn Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	ON / OFF [-]		
Default value	ON	Alternative config	NO
Step	H		
Comm object	8482	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			
This setpoint enables or disables Wrn Messages.			
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.			

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BOC Message

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]			
Default value	ON	Alternative config	NO	
Step	H			
Comm object	10566	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is	Only if relevant module is installed		
Description				
This setpoint enables or disables BOC Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				



Sd Messages

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0	
Range [units]	ON / OFF [-]			
Default value	ON	Alternative config	NO	
Step	[-]			
Comm object	8484	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is	Only if relevant module is installed		
Description				
This setpoint enables or disables Sd Messages.				
This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.				

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Telephone Number 1

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24296	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.



Telephone Number 2

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24295	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.

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Telephone Number 3

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24143	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.



Telephone Number 4

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0
Range [units]	031 characters [-]		
Default value	[-]	Alternative config	NO
Step	[-]		
Comm object	24142	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed		
Description			

Enter in this setpoint either a valid GSM phone number where the alarm messages shall be sent. For GSM numbers use either the national format (i.e. the number you would dial if you wanted to make a local call) or the full international format beginning with a "+" character followed by the country prefix.

IMPORTANT: Telephone number has to be entered without spaces.

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AirGate Connection

Setpoint group	CM-GPRS; CM-4G- GPS	Related FW	1.0.0	
Range [units]	DISABLED / ENABLED	DISABLED / ENABLED [-]		
Default value	ENABLED	Alternative config	NO	
Step	[-]	E Contraction of the second se		
Comm object	24273	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is	installed + conditioned by	the setpoint Mode (page 479)	
Description				
This setpoint enable	e or disable AirGate connec	tion via CM-GPRS or via C	CM-4G-GPS.	
DISABLED: C	only SMS are sent. Internet	nly SMS are sent. Internet-enabled SIM card is not required. AirGate is not used.		
ENABLED T	nis mode uses the "AirGate" service. Internet-enabled SIM card must be used. The rGate server address is adjusted by the setpoint AirGate Address (page 260) .			
IMPORTANT: When this setpoint is changed the controller has to be restarted to apply changes.				



ComAp TCP Port

Setpoint group	CM-GPRS; CM-4G- GPS; Ethernet	Related FW	1.0.0
Range [units]	065 535[-]		
Default value	23	Alternative config	NO
Step	[-]		
Comm object	24374	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant module is installed + conditioned by the setpoint Mode (page 479) (CM-GPRS module)		

Description

This setpoint is used to adjust the port number, which is used for Ethernet connection to a PC with any of ComAp PC program (i.e. InteliConfig). This setpoint should be adjusted to 23, which is the default port used by all ComAp PC programs. A different value should be used only in special situations as e.g. sharing one public IP address among many controllers or to overcome a firewall restrictions.

IMPORTANT: If AirGate is used, this setpoint has to be adjusted to 23.

Note: This setpoint is common for Ethernet, CM-GPRS and CM-4G-GPS modules.

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Group: EM-BIO8-EFCP

Earth Fault Current Protection

Setpoint group	EM-BIO8-EFCP	Related FW	1.0.0		
Range [units]	DISABLED / ENABLED	DISABLED / ENABLED [-]			
Default value	ENABLED Alternative config NO				
Step	[-]				
Comm object	11631	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Only if relevant module is installed				
Description					
This setpoint can blo	ock or allow Earth fault Curr	rent protection.			
DISABLED E	arth fault current protection is blocked.				
ENABLED Example by (p	rth fault current protection is allowed. Behavior of Earth fault current protection is set these setpoints: Earth Fault CT Input Range (page 490), Earth Fault CT Ratio age 490), Earth Fault Delay (page 490) and Earth Fault Sd (page 491).				



Earth Fault Delay

Setpoint group	EM-BIO8-EFCP	Related FW	1.0.0	
Range [units]	0,03 5,00 [s]			
Default value	0,10 s	Alternative config	NO	
Step	0,01 s			
Comm object	11633	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
Delay for Earth Fault Current protection.				

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Earth Fault CT Input Range

Setpoint group	EM-BIO8-EFCP	Related FW	1.0.0		
Range [units]	1 [A] / 5 [A]				
Default value	5 A	Alternative config	NO		
Step	[-]				
Comm object	14340	Related applications	MINT, SPtM		
Config level	Standard	Standard			
Setpoint visibility	Only if relevant module is	installed			
Description					
There are 2 physical inputs for Earth Fault Current Protection (page 489) . Value of this setpoint has to be set on value of physical input which is presently in use.					

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Earth Fault CT Ratio

Setpoint group	EM-BIO8-EFCP	Related FW	1.0.0	
Range [units]	1 2000 [1/(1or5)A]			
Default value	500 1/(1or5)A	Alternative config	NO	
Step	1A/1A; 1A/5A			
Comm object	14339	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				

Earth Fault current transformer ratio.

Note: Type of units depends on setpoint **Earth Fault CT Input Range (page 490)** which have to be set before this setpoint.



Earth Fault Sd

Setpoint group	EM-BIO8-EFCP	Related FW	1.0.0	
Range [units]	0,03 5,00 [A]			
Default value	0,30 A	Alternative config	NO	
Step	0,01 [A]			
Comm object	11632	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant module is installed			
Description				
Limit value for Earth Fault Current protection.				

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Group: PLC

PLC Setpoint 1

Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10440	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via	a configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	- 1 -	0.0	0 Apply	
	Image 9.69 Screen of co	nfiguration from InteliC	onfig	
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution II	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit k	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	/alue [-]	
Comm object	10441	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	t in PLC logic.		
Configuration of setpo	int:		
Configuration is made vi	a configuration PC tool InteliC	Config	
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:
	· 1 ·	0	0 _ Apply
	Image 9.70 Screen of co	nfiguration from InteliC	onfig
PLC Setpoint name	Name of the setpoint (032 ch	naracters)	
Dimension I	Dimension of value of the setpoint.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	Depends on resolution of value [-]		
Comm object	10442	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made vi	a configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	· 1 ·	0	0 _ Apply	
	Image 9.71 Screen of co	nfiguration from InteliC	onfig	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	Depends on resolution of value [-]		
Comm object	10443	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made vi	a configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	* 1 *	0	U Apply	
	Image 9.72 Screen of co	nfiguration from InteliC	onfig	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension	Dimension of value of the setpoint.			
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	Depends on resolution of value [-]		
Comm object	10444	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made vi	a configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	· 1 ·	0 _	0 _ Apply	
	Image 9.73 Screen of co	nfiguration from InteliC	onfig	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension	Dimension of value of the setpoint.			
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0		
Range [units]	Depends on resolution of value [-]				
Default value	Depends on resolution of value [-]	Alternative config	NO		
Step	Depends on resolution of v	Depends on resolution of value [-]			
Comm object	10445	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant setpoint is	used in PLC			
Description					
Adjustable value for input	in PLC logic.				
Configuration of setpoi	nt:				
Configuration is made via	configuration PC tool InteliC	Config	t:		
	- 1 -	0.0	0 C Apply		
	Image 9.74 Screen of configuration from InteliConfig				
PLC Setpoint name	lame of the setpoint (032 ch	naracters)			
Dimension D	imension of value of the setp	point.			
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.				
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10446	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
Image 9.75 Screen of configuration from InteliConfig				
PLC Setpoint name	etpoint name Name of the setpoint (032 characters)			
Dimension	Dimension of value of the setpoint.			
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	/alue [-]	
Comm object	10447	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	t in PLC logic.		
Configuration of setpo	int:		
Configuration is made via configuration PC tool InteliConfig			
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:
- 1 - 0 _ 0 _ Apply			
Image 9.76 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 characters)		
Dimension	Dimension of value of the setpoint.		
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10448	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 - 0 C Apply			
Image 9.77 Screen of configuration from InteliConfig				
PLC Setpoint name N	Name of the setpoint (032 characters)			
Dimension D	Dimension of value of the setpoint.			
Resolution ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	/alue [-]	
Comm object	10449	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for inpu	t in PLC logic.		
Configuration of setpo	int:		
Configuration is made via configuration PC tool InteliConfig			
	- 1 - 0 C Apply		
Image 9.78 Screen of configuration from InteliConfig			Config
PLC Setpoint name	Name of the setpoint (032 characters)		
Dimension [Dimension of value of the setpoint.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10450	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via configuration PC tool InteliConfig			
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	C Apply
		0.0	о _ Арриу
Image 9.79 Screen of configuration from InteliConfig			Config
PLC Setpoint name N	Name of the setpoint (032 characters)		
Dimension D	Dimension of value of the setpoint.		
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10451	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via configuration PC tool InteliConfig			
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:
	- 1 -	0.0	0 Apply
Image 9.80 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 characters)		
Dimension E	Dimension of value of the setpoint.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10452	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit: - 1 - 0 0 Apply				
Image 9.81 Screen of configuration from InteliConfig				
PLC Setpoint name	Name of the setpoint (032 characters)			
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10453	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
Image 9.82 Screen of configuration from InteliConfig			Config	
PLC Setpoint name	Name of the setpoint (032 characters)			
Dimension I	Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			


Setpoint group	PLC	Related FW	1.0.0		
Range [units]	Depends on resolution of v	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO		
Step	Depends on resolution of v	/alue [-]			
Comm object	10454	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant setpoint is	used in PLC			
Description					
Adjustable value for input	t in PLC logic.				
Configuration of setpo	int:				
Configuration is made via configuration PC tool InteliConfig					
	- 1 - 0 C Apply				
	Image 9.83 Screen of co	nfiguration from InteliC	Config		
PLC Setpoint name	Name of the setpoint (032 ch	naracters)			
Dimension I	Dimension of value of the setpoint.				
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.				
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10455	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made vi	Configuration is made via configuration PC tool InteliConfig			
	- 1 -	0 ()	0 C Apply	
Image 9.84 Screen of configuration from InteliConfig				
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10456	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	C Apply
			о _ мррту
	Image 9.85 Screen of co	nfiguration from InteliC	Config
PLC Setpoint name N	ame of the setpoint (032 ch	aracters)	
Dimension D	Dimension of value of the setpoint.		
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10457	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpo	nt:		
Configuration is made via	configuration PC tool InteliC	Config	
PLC Setpoint name: Dimension: Resolution: Low limit: High limit: - 1 - 0 C Apply Apply			
	Image 9.86 Screen of co	nfiguration from InteliC	Config
PLC Setpoint name	Name of the setpoint (032 characters)		
Dimension E	imension of value of the setp	point.	
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10458	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
	- 1 -	0 0	0 C Apply	
	Image 9.87 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10459	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 -	0 0	0 C Apply	
	Image 9.88 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setp	point.		
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	he highest value of setpoint. Digit place of this value can be decrease or increase y resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10460	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpo	int:			
Configuration is made via	a configuration PC tool InteliC	Config		
PLC Setpoint name:	PLC Setpoint name: Dimension: Resolution: Low limit: High limit:			
	Image 9.89 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension [)imension of value of the setp	point.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10461	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	t.
i ce octpoint numer	- 1 -	0 0	0 C Apply
Image 9.90 Screen of configuration from InteliConfig			
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution R	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10462	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
	- 1 -	0.0	0 C Apply	
	Image 9.91 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setpoint.			
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10463	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
			a state of the second s	
	Image 9.92 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10464	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 - 0 0 Apply			
	Image 9.93 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of v	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10465	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 · O _ O _ Apply			
	Image 9.94 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10466	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	- 1 - 0 _ Apply			
	Image 9.95 Screen of co	nfiguration from InteliC	onfig	
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension D	Dimension of value of the setpoint.			
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10467	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
	- 1 - 0 0 Apply			
	Image 9.96 Screen of co	nfiguration from InteliC	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10468	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpo	nt:			
Configuration is made via	configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	- 1 *	0.0	0 C Apply	
	Image 9.97 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension E	Dimension of value of the setpoint.			
Resolution II	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10469	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:
	- 1 -	0.0	0 C Apply
	Image 9.98 Screen of co	nfiguration from InteliC	Config
PLC Setpoint name	lame of the setpoint (032 ch	aracters)	
Dimension D	imension of value of the setp	point.	
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10470	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	configuration PC tool InteliC	Config		
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	t:	
	- 1 -	0 0	0 C Apply	
	Image 9.99 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension D	Dimension of value of the setpoint.			
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0		
Range [units]	Depends on resolution of value [-]				
Default value	Depends on resolution of value [-]	Alternative config	NO		
Step	Depends on resolution of v	alue [-]			
Comm object	10471	Related applications	MINT, SPtM		
Config level	Standard				
Setpoint visibility	Only if relevant setpoint is	used in PLC			
Description					
Adjustable value for input	in PLC logic.				
Configuration of setpoi	nt:				
Configuration is made via	configuration PC tool InteliC	Config	+.		
PEC Setpoint name.	- 1 -	n *	0 Annly		
1	mage 9.100 Screen of co	onfiguration from Inteli	Config		
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)			
Dimension D	imension of value of the setp	point.			
Resolution ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.				
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.				



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10472	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpo	nt:			
Configuration is made via	Configuration PC tool InteliC	Config	t:	
	- 1 -	0 0	0 C Apply	
	Image 9.101 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension E	imension of value of the setp	point.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10473	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for inpu	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	Image 9.102 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10474	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpo	nt:		
Configuration is made via	a configuration PC tool InteliC	Config	t.
i ce octpoint numer	- 1 -	0	0 Apply
	Image 9.103 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name	lame of the setpoint (032 ch	aracters)	
Dimension [)imension of value of the setp	point.	
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10475	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	* •
FEC Setpoint name.	- 1 -	0 *	0 Anply
1	mage 9.104 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10476	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	t.
rec setpoint name.	- 1 -	0	0 Apply
<u> </u>	mage 9.105 Screen of co	nfiguration from Inteli	Config
	5	5	5
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10477	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpo	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	t:
	- 1 -	0.0	0 C Apply
Image 9.106 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	aracters)	
Dimension E	imension of value of the setp	point.	
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10478	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	÷.
PEC Setpoint name.	- 1 -	n *	0 Annly
			a a a a a a a a a a a a a a a a a a a
1	mage 9.107 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10479	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for inpu	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig				
	- 1 - 0 C Apply			
	Image 9.108 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10480	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	* •
FEC Setpoint name.	- 1 -	0 *	0 Anply
1	mage 9.109 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10481	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	Configuration PC tool InteliC	Config	t.	
i ce octpoint numer	- 1 -	0 0	0 Apply	
	Image 9.110 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension E	imension of value of the setp	point.		
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10482	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	Configuration PC tool InteliC	Config	t:	
, cooctpoint numer	- 1 -	0.0	0 C Apply	
	Image 9.111 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension E	Dimension of value of the setpoint.			
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10483	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	Image 9.112 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension I	Dimension of value of the setp	point.		
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10484	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	+.
PEC Setpoint name.		o *	0 Apply
1	mage 9.113 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name	Name of the setpoint (032 characters)		
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10485	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for inpu	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 - 0 0 Apply			
	Image 9.114 Screen of co	onfiguration from Inteli	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10486	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 - 0 C Apply			
	Image 9.115 Screen of co	onfiguration from Inteli	Config	
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10487	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	Configuration PC tool InteliC	Config	* •	
rec setpoint name.	- 1 -	0	0 Apply	
1	Image 9.116 Screen of configuration from InteliConfig			
PLC Setpoint name N	e Name of the setpoint (032 characters)			
Dimension D	imension of value of the setp	point.		
Resolution R	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10488	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit:				
	- 1 - 0 C Apply			
	Image 9.117 Screen of co	onfiguration from Inteli	Config	
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10489	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	configuration PC tool InteliC	Config	t.	
Tee setpoint nume.	- 1 -	0 0	0 C Apply	
1	Image 9.118 Screen of configuration from InteliConfig			
PLC Setpoint name N	ame of the setpoint (032 ch	aracters)		
Dimension D	imension of value of the setp	point.		
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			


Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10490	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	* .
FEC Setpoint name.	- 1 -	0 *	0 Anply
1	mage 9.119 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	/alue [-]		
Comm object	10491	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via configuration PC tool InteliConfig				
i coociponicionici	- 1 -	0 0	0 Apply	
	Image 9.120 Screen of configuration from InteliConfig			
PLC Setpoint name	lame of the setpoint (032 ch	naracters)		
Dimension E	imension of value of the setp	point.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10492	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	configuration PC tool InteliC	Config	* .
PEC Setpoint name.	- 1 -	0 *	0 Anply
ji	mage 9.121 Screen of co	n Intelion from Intelio	Config
			Johnig
PLC Setpoint name	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10493	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made via configuration PC tool InteliConfig PLC Setpoint name: Dimension: Resolution: Low limit: High limit: - 1 - 0 0 Apply				
	Image 9.122 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setpoint.			
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10494	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	* •
FEC Setpoint name.	- 1 -	0 *	0 Anply
<u> </u>	mage 9.123 Screen of co	nfiguration from Inteli	Config
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10495	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	t in PLC logic.			
Configuration of setpo	int:			
Configuration is made view PLC Setpoint name:	a configuration PC tool InteliC	Config	it:	
	- 1 -	0 0	0 C Apply	
	Image 9.124 Screen of configuration from InteliConfig			
PLC Setpoint name	Name of the setpoint (032 ch	naracters)		
Dimension [Dimension of value of the setp	point.		
Resolution i	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	value [-]		
Comm object	10496	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	configuration PC tool InteliC	Config	t.	
i ce octpoint numer	- 1 -	0 0	0 C Apply	
1	Image 9.125 Screen of configuration from InteliConfig			
PLC Setpoint name	ame of the setpoint (032 ch	naracters)		
Dimension D	imension of value of the setp	point.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10497	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	Configuration PC tool InteliC	Config	* •	
rec setpoint name.	- 1 -	0	0 Apply	
1	Image 9.126 Screen of configuration from InteliConfig			
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)		
Dimension D	imension of value of the setp	point.		
Resolution F	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10498	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	. .
PLC Setpoint name.	Dimension: Resolution:	Cow minit. High mini	0 Annly
			e
]	Image 9.127 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name	lame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10499	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	in PLC logic.		
Configuration of setpoi	nt:		
Configuration is made via	Configuration PC tool InteliC	Config	* •
rec setpoint name.	- 1 -	0	0 Apply
<u>k</u>	mage 9 128 Screen of co	n Intelion from Intelio	Config
			coning
PLC Setpoint name	ame of the setpoint (032 ch	naracters)	
Dimension D	imension of value of the setp	point.	
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0
Range [units]	Depends on resolution of value [-]		
Default value	Depends on resolution of value [-]	Alternative config	NO
Step	Depends on resolution of v	alue [-]	
Comm object	10500	Related applications	MINT, SPtM
Config level	Standard		
Setpoint visibility	Only if relevant setpoint is	used in PLC	
Description			
Adjustable value for input	t in PLC logic.		
Configuration of setpo	int:		
Configuration is made vi	a configuration PC tool InteliC	Config	
PLC Setpoint name:	Dimension: Resolution:	Low limit: High limi	C Apply
			o - nppn
	Image 9.129 Screen of co	onfiguration from Inteli	Config
PLC Setpoint name	Name of the setpoint (032 ch	naracters)	
Dimension	Dimension of value of the setp	point.	
Resolution	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.		
Low limit	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		
High limit	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.		



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	alue [-]		
Comm object	10501	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via	configuration PC tool InteliC	Config	t.	
Tee setpoint nume.	- 1 -	0 0	0 C Apply	
1	Image 9.130 Screen of configuration from InteliConfig			
PLC Setpoint name N	ame of the setpoint (032 ch	naracters)		
Dimension D	imension of value of the setp	point.		
Resolution Ir	Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	Depends on resolution of value [-]		
Comm object	10502	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via configuration PC tool InteliConfig				
			0 C Apply	
Image 9.131 Screen of configuration from InteliConfig				
PLC Setpoint name	PLC Setpoint name Name of the setpoint (032 characters)			
Dimension D	Dimension of value of the setpoint.			
Resolution F	esolution Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	he lowest value of setpoint. Digit place of this value can be decrease or increase y resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



Setpoint group	PLC	Related FW	1.0.0	
Range [units]	Depends on resolution of value [-]			
Default value	Depends on resolution of value [-]	Alternative config	NO	
Step	Depends on resolution of v	Depends on resolution of value [-]		
Comm object	10503	Related applications	MINT, SPtM	
Config level	Standard			
Setpoint visibility	Only if relevant setpoint is	used in PLC		
Description				
Adjustable value for input	in PLC logic.			
Configuration of setpoi	nt:			
Configuration is made via configuration PC tool InteliConfig				
Image 9.132 Screen of configuration from InteliConfig				
PLC Setpoint name	PLC Setpoint name Name of the setpoint (032 characters)			
Dimension D	imension of value of the setp	point.		
Resolution F	esolution Resolution of the value of the setpoint. Resolution adjust number of decimal places in low and high limit.			
Low limit b	The lowest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			
High limit b	The highest value of setpoint. Digit place of this value can be decrease or increase by resolution of setpoint.			



9.1.2 Values

What values are:

Values (or quantities) are analog or binary data objects, measured or computed by the controller, that are intended for reading from the controller screen, PC, MODBUS, etc. Values are organized into groups according to their meaning.

Invalid flag

If valid data is not available for a particular value, the invalid flag is set to it. This situation may be due to the following:

- > The value is not being evaluated in the scope of the current application and configuration.
- Sensor fail has been detected on an analog input.
- The configured ECU or extension module does not provide the particular value.
- ▶ The communication with the ECU or extension module is interrupted.

A value containing the invalid flag is displayed as "#####" in InteliConfig and on the controller screen. If such a value is read out via MODBUS, it will contain the data 32768 in the case of signed values and 65535 in the case of unsigned values.

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Group: Load	
Group: Mains/Bus	
Group: Power Management	
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For full list of setpoints go to the chapter List of values (page 556).



List of values

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Group: Engine

DEF Level

Value group	Engine	Related FW	1.0.0	
Units	%			
Comm object	14522	Related applications	MINT, SPtM	
Description				
The level of diesel exhaust fluid tank.				

O back to List of values

DPF Ash Load

Value group	Engine	Related FW	1.0.0	
Units	%			
Comm object	12483	Related applications	MINT, SPtM	
Description				
The rate of ash in DPF (Diesel particulate filter).				

O back to List of values

DPF Soot Load

Value group	Engine	Related FW	1.0.0	
Units	%			
Comm object	12484	Related applications	MINT, SPtM	
Description				
The rate of soot in DPF (Diesel particulate filter).				

back to List of values

ECU-BIN 1

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10153	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				

Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.



ECU-BIN 2

Va	ue group	Engine	Related FW	1.0.0
Un	its	Depends on ECU value		
Co	mm object	10154	Related applications	MINT, SPtM
De	scription			
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature				

[°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.

O back to List of values

ECU-BIN 3

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10155	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.				

O back to List of values

ECU-BIN 4

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10156	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				

Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.

O back to List of values

ECU-BIN 5

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10157	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.				



ECU-BIN 6

Va	ue group	Engine	Related FW	1.0.0
Un	its	Depends on ECU value		
Co	mm object	10158	Related applications	MINT, SPtM
De	scription			
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature				

[°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.

O back to List of values

ECU-BIN 7

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10159	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.				

O back to List of values

ECU-BIN 8

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10160	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				

Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.

back to List of values

ECU-BIN 9

Value group	Engine	Related FW	1.0.0	
Units	Depends on ECU value			
Comm object	10161	Related applications	MINT, SPtM	
Description				
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.				
Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.				



ECU-BIN-EXT-1

Value	group	Engine	Related FW	1.0.0	
Units Depends on ECU value					
Com	n object	10173	Related applications	MINT, SPtM	
Description					
This is one of the inputs, which are defined by ECU. Order of values depends on type of ECU.					

Note: Usually there are engine speed[RPM], fuel rate[L/h], coolant temperature[°C], intake temperature [°C], oil pressure[bar], boost pressure[bar], load[%], oil temperature[°C] etc.

O back to List of values

ECU Frequency Select

Value group	Engine	Related FW	1.0.0		
Units	-				
Comm object	12926	Related applications	MINT, SPtM		
Description					

Shows selected frequency of ECU. The value is calculated from setpoint Nominal Frequency (page 247)

- If is Nominal Frequency (page 247) in range from 45 Hz to 54 Hz, is considered as 50 Hz application. The value is set to 0.
- If is Nominal Frequency (page 247) in range from 55 Hz to 65 Hz, is considered as 60 Hz application. The value is set to 1.

O back to List of values

ECU State

Value group	Engine	Related FW	1.0.0		
Units	-				
Comm object	10034	Related applications	MINT, SPtM		
Description					
Shows binary status	(0 or 1) of ECU:				
ECU Yellow L	amp				
ECU Red Lamp					
Wait To Start					



RPM

Value group	Engine	Related FW	1.0.0		
Units	RPM				
Comm object	10123	Related applications	MINT, SPtM		
Description					
 This value contains the current engine speed. The value is obtained from one of the following sources: ECU, if an ECU is configured 					

- Pickup input
- Generator frequency

O back to List of values

Speed Required RPM

Value group	Engine	Related FW	1.0.0		
Units	RPM				
Comm object	10006	Related applications	MINT, SPtM		
Description					
Requested engine speed.					

O back to List of values

Group: Generator

Generator kW

Value group	Generator	Related FW	1.0.0		
Units	kW				
Comm object	8202	Related applications	MINT, SPtM		
Description					
Generator active power.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this					

case the range of value is decrease 10 times.

O back to List of values

Generator kW L1

Value group	Generator	Related FW	1.0.0		
Units	kW				
Comm object	8524	Related applications	MINT, SPtM		
Description					
Generator active power in phase L1.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.					



Generator kW L2

Value group	Generator	Related FW	1.0.0		
Units	kW				
Comm object	8525	Related applications	MINT, SPtM		
Description					
Generator active power in phase L2.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.			ia InteliConfig PC tool). In this		

O back to List of values

Generator kW L3

Value group	Generator	Related FW	1.0.0		
Units	kW				
Comm object 8526		Related applications	MINT, SPtM		
Description					
Generator active power in phase L3.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.					

O back to List of values

Generator kVA

Value group	Generator	Related FW	1.0.0		
Units	kVA				
Comm object	8565	Related applications	MINT, SPtM		
Description					
Generator apparent power.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.					

0

back to List of values

Generator kVA L1

Value group	Generator	Related FW	1.0.0		
Units	kVA				
Comm object	8530	Related applications	MINT, SPtM		
Description					
Generator apparent p	ower L1.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.					



Generator kVA L2

Value group	Generator	Related FW	1.0.0		
Units	kVA				
Comm object	8531	Related applications	MINT, SPtM		
Description					
Generator apparent power L2.					
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.					

O back to List of values

Generator kVA L3

Value group	Generator	Related FW	1.0.0	
Units	kVA			
Comm object	8532	Related applications	MINT, SPtM	
Description				
Generator apparent power L3.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				

O back to List of values

Generator kVAr

Value group	Generator	Related FW	1.0.0	
Units	kVAr			
Comm object	8203	Related applications	MINT, SPtM	
Description				
Generator reactive power.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this				

case the range of value is decrease 10 times.

O back to List of values

Generator kVAr L1

Value group	Generator	Related FW	1.0.0	
Units	kVAr			
Comm object	8527	Related applications	MINT, SPtM	
Description				
Generator reactive power in phase L1.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				



Generator kVAr L2

Value group	Generator	Related FW	1.0.0	
Units	kVAr			
Comm object	8528	Related applications	MINT, SPtM	
Description				
Generator reactive power in phase L2.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				

• back to List of values

Generator kVAr L3

Value group	Generator	Related FW	1.0.0	
Units	kVAr			
Comm object	8529	Related applications	MINT, SPtM	
Description				
Generator reactive power in phase L3.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				

O back to List of values

Generator Load Character

Value group	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8395	Related applications	MINT, SPtM	
Description				
Character of the generator load. "L" means inductive load, "C" is capacitive and "R" is resistive load (power				
factor = 1).				

O back to List of values

Generator Load Character L1

Value group	Generator	Related FW	1.0.0
Units	[-]		
Comm object	8626	Related applications	MINT, SPtM
Description			
Character of the generator load in the L1 phase. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).			



Generator Load Character L2

Value group	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8627	Related applications	MINT, SPtM	
Description				
Character of the generator load in the L2 phase. "L" means inductive load, "C" is capacitive and "R" is				
resistive load (power factor = 1).				

O back to List of values

Generator Load Character L3

Value group	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8628	Related applications	MINT, SPtM	
Description				
Character of the generator load in the L3 phase. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).				

O back to List of values

Generator Power Factor

Generator	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8204	Related applications	MINT, SPtM	
Description				
Generator power factor.				

O back to List of values

Generator Power Factor L1

Generator	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8533	Related applications	MINT, SPtM	
Description				
Generator power factor in phase L1.				

O back to List of values

Generator Power Factor L2

Generator	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8534	Related applications	MINT, SPtM	
Description				
Generator power factor in phase L2.				



Generator Power Factor L3

Generator	Generator	Related FW	1.0.0	
Units	[-]			
Comm object	8535	Related applications	MINT, SPtM	
Description				
Generator power factor in phase L3.				

O back to List of values

Generator Frequency

Value group	Generator	Related FW	1.0.0	
Units	Hz			
Comm object	8210	Related applications	MINT, SPtM	
Description				
Frequency of generator.				

O back to List of values

Generator Voltage L1-L2

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	9628	Related applications	MINT, SPtM	
Description				
Generator phase to phase voltage between L1 and L2 phases.				

O back to List of values

Generator Voltage L1-N

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	8192	Related applications	MINT, SPtM	
Description				
Generator voltage on phase 1.				

O back to List of values

Generator Voltage L2-L3

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	9629	Related applications	MINT, SPtM	
Description				
Generator phase to phase voltage between L2 and L3 phases.				



Generator Voltage L2-N

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	8193	Related applications	MINT, SPtM	
Description				
Generator voltage on phase 2.				

O back to List of values

Generator Voltage L3-L1

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	9630	Related applications	MINT, SPtM	
Description				
Generator phase to phase voltage between L3 and L1 phases.				

• back to List of values

Generator Voltage L3-N

Value group	Generator	Related FW	1.0.0	
Units	V			
Comm object	8194	Related applications	MINT, SPtM	
Description				
Generator voltage on phase 3.				

O back to List of values

Generator Current L1

Value group	Generator	Related FW	1.0.0	
Units	A			
Comm object	8198	Related applications	MINT, SPtM	
Description				
Generator current phase L1.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this				

case the range of value is decrease 10 times.



Generator Current L2

Value group	Generator	Related FW	1.0.0	
Units	A			
Comm object	8199	Related applications	MINT, SPtM	
Description				
Generator current phase L2.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				

O back to List of values

Generator Current L3

Value group	Generator	Related FW	1.0.0	
Units	A			
Comm object	8200	Related applications	MINT, SPtM	
Description				
Generator current phase L3.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				

back to List of values

Slip Angle

Value group	Generator	Related FW	1.0.0	
Units	0			
Comm object	8225	Related applications	MINT, SPtM	
Description				
Slip angle during synchronization.				

O back to List of values

Slip Frequency

Value group	Generator	Related FW	1.0.0
Units	Hz		
Comm object	8224	Related applications	MINT, SPtM
Description			
Slip frequency during synchronization.			



Nominal Current

Value group	Generator	Related FW	1.0.0
Units	A		
Comm object	9978	Related applications	MINT, SPtM
Description			
Generator nominal current.			

back to List of values

Nominal Power

Value group	Generator	Related FW	1.0.0
Units	V		
Comm object	9018	Related applications	MINT, SPtM
Description			
Generator nominal power.			

O back to List of values

Nominal Voltage

Value group	Generator	Related FW	1.0.0
Units	V		
Comm object	9917	Related applications	MINT, SPtM
Description			
Generator nominal voltage.			

O back to List of values

Earth Fault Current

Value group	Generator	Related FW	1.0.0
Units	A		
Comm object	14325	Related applications	MINT, SPtM
Description			
Measured value of fault for evaluation of earth fault protection.			



Group: Load

Load kW

Value group	Load	Related FW	1.0.0
Units	kW		
Comm object	10601	Related applications	MINT, SPtM
Description			
Load active power.			
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.			

O back to List of values

Load kVAr

Load	Related FW	1.0.0	
kVAr			
10644	Related applications	MINT, SPtM	
Description			
Load reactive power.			
	Load kVAr 10644	Load Related FW kVAr 10644 Related applications	

Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.

O back to List of values

Load Power Factor

Load	Load	Related FW	1.0.0
Units	[-]		
Comm object	9025	Related applications	MINT, SPtM
Description			
Load power factor.			

O back to List of values

Load Character

Value group	Load	Related FW	1.0.0
Units	A		
Comm object	9026	Related applications	MINT, SPtM
Description			
Character of the load. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).			

Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.



Group: Mains/Bus

Mains/Bus Frequency

Value group	Mains	Related FW	1.0.0
Units	Hz		
Comm object	8211	Related applications	MINT, SPtM
Description			
Frequency of mains/bus.			

O back to List of values

Mains/Bus Voltage L1-L2

Value group	Mains	Related FW	1.0.0	
Units	V			
Comm object	9631	Related applications	MINT, SPtM	
Description				
Mains/Bus phase to phase voltage between L1 and L2 phases.				

O back to List of values

Mains/Bus Voltage L1-N

Value group	Mains	Related FW	1.0.0
Units	V		
Comm object	8195	Related applications	MINT, SPtM
Description			
Mains/Bus voltage on phase 1.			

back to List of values

Mains/Bus Voltage L2-L3

Value group	Mains	Related FW	1.0.0
Units	V		
Comm object	9632	Related applications	MINT, SPtM
Description			
Mains/Bus phase to phase voltage between L2 and L3 phases.			

O back to List of values

Mains/Bus Voltage L2-N

Value group	Mains	Related FW	1.0.0	
Units	V			
Comm object	8196	Related applications	MINT, SPtM	
Description				
Mains/Bus voltage on phase 2.				



Mains/Bus Voltage L3-L1

Value group	Mains	Related FW	1.0.0	
Units	V			
Comm object	9633	Related applications	MINT, SPtM	
Description				
Mains/Bus phase to phase voltage between L3 and L1 phases.				

O back to List of values

Mains/Bus Voltage L3-N

Value group	Mains	Related FW	1.0.0	
Units	V			
Comm object	8197	Related applications	MINT, SPtM	
Description				
Mains/Bus voltage on phase 3.				

O back to List of values

Mains/Bus Current L1

Value group	Mains	Related FW	1.0.0	
Units	A			
Comm object	8208	Related applications	SPtM	
Description				
Mains current in phase L1.				

O back to List of values

Mains Import kW

Value group	Mains	Related FW	1.0.0	
Units	kW			
Comm object	8703	Related applications	SPtM	
Description				
Imported kW from mains.				

O back to List of values

Mains Import kVAr

Value group	Mains	Related FW	1.0.0	
Units	kVAr			
Comm object	8704	Related applications	SPtM	
Description				
Imported kVAr from mains.				



Mains Power Factor

Value group	Mains	Related FW	1.0.0	
Units	Hz			
Comm object	8705	Related applications	SPtM	
Description				
Mains power factor.				

O back to List of values

Mains Load Character

Value group	Mains	Related FW	1.0.0
Units	Hz		
Comm object	8709	Related applications	SPtM
Description			
Character of mains load. "L" means inductive load, "C" is capacitive and "R" is resistive load (power factor = 1).			

O back to List of values

Max Vector ShiftMaxVectorS

Value group	MainsMains protect	Related FW	1.0.0
Units	Hz		
Comm object	9847	Related applications	SPtM
Description			
This is maximal measured value of vector shift of the generator voltage. It is set to zero always when Controller goes to parallel to mains operation (When Vector Shift Protection = PARALLEL ONLY) or when MCB gets closed (when Vector shift protection = ENABLED).			

O back to List of values

Group: Power Management

Engine Priority

Value group	Power Management	Related FW	1.0.0
Units	-		
Comm object	8624	Related applications	MINT
Description			

This value shows current priority number. It corresponds to the setpoint **Priority (page 333)** except following situations:

- ▶ If at least one of binary inputs **TOP PRIORITY** (PAGE 680) is configured on some source and is active
- #Priority Auto Swap (page 334) is active



Actual Reserve

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	15805	Related applications	MINT	
Description				
Actual absolute reserve in power management.				

O back to List of values

Actual Relative Reserve

Value group	Power Management	Related FW	1.0.0		
Units	%				
Comm object	10788	Related applications	MINT		
Description					
Actual relative reserve in power management.					

O back to List of values

Active Power Required

Value group	Speed/Load Control	Related FW	1.0.0		
Units	kW				
Comm object	8663	Related applications	MINT, SPtM		
Description					
This value contains actual required load level, which is used as the input into the load regulation loop in the parallel to mains operation.					

O back to List of values

Start Reserve

Value group	Power Management	Related FW	1.0.0		
Units	kW				
Comm object	15806	Related applications	MINT		
Description					
Actual absolute reserve for start.					

O back to List of values

Stop Reserve

Value group	Power Management	Related FW	1.0.0		
Units	kW				
Comm object	15807	Related applications	MINT		
Description					
Actual absolute reserve - when the reserve is higher than this value the last started gen-set (the gen-set with the highest priority) is stopped.					


Start Relative Reserve

Value group	Power Management	Related FW	1.0.0	
Units	%			
Comm object	10786	Related applications	MINT	
Description				
Actual relative reserve for start.				

back to List of values

Stop Relative Reserve

Value group	Power Management	Related FW	1.0.0	
Units	%			
Comm object	10787	Related applications	MINT	
Description				
Actual relative reserve - when the relative reserve is higher than this value the last started gen-set (the gen-				

set with the highest priority) is stopped.

back to List of values

Actual Active Power In PM

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	10657	Related applications	MINT	
Description				
Actual value of active power from all gen-sets running in power management.				

O back to List of values

Actual Reactive Power In PM

Value group	Power Management	Related FW	1.0.0	
Units	kVAr			
Comm object	10656	Related applications	MINT	
Description				
Actual value of reactive power from all gen-sets running in power management.				

O back to List of values

Running Nominal Power In PM

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	10658	Related applications	MINT	
Description				
Actual nominal power of all gen-sets in power management, which are running.				



Running Nominal Power Of All

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	10999	Related applications	MINT	
Description				
Actual nominal power of all gen-sets, which are running.				

O back to List of values

Available Nominal Power

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	10998	Related applications	MINT	
Description				
Available nominal power of all gen-sets in power management.				

O back to List of values

Minimal Running Nominal Power

Value group	Power Management	Related FW	1.0.0	
Units	kW			
Comm object	10012	Related applications	MINT	
Description				
Actual minimal nominal power of all gen-sets, which are running.				

back to List of values

Actual Power Band

Value group	Power Management	Related FW	1.0.0	
Units	-			
Comm object	8974	Related applications	MINT	
Description				

State of all gen-sets in actual power band of power management. 1 means that gen-set is running, 0 means that gen set is stopped.

Note: This value is evaluated only in controller with the lowest CAN address.



Next Power Band

Value group	Power Management	Related FW	1.0.0
Units	-		
Comm object	8975	Related applications	MINT
Description			
State of all gen-sets in next higher power band of power management. 1 means that gen-set is running, 0 means that gen set is stopped.			

Note: This value is evaluated only in controller with the lowest CAN address.

O back to List of values

Group: Speed/Load ControlLoad Control

Speed Regulator Output

Value group	Speed/Load Control	Related FW	1.0.0	
Units	V			
Comm object	9052	Related applications	MINT, SPtM	
Description				
This is the actual voltage on the speed governor output of the controller. In case the output is switched to PWM mode, the relation is $10 \text{ V} \sim 100 \%$ PWM10 V is 0% PWM				

back to List of values

Speed Request

Value group	Speed/Load Control	Related FW	1.0.0	
Units	%			
Comm object	10137	Related applications	MINT, SPtM	
Description				
This value contains the speed control signal expressed in %. This value is used for digital interfacing (via a				
communication bus) with ECUs that require the requested speed in %.				

O back to List of values

Requested RPM

Value group	Speed/Load Control	Related FW	1.0.0	
Units	RPM			
Comm object	10006	Related applications	MINT, SPtM	
Description				
This value contains the speed which is currently requested by the controller from the attached ECU. This value is used for digital interfacing (via a communication bus) with ECUs that require the requested speed				

directly in RPM.



Group: Voltage/PF Control

Reactive Power Required

Value group	Voltage/PF Control	Related FW	1.0.0	
Units	kVAr			
Comm object	12877	Related applications	MINT, SPtM	
Description				
Requested reactive power.				

O back to List of values

Voltage Regulator Output

Value group	Voltage/PF Control	Related FW	1.0.0	
Units	V			
Comm object	9053	Related applications	MINT, SPtM	
Description				
Actual voltage between the AVR OUT and AVR COM terminals.				

back to List of values

Voltage Request

Value group	Voltage/PF Control	Related FW	1.0.0	
Units	%			
Comm object	14997	Related applications	MINT, SPtM	
Description				
Internal Voltage request of internal Voltage regulator.				

O back to List of values

Group: Controler I/O

E-STOP

Value group	Controler I/O	Related FW	1.0.0	
Units	[-]			
Comm object	15780	Related applications	MINT, SPtM	
Description				
 Shows number of E-STOP input - the same principle of visualization like binary inputs. Principle of value (principle of normally close binary input): 1 - E-STOP has voltage - state is OK 0 - E-STOP has no voltage - protection is active 				



Analog Input 1

Value group	Controler I/O	Related FW	1.0.0	
Units	Configurable			
Comm object	9151	Related applications	MINT, SPtM	
Description				
This is the value of the analog input 1 of the controller.				

back to List of values

Analog Input 2

Value group	Controler I/O	Related FW	1.0.0	
Units	Configurable			
Comm object	9152	Related applications	MINT, SPtM	
Description				
This is the value of the analog input 2 of the controller.				

O back to List of values

Analog Input 3

Value group	Controler I/O	Related FW	1.0.0	
Units	Configurable			
Comm object	9153	Related applications	MINT, SPtM	
Description				
This is the value of the analog input 3 of the controller.				

O back to List of values

Analog Input 4

Value group	Controler I/O	Related FW	1.0.0	
Units	Configurable			
Comm object	9154	Related applications	MINT, SPtM	
Description				
This is the value of the analog input 4 of the controller.				

O back to List of values

Battery Volts

Value group	Controler I/O	Related FW	1.0.0	
Units	V			
Comm object	8213	Related applications	MINT, SPtM	
Description				
Controller supply voltage.				



Binary Inputs

Value group	Controler I/O	Related FW	1.0.0	
Units	[-]			
Comm object	8235	Related applications	MINT, SPtM	
Description				
State of the binary inputs of the controller.				

O back to List of values

Binary Outputs

Value group	Controler I/O	Related FW	1.0.0	
Units	[-]			
Comm object	8239	Related applications	MINT, SPtM	
Description				
State of the binary outputs of the controller.				

O back to List of values

D+

Value group	Controler I/O	Related FW	1.0.0
Units	V		
Comm object	10603	Related applications	MINT, SPtM
Description			
D+ terminal voltage.			

O back to List of values

Group: Statistics

Genset kVArh

Value group	Statistics	Related FW	1.0.0	
Units	kVArh			
Comm object	8539	Related applications	MINT, SPtM	
Description				
Counter of gen-set reactive power.				
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.				



Genset kWh

Value group	Statistics	Related FW	1.0.0
Units	kWh		
Comm object	8205	Related applications	MINT, SPtM
Description			
Counter of gen-set active power.			
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.			

O back to List of values

Mains kVArh

Value group	Statistics	Related FW	1.0.0
Units	kVArh		
Comm object	11026	Related applications	MINT, SPtM
Description			
Counter of mains reactive power.			
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.			

O back to List of values

Mains kWh

Value group	Statistics	Related FW	1.0.0
Units	kWh		
Comm object	11025	Related applications	MINT, SPtM
Description			
Counter of mains active power.			
Note: This value can be also switch into one decimal power format (via InteliConfig PC tool). In this case the range of value is decrease 10 times.			

O back to List of values

Maintenance 1

Value group	Statistics	Related FW	1.0.0
Units	hours		
Comm object	10528	Related applications	MINT, SPtM
Description			
Countdown until next maintenance 1. Initial value can be set in Maintenance Timer 1 (page 302).			



Maintenance 2

Value group	Statistics	Related FW	1.0.0
Units	hours		
Comm object	10529	Related applications	MINT, SPtM
Description			
Countdown until next maintenance 2. Initial value can be set in Maintenance Timer 2 (page 303).			

O back to List of values

Maintenance 3

Value group	Statistics	Related FW	1.0.0	
Units	hours			
Comm object	10530	Related applications	MINT, SPtM	
Description				
Countdown until next maintenance 3. Initial value can be set in Maintenance Timer 3 (page 303).				

O back to List of values

Num E-Stops

Value group	Statistics	Related FW	1.0.0	
Units	[-]			
Comm object	11195	Related applications	MINT, SPtM	
Description				
Emergency stop alarms counter.				

O back to List of values

Num Starts

Value group	Statistics	Related FW	1.0.0
Units	[-]		
Comm object	8207	Related applications	MINT, SPtM
Description			
Engine start commands counter. The counter is increased by 1 even if the particular start command will take			

Engine start commands counter. The counter is increased by 1 even if the particular start command will take more than one attempt.

O back to List of values

Rental 1

Value group	Statistics	Related FW	1.0.0
Units	hours		
Comm object	14328	Related applications	MINT, SPtM
Description			
Remaining hours of Rental Timer 1 (page 441).			



Rental 2

Value group	Statistics	Related FW	1.0.0	
Units	days			
Comm object	14369	Related applications	MINT, SPtM	
Description				
Remaining hours of Rental Timer 2 (page 443).				

back to List of values

Running Hours

Value group	Statistics	Related FW	1.0.0	
Units	hours			
Comm object	8206	Related applications	MINT, SPtM	
Description				
Engine operation hours counter. The engine hours are incremented in the controller while the engine is running.				
Note: If an ECU is configured and it provides engine hours value, the value is taken from the ECU.				

O back to List of values

Shutdowns

Value group	Statistics	Related FW	1.0.0	
Units	[-]			
Comm object	11196	Related applications	MINT, SPtM	
Description				
Shutdown alarms counter. This counter counts all occurrences of a shutdown alarm, not only real shutdowns				

of the gen-set, i.e. the counter is increased by 2 if two shutdown alarms appear simultaneously.

O back to List of values

Time Till Empty

Value group	Statistics	Related FW	1.0.0	
Units	days			
Comm object	13770	Related applications	MINT, SPtM	
Description				
Assessment in days when the fuel tank will be empty.				

Note: This value is based on setpoint **Fuel Tank Volume (page 298)** and value from ECU Fuel Rate. For correct calculation of this value is necessary to have configured ECU which send Fuel Rate value, otherwise this value can't be calculated.



Time Till Empty

Value group	Statistics	Related FW	1.0.0	
Units	hours			
Comm object	13771	Related applications	MINT, SPtM	
Description				
Assessment in hours when the fuel tank will be empty.				
Note: This value is based on setpoint Fuel Tank Volume (page 298) and value from ECU Fuel Rate.				

For correct calculation of this value is necessary to have configured ECU which send Fuel Rate value, otherwise this value can't be calculated.

back to List of values

Time Till Empty

Value group	Statistics	Related FW	1.0.0
Units	minutes		
Comm object	13772	Related applications	MINT, SPtM
Description			

Assessment in minutes when the fuel tank will be empty.

Note: This value is based on setpoint **Fuel Tank Volume (page 298)** and value from ECU Fuel Rate. For correct calculation of this value is necessary to have configured ECU which send Fuel Rate value, otherwise this value can't be calculated.

back to List of values

Total Fuel Consumption

Value group	Statistics	Related FW	1.0.0
Units	L		
Comm object	9040	Related applications	MINT, SPtM
Description			

Value containing total amount of consumed fuel by engine. The controller automatically updates this value every 30 s. The controller can calculate it in three ways:

- Direct reading from ECU
- Calculation based on actual fuel consumption reading from ECU
- Calculation from fuel level drop in tank (using Fuel Level Analog Input + Fuel Tank Volume (page 298) setpoint)

Note: The accuracy of Total Fuel Consumption depends on the precision of ECU values or precision of **Fuel Tank Volume (page 298)** and fuel level sensor.



Group: InfoInfo

Application Mode

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	14446	Related applications	MINT, SPtM	
Description				
This Value mirrors the active application in the controller.				
The intend of use it to display the value of the active application in InteliConfig or at the screen of the				

controller.

back to List of values

Load Shedding StatusStatLdShed

Value group	IL InfoLoad shedding	Related FW	1.0.0	
Units	[-]			
Comm object	9591 Related applications MINT, SPtM			
Description				
The value contains actual "load shedding stage. The Value can get the values of the range 0 to 3, where 0 means no load shedding stage is active and 1, 2 or 3 means that the corresponding loadshedding stage is active.				

back to List of values

Engine State

Value group	Info	Related FW	1.0.0	
Units	[-]			
Comm object	9244	Related applications	MINT, SPtM	
Description				
The value contains actual "engine state" message which is shown on the main screen of the controller.				

O back to List of values

Breaker State

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	9245	Related applications	MINT, SPtM	
Description				
The value contains actual "breaker state" message which is shown on the main screen of the controller.				



Timer Text

Value group	IL Info	Related FW	1.0.0
Units	[-]		
Comm object	10040	Related applications	MINT, SPtM
Description			

Description

The value contains the numeric code of the "Current process timer" text which is shown on the main screen of the controller.

The assignment of texts to the codes can be obtained using InteliConfig. Open any connection (also offline with a previously saved archive) and go to the Tools ribbon -> Generate CFG image (all). The resulting file will contain the assignment of texts to the codes.

O back to List of values

Connection Type

Value group	IL Info	Related FW	1.0.0
Units	[-]		
Comm object	12944	Related applications	MINT, SPtM
Description			
The text of this value represents the connection type which is adjusted in setpoint Connection type (page 244) .			

O back to List of values

SPI Module A

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	14447	Related applications	MINT, SPtM	
Description				
The name of plug-in module which is inserted in slot A.				

O back to List of values

SPI Module B

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	14448	Related applications	MINT, SPtM	
Description				
The name of plug-in module which is inserted in slot B.				



Timer Value

Value group	IL Info	Related FW	1.0.0
Units	[HH:MM:SS]		
Comm object	14147	Related applications	MINT, SPtM
Description			

The value contains the "Current process timer" value which is shown on the main screen of the controller.

O back to List of values

ID String

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	24501	Related applications	MINT, SPtM	
Description				
Name of controller which is used in InteliConfig in command bar.				

O back to List of values

FW Version

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	24339	Related applications	MINT, SPtM	
Description				
Major and minor firmware version number.				

O back to List of values

Application

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	8480	Related applications	MINT, SPtM	
Description				
The value contains actual application in controller.				

O back to List of values

FW Branch

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	8707	Related applications	MINT, SPtM	
Description				
The value contains actual branch of firmware in controller.				



Password Decode

Value group	IL Info	Related FW	1.0.0	
Units	[-]			
Comm object	24202	Related applications	MINT, SPtM	
Description				
This value contains a number which can be used for retrieving a lost password. Send this number together				

I his value contains a number which can be used for retrieving a lost password. Send this number together with the controller serial number to your distributor if you have lost your password.

O back to List of values

CAN16

Value group	IL Info	Related FW	1.0.0
Units	V		
Comm object	8546	Related applications	MINT, SPtM
Description			
Bits of this value show "1" if the controller receives messages from the controller which has address corresponding with the bit position. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 1-16.			

O back to List of values

CAN32

Value group	IL Info	Related FW	1.0.0	
Units	V			
Comm object	8827	Related applications	MINT, SPtM	
Description				
Bits of this value show "1" if the controller receives messages from the controller which has address				
corresponding with the bit position. Bit 0 represents address 17 etc. This value contains information about				
controllers with addresses 17-32.				

O back to List of values

Reg16

Value group	IL Info	Related FW	1.0.0	
Units				
Comm object	11081	Related applications	MINT, SPtM	
Description				
Bits of this value show "1" if the controller which has address corresponding with the bit position plays active				

role in the power management. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 1-16.



Reg32

Value group	IL Info	Related FW	1.0.0	
Units				
Comm object	11082	Related applications	MINT, SPtM	
Description				

Bits of this value show "1" if the controller which has address corresponding with the bit position plays active role in the power management. Bit 0 represents address 17 etc. This value contains information about controllers with addresses 17-32.

back to List of values

Gen Loaded 16

Value group	IL Info	Related FW	1.0.0	
Units	V			
Comm object	10196	Related applications	MINT, SPtM	
Description				

Bits of this value show "1" if the controller which has address corresponding with the bit position plays active role in the power management. Bit 0 represents address 1 etc. This value contains information about controllers with addresses 1-16.

back to List of values

Gen Loaded 32

Value group	IL Info	Related FW	1.0.0	
Units	V			
Comm object	10197	Related applications	MINT, SPtM	
Description				

Bits of this value show "1" if the controller which has address corresponding with the bit position plays active role in the power management. Bit 0 represents address 17 etc. This value contains information about controllers with addresses 17-32.

back to List of values

Group: Log Bout

Log Bout 1

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9143	Related applications	MINT, SPtM	
Description				
State of binary outputs.				



Log Bout 2

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9144	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

back to List of values

Log Bout 3

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9145	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 4

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9146	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 5

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9147	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 6

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9148	Related applications	MINT, SPtM	
Description				
State of binary outputs.				



Log Bout 7

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9149	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

back to List of values

Log Bout 8

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	9150	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 9

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	11896	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 10

Value group	Log Bout	Related FW	1.0.0	
Units	[-]			
Comm object	11897	Related applications	MINT, SPtM	
Description				
State of binary outputs.				

O back to List of values

Log Bout 11

Value group	Log Bout	Related FW	1.0.0		
Units	[-]				
Comm object	11898	Related applications	MINT, SPtM		
Description					
State of binary outputs.					



Group: Ethernet

AirGate Status

Val	ue group	Ethernet	Ethernet Related FW 1.0.0		
Units [-]					
Со	mm object	24344	24344 Related applications MINT, SPtM		
Des	scription				
Dia	gnostic code	for AirGate connection. Helps	s in troubleshooting.		
	Code	ode Description			
	0	Ethernet cable is disconnec	ernet cable is disconnected		
	1	Controller registered, waitin	ntroller registered, waiting for authorization		
	2	Not possible to register, cor	t possible to register, controller blacklisted		
	3	Not possible to register, ser	t possible to register, server has no more capacity		
	4	Not possible to register, oth	t possible to register, other reason		
	5	Controller registered and au	thorized		

O back to List of values

AirGate ID

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24345	Related applications	MINT, SPtM		
Description					
Identification string generated by AirGate server for the purpose of establishing communication via InteliConfig or any other supported PC tool.					

O back to List of values

Primary DNS

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24181	Related applications	MINT, SPtM		
Description					
Current domain name server.					

back to List of values

Secondary DNS

Value group	Ethernet	Related FW	1.0.0
Units	[-]		
Comm object		Related applications	MINT, SPtM
Description			



ETH Interface Status

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24180	Related applications	MINT, SPtM		
Description					
Current status of ethernet communication.					

O back to List of values

Ethernet PHY mode

Value group	Ethernet	Related FW	1.0.0
Units	[-]		
Comm object		Related applications	MINT, SPtM
Description			

back to List of values

Current Gateway

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24182	Related applications	MINT, SPtM		
Description					
Current gateway address.					

O back to List of values

Current IP Address

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24184	Related applications	MINT, SPtM		
Description					
Current IP address of the controller.					



Last Email Result

Val	ue group	Ethernet Related FW 1.0.0				
Units [-]						
Со	Comm object 24332 Related applications MINT, SPtM			MINT, SPtM		
Des	Description					
Res	Result of last email, which was sent by controller.					
	Code	Description				
	0	Email	was successfully sent.			
	2	It is no	ot possible to establish cor	nnection with SMTP serve	r.	
	3	SMTF	server is not ready for co	mmunication.		
	8	HELO command was refused.				
	9	EHLO command was refused.				
	11	AUTH LOGIN command was refused.				
	12	Wrong user name.				
	13	Wrong password.				
	14	MAIL	FROM command was refu	used.		
	15	RCPT	TO command was refuse	ed.		
	16	DATA	command was refused.			
	17	Sendi	ng of email failed.			
	20	QUIT	command was refused.			
	25	It is impossible to create data for command DATA.				
	26	It is in	npossible to read data for c	command DATA.		
	27	Email address can't be read.				
	30	SMTF	eserver address translatio	n error (from DNS server).		
	31	Error r	eading email content data	(24327).		

O back to List of values

MAC Address

Value group	Ethernet	Related FW	1.0.0	
Units	[-]			
Comm object	24333	Related applications	MINT, SPtM	
Description				
Current MAC address of the controller ethernet interface.				



Current Subnet Mask

Value group	Ethernet	Related FW	1.0.0		
Units	[-]				
Comm object	24183	Related applications	MINT, SPtM		
Description					
Current subnet mask.					

back to List of values

Group: CM-GPRS

AirGate Status

Value group		CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units		[-]			
Со	nm object	24308	Related applications	MINT, SPtM	
Des	scription				
Dia	gnostic code f	or AirGate connection. Help	s in troubleshooting.		
Code Description		Description			
0 SIM card is not inserted					
	1	Controller registered, waitir	ng for authorization		
	2	Not possible to register, co	possible to register, controller blacklisted		
3 Not po		Not possible to register, se	possible to register, server has no more capacity		
4 Not possible to register,		Not possible to register, oth	ther reason		
5 Controller registered and auth		Ithorized			

O back to List of values

AirGate ID

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24309	Related applications	MINT, SPtM	
Description				
Identification string generated by AirGate server for the purpose of establishing communication via InteliConfig or any other supported PC tool.				



Connection Type

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0		
Units	[-]				
Comm object	24146	Related applications	MINT, SPtM		
Description					
The type of data connection.					

O back to List of values

Cell Diag Code

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24288	Related applications	MINT, SPtM	
Description				

Diagnostic code for the CM-GPRS or CM-4G-GPS module.

GSM Diag Code – Common list of diagnostic codes for cellular modules

Code	Description
0	OK. No error.
1	Not possible to hang up.
2	Modul is switched off
3	Module is switched on
4	Module – error in initialization
5	Module – not possible to set the APN
6	Module – not possible to connect to GPRS network
7	Module – not possible to retrieve IP address
8	Module – not accepted DNS IP address
9	Error in modem detection
10	Error in initialization of analog modem
11	SIM card is locked (Possibly PIN code required, PIN needs to be deactivated) or unknown status of SIM locking
12	No GSM signal
13	Not possible to read the SIM card parameters
14	GSM modem did not accepted particular initialization command, possibly caused by locked SIM card
15	Unknown modem
16	Bad answer to complement initialization string
17	Not possible to read GSM signal strength
18	CDMA modem not detected
19	No CDMA network



20	Unsuccessful registration to CDMA network
21	SIMCom/ME909s: can't read FW version
22	SIMCom: GSM signal not found
23	SIMCom: can't detect module speed
24	SIMCom: HW reset issued
25	PUK is required
26	Error of SIM card detected
27	ME909s: can't set module bps
28	ME909s: can't set link configuration
29	ME909s: can't do power-off
30	ME909s: can't do power-on
31	ME909s: can't do hardware reset
32	ME909s: ME909s not started
33	ME909s: switch off issued
34	ME909s: switch on issued
35	ME909s: HW reset issued
36	ME909s: can't switch echo off
37	ME909s: can't find out state of registration
38	ME909s: GSM signal not found
39	ME909s: no SIM memory for SMS
40	ME909s: waiting for registration
41	Can't read operator name
42	ME909s: can't set flow control
43	APN not typed
255	Only running communication is needed to indicate

O back to List of values

Cell ErrorRate

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	%			
Comm object	24300	Related applications	MINT, SPtM	
Description				
This value contains information about relative quality of the cellular signal received by the CM-GPRS module or by CM-4G-GPS module. The lower value means higher quality of signal.				



Cell Signal Lev

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0
Units	%		
Comm object	24302	Related applications	MINT, SPtM
Description			
This value contains information about relative strength of the cellular signal received by the CM-GPRS module or by CM-4G-GPS module. It is a relative value helping to find the best signal and for troubleshooting cases.			

O back to List of values

Cell Status

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24290	Related applications	MINT, SPtM	
Description				
The text of this value represents the status of the GSM modem.				



Last Email Result

Value group			CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0		
Uni	its		[-]				
Со	Comm object		24307	Related applications	MINT, SPtM		
Des	Description						
Result of last email, which was sent by controller.							
Code Description							
	0	Email	was successfully sent.				
	2	It is no	ot possible to establish co	nnection with SMTP serve	er.		
	3	SMTF	P server is not ready for co	mmunication.			
	4	Maxin	num length of data can't be	e read.			
	5	No ap	peal to send command.				
	6	Comn	nand can't be send.				
	7	Comn	nand can't be send.				
8 HELO		HELC	LO command was refused.				
11 AUTH LOGIN command was refused. 12 Wrong user name.							
13 Wrong password.		g password.	l.				
	14	MAIL	FROM command was refused.				
	15	RCPT	T TO command was refused.				
	16	DATA	A command was refused.				
	17	Sendi	ng of email failed.				
	18	SMTF	MTP server refused the data of email.				
	19	SMTF	MTP server refused the data of email.				
	20	QUIT	command was refused.				
	21	Lost c	ost of connection.				
	23	Error	during closing the connect	ion.			
	24	No an	swer from server.				
	25	It is in	is impossible to create data for command DATA.				
	26	It is in	npossible to read data for o	command DATA.			
	28	Error	of encoding.				
29 There			here was no attempt to send email.				



Operator

Value group)	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0
Units		[-]		
Comm obje	ct	24147	Related applications	MINT, SPtM
Description				
The name of operator which to SIM card is connected.				
Note: If I	Note: If roaming service is used then prefix "R" is added before the name of operator.			

O back to List of values

Group: CM-4G-GPS

Altitude

Value group	CM-4G-GPS (GPS part)	Related FW	1.0.0	
Units	m			
Comm object	24266	Related applications	MINT, SPtM	
Description				
Actual GPS altitude.				

O back to List of values

HomePosDist

Value group	CM-4G-GPS (GPS part)	Related FW	1.0.0	
Units	km			
Comm object	11680	Related applications	MINT, SPtM	
Description				
Actual distance from home position. Home position is adjusted via setpoints Home Latitude (page 446)				

and Home Longitude (page 446) or by binary input GEO HOME POSITION (PAGE 668).

O back to List of values

Latitude

Value group	CM-4G-GPS (GPS part)	Related FW	1.0.0	
Units	[-]			
Comm object	24268	Related applications	MINT, SPtM	
Description				
Actual GPS latitude. Positions on north hemisphere have positive value, position on south hemisphere have negative value.				



Longitude

Value group	CM-4G-GPS (GPS part)	Related FW	1.0.0	
Units	[-]			
Comm object	24267	Related applications	MINT, SPtM	
Description				
Actual GPS longitude. Positions on east hemisphere have positive value, position on west hemisphere have				

Actual GPS longitude. Positions on east hemisphere have positive value, position on west hemisphere have negative value.

back to List of values

Satellites

Value group	CM-4G-GPS (GPS part)	Related FW	1.0.0	
Units	[-]			
Comm object	24265	Related applications	MINT, SPtM	
Description				
Number of available satellites for GPS location.				

O back to List of values

AirGate ID

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24309	Related applications	MINT, SPtM	
Description				
Identification string generated by AirGate server for the purpose of establishing communication via InteliConfig or any other supported PC tool.				



AirGate Status

Val	ue group	Ċ	CM-GPRS; CM-4G- GPS (4G part) Related FW 1.0.0		
Uni	ts	[-	-]		
Со	nm object	2	24308	Related applications	MINT, SPtM
Des	scription				
Dia	gnostic code f	or Air	Gate connection. Helps	in troubleshooting.	
	Code	Desc	scription		
	0	SIM	I card is not inserted		
	1	Cont	ntroller registered, waiting for authorization		
	2	Not p	t possible to register, controller blacklisted		
	3	Not p	t possible to register, server has no more capacity		
	4	Not p	t possible to register, other reason		
	5	Cont	ntroller registered and authorized		

O back to List of values

Connection Type

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24146	Related applications	MINT, SPtM	
Description				
The type of data connection.				

O back to List of values

Cell Diag Code

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24288	Related applications	MINT, SPtM	
Description				
Disgnastic and for the CM CDDS or CM 4C CDS module				

Diagnostic code for the CM-GPRS or CM-4G-GPS module.

GSM Diag Code – Common list of diagnostic codes for cellular modules

Code	Description
0	OK. No error.
1	Not possible to hang up.
2	Modul is switched off
3	Module is switched on



4	Module – error in initialization
5	Module – not possible to set the APN
6	Module – not possible to connect to GPRS network
7	Module – not possible to retrieve IP address
8	Module – not accepted DNS IP address
9	Error in modem detection
10	Error in initialization of analog modem
11	SIM card is locked (Possibly PIN code required, PIN needs to be deactivated) or unknown status of SIM locking
12	No GSM signal
13	Not possible to read the SIM card parameters
14	GSM modem did not accepted particular initialization command, possibly caused by locked SIM card
15	Unknown modem
16	Bad answer to complement initialization string
17	Not possible to read GSM signal strength
18	CDMA modem not detected
19	No CDMA network
20	Unsuccessful registration to CDMA network
21	SIMCom/ME909s: can't read FW version
22	SIMCom: GSM signal not found
23	SIMCom: can't detect module speed
24	SIMCom: HW reset issued
25	PUK is required
26	Error of SIM card detected
27	ME909s: can't set module bps
28	ME909s: can't set link configuration
29	ME909s: can't do power-off
30	ME909s: can't do power-on
31	ME909s: can't do hardware reset
32	ME909s: ME909s not started
33	ME909s: switch off issued
34	ME909s: switch on issued
35	ME909s: HW reset issued
36	ME909s: can't switch echo off
37	ME909s: can't find out state of registration
38	ME909s: GSM signal not found
39	ME909s: no SIM memory for SMS
40	ME909s: waiting for registration



41	Can't read operator name
42	ME909s: can't set flow control
43	APN not typed
255	Only running communication is needed to indicate

back to List of values

Cell ErrorRate

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	%			
Comm object	24300	Related applications	MINT, SPtM	
Description				

This value contains information about relative quality of the cellular signal received by the CM-GPRS module or by CM-4G-GPS module. The lower value means higher quality of signal.

back to List of values

Cell Signal Lev

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	%			
Comm object	24302	Related applications	MINT, SPtM	
Description				
This value contains information about relative strength of the cellular signal received by the CM-GPRS				

module or by CM-4G-GPS module. It is a relative value helping to find the best signal and for troubleshooting cases.

back to List of values

Cell Status

Value group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0	
Units	[-]			
Comm object	24290	Related applications	MINT, SPtM	
Description				
The text of this value represents the status of the GSM modem.				



Last Email Result

Val	ue group	IP CM-GPRS; CM-4G- GPS (4G part) Related FW 1.0.0			1.0.0	
Units [-]			[-]			
Со	Comm object 24307 Related applications MINT, SPtM			MINT, SPtM		
Des	scription					
Res	sult of last	email, v	which was sent by control	er.		
	Code	Desci	ription			
	0	Email	was successfully sent.			
	2	It is no	ot possible to establish co	nnection with SMTP serve	er.	
	3	SMTF	P server is not ready for co	mmunication.		
	4	Maxin	num length of data can't be	e read.		
	5	No ap	peal to send command.			
	6	Comn	nand can't be send.			
	7	Comn	nand can't be send.			
	8	HELC	command was refused.			
	11	AUTH	AUTH LOGIN command was refused.			
	12	Wrong user name.				
	13	Wrong	Wrong password.			
	14	MAIL	MAIL FROM command was refused.			
	15	RCPT TO command was refused.				
	16	DATA	command was refused.			
	17	Sendi	ng of email failed.			
	18	SMTF	server refused the data o	f email.		
	19	SMTF	server refused the data o	f email.		
	20	QUIT	command was refused.			
	21	Lost c	of connection.			
	23	Error	during closing the connect	ion.		
	24	No an	swer from server.			
	25	It is in	npossible to create data fo	r command DATA.		
	26	It is in	npossible to read data for o	command DATA.		
	28	Error	of encoding.			
	29	There was no attempt to send email.				



Operator

Va	ue group	CM-GPRS; CM-4G- GPS (4G part)	Related FW	1.0.0
Un	its	[-]		
Co	mm object	24147	Related applications	MINT, SPtM
Description				
The name of operator which to SIM card is connected.				
<i>Note:</i> If roaming service is used then prefix "R" is added before the name of operator.				

O back to List of values

Group: Date/Time

Time

Value group	Date/Time	Related FW	1.0.0	
Units	HH:MM:SS			
Comm object	24554	Related applications	MINT, SPtM	
Description				
Shows setup time.				

back to List of values

Date

Value group	Date/Time	Related FW	1.0.0	
Units	DD.MM.YYYY			
Comm object	24553	Related applications	MINT, SPtM	
Description				
Shows setup date.				

O back to List of values

Group: Plug-In I/O

EM BIO A

Value group	Plug-In I/O	Related FW	1.0.0	
Units	[-]			
Comm object	14291	Related applications	MINT, SPtM	
Description				
Binary inputs from extension module in slot A.				



EM BIO B

Value group	Plug-In I/O	Related FW	1.0.0		
Units	[-]				
Comm object	14292	Related applications	MINT, SPtM		
Description					
Binary inputs from extension module in slot B.					

back to List of values

Group: PLC

PLC Resource 1

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10504	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC Resource 2

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10505	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC Resource 3

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10506	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC Resource 4

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10507	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				



PLC Resource 5

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10508	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

back to List of values

PLC Resource 6

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10509	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC Resource 7

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10510	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC Resource 8

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10511	Related applications	MINT, SPtM	
Description				
Internal state of PLC countdowns (e.g. state of block Timer etc.).				

O back to List of values

PLC-BOUT 1

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10424	Related applications	MINT, SPtM	
Description				
State of binary outputs of PLC.				



PLC-BOUT 2

Value group	PLC	Related FW	1.0.0
Units	[-]		
Comm object	10425	Related applications	MINT, SPtM
Description			
State of binary outputs of PLC.			

back to List of values

PLC-BOUT 3

Value group	PLC	Related FW	1.0.0
Units	[-]		
Comm object	10426	Related applications	MINT, SPtM
Description			
State of binary outputs of PLC.			

O back to List of values

PLC-BOUT 4

Value group	PLC	Related FW	1.0.0
Units	[-]		
Comm object	10427	Related applications	MINT, SPtM
Description			
State of binary outputs of PLC.			

O back to List of values

PLC-BOUT 5

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10428	Related applications	MINT, SPtM	
Description				
State of binary outputs of PLC.				

O back to List of values

PLC-BOUT 6

Value group	PLC	Related FW	1.0.0
Units	[-]		
Comm object	10429	Related applications	MINT, SPtM
Description			
State of binary outputs of PLC.			



PLC-BOUT 7

Value group	PLC	Related FW	1.0.0	
Units	[-]			
Comm object	10430	Related applications	MINT, SPtM	
Description				
State of binary outputs of PLC.				
ComAp >

9.1.3 Logical binary inputs

What Logical binary inputs are:

Logical binary inputs are inputs for binary values and functions.

Alphabetical groups of Logical binary inputs

LBI: A	615
LBI: B	
LBI: C	
LBI: D	
LBI: E	
LBI: F	665
LBI: G	
LBI: H	
LBI: I	
LBI: L	670
LBI: M	671
LBI: N	
LBI: O	
LBI: R	
LBI: S	
LBI: T	

For full list of Logical binary inputs go to the chapter Logical binary inputs alphabetically (page 614).



Logical binary inputs alphabetically

Access Lock	615
Alternate Config 2	615
Alternate Config 3	615
AMF Start Block	615
Battery Charger	616
BIN Protection 1	616
BIN Protection 02	617
BIN Protection 03	618
BIN Protection 04	619
BIN Protection 05	620
BIN Protection 06	621
BIN Protection 07	622
BIN Protection 08	623
BIN Protection 09	624
BIN Protection 10	625
BIN Protection 11	626
BIN Protection 12	627
BIN Protection 13	628
BIN Protection 14	629
BIN Protection 15	630
BIN Protection 16	631
BIN Protection 17	632
BIN Protection 18	633
BIN Protection 19	634
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Mains Fail Block671
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Remote AUTO 675
Remote Ctrl Lock 675
Remote MAN675
Remote OFF676
Remote Start/Stop677
Remote TEST678
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Start Button680
Stop Button680
Top Priority 680



LBI: A

Access Lock

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1			
Description				
When this input is closed, no setpoints can be adjusted from controller's front panel and controller mode (OFF / MAN / AUTO / TEST) cannot be changed.				
Note: Access Lock does not protect setpoints and mode changing from InteliConfig. To avoid unqualified changes the selected setpoints have to be password protected.				
Also the buttons Fault Reset 🔼 and Horn Reset 陸 are not blocked at all and buttons Start 💶 and Stop				
o in MAN mode are not blocked.				

• back to Logical binary inputs alphabetically

Alternate Config 2

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	859			
Description				
This binary input can switch between configuration sets. When this binary input is active, setpoints in				
Alternate Config group are switched to the second set (setpoints with number 2).				

• back to Logical binary inputs alphabetically

Alternate Config 3

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	860			
Description				
This binary input can switch between configuration sets. When this binary input is active, setpoints in Alternate Config group are switched to the third set (setpoints with number 3).				

O back to Logical binary inputs alphabetically

AMF Start Block

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	211			
Description				
This binary input can allow or block the AMF start. In case of running gen-set in AUTO mode gen-set goes to cooling procedure and stops.				



LBI: B

Battery Charger

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	623			
Description				
When binary input is active and his delay Battery Charger Fail Delay (page 302) is out of time than alarm				

Battery Charger Fail (page 795) is activated, written into history log and logical binary output AL BATTERY CHARGER (PAGE 686) is activated.

O back to Logical binary inputs alphabetically

BIN Protection 1

Rel	ated FW	1.0.0 Related applications MINT, SPtM			
Со	Comm object 9999				
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only	
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	- Indic Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn Binary input is used for warning protection only.				
Stp Binary input is used for slow stop protection					
	BOC	Binary input is used for l	BOC (Breaker Open and C	cooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	t reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
BO Breaker open protection without reset. Protection is signalized with red LED but the alarm is not in alarm list.			is signalized with red LED status		
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list. Sensor fail protection.			
	FLS				



Rel	ated FW	1.0.0 Related applications MINT, SPtM				
Со	Comm object 9998					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.					
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is		
	AL Indic Binary input is not used for protection. Only alarmlist record is made if binary input is active.			ist record is made if binary input		
	Wrn	Binary input is used for	warning protection only.			
StpBinary input is used for slow stop protectionBOCBinary input is used for BOC (Breaker Open and Cooling) protection.						
			ooling) protection.			
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BOR	Breaker open protection with reset. Protection is signalized with red LED statusand alarm is recorded in alarm list.Sensor fail protection.				
	FLS					



Rel	ated FW	1.0.0 Related applications MINT, SPtM				
Со	Comm object 9997					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is		
AL Indic Binary input is not used for protection. Only alarmlist record is made if binary in is active.			ist record is made if binary input			
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
BOC Binary input is used for BOC (Brea			BOC (Breaker Open and C	cooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BORBreaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			ignalized with red LED status		
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Cor	Comm object 9996					
Des	cription					
This	binary input is fo	or general input function us	ed as alarm.			
l	Protection ty	pes				
Monitoring Binary input is not used for protection or any other function. Signal is of monitored.			function. Signal is only			
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is		
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input		
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for	slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	cooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm		
	ВО	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
BORBreaker open protection with reset. Protection is sigand alarm is recorded in alarm list.			ignalized with red LED status			
	FLS	Sensor fail protection.				



Related FW 1.0.0 Related applications MINT			MINT, SPtM			
Comm object 9995						
Des	scription					
Thi	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
Monitoring Binary input is not use monitored.			for protection or any other	function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for shutdown protection.				
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	MPR	Mains protection with re is recorded in alarm list.	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	BO	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
FLS Sensor fail protection.						



Related FW 1.0.0		1.0.0	Related applications	MINT, SPtM		
Со	Comm object 9994					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
Monitoring Binary input is not used for protection or any other function. Signal i monitored.			function. Signal is only			
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input		
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for	slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm		
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Co	mm object	9993				
Des	scription					
Thi	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
Monitoring Binary input is no monitored.			for protection or any other	function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	Binary input is used for shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm		
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
FLS Sensor fail protection.						



Related FW1.0.0Related applicationsMINT, SPtM			MINT, SPtM			
Comm object 9992						
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
Monitoring Binary input is not used for protection or any other monitored.			function. Signal is only			
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm		
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9991					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.		
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BORBreaker open protection with reset. Protectionand alarm is recorded in alarm list.		with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.			



Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Comm object 9990					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
FLS Sensor fail protection.					



Related FW 1.0.0 Related applications MINT, SPtM		MINT, SPtM				
Comm object 9989						
Des	scription					
Thi	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
Monitoring Binary input is not used for protection or any other furmonitored.			function. Signal is only			
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for shutdown protection.				
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	MPR	Mains protection with re is recorded in alarm list.	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	BO	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	BOR	Breaker open protection and alarm is recorded in	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.				



Rel	ated FW	1.0.0	Related applications	MINT, SPtM		
Со	mm object	9988				
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
Monitoring Binary input is not used for protection or any other monitored.			for protection or any other	function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm		
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW 1.0.0			Related applications	MINT, SPtM	
Comm object 9987					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.0.0 Related applications MINT, SPtM			MINT, SPtM		
Со	Comm object 9986				
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	r BOC (Breaker Open and Cooling) protection.		
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
	BOR	Breaker open protection and alarm is recorded in	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.		
	FLS	Sensor fail protection.			



Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Со	mm object	9985			
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for prote monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9984					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for prot monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Related FW1.0.0Related applicationsMINT, SPtM			MINT, SPtM		
Comm object 9983					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function. Signal is monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for	warning protection only.		
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Related FW 1.0		1.0.0	Related applications	MINT, SPtM	
Со	mm object	9982			
Des	scription				
Thi	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function. S monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.0.0		1.0.0	Related applications	MINT, SPtM	
Comm object 9981					
Des	scription				
Thi	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function. Signal monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9980					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for prote monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	во	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
BOR Breaker open protection with reset. Protection and alarm is recorded in alarm list.		with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9979					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BOR Breaker open protection with reset. Protection and alarm is recorded in alarm list.		with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9978					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any oth monitored.			for protection or any other	function. Signal is only	
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BORBreaker open protection with reset. Pro and alarm is recorded in alarm list.		with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9977					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other fund monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BORBreaker open protection with reset. Protection is signalized with red and alarm is recorded in alarm list.		ignalized with red LED status			
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Cor	nm object	9976			
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	ВО	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.		1.0.0	Related applications	MINT, SPtM	
Со	mm object	9975			
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection ty	pes			
Monitoring Binary input is not used for protection or any other function. S monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM	
Comm object 9974					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. S monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.0.		1.0.0	Related applications	MINT, SPtM	
Comm object 9973					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW		1.0.0	Related applications	MINT, SPtM		
Cor	nm object	9972				
Des	Description					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	ВО	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object		9971				
Des	Description					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for shutdown protection.				
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	ВО	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object		9970				
Des	Description					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	ВО	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object		9969				
Des	Description					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	ВО	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object		9968				
Des	Description					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	ВО	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object		9967				
Des	scription					
This	This binary input is for general input function used as alarm.					
Protection types						
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.				
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.				
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	BO	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				


Related FW 1.0.0 Related applications MINT, SPtM		MINT, SPtM			
Со	Comm object 9966				
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
	Monitoring	ring Binary input is not used for protection or any other function. Signal is only monitored.			
	HistRecOnl	Binary input is not used active.	for protection. Only history	y record is made if binary input is	
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wm	Binary input is used for	warning protection only.		
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	BOC (Breaker Open and C	cooling) protection.	
	Sd	Binary input is used for shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	alized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.0.0 Related applications MINT, SPtM			MINT, SPtM		
Comm object 9965					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only	
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wm	Binary input is used for	input is used for warning protection only.		
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Comm object 9964					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only	
HistRecOnl Binary input is not used for protection. Only history record is made if bi active.			/ record is made if binary input is		
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wrn	Binary input is used for	warning protection only.		
	Stp	Binary input is used for	slow stop protection		
	BOC	Binary input is used for	Binary input is used for BOC (Breaker Open and Cooling) protection.		
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	t reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	ВО	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BOR Breaker open protection with reset. Protection is si and alarm is recorded in alarm list.		ignalized with red LED status			
	FLS	Sensor fail protection.			



Rel	ated FW	1.0.0	Related applications	MINT, SPtM		
Со	Comm object 9963					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	y record is made if binary input is		
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input		
	Wrn	Binary input is used for	warning protection only.			
	Stp	Binary input is used for	slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	Cooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	alized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm		
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
BORBreaker open protection with reset. Protection is signalized and alarm is recorded in alarm list.		ignalized with red LED status				
	FLS	Sensor fail protection.				



Related FW		1.0.0	Related applications	MINT, SPtM		
Cor	nm object					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only			
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is		
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input		
	Wrn	Binary input is used for warning protection only.				
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.				
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection withou alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm		
	ВО	Breaker open protection but the alarm is not in al	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.			
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status		
	FLS	Sensor fail protection.				



Rel	ated FW	1.0.0	Related applications	MINT, SPtM		
Comm object 9961						
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection types					
	Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is		
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input		
	Wrn	Binary input is used for	warning protection only.			
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.		
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm		
	ВО	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status		
BOR Breaker open protection with reset. Protection is signalized and alarm is recorded in alarm list.		ignalized with red LED status				
	FLS	Sensor fail protection.				



Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Comm object 9960					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
	Monitoring	nitoring Binary input is not used for protection or any other function. Signal is only monitored.			
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wm	Binary input is used for	warning protection only.		
	Stp	Binary input is used for	slow stop protection	top protection	
	BOC	Binary input is used for	Binary input is used for BOC (Breaker Open and Cooling) protection.		
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection and alarm is recorded in	with reset. Protection is s alarm list.	ignalized with red LED status	
	FLS	Sensor fail protection.			



Related FW 1.0.0 Related applications MINT, SPtM			MINT, SPtM		
Comm object 9959					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wm	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for	BOC (Breaker Open and C	cooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.		
	MPR	Mains protection with re is recorded in alarm list.	set. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Comm object 9958					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
	Monitoring	onitoring Binary input is not used for protection or any other function. Signal is only monitored.			
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wrn	Binary input is used for	warning protection only.		
	Stp	Binary input is used for	slow stop protection	op protection	
	BOC	Binary input is used for	BOC (Breaker Open and C	ooling) protection.	
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
BOR Breaker open protection with reset. Protection is s and alarm is recorded in alarm list.		ignalized with red LED status			
	FLS	Sensor fail protection.			



Related FW 1.0.0 Related applications MINT, SPtM		MINT, SPtM			
Comm object 9957					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input	
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	во	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Related FW 1.0.0 Related applications MINT, SPtM			MINT, SPtM		
Comm object 9956					
Des	scription				
This	s binary input is fo	or general input function us	ed as alarm.		
	Protection types				
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only		
	HistRecOnl	Binary input is not used active.	for protection. Only history	/ record is made if binary input is	
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.			
	Wrn	Binary input is used for warning protection only.			
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for	shutdown protection.		
	MP	Mains protection withou alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the	
	MPR	Mains protection with re is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm	
	BO	Breaker open protection but the alarm is not in al	without reset. Protection arm list.	is signalized with red LED status	
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.			
	FLS	Sensor fail protection.			



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9955		
Description			
This binary input is	for general input function us	ed as alarm.	
Protection	ypes		
Monitoring Binary input is not used for protection or any other function. Signal is only monitored.			function. Signal is only
HistRecOnl	Binary input is not used active.	for protection. Only history	y record is made if binary input is
AL Indic	Binary input is not used is active.	for protection. Only alarml	ist record is made if binary input
Wm	Binary input is used for	warning protection only.	
Stp	Binary input is used for	slow stop protection	
BOC	Binary input is used for	BOC (Breaker Open and C	cooling) protection.
Sd	Binary input is used for	shutdown protection.	
MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	alized with red LED status but the
MPR	Mains protection with realist is recorded in alarm list.	eset. Protection is signalize	ed with red LED status and alarm
BO Breaker open protection without reset. Protection is signalized with red LED but the alarm is not in alarm list. BOR Breaker open protection with reset. Protection is signalized with red LED state and alarm is recorded in alarm list.		without reset. Protection arm list.	is signalized with red LED status
		ignalized with red LED status	
FLS	Sensor fail protection.		



Related FW		1.0.0	Related applications	MINT, SPtM		
Comm object	Comm object 9954					
Description	Description					
This binary inpu	ıt is fo	r general input function us	ed as alarm.			
Protectio	n ty	pes				
Monitoring		Binary input is not used monitored.	for protection or any other	function. Signal is only		
HistRecOr	าไ	Binary input is not used active.	Binary input is not used for protection. Only history record is made if binary input is active.			
AL Indic		Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
Wrn		Binary input is used for	warning protection only.			
Stp		Binary input is used for slow stop protection				
BOC		Binary input is used for BOC (Breaker Open and Cooling) protection.				
Sd		Binary input is used for	shutdown protection.			
MP		Mains protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
MPR		Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
BO		Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
BOR		Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
FLS		Sensor fail protection.				



Rel	ated FW	1.0.0	Related applications	MINT, SPtM		
Со	Comm object 9953					
Des	scription					
This	s binary input is fo	or general input function us	ed as alarm.			
	Protection ty	pes				
	Monitoring	Binary input is not used monitored.	for protection or any other	function. Signal is only		
	HistRecOnl	Binary input is not used active.	Binary input is not used for protection. Only history record is made if binary input is active.			
	AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.				
	Wm	Binary input is used for	warning protection only.			
	Stp	Binary input is used for slow stop protection				
	BOC	Binary input is used for	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for	shutdown protection.			
	MP	Mains protection without alarm is not in alarm list	t reset. Protection is signa	lized with red LED status but the		
	MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	во	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.				
	BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.				
	FLS	Sensor fail protection.				



Related FW	1.0.0	Related applications	MINT, SPtM			
Comm object	Comm object 9952					
Description	Description					
This binary input is fo	or general input function us	ed as alarm.				
Protection ty	pes					
Monitoring	Binary input is not used monitored.	for protection or any other	function. Signal is only			
HistRecOnl	Binary input is not used active.	Binary input is not used for protection. Only history record is made if binary input is active.				
AL Indic	Binary input is not used for protection. Only alarmlist record is made if binary input is active.					
Wm	Binary input is used for warning protection only.					
Stp	Binary input is used for	slow stop protection				
BOC	Binary input is used for	BOC (Breaker Open and C	cooling) protection.			
Sd	Binary input is used for	shutdown protection.				
MP	Mains protection without alarm is not in alarm list	it reset. Protection is signa	lized with red LED status but the			
MPR	Mains protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.					
во	Breaker open protection without reset. Protection is signalized with red LED status but the alarm is not in alarm list.					
BOR	Breaker open protection with reset. Protection is signalized with red LED status and alarm is recorded in alarm list.					
FLS	Sensor fail protection.					



LBI: C

Coolant Temp

Rel	ated FW	1.0.0	Related applications	MINT, SPtM	
Comm object 625					
Des	scription				
Bin	ary input for Cool	ANT TEMP (PAGE 771) pro	tection.		
	Protection ty	pes			
	Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.			
	HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.			
	Wm	Binary input is used for v	warning protection only.		
	Stp	Binary input is used for slow stop protection			
	BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.			
	Sd	Binary input is used for s	shutdown protection.		

O back to Logical binary inputs alphabetically

LBI: D

Droop Unload Disl

Related FW	1.0.0	Related applications	MINT		
Comm object	597				
Description					
Activation of this logical binary input avoids the soft unload function of the gen-set if it is running in droop. GCB is opened immediately after the stop request or pressing of GCB button. If this input is not active the unloading is given by the setpoint Load Ramp (page 353) .					
Notes This funct	ion io wood whon the rolin r	a athan war a at to take ave	with a load of the way act which is		

Note: This function is used when there is no other gen-set to take over the load of the gen-set which is being unloaded.



LBI: E

Emergency MAN

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	45		
Description			

This input is designed to allow the gen-set or breakers to be controlled externally, not by the controller. This feature can be useful in case of or in case of some failure, which disables the gen-set or breakers to be controlled by the controller, but the gen-set itself is operational.

The controller behaves in the following way:

- Shows the text EmergMan in the engine status on the main screen.
- Stops all functions regarding the gen-set or breaker control, deactivates all outputs related to it.
- Stop Fail alarm is not being evaluated and stop solenoid is not activated if nonzero speed is detected.
- When the input is deactivated, the controller takes control according to the situation in the moment of deactivation, i.e. the gen-set remains running loaded if it was running and GCB was closed in the moment the input was deactivated.

back to Logical binary inputs alphabetically

Emergency Stop

Related FW	1.0.0	Related applications	MINT, SPtM			
Comm object	40					
Description						
When this binary input is activated, gen-set is immediately stopped. Also binary outputs are disconnected.						
Alarm Emergency Stop (page 820) is activated.						

back to Logical binary inputs alphabetically

LBI: F

Fault Reset Button

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	191				
Description					
Binary input has the same function as Fault Reset button 🔼 on the InteliGen 500 front panel.					

O back to Logical binary inputs alphabetically

Force Droop Oper

Related FW	1.0.0	Related applications	MINT		
Comm object	788				
Description					
When this logical binary input is active, the regulations is forced to droop (the same behavior like the setpoint					
Load/Var Sharing Regulation Type (page 361) = Droop.					



Force Island

Related FW	1.0.0	Related applications	SPtM
Comm object	787		
Description			

Activation of this logical binary input start the gen-set and go to island operation. Transition of load from mains is adjusted via setpoint **Transfer Mains To Gen Bus (page 351)**.

back to Logical binary inputs alphabetically

Force Parallel

Related FW	1.0.0	Related applications	MINT, SPtM			
Comm object	786					
Description						

Activation of this logical binary input start the gen-set system and go to parallel operation if mains is healthy. Island operation is not allowed.

O back to Logical binary inputs alphabetically

Force Protection Disable

Related FW	1.0.0	Related applications	MINT, SPtM			
Comm object	920					
Description	Description					
Selected protections are disabled, if LBI: Force Protection Disable is active						
Activation and deactivation of this binary input will create history record:						
Force Protection Disable active						
Force Protection Disable inactive						
Behaviour depends on configuration of LBI - normally close or normally open.						



Fuel Level

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	626		

Description

Binary input for FUEL LEVEL (PAGE 772) protection.

Protection types

Monitoring	Binary input is not used for protection or any other function. Signal is only monitored.
HistRecOnl	Binary input is not used for protection. Only history record is made if binary input is active.
Wrn	Binary input is used for warning protection only.
Stp	Binary input is used for slow stop protection
BOC	Binary input is used for BOC (Breaker Open and Cooling) protection.
Sd	Binary input is used for shutdown protection.

• back to Logical binary inputs alphabetically

Fuel Pump On/Off

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	694		
Description			

Description

This binary input is used for manual control of binary output FUEL PUMP (PAGE 715).

Note: This binary input is basically designed for ON and OFF switch (switch with arrestment in these positions) because controller reacts to rising and falling edge of signal in this input.

IMPORTANT: When binary input FUEL PUMP ON/OFF (PAGE 667) is configured then binary output FUEL PUMP (PAGE 715) is control by this binary input. Setpoints Fuel Pump On (page 299) and Fuel Pump Off (page 300) are not evaluated!

IMPORTANT: It is necessary to configure analog input FUEL LEVEL (PAGE 772) for proper function of this binary input.

O back to Logical binary inputs alphabetically

LBI: G

GCB Button

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	193		
Description			
Binary input has the MAN mode only.	same function as GCB but	ton $1/0$ on the InteliGen 50	0 front panel. It is evaluated in



GCB Feedback



O back to Logical binary inputs alphabetically

Geo Home Position

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	219		
Description			
This binary input ca Home Latitude (p coordinates from G	n be used to adjust home pa age 446) and Home Longit PS signal.	osition of gen-set. In case t t ude (page 446) are adjust	that binary input is active, setpoints ed automatically from actual
Note: Input has	to be activated for at least	2 seconds.	





Geo-Fencing Enabled

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	218			
Description				
This binary input enables or disables Fence 1 Protection (page 449) and Fence 2 Protection (page 450) if				
Geo-Fencing (page 448) is adjusted to value "LBI Enable".				

back to Logical binary inputs alphabetically

Group link

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	59		

Description

This input is used for logical connection and disconnection of two gen-set groups selected with setpoints **Group Link L (page 344)** and **Group Link R (page 345)**. If the input is active, then the two selected groups will perform power management, load sharing and kVAr sharing together as one large group.

Note: This function is independent on the group which the particular controller belongs to, i.e. the controller can provide linking function e.g. for groups 3,4 although it belongs to group 2.

O back to Logical binary inputs alphabetically

LBI: H

Horn Reset Button

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	192			
Description				
Binary input has the same function as Horn reset 陸 button on the InteliGen 500 front panel.				

O back to Logical binary inputs alphabetically

LBI: I

Idle Speed

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	624			
Description				
This binary input changes cooling speed from nominal to idle.				



LBI: L

Lang Selection 1

Comm object 107	Related FW	1.0.0	Related applications	MINT, SPtM
	Comm object	107		
Description	Description			

Use this binary input with binary input LANG SELECTION 2 (PAGE 670) to choose required language of controller. The system is based on binary numbers.

Binary input	Binary number	Active language
Language Selection 1 is active	1	First language (English)
LANG SELECTION 2 (PAGE 670) is active	2	Second language
Language Selection 1 and LANG SELECTION 2 (PAGE 670) are active	3	Third language

• back to Logical binary inputs alphabetically

Lang Selection 2

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	108		

Description

Use this binary input with binary input LANG SELECTION 1 (PAGE 670) to choose required language of controller. The system is based on binary numbers.

Binary input	Binary number	Active language
LANG SELECTION 1 (PAGE 670) is active	1	First language (English)
Lang Selection 2 is active	2	Second language
LANG SELECTION 1 (PAGE 670) and Lang Selection 2 are active	3	Third language

O back to Logical binary inputs alphabetically

Load Res 2 Active

Related FW	1.0.0	Related applications	MINT	
Comm object	49			
Description				
Activation of this logical binary input changes the set of load reserve setpoint, which are used in Power management (page 79) . This input is used to activate the load reserve set 2 instead of the set 1, which is				

active by default.



LBI: M

Mains Fail Block

the MCB is closed.

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	622			
Description				
If the input is closed, the automatic start of the gen-set at Mains failure is blocked. In case of running gen-set				
in AUTO mode, timer Mains Return Delay (page 319) is started and when it elapses GCB is opened, gen-				
set goes to cooling procedure and stops. When GCB is opened after Open Transfer Min Break (page 350)				

Note: This input simulates healthy Mains.

O back to Logical binary inputs alphabetically

Manual Load Reconnection

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	60			
Description				
This input is used for	manual reconnection of th	e last disconnected part of	f the load, if the load has dropped	
below the setpoint Load Reconnection Level (page 330). This works only if automatic reconnection is				
disabled, i.e. the setpoint Auto Load Reconnection (page 331) = Disabled.				

O back to Logical binary inputs alphabetically

MCB Button

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	194			
Description				
This binary input has the same function as MCB button $1/0$ on the InteliGen 500 front panel. It is evaluated in MAN mode only.				



MCB Feedback



O back to Logical binary inputs alphabetically



Min Run Power Active

Related FW	1.0.0	Related applications	MINT	
Comm object	52			
Description				
This input is used to activate the function minimal running power, which is adjusted via setpoint #Min Run Power (page 339) .				

O back to Logical binary inputs alphabetically

LBI: N

NCB Feedback

Related FW	1.0.0	Related applications	MINT
Comm object	67		
Description			
This input is used for connection of feedback contact from the neutral contactor. If the input is active, the controller will consider the neutral contactor as closed and vice versa. See also setpoint #Neutral Contactor Control (page 237) .			

Source to Logical binary inputs alphabetically

Not Used

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	184			
Description				
Binary input has no function. Use this configuration when binary input is not used.				



LBI: O

Oil Pressure

Re	lated FW	1.0.0	Related applications	MINT, SPtM
Comm object 43				
De	scription			
Bir	ary input for OIL F	PRESSURE (PAGE 774) prot	ection.	
Protection types				
Monitoring Binary input is not used for protection or any other function. Signal monitored.			function. Signal is only	
HistRecOnl Binary input is not used for protection. Only history record is made if binary input is active.			/ record is made if binary input is	
	Wrn Binary input is used for warning protection only.			
	Sd Binary input is used for shutdown protection.			

IMPORTANT: This binary input is also used for evaluating engine running condition.

Example: Normally close connection - when LBI is closed then oil pressure is OK and is higher than starting oil pressure.

Note: In case that you want to use binary input of oil pressure sensor just for protection please use one of the **BIN PROTECTION 1** (PAGE 616).

O back to Logical binary inputs alphabetically

LBI: R

Regeneration Force

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	680			
Description				
When this binary input is activated, the controller send request for force regeneration of DPF (diesel particulate filter) to ECU.				
Note: ECU with Tier IV support is required for proper functionality.				

back to Logical binary inputs alphabetically

Regeneration Inhib

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	679				
Description	Description				
When this binary input is activated, the controller sends request to inhibit regeneration of DPF (diesel particulate filter) to ECU.					
Note: ECU with Tier IV support is required for proper functionality.					



Remote AUTO

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	620				
Description					
The controller is switched to the AUTO mode (there are four modes OFF / MAN / AUTO / TEST) when this binary input is closed. When opens controller is switched back to previous mode.					
This binary input has	the lowest priority from Re	emote OFF / MAN / AUTO	/ TEST binary inputs		
Remote control p	priority:				
Remote OFF	(Highest priority)				
Remote TEST					
Remote MAN					
Remote AUT	Remote AUTO (Lowest Priority)				

• back to Logical binary inputs alphabetically

Remote Ctrl Lock

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	4		
Description			
If the input is active, the controller will not accept any actions regarding the system control – e.g. writing of commands and setpoint changes via remote communication interfaces.			

O back to Logical binary inputs alphabetically

Remote MAN

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	618		
Description			
The controller is switched to the MAN mode (there are four modes OFF / MAN / AUTO / TEST) when this binary input is closed. When opens controller is switched back to previous mode.			
Remote control priority:			
Remote OFF (Highest priority)			

- Remote TEST
- Remote MAN
- Remote AUTO (Lowest Priority)



Remote OFF

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	617		
Description			
The controller is switched to the OFF mode (there are four modes OFF / MAN / AUTO / TEST) when this binary input is closed. When opens controller is switched back to previous mode.			
Remote control priority:			
Remote OFF (Highest priority)			
Remote TEST			
Remote MAN			
Remote AUT	O (Lowest Priority)		



Remote Start/Stop

Rel	Plated FW 1.0.0 Related applications MINT, SPtM		MINT, SPtM		
Cor	omm object 38				
Des	scription				
Jse	e this input to star	t and stop the gen-set in A	UTO mode and TEST mod	le.	
	Taken action ir	SPtM application (AUT	O Mode)		
	Activo	Start genset, synchroni Regardless the Mains p	zation, parallel operation (t params OK.	paseload/Imp/Exp),	
	Active	Start the genster	to Island if Mains Not OK		
		Reverse synchro	onisation when mains gets	restored	
	Inactive	Unloading of the ger	nset if it is running in parall	el, stop the genset.	
	Taken action in	MINT application (AUT	O Mode)		
	Active	Start the Genset - After using the existing Remo visible in any applicatio	Start the Genset - After Powermanagement/ #System Start Delay (Actually is using the existing REMOTE START/STOP (PAGE 677) internaly (this LBI is not visible in any application)).		
	Inactive	Stop the Genset - After Powermanagement/ #System Stop Delay (Actually is using the existing LBI REMOTE START/STOP (PAGE 677) internaly (this LBI is not visible in any application)).			
	Taken action in AMF application (AUTO Mode)				
		Start the genset	and stay running with oper	ned GCB if Mains OK.	
	Active	Go to Island if Mains fails (due to AMF function).			
		If Mains is not O	K the AMF function starts	the genset to Island anyway.	
	Inactivo	Stop the genset	if Mains is OK.		
	mactive	If Mains not Ok t	he genset stays running d	ue to AMF function anyway.	
	Taken action in	MRS application (AUT	O Mode)		
	A	Start the Genset	- No delay		
	Active Close GCB				
		Open GCB			
	► Stop the G		- No delay		
	Note: In the SPT application and c	M and AMF application the	ere are more LBIs that can he Common I BI Remote S	influence the state of the Start/Stop	

-



Remote TEST

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	621			
Description				
The controller is switched to the TEST mode (there are four modes OFF / MAN / AUTO / TEST) when this binary input is closed. When opens controller is switched back to previous mode.				
Remote control p	Remote control priority:			
Remote OFF	Remote OFF (Highest priority)			
Remote TES ⁻	Remote TEST			
Remote MAN				
Remote AUT	O (Lowest Priority)			



Remote Test On Load

Related FW 1.0.0		Related applications	MINT, SPtM			
Comm object 61						
Des	Description					
Clo	sing of the GCE	3 in MRS and MINT or t	ranst	ferring of the load from the	mains to genset in SPTM and AMF	
	Application	TEST	Rer	note TEST On Load		
SF			Act is tr FOF set	ive: Gen-set is put to TES ransfered to the genset. Th RCE ISLAND (PAGE 666). Th tings is performed.	T mode. On the top of it the load e same behaviour like the LBI ne load transfer according to the	
	SPtM			Note: Whenever the LBI F is active, the LBI REMOTE higher priority because it ta FORCE ISLAND (PAGE 666	REMOTE START/STOP (PAGE 677) TEST ON LOAD (PAGE 679) has akes the same action like LBI)	
		Gen-set started and running until the TEST mode deactivated	Ina beh load on t	ctive: Gen-set comes back laves accordingly to this m d can be transfered back to he genset (MAN).	k to the original mode and ode and other conditions. (the the mains (OFF, AUTO) or stay	
	MRS		Act is c ST/	i ve: Gen-set is put to TES losed. The same behaviou ART/ S TOP (PAGE 677)	T mode. On the top of it the GCB r like the LBI Rемоте	
			Ina beh	ctive: Gen-set comes back aves accordingly to this m	to the original mode and other conditions.	
	MINT		Act is c The 677	ive: Gen-set is put to TES losed (synchronized if the same behaviour like the L).	T mode. On the top of it the GCB common bus bar is not dead). BI Rемоте Start/Stop (РАGE	
			Ina beh	ctive: Gen-set comes back aves accordingly to this m	< to the original mode and ode and other conditions.	
	AMF		Act is tr FOF	ive: Gen-set is put to TES ansfered to the genset. Th RCE ISLAND (PAGE 666) . Th formed.	T mode. On the top of it the load e same behaviour like the LBI ne open load transfer is	
		lı b la	Ina beh load on t	ctive: Genset comes back aves accordingly to this m d can be transfered back to he genset (MAN).	to the original mode and ode and other conditions. (the the mains (OFF, AUTO) or stay	



LBI: S

Sd Override

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	44		
Description			
If this input is active, all alarms except Emergency Stop and Overspeed are suppressed. The suppressed			

alarms will be displayed in the alarm list, but they will not take effect regarding the gen-set control.

Note: Sd Override (page 680) is indicated in the alarm list if Sd Override mode is active to inform the operator that the engine is not protected.

IMPORTANT: MISUSE OF THIS INPUT CAN CAUSE DAMAGE TO THE GEN-SET!

• back to Logical binary inputs alphabetically

Start Button

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	189		
Description			
Binary input has the same function as Start Button 🛄 on the InteliGen 500 front panel. It is evaluated in MAN mode only.			

O back to Logical binary inputs alphabetically

Stop Button

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	190		
Description			
Binary input has the same function as Stop Button on the InteliGen 500 front panel. It is evaluated in MAN Mode only.			

O back to Logical binary inputs alphabetically

LBI: T

Top Priority

Related FW	1.0.0	Related applications	MINT
Comm object	199		
Description			
If this input is active, Priority (page 333) .	the controller will have the	highest priority in the grou	ip independent of the setpoint

ComAp >

9.1.4 Logical binary outputs

What Logical binary outputs are:

Logical binary outputs are outputs for binary values and functions.

Alphabetical groups of Logical binary outputs

LBO: A	684
LBO: B	
LBO: C	710
LBO: D	711
LBO: E	711
LBO: F	
LBO: G	716
LBO: H	722
LBO: I	
LBO: L	725
LBO: M	725
LBO: N	730
LBO: P	731
LBO: R	734
LBO: S	735
LBO: T	

For full list of Logical binary outputs go to the chapter Logical binary outputs alphabetically (page 682).



Logical binary outputs alphabetically

Air Valves	.684
AL AIN 1 Sd+BOC	.684
ALAIN 1 Wm	.684
AL AIN 2 Sd+BOC	.685
AL AIN 2 Wrn	.685
AL AIN 3 Sd+BOC	.685
AL AIN 3 Wrn	.685
AL AIN 4 Sd+BOC	.685
AL AIN 4 Wrn	.686
AL Battery Flat	686
AL Battery Charger	.686
AL Battery Voltage	.686
AL Common BOC	.686
AL Common Fls	.687
AL Common SdMPR	687
AL Common Stp	.687
AL Common Wrn	.687
AL CoolantTemp Low	.688
AL CoolantTemp Sd	688
AL CoolantTemp Wrn	.688
AL D+ Fail	688
AL Earth Fault	688
AL Fence 1	.689
AL Fence 2	.689
AL Fuel Level Sd	689
AL Fuel Level Wrn	.689
AL Gen Freq Wrn	.689
AL GenBus Frequency	.690
AL Gen Overfrequency	690
AL Gen Overvoltage	690
AL Gen Underfrequency	.690
AL Gen Undervoltage	.690
AL Gen Voltage Wrn	691
AL GenBus Voltage	.691
AL Mains Fail	.691
AL Mains Frequency	.691
AL Mains Voltage	691

AL Maintenance 1	.692
AL Maintenance 2	.692
AL Maintenance 3	.692
AL Oil Press Sd	692
AL Oil Press Wrn	.692
AL Overcurrent	. 693
AL Overload BOC	.693
AL Overload Wrn	.693
AL Overspeed	. 693
AL Rental Timer 1	.694
AL Rental Timer 2	.694
AL Start Fail	695
AL Stop Fail	.695
AL Underspeed	.695
Alarm	.695
AIN Switch01	.696
AIN Switch02	.696
AIN Switch03	.697
AIN Switch04	.697
AIN Switch05	.698
AIN Switch06	.698
AIN Switch07	.699
AIN Switch08	.699
AIN Switch09	.700
AIN Switch10	.700
AIN Switch11	.701
AIN Switch12	.701
AIN Switch13	.702
AIN Switch14	.702
AIN Switch15	.703
AIN Switch16	.703
AIN Switch17	.704
AIN Switch18	.704
AIN Switch19	.705
AIN Switch20	.705
AVR Down	.706
AVR Up	.706

BIN 1 Status	.706
BIN 2 Status	.707
BIN 3 Status	.707
BIN 4 Status	.708
BIN 5 Status	.708
BIN 6 Status	.709
BIN 7 Status	.709
BIN 8 Status	.710
Cooling Pump	710
Cooling	.711
Display Fail	.711
ECU Communic Error	. 711
ECU Communic OK	.711
ECU Power Relay	. 712
ECU Red Lamp	. 712
ECU Run Stop	. 713
ECU Wait To Start	.713
ECU Yellow Lamp	. 713
Exercise Timer 1	. 713
Exercise Timer 2	.714
FltRes	.714
Frequency Select	. 714
Fuel Pump	.715
Fuel Solenoid	.715
GCB Close/Open	. 716
GCB OFF Coil	.717
GCB ON Coil	.718
GCB UV Coil	.718
GeneratorBus Healthy	.720
Glow Plugs	720
Heartbeat	. 722
HEST Lamp	722
Horn	.722
Idle/Nominal	.723
Ignition	723
Ignition On	.724
Load Shedding Stage 1	.725



Load Shedding Stage 2 725
Load Shedding Stage 3 725
Mains Healthy725
Manual Ready726
MCB Close/Open726
MCB OFF Coil727
MCB ON Coil728
MCB UV Coil729
Mode AUTO730
Mode MAN730
Mode OFF730
Mode TEST730
NCB Close/Open730
Not In AUTO731
Not Used731
Peak Shaving Active731
Power Switch732
Prestart732
Ready To AMF734
Ready To Load734
Ready734
RegenerationNeededRegen
Needed735
Running735
Sd Override735
Speed Down736
Speed Up736
Starter737
Still Log 0737
Still Log 1737
Stop Pulse738
Stop Solenoid738
Supplying Load739
System Reserve OK739
Temperature Switch 740



LBO: A

Air Valves

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1247		
– • •			

Description

This output closes together with binary output **PRESTART (PAGE 732)** and opens after the engine is stopped or in case that engine is not ready.



O back to Logical binary outputs alphabetically

AL AIN 1 Sd+BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 1386				
Description				
The output is closed when there is the shutdown or BOC alarm from the analog input 1 of the controller present in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL AIN 1 Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 1382				
Description				
The output is closed when there is the warning alarm from the analog input 1 of the controller present in the alarmlist or isn't confirmed.				


AL AIN 2 Sd+BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1387			
Description				
The output is closed when there is the shutdown or BOC alarm from the analog input 2 of the controller present in the alarmlist or isn't confirmed.				

• back to Logical binary outputs alphabetically

AL AIN 2 Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1383			
Description				
The output is closed when there is the warning alarm from the analog input 2 of the controller present in the				

alarmlist or isn't confirmed.

• back to Logical binary outputs alphabetically

AL AIN 3 Sd+BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1388			
Description				
The output is closed when there is the shutdown or BOC alarm from the analog input 3 of the controller present in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL AIN 3 Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1384			
Description				
The output is closed when there is the warning alarm from the analog input 3 of the controller present in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL AIN 4 Sd+BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1389			
Description				
The output is closed when there is the shutdown or BOC alarm from the analog input 4 of the controller present in the alarmlist or isn't confirmed.				



AL AIN 4 Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1385			
Description				
The output is closed when there is the warning alarm from the analog input 4 of the controller present in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL Battery Flat

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1292			
Description				
This output is active when the Sd Battery Flat (page 821) or Wrn Battery < Voltage (page 801)Wrn				
Battery Voltage (page 795) alarm is present in the alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL Battery Charger

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1272			
Description				
This output is active when the Battery Charger Fail (page 795) alarm is present in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL Battery Voltage

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1293			
Description				
This output is active when the Wrn Battery Voltage (page 795)Wrn Battery > Voltage (page 800) or Wrn Battery < Voltage (page 801) alarm is present in the alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Common BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	9			
Description				
Output closes when any BOC alarm appears.				
The output opens, if:				
No BOC alarm is active and				
Fault reset button is pressed				



AL Common Fls

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	6			
Description				
Output closes w	hen any sensor fail alarm appears	S.		
The output opens, if:				
No sensor fail alarm is active and				
Fault reset button is pressed				

AL Common SdMPR

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	4			
Description				
Output closes w	hen any shutdown mains protect	ion with reset alarm appears.		
The output open	s, if:			
No shutdown mains protection with reset alarm is active and				
Fault reset button is pressed				

O back to Logical binary outputs alphabetically

AL Common Stp

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	5			
Description				
Output closes w	hen any slow stop alarm appears	i.		
The output opens	s, if:			
No slow stop alarm is active and				
Fault reset button is pressed				

O back to Logical binary outputs alphabetically

AL Common Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	3			
Description				
Output closes w	hen any warning alarm appears.			
The output opens, if:				
No warning alarm is active and				
Fault reset button is pressed				



AL CoolantTemp Low

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1295			
Description				
The output is closed when there is the Wrn Coolant Temperature Low (page 801) alarm from the				
COOLANT TEMP (PAGE 771) in the alarmlist or isn't confirmed.				

• Logical binary outputs alphabetically (page 682)

AL CoolantTemp Sd

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1421			
Description				
The output is closed when there is the chutdown or DOC close from the Cool AVE TEVE (24 or 774) in the				

The output is closed when there is the shutdown or BOC alarm from the **COOLANT TEMP (PAGE 771)** in the alarmlist or isn't confirmed.

• Logical binary outputs alphabetically (page 682)

AL CoolantTemp Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1420			
Description				
The output is closed when there is the warning alarm from the COOLANT TEMP (PAGE 771) in the alarmlist or isn't confirmed.				
Note: Binary output is also active if protection type is set to HistRecOnl and threshold level for history record is reach.				

O back to Logical binary outputs alphabetically

AL D+ Fail

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1260			
Description				
This output is active when the Wrn Charging Alternator Fail (page 800) alarm is present in the alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Earth Fault

Re	lated FW	1.0.0	Related applications	MINT, SPtM
Co	mm object	1294		
De	scription			
This output is active when the Sd Earth Fault Current (page 822) alarm is present in alarm list or isn't confirm.				
Note: It is strongly recommended to use this output only onetime.				



AL Fence 1

Related FW 1.0.0	Related applications	MINT, SPtM		
Comm object 1548	1548			
Description				
This output is active when the Wrn Fence 1 Alarm (page 802) or BOC Fence 1 Alarm (page 831) or Sd Fence 1 Alarm (page 823) (depends on configuration of alarm type) alarm is present in the alarmlist or isn't				

O back to Logical binary outputs alphabetically

AL Fence 2

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	1549				
Description					
This output is active when the Wrn Fence 2 Alarm (page 803) or BOC Fence 2 Alarm (page 832) or Sd					
confirm.					

O back to Logical binary outputs alphabetically

AL Fuel Level Sd

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	t 1423			
Description				
The output is closed when there is the shutdown or BOC alarm from the FUEL LEVEL (PAGE 772) in the alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL Fuel Level Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1422			
Description				
The output is closed when there is the warning alarm from the FUEL LEVEL (PAGE 772) in the alarmlist or isn't confirmed.				

Note: Binary output is also active if protection type is set to HistRecOnl and threshold level for history record is reach.

O back to Logical binary outputs alphabetically

AL Gen Freq Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1267			
Description				
This output is active generator frequency warning alarm is present in alarmlist or isn't confirm.				



AL GenBus Frequency

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1266			
Description				
This output is active when at least one generator frequency BOC or Sd alarm is present in alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL Gen Overfrequency

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1264			
Description				
This output is active when at least one generator overfrequency alarm is present in alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL Gen Overvoltage

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1261			
Description				
This output is active when at least one generator overvoltage alarm is present in alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Gen Underfrequency

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1265		
Description			
This output is active when at least one generator underfrequency alarm is present in alarmlist or isn't confirm.			

O back to Logical binary outputs alphabetically

AL Gen Undervoltage

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1262			
Description				
This output is active when at least one generator undervoltage alarm is present in alarmlist or isn't confirm.				



AL Gen Voltage Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	:t 1289			
Description				
This output is active when at least one generator voltage warning alarm is present in alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL GenBus Voltage

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	t 1263			
Description				
This output is active when at least one generator voltage BOC or Sd alarm is present in alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Mains Fail

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	197			
Description				
Output for signaling Mains Failure. This output is active when at least one mains frequency BOC or Sd alarm or at least one mains voltage BOC or Sd alarm is present in alarmlist or isn't confirmed.				

O back to Logical binary outputs alphabetically

AL Mains Frequency

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1271			
Description				
This output is active when at least one mains frequency BOC or Sd alarm is present in alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Mains Voltage

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1270			
Description				
This output is active when at least one mains voltage BOC or Sd alarm is present in the alarmlist or isn't confirm.				



AL Maintenance 1

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1254			
Description				
This output is active when the Alarm Maintenance 1 is present in the alarmlist. It means that counter of				
maintenance is on zero or the Alarm Maintenance 1 isn't confirm.				

O back to Logical binary outputs alphabetically

AL Maintenance 2

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1255			
Description				
This output is active when the Alarm Maintenance 2 is present in the alarmlist. It means that counter of				
maintenance is on zero or the Alarm Maintenance 2 isn't confirm.				

O back to Logical binary outputs alphabetically

AL Maintenance 3

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1256			
Description				
This output is active when the Alarm Maintenance 3 is present in the alarmlist. It means that counter of maintenance is on zero or the Alarm Maintenance 3 isn't confirm.				

O back to Logical binary outputs alphabetically

AL Oil Press Sd

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1419			
Description				
The output is closed when there is the shutdown alarm from the OIL PRESSURE (PAGE 774) in the alarmlist or				
isn't confirmed.				

O back to Logical binary outputs alphabetically

AL Oil Press Wrn

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	1418				
Description					
The output is closed when there is the warning alarm from the OIL PRESSURE (PAGE 774) in the alarmlist or isn't confirmed.					
Note: Binary output is also active if protection type is set to HistRecOnl and threshold level for history record is reach.					



AL Overcurrent

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	109			
Description				
This output is active when the BOC Overcurrent IDMT (page 836) or BOC Short Circuit (page 837)				
alarm is present in alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL Overload BOC

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1268			
Description				
This output is active when the Sd Overload (page 828) alarm is present in the alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Overload Wrn

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1269			
Description				
This output is active when the Wrn Overload (page 810) alarm is present in alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Overspeed

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	779			
Description				
This output is active when the Sd Overspeed (page 829) alarm is present in the alarmlist or isn't confirm.				



AL Rental Timer 1



O back to Logical binary outputs alphabetically

AL Rental Timer 2





AL Start Fail

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1291			
Description				
This output is active when the Sd Start Fail (page 830) alarm is present in the alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

AL Stop Fail

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	339			
Description				
This output is active when the Wrn Stop Fail (page 811) alarm is present in the alarmlist or isn't confirm.				

• back to Logical binary outputs alphabetically

AL Underspeed

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1296			
Description				
This output is active when the Sd Underspeed (page 830) alarm is present in the alarmlist or isn't confirm.				

O back to Logical binary outputs alphabetically

Alarm

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	2			
Description				
The output is designed to be used as external alarm indication such as a red bulb in the control room etc. The output is active when at least one unconfirmed alarm is present in the alarmlist and remains active until confirmation of alarm.				



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1400		

Description

This is an output from the General Analog Input 1 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 1 On (page 367)** and **Analog Switch 1 Off (page 368)**. The value is measured from **AIN SWITCH 01 (PAGE 764)** analog input.



• back to Logical binary outputs alphabetically

AIN Switch02

	Related FW	1.0.0	Related applications	MINT, SPtM
Comm object 1401	Comm object	1401		

Description

This is an output from the General Analog Input 2 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 2 On (page 370)** and **Analog Switch 2 Off (page 371)**. The value is measured from **AIN SWITCH 02 (PAGE 764)** analog input.







Comm object 1402	Related FW	1.0.0	Related applications	MINT, SPtM
	Comm object	1402		

Description

This is an output from the General Analog Input 3 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 3 On (page 373)** and **Analog Switch 3 Off (page 374)**. The value is measured from **AIN SWITCH 03 (PAGE 764)** analog input.



• back to Logical binary outputs alphabetically

AIN Switch04

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1403		

Description

This is an output from the General Analog Input 4 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 4 On (page 376)** and **Analog Switch 4 Off (page 377)**. The value is measured from **AIN SWITCH 04 (PAGE 765)** analog input.





Comm object 1787	Related FW	1.0.0	Related applications	MINT, SPtM
	Comm object	1787		

Description

This is an output from the General Analog Input 5 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 5 On (page 379)** and **Analog Switch 5 Off (page 380)**. The value is measured from **AIN SWITCH 05 (PAGE 765)** analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch06

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1788		

Description

This is an output from the General Analog Input 6 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 6 On (page 382)** and **Analog Switch 6 Off (page 383)**. The value is measured from **AIN SWITCH 06 (PAGE 765)** analog input.





Comm object 1789	Related FW	1.0.0	Related applications	MINT, SPtM
	Comm object	1789		

Description

This is an output from the General Analog Input 7 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 7 On (page 385)** and **Analog Switch 7 Off (page 386)**. The value is measured from **AIN SWITCH 07 (PAGE 766)** analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch08

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1790		

Description

This is an output from the General Analog Input 8 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 8 On (page 388)** and **Analog Switch 8 Off (page 389)**. The value is measured from **AIN SWITCH 08 (PAGE 766)** analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1791		

Description

This is an output from the General Analog Input 9 switch function. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 9 On (page 391)** and **Analog Switch 9 Off (page 392)**. The value is measured from **AIN SWITCH 09 (PAGE 766)** analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch10

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1792		

Description

This is an output from the General Analog Input 10 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 10 On (page 394) and Analog Switch 10 Off (page 395). The value is measured from AIN SWITCH 10 (PAGE 767) analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1793		

Description

This is an output from the General Analog Input 11 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 11 On (page 397) and Analog Switch 11 Off (page 398). The value is measured from AIN SWITCH 11 (PAGE 767) analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch12

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1794		

Description

This is an output from the General Analog Input 12 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 12 On (page 400) and Analog Switch 12 Off (page 401). The value is measured from AIN SWITCH 12 (PAGE 767) analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1795		

Description

This is an output from the General Analog Input 13 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 13 On (page 403) and Analog Switch 13 Off (page 404). The value is measured from AIN SWITCH 13 (PAGE 768) analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch14

Comm object 1796	

Description

This is an output from the General Analog Input 14 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 14 On (page 406) and Analog Switch 14 Off (page 407). The value is measured from AIN SWITCH 14 (PAGE 768) analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1797		

Description

This is an output from the General Analog Input 15 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 15 On (page 409) and Analog Switch 15 Off (page 410). The value is measured from AIN SWITCH 15 (PAGE 768) analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch16

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1798		

Description

This is an output from the General Analog Input 16 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 16 On (page 412) and Analog Switch 16 Off (page 413). The value is measured from AIN SWITCH 16 (PAGE 769) analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1799		

Description

This is an output from the General Analog Input 17 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 17 On (page 415) and Analog Switch 17 Off (page 416). The value is measured from AIN SWITCH 17 (PAGE 769) analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch18

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1800		

Description

This is an output from the General Analog Input 18 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 18 On (page 418) and Analog Switch 18 Off (page 419). The value is measured from AIN SWITCH 18 (PAGE 769) analog input.





Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1801		

Description

This is an output from the General Analog Input 19 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 19 On (page 421) and Analog Switch 19 Off (page 422). The value is measured from AIN SWITCH 19 (PAGE 770) analog input.



• Logical binary outputs alphabetically (page 682)

AIN Switch20

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1802		

Description

This is an output from the General Analog Input 20 switch function. The behavior of the switch depends on the adjustment of the setpoints Analog Switch 20 On (page 424) and Analog Switch 20 Off (page 425). The value is measured from AIN SWITCH 20 (PAGE 770) analog input.





AVR Down

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	55		
Description			
This output together with the complementary output AVR UP (PAGE 706) is designed for voltage and power			
factor control at gen-sets, where the AVR does not support analog control.			

O back to Logical binary outputs alphabetically

AVR Up

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	ect 54		
Description			
This output together with the complementary output AVR Down (PAGE 706) is designed for voltage and power factor control at gen-sets, where the AVR does not support analog control.			

O back to Logical binary outputs alphabetically

LBO: B

BIN 1 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1374		

Description

This output is closed, when Binary Input 1 is active and open when Binary Input 1 is inactive. When Binary Input 1 is used for BIN protection function then this output is closed when BIN protection alarm is in Alarmlist.

Note: When LBI 1 is used like protection, then state of this LBO is connected with this protection e.g. when LBI is inactive but alarm of protection is not confirm in alarmlist, LBO is still active.





BIN 2 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1375		
– • <i>•</i>			

Description

This output is closed, when Binary Input 2 is active and open when Binary Input 2 is inactive. When Binary Input 2 is used for BIN protection function then this output is closed when BIN protection alarm is in Alarmlist.

Note: When LBI 2 is used like protection, then state of this LBO is connected with this protection e.g. when LBI is inactive but alarm of protection is not confirm in alarmlist, LBO is still active.



O back to Logical binary outputs alphabetically

BIN 3 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1376		
Description			
This output is closed, whe Input 3 is used for BIN prot Alarmlist.	n Binary Input 3 is active and tection function then this out	d open when Binary Input 3 i put is closed when BIN prot	s inactive. When Binary ection alarm is in
Note: When LBI 3 is u when LBI is inactive bu	sed like protection, then stat ut alarm of protection is not c	te of this LBO is connected confirm in alarmlist, LBO is s	with this protection e.g. still active.
Binary Input Status Output			Binary input is active
		Tim	e
	Image 9.162 Bi	nary Input 3 Status	



BIN 4 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1377		
Description			

Description

This output is closed, when Binary Input 4 is active and open when Binary Input 4 is inactive. When Binary Input 4 is used for BIN protection function then this output is closed when BIN protection alarm is in Alarmlist.

Note: When LBI 4 is used like protection, then state of this LBO is connected with this protection e.g. when LBI is inactive but alarm of protection is not confirm in alarmlist, LBO is still active.



O back to Logical binary outputs alphabetically

BIN 5 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1378		
Description			
This output is closed, whe Input 5 is used for BIN prot Alarmlist.	n Binary Input 5 is active and tection function then this out	d open when Binary Input 5 i put is closed when BIN prot	s inactive. When Binary ection alarm is in
Note: When LBI 5 is u when LBI is inactive bu	sed like protection, then stat ut alarm of protection is not c	te of this LBO is connected confirm in alarmlist, LBO is s	with this protection e.g. still active.
Binary Input Status Output			Binary input is active
		Tim	e
	Image 9.164 Bi	nary Input 5 Status	



BIN 6 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1379		
B 1.4			

Description

This output is closed, when Binary Input 6 is active and open when Binary Input 6 is inactive. When Binary Input 6 is used for BIN protection function then this output is closed when BIN protection alarm is in Alarmlist.

Note: When LBI 6 is used like protection, then state of this LBO is connected with this protection e.g. when LBI is inactive but alarm of protection is not confirm in alarmlist, LBO is still active.



O back to Logical binary outputs alphabetically

BIN 7 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1380		
Description			
This output is closed, whe Input 7 is used for BIN prot Alarmlist.	n Binary Input 7 is active and tection function then this out	d open when Binary Input 7 i put is closed when BIN prot	s inactive. When Binary ection alarm is in
Note: When LBI 7 is u when LBI is inactive bu	sed like protection, then stat ut alarm of protection is not o	te of this LBO is connected confirm in alarmlist, LBO is s	with this protection e.g. still active.
Binary Input Status Output			Binary input is active
		Tim	e
	Image 9.166 Bi	nary Input 7 Status	



BIN 8 Status

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1381		
Description			

Description

This output is closed, when Binary Input 8 is active and open when Binary Input 8 is inactive. When Binary Input 8 is used for BIN protection function then this output is closed when BIN protection alarm is in Alarmlist.

Note: When LBI 8 is used like protection, then state of this LBO is connected with this protection e.g. when LBI is inactive but alarm of protection is not confirm in alarmlist, LBO is still active.



O back to Logical binary outputs alphabetically

LBO: C

Cooling Pump

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	40		
Description			
This output is dedicated f remains closed until the g pause or the Emergency	or coolant pump control. It is jen-set is stopped and After Stop occurs or the controller	closed in the moment the g Cooling Time (page 282) is switched to OFF mode.	en-set is started and elapses or the cranking
Cooling Pump Output	Cranking Fail Cranking Pause Cranking		Engine is running
Off		Cooling Engine is ready	



Cooling

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	74			
Description				
The output closes when gen-set is in Cooling state.				

O back to Logical binary outputs alphabetically

LBO: D

Display Fail

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object				
Description				
This output indicates controller display failure.				

O back to Logical binary outputs alphabetically

LBO: E

ECU Communic Error

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	348				
Description					
This output is ac has dropped out.	This output is active when an ECU is configured, but the communication with the ECU is not established or has dropped out.				
Note: When ECU Power ReLAY (PAGE 712) is not configured, output is evaluated all the time. If ECU Power ReLAY (PAGE 712) is configured, output is evaluated only when engine is not stop (ECU Power ReLAY (PAGE 712) is active)					

Source of the second second

ECU Communic OK

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	347				
Description					
This output is ac established.	This output is active when an ECU is configured, connected and the communication with the ECU is established.				
Noto: When ECII Dower BELAY (pace 712) is not configured output is evaluated all the time. If ECII					

Note: When ECU Power Relay (PAGE 712) is not configured, output is evaluated all the time. If ECU Power Relay (PAGE 712) is configured, output is evaluated only when engine is not stop (ECU Power Relay (PAGE 712) is active).



ECU Power Relay

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	116		
B			

Description

This output is to be used for control of "keyswitch" input of an ECU. If the particular ECU does not have keyswitch or a similar input, it can be used for control of DC power for the ECU.

The output closes together with **PRESTART (PAGE 732)** and remains closed for the entire duration that the engine is running. It is opened at the moment that the engine comes to a stop (i.e. together with the **FUEL SOLENOID (PAGE 715)**).



IMPORTANT: This LBO also affects evaluation of Sd ECU Communication Fail (page 822) or Wrn ECU Communication Fail (page 802) alarms. With configured LBO ECU Power Relay, these alarms are evaluated only when this LBO is active. Without configured LBO ECU Power Relay, these alarm are evaluated all the time.

O back to Logical binary outputs alphabetically

ECU Red Lamp

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	350		
Description			
This output is ac and the engine sl frame on standar not provide the fl	tive when the ECU sends an act hould not be operated until a serv rd J1939 ECUs. Some ECUs pro ag at all.	ive "red lamp" flag, i.e. it has de rice check is performed. This fla ovide this flag in their own propr	tected a critical malfunction ag is taken from the DM1 ietary frames and some do

Solution between the second se



ECU Run Stop

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	958				
Description					
Signal for starting and stopping of ECU.					

O back to Logical binary outputs alphabetically

ECU Wait To Start

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	959				
Description					
This output is active when the ECU Wait To Start lamp is received.					

• back to Logical binary outputs alphabetically

ECU Yellow Lamp

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	349				
Description					
This output is active when the ECU sends an active "yellow lamp" flag, i.e. it has detected a non-critical malfunction. This flag is taken from the DM1 frame on standard J1939 ECUs. Some ECUs provide this flag					
in their own proprietary frames and some do not provide the flag at all.					

• back to Logical binary outputs alphabetically

Exercise Timer 1

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1250		
_			

Description

This is an output from the Exercise timer 1. This output makes it easy to make periodic tests of the gen-set and its activation depends on the setpoints in the **Subgroup: Timer 1 (page 427)** subgroup. This output is active when Timer 1 is active.

Note: In the event that both Timers are active at the same time, **Subgroup: Timer 1 (page 427)** has a higher priority than **Subgroup: Timer 2 (page 434)**.



Exercise Timer 2

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1251		
Description			

This is an output from the Exercise timer 2. This output makes it easy to make periodic tests of the gen-set and its activation depends on the setpoints in the **Subgroup: Timer 2 (page 434)** subgroup. This output is active when Timer 2 is active.

Note: In the event that both Timers are active at the same time, **Subgroup: Timer 1 (page 427)** has a higher priority than **Subgroup: Timer 2 (page 434)**.

0	back	to I	Logical	binary	outputs	alphabetically
<u> </u>						

LBO: F

FltRes

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	592				
Description					
This output provi	des 1s pulse when:				
Fault Res	et button is pressed on the contro	oller front facia or			
Fault Reset button is pressed on any of external local/remote terminals or					
Fault Reset command is received via communication line or					
the input I	FAULT RESET BUTTON is activated.				

O back to Logical binary outputs alphabetically

Frequency Select

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	1815				
Description					
The Frequency select output is opened when Nominal Frequency (Frequency Settings) is equal to 50Hz and					
closed when Nominal Frequency (Frequency Settings) is equal to 60Hz.					



Fuel Pump

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1253		
Description			

Description

Output closes when the value of Fuel Level lies under the value of Fuel Pump On (page 299) setpoint and opens when value of Fuel Pump Off (page 300) is reached.

This output also can be closed by binary input FUEL PUMP ON/OFF (PAGE 667). In this case the binary output FUEL PUMP ON (PAGE 299) is closed until the binary input FUEL PUMP ON/OFF (PAGE 667) is active or until the value of Fuel Pump Off (page 300) is reached.

Note: Setpoints *Fuel Pump On (page 299)* and *Fuel Pump Off (page 300)* are invisible until configuration of this LBO.

back to Logical binary outputs alphabetically

Fuel Solenoid





The output opens when:

- Emergency Stop comes
- cooled gen-set is stopped
- ▶ in pause between repeated starts

back to Logical binary outputs alphabetically

LBO: G

GCB Close/Open

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	41		

Description

The output controls the generator circuit breaker. Its state represents the breaker position requested by the controller. The breaker must react within 5 seconds to a close or open command, otherwise an alarm is issued.

Note: InteliGen 500 controllers can work even without breaker feedbacks, in this case do not configure the feedback to binary inputs.







back to Logical binary outputs alphabetically

GCB OFF Coil







GCB ON Coil



O back to Logical binary outputs alphabetically

GCB UV Coil

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	44				
Description					
The output is intended for control of undervoltage coil of generator circuit breaker. The output is active the					





whole time when the generator is running. The output is deactivated for at least 5 seconds in the moment the breaker has to be switched off.



GeneratorBus Healthy

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	77				
Description					
This output is active when the generatorbus voltage, frequency and voltage unbalance is within limits. It is deactivated:					

- immediately when the voltage/frequency/voltage unbalance gets out of limits (when GCB is not closed)
 - or
- with an appropriate delay after the voltage/frequency/voltage unbalance has got out of limits (when GCB is closed)

O back to Logical binary outputs alphabetically

Glow Plugs

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1252		

Description

This output is dedicated for diesel engine only. This output will close for exact time pre-set by setpoint **Glow Plugs Time (page 275)** before every starting attempt. The output opens in same time as the **STARTER** (PAGE 737) output closes (100 ms after **PRESTART (PAGE 732)** output opens).


ComAp >





LBO: H

Heartbeat

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	81			
Description				
This output toggles on/off in a period of 500 ms whenever the controller is switched on and functional.				

O back to Logical binary outputs alphabetically

HEST Lamp

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1373			
Description				
This output is closed if ECU send signal HEST Lamp. If ECU stop send HEST LAMP signal binary input will				
be opened without no matter if alarms in alarmlist are confirmed or not.				

O back to Logical binary outputs alphabetically

Horn

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	1		
Description			
The output desig each time a new Fault rese Horn rese	ned to be used for acoustic indica alarm has appeared and remains et 🏊 is pressed t 🕪 is pressed	ation of a newly appeared alarm active until one of the following	n. The output is activated g events occurs:
Horn Timeout (page 251) has elapsed			



LBO: I

Idle/Nominal

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	39		

Description

This output is used for switching between idle speed and nominal speed of the engine during the startup phase, if this feature (input) is available on the particular engine. In the case of some EFI engines, the idle/nominal switching is performed over the communication bus.

The output Idle/Nominal closes after the timer Idle Time (page 276) elapses. The Idle Time (page 276) starts to countdown when Starting RPM (page 273) reached. The underspeed protection is not evaluated during fixed 5 seconds period after reaching Starting RPM (page 273). A Start Fail protection occurs if the RPM drop below 2RPM during idle.



back to Logical binary outputs alphabetically

Ignition

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	37		
Description			

This output is dedicated to controlling the ignition at a gas engine. The output is closed together with binary output FUEL SOLENOID (PAGE 715) in the moment when the timer Sd Ventilation Time (page 280) elapsed and the gen-set reaches at least 30 RPM during cranking. The timer Sd Ventilation Time (page 280) become active when the gen-set has been stopped for any Sd protection or the controller has been turned on only before first cranking attempt. The output is opened 500ms after all Additional running engine indications (page 132) will be inactive. The output is opened when the genset has to be stopped or in pause during repeated starts.





O back to Logical binary outputs alphabetically

Ignition On

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	ct 1257				
Description					
This input is on since start button is pressed till the unit is completely stopped (or the engine doesn't start or Sd or E-Stop becomes active)					
Note: This function is the same as ECU Power ReLAY (PAGE 712). Ignition ON stays there from historical reasons.					



LBO: L

Load Shedding Stage 1

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	51			
Description				
Particular instan	ces of the load shedding function	ality		
The load shedding outputs are activated (load is beeing shedd) in the order 1, 2, 3.				
The load shedding outputs are deactivated (load is beeing reconnected) in the order 3, 2, 1.				

The load disconnected by the LBO Nr.1 is the less essential load of these three possible loads instances.

O back to Logical binary outputs alphabetically

Load Shedding Stage 2

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	52			
Description				
Particular instan	ces of the load shedding function	ality		
The load shedding outputs are activated (load is beeing shedd) in the order 1, 2, 3.				
The load shedding outputs are deactivated (load is beeing reconnected) in the order 3, 2, 1.				
The load disconnected by the LBO Nr.1 is the less essential load of these three possible loads instances.				

O back to Logical binary outputs alphabetically

Load Shedding Stage 3

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	53			
Description				
Particular instan	ces of the load shedding function	ality		
The load sheddi	ng outputs are activated (load is l	beeing shedd) in the order 1, 2,	3.	
The load shedding outputs are deactivated (load is beeing reconnected) in the order 3, 2, 1.				
The load disconnected by the LBO Nr.1 is the less essential load of these three possible loads instances.				
The load disconnected by the LBO Nr. 1 is the less essential load of these three possible loads instances.				

Source of the second second

LBO: M

Mains Healthy

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	78			
Description				
This output is active while mains failure is not detected and mains voltage and frequency is within limits.				



Manual Ready

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1258			
Description				
This output is active when controller is in MAN mode and the engine is stopped and it is possible to start it i.e. no red alarm is activated or SD OVERRIDE (PAGE 680) is active (Output READY (PAGE 734) is active).				

O back to Logical binary outputs alphabetically

MCB Close/Open

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	45		
Description			

Description

The output controls the mains circuit breaker. Its state represents the breaker position requested by the controller. The breaker must react within 5 seconds to a close or open command, otherwise an alarm is issued.









O back to Logical binary outputs alphabetically

MCB OFF Coil





MCB ON Coil



O back to Logical binary outputs alphabetically



MCB UV Coil

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	48		
Decembration			

Description

The output is intended for control of undervoltage coil of mains circuit breaker. The output is active the whole time when the controller is switched on. The output is deactivated for at least 5 seconds in the moment the breaker has to be switched off.



O back to Logical binary outputs alphabetically



Mode AUTO

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	omm object 19			
Description				
This output is active whenever the controller is in AUTO mode.				

O back to Logical binary outputs alphabetically

Mode MAN

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 18				
Description				
This output is active whenever the controller is in MAN mode.				

• back to Logical binary outputs alphabetically

Mode OFF

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 17				
Description				
This output is active whenever the controller is in OFF mode.				

O back to Logical binary outputs alphabetically

Mode TEST

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 20				
Description				
This output is active whenever the controller is in TEST mode.				

O back to Logical binary outputs alphabetically

LBO: N

NCB Close/Open

Related FW	1.0.0	Related applications	MINT	
Comm object 50				
Description				
Neutral circuit breaker Close/Open output controls the generator neutral circuit breaker. It is intended for contactors – provides a continual active signal if NCB should be closed.				



Not In AUTO

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	Comm object 1248			
Description				
This output is active when controller isn't in AUTO mode.				

O back to Logical binary outputs alphabetically

Not Used

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 286				
Description				
Output has no function.				

• back to Logical binary outputs alphabetically

LBO: P

Peak Shaving Active

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object 2118				
Description				
Active anytime, when the peak shaving start condition is fulfilled.				



Power Switch

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	290		
Description			

Description

This is an output from the Power switch function. The behavior of the switch depends on the adjustment of the setpoints **Power Switch On (page 282)** and **Power Switch Off (page 283)**. When the dummy load function is used the switching ON of Power switch is block when the engine isn't running and is allowed 30 s after start of the engine.



Note: Setpoints **Power Switch On (page 282)** and **Power Switch Off (page 283)** are invisible until configuration of this LBO.

• back to Logical binary outputs alphabetically

Prestart

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	36		
Description			
This output can be used for closed for time period of P 737) output closes.	or control of any device, whic restart Time (page 273) . Th	h has to be activated just b ne output opens 100 ms bef	efore start. The output is ore the S TARTER (PAGE
Binary Outputs Starter On	tart Time	Engine is running	Engine RPM
		Starting RPM Tin	→ ne
	Image 9.19	95 Engine start	

ComAp >



Source of the second second



LBO: R

Ready To AMF

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	object 324			
Description				
The output is closed if the gen-set is ready to start automatically and take the load if the mains fails, i.e.:				

- the controller is in AMF operating mode
- the controller is in AUTO controller mode and
- no red alarm is present in the alarmlist
- when the red alarm is confirmed during Stop Valve and other requirements are fulfilled then the LBO is still inactive until the state ready

• back to Logical binary outputs alphabetically

Ready To Load

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	58			
Description				
The output is closed whenever the GCB is closed or can be closed i.e. the stabilization phase is finished, the gen-set is running and the Minimal Stabilization Time (page 278) timer has elapsed. and the gen-set voltage and frequency are within limits.				
If GCB is open then gen-set voltage and frequency must be in limits.				
If GCB is close t	hen gen-set voltage and frequend	cy can be out of limits, but prote	ection delay can't be count	
down. If gen-set	voltage and frequency will return	into limits until delay is count of	down then output is still	

closed.

O back to Logical binary outputs alphabetically

Ready

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	62			
Description				
The binary output is closed, when the engine is stopped and it is possible to start it i.e. no red alarm is activated or SD OVERRIDE (PAGE 680) is active.				
The binary output is switch on when the Ready state occurs.				
The binary output is switch off when the Prestart or the Not Ready or the Stop state occurs i.e. always				

except Ready state.



RegenerationNeededRegen Needed

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	1372				
Description					
This output is closed when DPF lamp from ECU is active.					

O back to Logical binary outputs alphabetically

Running

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	67		
Description			

Description

The output is designed to be used as an indication that the gen-set is running. The output closes if FUEL SOLENOID (PAGE 715) is closed and STARTER (PAGE 737) and PRESTART (PAGE 732) are open. The out remains close until engine stop and cooling period elapses.



O back to Logical binary outputs alphabetically

LBO: S

Sd Override

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	962			
Description				
The output is closed if SD OVERRIDE (PAGE 680) input is active and open if SD OVERRIDE (PAGE 680) input is				
inactive. This output is usually used to send information about SD OVERRIDE (PAGE 680) input into ECU.				



Speed Down

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	57				
Description					
This output together with the complementary output SPEED UP (PAGE 736) are designed for speed and power control at gen-sets where the speed governor does not support analogue control.					

O back to Logical binary outputs alphabetically

Speed Up

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	56				
Description					
This output together with the complementary output SPEED DOWN (PAGE 736) are designed for speed and power control at gen-sets where the speed governor does not support analogue control.					



Starter

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	24		

Description

This output is dedicated for starter motor control. The number of cranking attempts is adjusted by setpoint **Cranking Attempts (page 271)** in Engine Settings group. Cranking fail pause is adjusted by setpoint **Cranking Fail Pause (page 272)**.



Image 9.199 Starter

The starter output opens when:

- the "firing" speed is reached
- maximum time of cranking is exceeded
- request to stop comes up
- D+ value is higher than 80%
- Oil pressure value is higher than Starting Oil Pressure (page 274)
- Generator voltage > 25% of Nominal Voltage Ph-N (page 246) or Nominal Voltage Ph-Ph (page 246) (any phase)

Solution between the second se

Still Log 0

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	oject 26				
Description					
Logical binary output which is still in logical 0.					

O back to Logical binary outputs alphabetically

Still Log 1

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	27				
Description					
Logical binary output which is still in logical 1.					



Stop Pulse

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	25		
Description			
Output is active for 1 second	ond after STOP SOLENOID (PA	GE 738) output activation. T	his signal is sent to ECU
in case of engine stop req	uest.		
Binary Output	Stop Time	>	
Stop Solenoid On			
Stop Solenoid Off			
Stop Pulse On			
Stop Pulse Off			
···	1s		
l Stop reque	t	Time	2
Image 9.200 Stop Pulse			

O back to Logical binary outputs alphabetically

Stop Solenoid

Related FW	1.0.0	Related applications	MINT, SPtM		
Comm object	23				
Description					
This output is dedicated to control the stop solenoid (valve). The output closes when an engine stop command is received and is deactivated 12 s after last running engine indication went off, i.e. engine is stopped.					
Stop Solenoid Output	Engine run	12 s →	RPM / Frequency		
			D+		
			Oil Pressure		
			Generator Voltage		
			Fuel Solenoid is opened		
	8				
······	Stop Time	Gen-set stopped			
Stop		Time	2		
	Image 9.201	Stop Solenoid 1			





• Logical binary outputs alphabetically (page 682)

Supplying Load

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	1249			
Description	Description			
The binary output depends on measured generator active power. Power is compared with generator nominal active power with use of hysteresis and with delay of switch 1 s.				
When the measured active power is equal or bigger than 5 % of Nominal Power (page 242) for 1 s than the binary output is closed.				
When the measured active power is equal or lower than 3 % of Nominal Power (page 242) for 1 s than the binary output is opened.				

O back to Logical binary outputs alphabetically

System Reserve OK

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	87		
Description			
This LBO is active when System Reserve is higher than the actual reserve for start of next gen-sets.			



LBO: T

Temperature Switch





9.1.5 Logical analog inputs

What Logical analog inputs are:

Logical analog inputs are inputs for analog values.

Alphabetical groups of Logical analog inputs

LAI: A	
LAI: C	
LAI: D	
LAI: F	
LAI: M	
LAI: N	
LAI: O	

For full list of Logical analog inputs go to the chapter Logical analog inputs alphabetically (page 742).

ComAp >

Logical analog inputs alphabetically

AIN Prot01744
AIN Prot02745
AIN Prot03746
AIN Prot04747
AIN Prot05748
AIN Prot06749
AIN Prot07750
AIN Prot08751
AIN Prot09752
AIN Prot10753
AIN Prot11754
AIN Prot12755
AIN Prot13756
AIN Prot14757
AIN Prot15758
AIN Prot16759
AIN Prot17760
AIN Prot18761
AIN Prot19762
AIN Prot20763
AIN Switch 01764
AIN Switch 02764
AIN Switch 03764
AIN Switch 04765
AIN Switch 05765
AIN Switch 06765
AIN Switch 07766
AIN Switch 08766
AIN Switch 09766
AIN Switch 10767
AIN Switch 11767
AIN Switch 12767
AIN Switch 13768
AIN Switch 14768
AIN Switch 15768
AIN Switch 16769
AIN Switch 17769

AIN Switch 18769)
AIN Switch 19770)
AIN Switch 20770)
Coolant Temp771	
Display Brightness772	2
Fuel Level772	2
Mains Import	
Measurement773	3
Not Used773	3
Oil Pressure	ŀ
Oil Temp775	5



LAI: A



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9999		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 1 Wrn (page 366)** and **Analog Protection 1 Sd (page 366)**. Delay is adjusted by setpoint **Analog Protection 1 Delay (page 367)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9998		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 2 Wrn (page 368)** and **Analog Protection 2 Sd (page 369)**. Delay is adjusted by setpoint **Analog Protection 2 Delay (page 369)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9997		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 3 Wrn (page 371)** and **Analog Protection 3 Sd (page 372)**. Delay is adjusted by setpoint **Analog Protection 3 Delay (page 372)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9996		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 4 Wrn (page 374)** and **Analog Protection 4 Sd (page 375)**. Delay is adjusted by setpoint **Analog Protection 4 Delay (page 375)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9995		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 5 Wrn (page 377)** and **Analog Protection 5 Sd (page 378)**. Delay is adjusted by setpoint **Analog Protection 5 Delay (page 378)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9994		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 6 Wrn (page 380)** and **Analog Protection 6 Sd (page 381)**. Delay is adjusted by setpoint **Analog Protection 6 Delay (page 381)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9993		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 7 Wrn (page 383)** and **Analog Protection 7 Sd (page 384)**. Delay is adjusted by setpoint **Analog Protection 7 Delay (page 384)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9992		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 8 Wrn (page 386)** and **Analog Protection 8 Sd (page 387)**. Delay is adjusted by setpoint **Analog Protection 8 Delay (page 387)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9991		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 9 Wrn (page 389)** and **Analog Protection 9 Sd (page 390)**. Delay is adjusted by setpoint **Analog Protection 9 Delay (page 390)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9990		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 10 Wrn (page 392)** and **Analog Protection 10 Sd (page 393)**. Delay is adjusted by setpoint **Analog Protection 10 Delay (page 393)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9989		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 11 Wrn (page 395)** and **Analog Protection 11 Sd (page 396)**. Delay is adjusted by setpoint **Analog Protection 11 Delay (page 396)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9988		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 12 Wrn (page 398)** and **Analog Protection 12 Sd (page 399)**. Delay is adjusted by setpoint **Analog Protection 12 Delay (page 399)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9987		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 13 Wrn (page 401)** and **Analog Protection 13 Sd (page 402)**. Delay is adjusted by setpoint **Analog Protection 13 Delay (page 402)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.


Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9986		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 14 Wrn (page 404)** and **Analog Protection 14 Sd (page 405)**. Delay is adjusted by setpoint **Analog Protection 14 Delay (page 405)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9985		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 15 Wrn (page 407)** and **Analog Protection 15 Sd (page 408)**. Delay is adjusted by setpoint **Analog Protection 15 Delay (page 408)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9984		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 16 Wrn (page 410)** and **Analog Protection 16 Sd (page 411)**. Delay is adjusted by setpoint **Analog Protection 16 Delay (page 411)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9983		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 17 Wrn (page 413)** and **Analog Protection 17 Sd (page 414)**. Delay is adjusted by setpoint **Analog Protection 17 Delay (page 414)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9982		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 18 Wrn (page 416)** and **Analog Protection 18 Sd (page 417)**. Delay is adjusted by setpoint **Analog Protection 18 Delay (page 417)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9981		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 19 Wrn (page 419)** and **Analog Protection 19 Sd (page 420)**. Delay is adjusted by setpoint **Analog Protection 19 Delay (page 420)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9980		
Description			

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Analog Protection 20 Wrn (page 422)** and **Analog Protection 20 Sd (page 423)**. Delay is adjusted by setpoint **Analog Protection 20 Delay (page 423)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
AL Indic	Analog value is not used for protection. Only alarmlist record is made if analog value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn+BOR	Analog value is used for warning and breaker open protection
BOR	Analog value is used for breaker open protection
Wrn+MPR	Analog value is used for warning and mains protection
MPR	Analog value is used for mains protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	209		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH01 (PAGE 696)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 1 On (page 367)** and **Analog Switch 1 Off (page 368)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 02

1.0.0	Related applications	MINT, SPtM		
210				
Description				
Logical analog input designed for general value received from analog sensor. For more information about				
wiring of analog inputs see Analog inputs on page 41. This analog input controls logical binary output AIN				
1 2	.0.0 10 signed for general value see Analog inputs on	.0.0 Related applications 10 signed for general value received from analog sens see Analog inputs on page 41. This analog input		

wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH02 (PAGE 696)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 2 On (page 370)** and **Analog Switch 2 Off (page 371)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

back to Logical analog inputs alphabetically

AIN Switch 03

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	211		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH03 (PAGE 697)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 3 On (page 373)** and **Analog Switch 3 Off (page 374)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



	0.0	Related applications	MINT, SPtM
Comm object 212	2		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH04 (PAGE 697)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 4 On (page 376)** and **Analog Switch 4 Off (page 377)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 05

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	278			
Description				
Logical analog input designed for general value received from analog sensor. For more information about				
wiring of analog inputs see Analog inputs on page 41. This analog input controls logical binary output AIN				
SWITCH05 (PAGE 698). The behavior of the switch depends on the adjustment of the setpoints Analog				
Switch 5 On (page 379) and Analog Switch 5 Off (page 380).				

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

back to Logical analog inputs alphabetically

AIN Switch 06

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	279		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH06 (PAGE 698)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 6 On (page 382)** and **Analog Switch 6 Off (page 383)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	280		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH07 (PAGE 699)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 7 On (page 385)** and **Analog Switch 7 Off (page 386)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 08

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	281			
Description				
Logical analog input wiring of analog inpu SwitcH08 (PAGE 69 Switch 8 On (page	designed for general value ts see Analog inputs on 9). The behavior of the swit 388) and Analog Switch {	received from analog sens page 41 . This analog inpu tch depends on the adjustr 8 Off (page 389) .	sor. For more information about at controls logical binary output AIN ment of the setpoints Analog	

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

back to Logical analog inputs alphabetically

AIN Switch 09

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	282		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH09 (PAGE 700)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 9 On (page 391)** and **Analog Switch 9 Off (page 392)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	283		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH10 (PAGE 700)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 10 On (page 394)** and **Analog Switch 10 Off (page 395)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 11

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	284		
Description			
Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs see Analog inputs on page 41 . This analog input controls logical binary output AIN SWITCH11 (PAGE 701). The behavior of the switch depends on the adjustment of the setpoints Analog			

Switch 11 On (page 397) and Analog Switch 11 Off (page 398).

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

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AIN Switch 12

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	285		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH12 (PAGE 701)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 12 On (page 400)** and **Analog Switch 12 Off (page 401)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	286		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH13 (PAGE 702)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 13 On (page 403)** and **Analog Switch 13 Off (page 404)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 14

Related FW	1.0.0	Related applications	MINT, SPtM	
Comm object	287			
Description				
Logical analog input	designed for general value	received from analog sens	sor. For more information about	
wiring of analog inputs see Analog inputs on page 41. This analog input controls logical binary output AIN				
SWITCH14 (PAGE 702). The behavior of the switch depends on the adjustment of the setpoints Analog				
Switch 14 On (page 406) and Analog Switch 14 Off (page 407).				

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

back to Logical analog inputs alphabetically

AIN Switch 15

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	288		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH15 (PAGE 703)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 15 On (page 409)** and **Analog Switch 15 Off (page 410)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	289		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH16 (PAGE 703)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 16 On (page 412)** and **Analog Switch 16 Off (page 413)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

• back to Logical analog inputs alphabetically

AIN Switch 17

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	290		
Description			
Logical analog input designed for general value received from analog sensor. For more information about			
wiring of analog inputs see Analog inputs on page 41. This analog input controls logical binary output AIN			
SWITCH17 (PAGE 704). The behavior of the switch depends on the adjustment of the setpoints Analog			
Switch 17 On (page 415) and Analog Switch 17 Off (page 416).			

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

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AIN Switch 18

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	291		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH18 (PAGE 704)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 18 On (page 418)** and **Analog Switch 18 Off (page 419)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.



Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	292		

Description

Logical analog input designed for general value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. This analog input controls logical binary output **AIN SWITCH19 (PAGE 705)**. The behavior of the switch depends on the adjustment of the setpoints **Analog Switch 19 On (page 421)** and **Analog Switch 19 Off (page 422)**.

Note: This function is not suitable for tristate or binary analog sensors.

IMPORTANT: This analog input has no protection. Input is designed only to control appropriate logical binary output.

O back to Logical analog inputs alphabetically

AIN Switch 20

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	293		
Description			
Logical analog input wiring of analog input Switch20 (PAGE 70 Switch 20 On (page	designed for general value ts see Analog inputs on 5). The behavior of the swite e 424) and Analog Switch	received from analog sens page 41 . This analog inpu tch depends on the adjustr 20 Off (page 425) .	sor. For more information about t controls logical binary output AIN ment of the setpoints Analog
Note: This funct	ion is not suitable for trista	te or binary analog sensors	5.
IMPORTANT	: This analog input has r	no protection. Input is de	esigned only to control

appropriate logical binary output.



LAI: C

Coolant Temp

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	67		
– • •			

Description

Logical analog input designed for coolant temperature value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Coolant Temperature Wrn (page 289)** and **Coolant Temperature Sd (page 290)**. Delay is adjusted by setpoint **Coolant Temperature Delay (page 290)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.

Note: This analog function can by also configured on binary input as binary function. In this case chose **COOLANT TEMP (PAGE 664)** binary input in the list of binary inputs. Delay of this binary input is adjusted via the same setpoint like for analog function.

IMPORTANT: Value from analog input has higher priority than value from ECU.



LAI: D

Display Brightness

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object			
Description			
Use this function to adjust display brightness. It is necessary to set Brightness control to External to use the			
function Display brightness settings (page 192)			

back to Logical analog inputs alphabetically

LAI: F

Fuel Level

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	78		
Description			

Logical analog input designed for fuel level value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Fuel Level Wrn (page 296)** and **Fuel Level Sd (page 296)**. Delay is adjusted by setpoint **Fuel Level Delay (page 297)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Example: Prote	ection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated +

Sensor fail alarm will be activated.

ComAp >

Note: This parameter has to be adjusted via InteliConfig.

IMPORTANT: For right behavior of this function, curve for analog input has to be in percentage.

Note: This analog function can by also configured on binary input as binary function. In this case chose **FUEL LEVEL (PAGE 667)** binary input in the list of binary inputs. Delay of this binary input is adjusted via the same setpoint like for analog function.

IMPORTANT: Value from analog input has higher priority than value from ECU.

back to Logical analog inputs alphabetically

LAI: M

Mains Import Measurement

Related FW	1.0.0	Related applications	MINT, SPtM						
Comm object	5								
Description									
Logical analog input designed for Mains import measurement (page 154) . Value from this input is used in load transfer from mains to generator. Load transfer is considered to be finished when this value is lower then Mains Unload MCB Open Window (page 353)									

O back to Logical analog inputs alphabetically

LAI: N

Not Used

Related FW	1.0.0	Related applications	MINT, SPtM					
Comm object	230							
Description								
Input has no function.								



LAI: O

Oil Pressure

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	9		
_ · ·			

Description

Logical analog input designed for oil pressure value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Oil Pressure Wrn (page 287)** and **Oil Pressure Sd (page 288)**. Delay is adjusted by setpoint **Oil Pressure Delay (page 288)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
Wrn	Analog value is used for warning protection only.
Wrn + Sd	Analog value is used for warning and Sd protection.
Sd	Analog value is used for Sd protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.

Note: This analog function can by also configured on binary input as binary function. In this case chose **OIL PRESSURE (PAGE 674)** binary input in the list of binary inputs. Delay of this binary input is adjusted via the same setpoint like for analog function.

IMPORTANT: Value from analog input has higher priority than value from ECU.



Oil Temp

Related FW	1.0.0	Related applications	MINT, SPtM
Comm object	77		

Description

Logical analog input designed for oil temperature value received from analog sensor. For more information about wiring of analog inputs **see Analog inputs on page 41**. Limits for this protection are adjusted by setpoints **Oil Temp Wrn (page 291)** and **Oil Temp Sd (page 292)**. Delay is adjusted by setpoint **Oil Temp Delay (page 292)**.

Protection types

Monitoring	Analog value is only measured and displayed on the LCD screen but not used for protection.
HistRecOnl	Analog value is only measured and displayed on the LCD screen but not used for protection. History record is made if value is out of the limits.
Wm	Analog value is used for warning protection only.
Wrn+Stp	Analog value is used for warning and slow stop protection
Stp	Analog value is used for slow stop protection
Wrn + BOC	Analog value is used for warning and BOC (Breaker Open and Cooling) protection.
BOC	Analog value is used for BOC (Breaker Open and Cooling) protection.
Wrn + Sd	Analog value is used for warning and shutdown protection.
Sd	Analog value is used for shutdown protection.

Note: This parameter has to be adjusted via InteliConfig.

Alarm

Under limit	Alarm is activated when value of analog input is under adjusted limits
Over limit	Alarm is activated when value of analog input is over adjusted limits
Under limit + fls	Alarm is activated when value of analog input is under adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.
Over limit + fls	Alarm is activated when value of analog input is over adjusted limits. If sensor fail is detected then the alarm with higher level is activate as well.

Example: Protection type is Wrn + Sd. When sensor fail is detected then Sd alarm will be activated + Sensor fail alarm will be activated.

Note: This parameter has to be adjusted via InteliConfig.

IMPORTANT: Value from analog input has higher priority than value from ECU.



9.1.6 PLC

List of PLC groups

Group: Basic Logical functions	
Group: Comparison of analog inputs	
Group: Time functions	
Group: Other functions	

For full list of PLC blocks go to the chapter List of PLC blocks (page 777).



List of PLC blocks

Group: Comparison of analog inputs Comparator With

Hysteresis	781
Comparator With Delay .	782

Group: Time functions

Timer	•••	••	•	 •	•	•	 •	•	 ••	•	•	• •	•	 78	33	5
Delay				 			 							78	35)



Group: Basic Logical functions

OR/AND

PLC group			Basic logical fu	inctions	OR/AND				
Related FW			1.0.0						
Related applications			MINT, SPtM						
Comm object		1		item 1					
Inp	outs		1						
	Input	Туре	Negation	Range	Function				
	Input 18	Binary	Yes	0/1	Inputs 18				
Ou	tputs								
	Output	Туре	Negation	Range	Function				
	Output	Binary Yes 0/1		0/1	Result of the logical operation				
_									

Description

The block performs logical operation OR / AND of 2 - 8 binary operands. The inputs as well as the output can be inverted.

Function OR

Input 1	Input 2	Output
0	0	0
0	1	1
1	0	1
1	1	1

Function AND

Input 1	Input 2	Output
0	0	0
0	1	0
1	0	0
1	1	1

There have to be at least 2 inputs every time. There may be up to 8 inputs configured.





O back to List of PLC blocks



XOR/RS

PLC group		Basic logical functions		XOR/RS	
Related FW		1.0.0			
Related applications		MINT, SPtM		12	
Co	mm object		2		Nem 2
Inputs					
	Input	Туре	Negation	Range	Function
	Input 12	Binary	Yes	0/1	Inputs 12
Ou	tputs				
	Output	Туре	Negation	Range	Function
	Output	Binary	Yes	0/1	Result of the logical operation

Description

The block provides logical function of two values - XOR or RS flip-flop. Both inputs and output can be inverted.

Function XOR

Input 1	Input 2	Output
0	0	0
0	1	1
1	0	1
1	1	0

Function RS

R	S	Q _{n+1}
0	0	Q _n
0	1	1
1	0	0
1	1	0



O back to List of PLC blocks



Group: Comparison of analog inputs

PLC group Related FW		Comparison of analog inputs		Comp Hyst		
		1.0.0			I-ON O	
Re	lated applica	tions	MINT, SPtM			item 4
Co	mm object		3			
Inp	outs					
	Input	Туре	Negation	Range		Function
	Input	Analog	No	Any		Compared value
	Input ON	Analog	No	Same as	s Input	Comparative level for switching on
	Input OFF	Analog	No	Same as	s Input	Comparative level for switching off
Ou	tputs					
	Output	Туре	Negation	Range		Function
	Output	Binary	No	0/1		Comparator output
Do	ecription					

Comparator With Hysteresis

Description

The block compares the input value with the comparative levels. The behavior depends on whether the ON level is higher than OFF level or vice versa.







back to List of PLC blocks

Comparator With Delay

PLC group		Comparison of analog inputs		Comp Time		
Related FW		1.0.0			12 O •	
Related applications MIN		MINT, SPtM			Item 2	
Comm object		4				
Inp	outs					
	Input	Туре	Negation	Range		Function
	Input 1	Analog	No	Any		Compared value
	Input 2	Analog	No	Same as Input 1		Comparative level
	Delay	Analog	No	0.0300	0,0 [s]	Comparative delay
Ou	tputs					
	Output	Туре	Negation	Range		Function
	Output	Binary	No	0/1		Comparator output
De	scription					
The block works as an analog switch. It compares the in switch on if the input is equal or higher than the compara				input value rative level	with the comparative level. The output will for time longer than the delay.	





O back to List of PLC blocks

Group: Time functions

Timer

PLC group		Time functions		Timer	
Related FW			1.0.0		e Run Rel
Related applications		MINT, SPtM		- Nerv	
Comm object		14		Item 1	
Inputs					
	Input	Туре	Negation	Range	Function
	Run	Binary	No	0/1	The timer runs only if this input is active or not connected
	Reload	Binary	No	0/1	This input reloads the timer to the initial value
	Reload value	Analog	No	0,03276,7 [s]	Initial value of the timer
Ou	tputs				





O back to List of PLC blocks



Delay

PLC group		Time functions		Delay
Related FW		1.0.0		Up o
Related applicat	ions	MINT, SPtM		Dn Res
Comm object		33		Hem o
Inputs				
Input	Туре	Negation	Range	Function

•••	•	•	
Binary	No	0/1	Input signal to be delayed
Analog	No	-3200,03200,0 [s, m, h]	Delay of the rising edge resp. pulse length generated by rising edge of the input
Analog	No	-3200,03200,0 [s, m, h]	Delay of the falling edge resp. pulse length generated by falling edge of the input
Binary	Νο	0/1	Resets the output to logical 0. The output remains in logical 0 until new rising edge appears on Input (when Input reset is deactivated already)
	Binary Analog Analog Binary	BinaryNoAnalogNoAnalogNoBinaryNo	Binary No 0/1 Analog No -3200,03200,0 [s, m, h] Analog No -3200,03200,0 [s, m, h] Binary No -3200,03200,0 [s, m, h] Binary No 0/1

Outputs

Output Binary No 0/1 Output	signal

Description

This block can work in two modes of operation:

- Delay mode the rising edge at the output is generated with delay of "input time up" when a rising edge at the input is detected. The falling edge at the output is generated with delay of "input time down" when a falling edge at the input is detected. If the delayed falling edge at the output came earlier than the delayed rising edge, then no pulse would be generated at the output.
- Pulse mode a pulse of "input time up" length is generated at the output when a rising edge is detected, a pulse of "input time down" length is generated at the output when a falling edge is detected.





O back to List of PLC blocks



Group: Other functions

Force History Record

PLC	C group		Other functions		Force Hist	
Rel	ated FW		1.0.0			
Rel	ated applica	tions	MINT, SPtM		and the second se	
Со	nm object		9		- nema	
Inp	uts					
	Input	Туре	Negation	Range	Function	
	Input	Binary	No	0/1	A record with configured text is recorded into the controller history when the input is activated.	
Outputs						
	No outputs.					
Des	scription					
This	This block writes a record with defined text into the history when the input is activated.					
PLC Editor: Function block Reset channel Input • Input: Message: • Government Message in history • OK © OK						
Image 9.214 Configuration of Force Hist block						
	Note: Maxim	al numbe	r of characters for l	history me	essage is 15.	

O back to List of PLC blocks

Force Protection

PLC group			Other functions 1.0.0 MINT, SPtM		Force Prot		
Related FW							
Related applications					Fis		
Comm object			10		nemo		
Inp	Inputs						
	Input Type		Negation	Range	Function		
	Lvl 1	Binary	Νο	0/1	The input activates yellow level of the configured protection if it is configured		
	LvI 2	Binary	No	0/1	The input activates red level of the configured protection if a red level protection is configured		
	Fls	Binary	No	0/1	The input activates sensor fail if a fls protection is configured		





O back to List of PLC blocks



Counter

PLC group		Other functions		Counter Cnt			
Related FW		1.0.0					
Related applications		MINT, SPtM		Cir item 1			
Comm object		11					
Inp	outs						
	Input	Туре	Nega	tion Range		Function	
	Input Count Up	Binary	No	0/1		Input at which the edges are counted	
	Input Preset Limit	Analog	No	03276)7 [-]	Counter value limit for activation of the output	
	Input Clear	Binary	No	0/1		Reset input	
Ou	tputs						
	Output	Туре	Nega	tion Range		Function	
	Output	Binary	No	0/1		Output is activated when the counter value exceeds the limit	

Description

The block works as a counter of edges (selectable rising, falling or both) with reset input and adjustable counting limit. The maximal counter value is 32767. The counter value is lost when the controller is switched off. The output is activated when the counter value is equal or higher than Input Preset Limit and stays active until the block reset is done using Input Clear. Activating of the Input Clear resets the counter value to 0 and deactivates the output. Holding the Input Clear active blocks the counting.

 Input Count Up: 	Counted signal		×
• Input Preset Limit:	10 🗘		\times D
• Input Clear:	Counter reset		\times
Output:	Counter output		
Edge type selector:	Rising Edge 🔹		
	Rising Edge	-	
	Falling Edge	ок	🙁 Cance
	Both Edges		

O back to List of PLC blocks

ComAp >

9.2 Alarms

9.2.1 Alarms level 1	. 790
9.2.2 Alarms level 2	. 818
9.2.3 Fail sensor and other types	837

What alarms are:

The controller evaluates two levels of alarms. For more information see Alarm management on page 111.

9.2.1 Alarms level 1

Warnings	793
Other type	811

For full list of Alarms level 1 go to List of alarms level 1 (page 791).

What alarms level 1 are:

The level 1 alarm indicates that a value or parameter is out of normal limits, but has still not reached critical level. For more information see Alarm types - Level 1 on page 113.



List of alarms level 1

Alarm Email 1 Fail793
Alarm Email 2 Fail793
Alarm Email 3 Fail793
Alarm Email 4 Fail793
Alarm SMS 1 Fail794
Alarm SMS 2 Fail794
Alarm SMS 3 Fail794
Alarm SMS 4 Fail794
Battery Charger Fail795
Wrn Battery Voltage 795
Bus CCW Rotation 795
Default Credentials 795
ECU Wait To Start796
Wrn Emergency Droop
Active796
Event Email 1 Fail796
Event Email 2 Fail796
Event Email 3 Fail796
Event Email 4 Fail797
Event SMS 1 Fail797
Event SMS 2 Fail797
Event SMS 3 Fail797
Event SMS 4 Fail798
Generator CCW Rotation .798
Mains CCW Rotation798
Rental Timer 1 Elapsed798
Rental Timer 2 Elapsed799
Rental Timer Block Start . 799
Soft Transfer Fail799
Speed Regulation Limit799
Voltage Regulation Limit799
Wrn AIN Prot800
Wrn Charging Alternator
Fail 800
Wrn BadPwrCfg800
Wrn Battery > Voltage 800
Wrn Battery < Voltage 801
Wrn BIN Protection 801

Wrn Coolant Temp801
Wrn Coolant Temperature
Low801
Wrn ECU Communication
Fail802
ECU Red Lamp 802
ECU Yellow Lamp 802
Wrn Fence 1 Alarm802
Wrn Fence 2 Alarm803
Wrn Fuel Level 803
Wrn Fuel Theft803
Wrn GCB Fail803
Wrn Generator L1 >
Voltage804
Wrn Generator L1 <
Voltage804
Wrn Generator L1L2 >
Voltage804
Wrn Generator L1L2 <
Voltage805
Wrn Generator L2 >
Voltage805
Wrn Generator L2 <
Voltage805
Wrn Generator L2L3 >
Voltage805
Wrn Generator L2L3 <
Voltage806
Wrn Generator L3 >
Wrn Generator L3 <
Voltage 807
Wrn Generator 1 31 1 <
Voltage
Wrn Generator >
Frequency
Wrn Generator <
Frequency



unattended
Module(slotA) -
unexpected816
Module(slotA) - unknown
module816
Module(slotB) - comm.
outage817
Module(slotB) - false
module817
Module(slotB) -
unattended817
Module(slotB) -
unexpected817
Module(slotB) - unknown
module818
Default Credentials 820
Default Credentials 822


Warnings

Alarm Email 1 Fail

Alarm Type	Other
Alarmlist message	Alarm Email 1 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm email to email address which is adjusted in setpoint Email Address 1 (page 481) and email wasn't send.

O back to List of alarms level 1

Alarm Email 2 Fail

Alarm Type	Other
Alarmlist message	Alarm Email 2 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm email to email address which is adjusted in setpoint Email Address 2 (page 481) and email wasn't send.

O back to List of alarms level 1

Alarm Email 3 Fail

Alarm Type	Other
Alarmlist message	Alarm Email 3 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm email to email address which is adjusted in setpoint Email Address 3 (page 481) and email wasn't send.

O back to List of alarms level 1

Alarm Email 4 Fail

Alarm Type	Other
Alarmlist message	Alarm Email 4 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm email to email address which is adjusted in setpoint Email Address 4 (page 482) and email wasn't send.



Alarm SMS 1 Fail

Alarm Type	Other
Alarmlist message	Alarm SMS 1 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm SMS to telephone number which is adjusted in setpoint Telephone Number 1 (page 486) and SMS wasn't send.

O back to List of alarms level 1

Alarm SMS 2 Fail

Alarm Type	Other
Alarmlist message	Alarm SMS 2 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm SMS to telephone number which is adjusted in setpoint Telephone Number 2 (page 487) and SMS wasn't send.

O back to List of alarms level 1

Alarm SMS 3 Fail

Alarm Type	Other
Alarmlist message	Alarm SMS 3 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm SMS to telephone number which is adjusted in setpoint Telephone Number 3 (page 487) and SMS wasn't send.

O back to List of alarms level 1

Alarm SMS 4 Fail

Alarm Type	Other
Alarmlist message	Alarm SMS 4 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an alarm SMS to telephone number which is adjusted in setpoint Telephone Number 4 (page 488) and SMS wasn't send.



Battery Charger Fail

Alarm Type	Warning
Alarmlist message	Battery Charge Fail
Alarm evaluated	Mains is OK
Related applications	MINT, SPtM
Description	This alarm is activated when logical binary input BATTERY CHARGER (PAGE 616) is active.

O back to List of alarms level 1

Wrn Battery Voltage

Alarm Type	Warning
Alarmlist message	Wrn Battery Voltage
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm informs the operator that the controller supply voltage is out of limits. The following setpoints are related to it:
	Battery Undervoltage (page 301)
	Battery Overvoltage (page 301)
	Battery <> Voltage Delay (page 302)

O back to List of alarms level 1

Bus CCW Rotation

Alarm Type	Warning
Alarmlist message	Bus CCW Rotation
Alarm evaluated	All the time
Related applications	MINT
Description	The controller detects phase sequence on bus voltage terminals. This protection is important after controller installation to avoid wrong voltage phase connection.

O back to List of alarms level 1

Default Credentials

Alarm Type	Warning
Alarmlist message	Default Credentials
Alarm evaluated	Default password / access code are used
Related applications	MINT, SPtM
Description	The alarm is issued, if the factory default password and/or access code are used and engine is running. Factory default password and access code are "0".
	IMPORTANT: Change password and/or access code to be able to operate a genset! Sd Default Credentials alarm is issued, if the default credentials are used and engine is not running!



ECU Wait To Start

Alarm Type	Warning
Alarmlist message	ECU Wait To Start
Alarm evaluated	Only when ECU is connected
Related applications	MINT, SPtM
Description	This alarm is activated when ECU send information that ECU Wait To Start lamp is activated. LBO ALARM (PAGE 695) is not activated, after deactivation of lamp, alarm automatically disappear.

O back to List of alarms level 1

Wrn Emergency Droop Active

Alarm Type	Warning
Alarmlist message	Wrn Emergency Droop Active
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm is issued when Emergency Droop regulation as active.

O back to List of alarms level 1

Event Email 1 Fail

Alarm Type	Other
Alarmlist message	Event Email 1 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event email to email address which is adjusted in setpoint Email Address 1 (page 481) and email wasn't send.

O back to List of alarms level 1

Event Email 2 Fail

Alarm Type	Other
Alarmlist message	Event Email 2 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event email to email address which is adjusted in setpoint Email Address 2 (page 481) and email wasn't send.

O back to List of alarms level 1

Event Email 3 Fail

Alarm Type	Other
Alarmlist message	Event Email 2 Fail
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event email to email address which is adjusted in setpoint Email Address 3 (page 481) and email wasn't send.

Event Email 4 Fail

Alarm Type	Other
Alarmlist message	Event Email 4 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event email to email address which is adjusted in setpoint Email Address 4 (page 482) and email wasn't send.

O back to List of alarms level 1

Event SMS 1 Fail

Alarm Type	Other
Alarmlist message	Event SMS 1 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event SMS to telephone number which is adjusted in setpoint Telephone Number 1 (page 486) and SMS wasn't send.

O back to List of alarms level 1

Event SMS 2 Fail

Alarm Type	Other
Alarmlist message	Event SMS 2 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event SMS to telephone number which is adjusted in setpoint Telephone Number 2 (page 487) and SMS wasn't send.

O back to List of alarms level 1

Event SMS 3 Fail

Alarm Type	Other
Alarmlist message	Event SMS 3 Fail
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event SMS to telephone number which is adjusted in setpoint Telephone Number 3 (page 487) and SMS wasn't send.

Event SMS 4 Fail

Alarm Type	Other
Alarmlist message	Event SMS 4 Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm indicates that there was a request to send an event SMS to telephone number which is adjusted in setpoint Telephone Number 4 (page 488) and SMS wasn't send.

O back to List of alarms level 1

Generator CCW Rotation

Alarm Type	Warning
Alarmlist message	Generator CCW Rotation
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The controller detects phase sequence on generator voltage terminals. This protection is important after controller installation to avoid wrong voltage phase connection.

O back to List of alarms level 1

Mains CCW Rotation

Alarm Type	Warning
Alarmlist message	Mains CCW Rotation
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The controller detects phase sequence on mains voltage terminals. This protection is important after controller installation to avoid wrong voltage phase connection.

O back to List of alarms level 1

Rental Timer 1 Elapsed

Alarm Type	Warning
Alarmlist message	Rental Timer 1 Elapsed
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm is activated when Rental Timer 1 (page 441) elapses.



Rental Timer 2 Elapsed

Alarm Type	Warning
Alarmlist message	Rental Timer 2 Elapsed
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm is activated when Rental Timer 2 (page 443) elapses.

O back to List of alarms level 1

Rental Timer Block Start

Alarm Type	Other
Alarmlist message	Rental Timer Block Start
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Alarm is active when there is start command and Rental Timer 1 (page 441) or Rental Timer 2 (page 443) elapsed.

O back to List of alarms level 1

Soft Transfer Fail

Alarm Type	Warning
Alarmlist message	Soft Transfer Fail
Alarm evaluated	During transition of load
Related applications	MINT, SPtM
Description	This alarm is issued when the unloading was not successful (Load Ramp (page 353) + 10 % gets elapsed).

O back to List of alarms level 1

Speed Regulation Limit

Alarm Type	Warning
Alarmlist message	Speed Regulation Limit
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	This alarm is issued when speed governor output (Speed control outputs (page 105)) stays close to one of the limit values for more than 2 seconds.

O back to List of alarms level 1

Voltage Regulation Limit

Alarm Type	Warning
Alarmlist message	Voltage Regulation Limit
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	This alarm is issued when AVR output (Voltage control outputs (page 107)) stays close to one of the limit values for more than 2 seconds.



Wrn AIN Prot

Alarm Type	Warning
Alarmlist message	Wrn + Name of analog input
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that value the general analog protection is out of warning protection limit.

O back to List of alarms level 1

Wrn Charging Alternator Fail

Alarm Type	Warning
Alarmlist message	Wrn Charging Alternator Fail
Alarm evaluated	Engine running only
Related applications	MINT, SPtM
Description	This alarm is issued if the engine is running and the voltage on the D+ terminal is lower than 80% of the controller supply voltage. This alarm works similar to the red "battery" alarm indicator on a vehicle dashboard. The setpoint has to be in Charge Fail or Enabled position to enable this alarm.

O back to List of alarms level 1

Wrn BadPwrCfg

Alarm Type	Warning
Alarmlist message	Wrn BadPwrCfg
Alarm evaluated	All the time
Related applications	MINT
Description	This alarm is issued when there is different power format on controller which are connected via CAN2.

O back to List of alarms level 1

Wrn Battery > Voltage

Alarm Type	Warning
Alarmlist message	All the time
Alarm evaluated	Wrn Battery > Voltage
Related applications	MINT, SPtM
Description	 This alarm informs the operator that the controller supply voltage is too high. The following setpoints are related to it: Battery Overvoltage (page 301) Battery <> Voltage Delay (page 302)



Wrn Battery < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Battery < Voltage
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This alarm informs the operator that the controller supply voltage is too low. The following setpoints are related to it: Battery Undervoltage (page 301) Battery <> Voltage Delay (page 302)

O back to List of alarms level 1

Wrn BIN Protection

Alarm Type	Warning
Alarmlist message	Wrn + Name of binary input
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Binary input also can be adjusted like alarm. In this case message in alarmlist contains prefix - Wrn and binary input name. This alarm occurs, when appropriate binary input is active.

O back to List of alarms level 1

Wrn Coolant Temp

Alarm Type	Warning
Alarmlist message	Wrn Coolant Temp
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the coolant temperature is higher than the temperature set in Coolant Temperature Wrn (page 289) setpoint.

O back to List of alarms level 1

Wrn Coolant Temperature Low

Alarm Type	Warning
Alarmlist message	Wrn Coolant Temperature Low
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the coolant temperature is lower than the temperature set in Coolant Temperature Low Wrn (page 295) setpoint.



Wrn ECU Communication Fail

Alarm Type	Warning
Alarmlist message	Wrn ECU Communication Fail
Alarm evaluated	With configured LBO ECU POWER RELAY (PAGE 712) - only when this LBO is active Without configured LBO ECU POWER RELAY (PAGE 712) - all the time
Related applications	MINT, SPtM
Description	This alarm occurs when an ECU is configured, but the communication with the ECU is not established or has dropped out.

O back to List of alarms level 1

ECU Red Lamp

Alarm Type	Other
Alarmlist message	ECU Red Lamp
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when an red ECU alarm is logged in Alarm List.
	Note: This lamp can be ignored during prestart phase. Use InteliConfig to enable this function.

O back to List of alarms level 1

ECU Yellow Lamp

Alarm Type	Other
Alarmlist message	ECU Yellow Lamp
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when an yellow ECU alarm is logged in Alarm List.
	Note: This lamp can be ignored during prestart phase. Use InteliConfig to enable this function.

O back to List of alarms level 1

Wrn Fence 1 Alarm

Alarm Type	Warning
Alarmlist message	Wrn Fence 1 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it:
	Geo-Fencing (page 448)
	Fence 1 Protection (page 449)
	Fence Radius 1 (page 447)



Wrn Fence 2 Alarm

Alarm Type	Warning
Alarmlist message	Wrn Fence 2 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it: Geo-Fencing (page 448)
	 Fence 2 Protection (page 450) Fence Radius 2 (page 447)

O back to List of alarms level 1

Wrn Fuel Level

Alarm Type	Warning
Alarmlist message	Wm Fuel Level
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the fuel level is lower than the level set in Fuel Level Wrn (page 296) setpoint.

O back to List of alarms level 1

Wrn Fuel Theft

Alarm Type	Warning
Alarmlist message	Wrn Fuel Theft
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when the fuel level value measured at relevant AI (Fuel Level) drops faster than is the limit adjusted by setpoint Maximal Fuel Drop (page 298) .

O back to List of alarms level 1

Wrn GCB Fail

Alarm Type	Warning
Alarmlist message	Wrn GCB Fail
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	 This alarm will occur when the GCB FEEDBACK (PAGE 668) input does not match the expected position given by the GCB CLOSE/OPEN (PAGE 716) output. It stays active until the mismatch between the output and feedback persists. If there was no command issued by the controller and the breaker (feedback) changes suddenly the position itself, the alarm will be issued immediately.
	The alarm will be also issued if the breaker does not respond to an open or
	close command within 2 seconds.

Wrn Generator L1 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L1 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phase 1. The following setpoints are related to it: Generator Overvoltage Wrn (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L1 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phase 1. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L1L2 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L1L2 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 1 and 2. The following setpoints are related to it: Generator Overvoltage Wrn (page 308) Generator <> Voltage Delay (page 309)



Wrn Generator L1L2 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L1L2 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 1 and 2. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L2 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L2 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phase 2. The following setpoints are related to it: Generator Overvoltage Wrn (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L2 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L2 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phase 2. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L2L3 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L2L3 > Voltage
Alarm evaluated	Generator excited only



Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase to phase voltage between phases 2 and 3. The following setpoints are related to it:
	Generator Overvoltage Wrn (page 308)
	Generator <> Voltage Delay (page 309)

Wrn Generator L2L3 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L2L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 2 and 3. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L3 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L3 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phase 3. The following setpoints are related to it: Generator Overvoltage Wrn (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L3 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phase 3. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)



Wrn Generator L3L1 > Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L3L1 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 3 and 1. The following setpoints are related to it: Generator Overvoltage Wrn (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator L3L1 < Voltage

Alarm Type	Warning
Alarmlist message	Wrn Generator L3L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 3 and 1. The following setpoints are related to it: Generator Undervoltage Wrn (page 309) Generator <> Voltage Delay (page 309)

O back to List of alarms level 1

Wrn Generator > Frequency

Alarm Type	Warning
Alarmlist message	Wrn Generator > Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Overfrequency Wrn (page 310) Generator <> Frequency Delay (page 311)

O back to List of alarms level 1

Wrn Generator < Frequency

Alarm Type	Warning
Alarmlist message	Wrn Generator < Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Underfrequency Wrn (page 311) Generator <> Frequency Delay (page 311)



Wrn Check DPF Status

Alarm Type	Warning
Alarmlist message	Wrn Check DPF Status
Alarm evaluated	When ECU is configured
Related applications	MINT, SPtM
Description	This alarm occurs when ECU send alarm message about Tier IV protection.
	Note: Tier IV protection have to be supported by ECU.

O back to List of alarms level 1

Wrn Maintenance 1

Alarm Type	Warning
Alarmlist message	Wrn Maintenance 1
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Adjust the setpoint Maintenance Timer 1 (page 302) to the interval of the next maintenance check. The value of the setpoint will count down while the engine is running and if reaches zero, this alarm will be issued. The alarm message will remain in the alarm list (even if the controller is switched off and on again) until the setpoint is re-adjusted to a positive value.

O back to List of alarms level 1

Wrn Maintenance 2

Alarm Type	Warning
Alarmlist message	Wrn Maintenance 2
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Adjust the setpoint Maintenance Timer 2 (page 303) to the interval of the next maintenance check. The value of the setpoint will count down while the engine is running and if reaches zero, this alarm will be issued. The alarm message will remain in the alarm list (even if the controller is switched off and on again) until the setpoint is re-adjusted to a positive value.



Wrn Maintenance 3

Alarm Type	Warning
Alarmlist message	Wrn Maintenance 3
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Adjust the setpoint Maintenance Timer 3 (page 303) to the interval of the next maintenance check. The value of the setpoint will count down while the engine is running and if reaches zero, this alarm will be issued. The alarm message will remain in the alarm list (even if the controller is switched off and on again) until the setpoint is re-adjusted to a positive value.

O back to List of alarms level 1

Wrn MCB Fail

Alarm Type	Warning
Alarmlist message	Wm MCB Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This alarm will occur when the MCB FEEDBACK (PAGE 672) input does not match the expected position given by the MCB CLOSE/OPEN (PAGE 726) output. It stays active until the mismatch between the output and feedback disappears. If there was no command issued by the controller and the breaker (feedback) changes suddenly the position itself, the alarm will be issued immediately. Self-opening of the breaker is not considered a fault and if all mains values are within limits, the command to reclose the breaker is issued after delay given by the setpoint Mains Return Delay (page 319) has elapsed. The alarm will be also issued, if the breaker does not respond to the close command within 2 seconds. After this period has elapsed the output MCB Close/Open is deactivated again and the next attempt to close the breaker will occur first after the alarm is reset. The alarm will be also issued if the breaker does not respond to the open command within 2 seconds. The output MCB Close/Open will stay deactivated. Closing of GCB is blocked until this alarm becomes inactive.

O back to List of alarms level 1

Wrn Oil Pressure

Alarm Type	Warning
Alarmlist message	Wrn Oil Pressure
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	This alarm indicates that the oil pressure is lower than the pressure set in Oil Pressure Wrn (page 287) setpoint.



Wrn Overload

Alarm Type	Warning
Alarmlist message	Wrn Overload
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 The alarm is issued when the gen-setmains power is over the limit for time period longer than the delay. The following setpoints are related to it: Overload Wrn (page 304) adjusts the overload limit. Overload Delay (page 304) Overload Del adjusts the delay.

O back to List of alarms level 1

Wrn Override All Sd

Alarm Type	Warning
Alarmlist message	Override All Sd
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when binary input SD OVERRIDE (PAGE 680) is activated.

O back to List of alarms level 1

Wrn Rental Timer 1

Alarm Type	Warning
Alarmlist message	Wrn Rental Timer 1
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs xx hours before Rental Timer 1 (page 441) elapsed. Hours are adjusted by setpoint Rental Timer 1 Wrn (page 443) .

O back to List of alarms level 1

Wrn Rental Timer 2

Alarm Type	Warning
Alarmlist message	Wrn Rental Timer 2
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs xx hours before Rental Timer 2 (page 443) elapsed. Hours are adjusted by setpoint Rental Timer 2 Wrn (page 445) .

O back to List of alarms level 1

Wrn Reverse Synchro Fail

Alarm Type	Warning
Alarmlist message	Wrn Reverse Synchro Fail
Alarm evaluated	During synchronization



Related applications	
Description	This alarm is issued when gen-set is synchronizing to the mains/bus via MCB and Synchronization Timeout (page 358) gets elapsed.

Wrn Stop Fail

Alarm Type	Warning
Alarmlist message	Wrn Stop Fail
Alarm evaluated	While the engine shall be stopped
Related applications	MINT, SPtM
Description	This alarm occurs if the gen-set shall be stopped, but some symptom indicates that it is not stopped. The period when the gen-set shall be stopped begins after the FUEL SOLENOID (PAGE 715) has been switched off and time delay Stop Time (page 281) has elapsed and lasts for the entire time the FUEL SOLENOID (PAGE 715) or STARTER (PAGE 737) are off.

O back to List of alarms level 1

Other type

ATT Filter Lamp

Alarm Type	Alarm indication
Alarmlist message	Aftertreatment
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Indicates the Aftertreatment filter needs to be regenerated.



ATT HEST Lamp

Alarm Type	Alarm indication
Alarmlist message	Aftertreatment
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Indicates High exhaust system temperature.

O back to List of alarms level 1

ATT SCR Error Lamp

Alarm Type	Alarm indication
Alarmlist message	Aftertreatment
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Indicates SCR system problems.

O back to List of alarms level 1

ATT DEF Level Lamp

Alarm Type	Alarm indication
Alarmlist message	Aftertreatment
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Indicates DEF fluid low level.

O back to List of alarms level 1

ATT Inhibited Lamp

Alarm Type	Alarm indication
Alarmlist message	Aftertreatment
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Indicates Aftertreatment regeneration is inhibited.

O back to List of alarms level 1

Dead Bus GCB Blocked

Alarm Type	Alarm indication
Alarmlist message	Dead Bus GCB Blocked
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm is issued when controller is in AUTO mode and Droop operation is active.



EM(A) - a message lost

Alarm Type	Other
Alarmlist message	EM(A) - a message lost
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with communication between controller and module in slot.

O back to List of alarms level 1

EM(A) - configuration mistake

Alarm Type	Other
Alarmlist message	EM(A) - configuration mistake
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with configuration of binary input or output of module in slot.

O back to List of alarms level 1

EM(A) - insufficient

Alarm Type	Other
Alarmlist message	EM(A) - insufficient
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that module does not support all required features.

O back to List of alarms level 1

EM(A) - missing or damaged

Alarm Type	Other
Alarmlist message	EM(A) - missing or damaged
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with communication with module in slot (in first 5 second there was no communication and module is configured in slot).



EM(B) - a message lost

Alarm Type	Other
Alarmlist message	EM(B) - a message lost
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with communication between controller and module in slot.

O back to List of alarms level 1

EM(B) - configuration mistake

Alarm Type	Other
Alarmlist message	EM(B) - configuration mistake
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with configuration of binary input or output of module in slot.

O back to List of alarms level 1

EM(B) - insufficient

Alarm Type	Other
Alarmlist message	EM(B) - insufficient
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that module does not support all required features.

O back to List of alarms level 1

EM(B) - missing or damaged

Alarm Type	Other
Alarmlist message	EM(B) - missing or damaged
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with communication with module in slot (in first 5 second there was no communication and module is configured in slot).

O back to List of alarms level 1

Generator CCW Rotation

Alarm Type	Warning
Alarmlist message	Generator CCW Rotation
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	The controller detects phase sequence on generator voltage terminals. This protection is important after controller installation to avoid wrong voltage phase.
	connection. There is a fixed defined phase sequence in InteliGen 500 controller:
	T35 = N, T36 = L1, T37 = L2 and T38 = L3. When the phases are connected in a
	different order, alarms are detected. This alarm prevent circuit breaker closing.

Mains CCW Rotation

Alarm Type	Alarm indication
Alarmlist message	Mains CCW Rotation
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The controller detects phase sequence on mains voltage terminals. This protection is important after controller installation to avoid wrong voltage phase connection. There is a fixed defined phase sequence in InteliGen 500 controller: $T39 = N$, $T40 =$ L1, T41 = L2 and T42 = L3. When the phases are connected in a different order, alarms are detected. This alarm prevent circuit breaker closing.

O back to List of alarms level 1

Manual Restore

Alarm Type	Alarm indication
Alarmlist message	Manual Restore
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Alarm is activated when controller is in AUTO mode, Return From Island (page 324) setpoint is set to manual, load is on gen-set a mains has returned.

O back to List of alarms level 1

Module(slotA) - comm. outage

Alarm Type	Other
Alarmlist message	Module(slotA) - comm. outage
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that there is a problem with communication between controller and module in slot.



Module(slotA) - false module

Alarm Type	Other	
Alarmlist message	Module(slotA) - fake module	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that false module is inserted in slot.	

O back to List of alarms level 1

Module(slotA) - unattended

Alarm Type	Other	
Alarmlist message	Module(slotA) - unattended	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that two same communication modules are inserted in slots and one of them will be inactive.	

O back to List of alarms level 1

Module(slotA) - unexpected

Alarm Type	Other	
Alarmlist message	Module(slotA) - unexpected	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that in slot is inserted different module than which is configured or the module is unconfigured and has to be configured for proper function.	

O back to List of alarms level 1

Module(slotA) - unknown module

Alarm Type	Other	
Alarmlist message	Module(slotA) - unknown module	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that unknown module is inserted in slot.	



Module(slotB) - comm. outage

Alarm Type	Other	
Alarmlist message	Module(slotB) - comm. outage	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that there is a problem with communication between controller and module in slot.	

O back to List of alarms level 1

Module(slotB) - false module

Alarm Type	Other	
Alarmlist message	Module(slotB) - fake module	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that false module is inserted in slot.	

O back to List of alarms level 1

Module(slotB) - unattended

Alarm Type	Other	
Alarmlist message	Module(slotB) - unattended	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that two same communication modules are inserted in slots and one of them will be inactive.	

O back to List of alarms level 1

Module(slotB) - unexpected

Alarm Type	Other	
Alarmlist message	Module(slotB) - unexpected	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that in slot is inserted different module than which is configured or the module is unconfigured and has to be configured for proper function.	



Module(slotB) - unknown module

Alarm Type	Other	
Alarmlist message	Module(slotB) - unknown module	
Alarm evaluated	All the time	
Related applications	MINT, SPtM	
Description	This alarm indicates that unknown module is inserted in slot.	

O back to List of alarms level 1

Wrn Fuel Transfer Failed

Alarm Type	Warning	
Alarmlist message	Wrn Fuel Transfer Failed	
Alarm evaluated	When FUEL PUMP (PAGE 715) is active	
Related applications	MINT, SPtM	
Description	This alarm will occur when there is no increase of fuel level when FUEL PUMP (PAGE 715) is active.	

O back to List of alarms level 1

Wrn Transferring Fuel

Alarm Type	Warning	
Alarmlist message	Transferring Fuel	
Alarm evaluated	When FUEL PUMP (PAGE 715) is active	
Related applications	MINT, SPtM	
Description	This alarm will occur when FUEL PUMP (PAGE 715) is active.	

O back to List of alarms level 1

9.2.2 Alarms level 2

Shutdown	
Other type	

For full list of Alarms level 2 go to List of alarms level 2 (page 819).

What alarms level 2 are:

The level 2 level alarm indicates that a critical level of the respective value or parameter has been reached. For more information see Alarm types - Level 2 on page 113.



List of alarms level 2

Emergency Stop 820
E-Stop820
Sd AIN Protec820
Sd Battery Flat
Sd BIN Protection821
Sd Coolant Temp821
Sd Current Unbalance 821
Sd Earth Fault Current822
Sd ECU Communication
Fail822
Sd Fence 1 Alarm823
Sd Fence 2 Alarm823
Sd Fuel Level823
Sd GCB Fail823
Sd Generator L1 > Voltage 824
Sd Generator L1 < Voltage 824
Sd Generator L1L2 >
Voltage824
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Voltage825
Sd Generator L2 > Voltage 825
Sd Generator L2 < Voltage 825
Sd Generator L2L3 >
Voltage825
Sd Generator L2L3 <
Voltage826
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Shutdown

Default Credentials

Alarm Type	Shutdown
Alarmlist message	Default Credentials
Alarm evaluated	Default password / access code are used
Related applications	MINT, SPtM
Description	The alarm is issued, if the factory default password and/or access code are used and engine is running. Factory default password and access code are "0".
	IMPORTANT: Change password and/or access code to be able to operate a genset!

O back to List of alarms level 1

Emergency Stop

Alarm Type	Shutdown
Alarmlist message	Emergency Stop
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Alarm is activated when binary input EMERGENCY STOP (PAGE 665) is activated. The gen-set shuts down in the moment the input is activated and starting is blocked until the input is deactivated and fault reset is pressed.
	Note: Use red emergency button placed on the switchboard door and connect it to a binary input of the controller. Then configure the function Emergency Stop to this binary input. It is recommended to use NC contact of the button.
	Note: The MCB control is not affected by this alarm.

O back to List of alarms level 2

E-Stop

Alarm Type	Shutdown
Alarmlist message	E-Stop
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Alarm is activated when dedicated E-Stop input is activated. The gen-set shuts down in the moment the input is activated and starting is blocked until the input is deactivated and fault reset is pressed.

O back to List of alarms level 2

Sd AIN Protec

Alarm Type	Sd
Alarmlist message	Sd + Name of analog input
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	This alarm indicates that value the general analog protection is out of shutdown protection limit.

Sd Battery Flat

Alarm Type	Shutdown
Alarmlist message	Sd Battery Flat
Alarm evaluated	During cranking
Related applications	MINT, SPtM
Description	This alarm will be issued if the controller was reset during cranking of the gen-set. If this situation occurs, the controller supposes the starting battery is so exhausted that its voltage drops so low when starter motor is energized that it causes controller reset.

O back to List of alarms level 2

Sd BIN Protection

Alarm Type	Shutdown
Alarmlist message	Sd + Name of binary input
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Binary input also can be adjusted like alarm. In this case message in alarmlist contains prefix - Sd and binary input name. This alarm occurs, when appropriate binary input is active.

O back to List of alarms level 2

Sd Coolant Temp

Alarm Type	Shutdown
Alarmlist message	Sd Coolant Temp
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the coolant temperature is higher than the temperature set in Coolant Temperature Sd (page 290) setpoint.

O back to List of alarms level 2

Sd Current Unbalance

Alarm Type	Shutdown
Alarmlist message	Sd Current Unbalance
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	This alarm evaluates the unbalance of the phase currents, i.e. the difference between highest and lowest phase current at any given time. The following setpoints are related to it:
	Current Unbalance BOC (page 307) adjusts the maximum allowed difference between the highest and lowest phase current at any given time.
	Current Unbalance BOC Delay (page 307) adjusts the alarm delay.

Default Credentials

Alarm Type	Shutdown
Alarmlist message	Default Credentials
Alarm evaluated	Default password / access code are used
Related applications	MINT, SPtM
Description	The alarm is issued, if the factory default password and/or access code are used and engine is running. Factory default password and access code are "0".
	IMPORTANT: Change password and/or access code to be able to operate a genset!

O back to List of alarms level 1

Sd Earth Fault Current

Alarm Type	Shutdown
Alarmlist message	Sd Earth Fault Current
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the value of earth fault current is higher than adjusted limit. The following setpoints are related to it:
	Earth Fault Sd (page 491) adjusts the maximum allowed earth fault current.
	Earth Fault Delay (page 490) adjusts the alarm delay.

O back to List of alarms level 2

Sd ECU Communication Fail

Alarm Type	Shutdown
Alarmlist message	Sd ECU Communication Fail
Alarm evaluated	With configured LBO ECU POWER RELAY (PAGE 712) - only when this LBO is active Without configured LBO ECU POWER RELAY (PAGE 712) - all the time
Related applications	MINT, SPtM
Description	This alarm occurs when an ECU is configured, but the communication with the ECU is not established or has dropped out.



Sd Fence 1 Alarm

Alarm Type	Shutdown
Alarmlist message	Sd Fence 1 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it:
	Geo-Fencing (page 448)
	Fence 1 Protection (page 449)
	Fence Radius 1 (page 447)

O back to List of alarms level 2

Sd Fence 2 Alarm

Alarm Type	Shutdown
Alarmlist message	Sd Fence 2 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it:
	Geo-Fencing (page 448)
	Fence 1 Protection (page 449)
	Fence Radius 1 (page 447)

O back to List of alarms level 2

Sd Fuel Level

Alarm Type	Shutdown
Alarmlist message	Sd Fuel Level
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the fuel level is lower than the level set in Fuel Level Sd (page 296) setpoint.

O back to List of alarms level 2

Sd GCB Fail

Alarm Type	Shutdown
Alarmlist message	Sd GCB Fail
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	 This alarm will occur when the GCB FEEDBACK (PAGE 668) input does not match the expected position given by the GCB CLOSE/OPEN (PAGE 716) output. It stays active until the mismatch between the output and feedback persists. If there was no command issued by the controller and the breaker (feedback) changes suddenly the position itself, the alarm will be issued immediately.
	The alarm will be also issued if the breaker does not respond to an open or close command within 5 seconds.

Sd Generator L1 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L1 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phase 1. The following setpoints are related to it: Generator Overvoltage Sd (page 307)
	Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L1 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase voltage in phases 1. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L1L2 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L1L2 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 1 and 2. The following setpoints are related to it: Generator Overvoltage Sd (page 307) Generator <> Voltage Delay (page 309)



Sd Generator L1L2 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L1L2 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 1 and 2. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L2 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L2 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phase 2. The following setpoints are related to it: Generator Overvoltage Sd (page 307)
	 Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L2 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L2 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phases 2. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L2L3 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L2L3 > Voltage
Alarm evaluated	Generator excited only



Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase to phase voltage between phases 2 and 3. The following setpoints are related to it:
	Generator Overvoltage Sd (page 307)
	Generator <> Voltage Delay (page 309)

Sd Generator L2L3 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L2L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 2 and 3. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L3 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L3 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phase 3. The following setpoints are related to it: Generator Overvoltage Sd (page 307) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L3 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phases 3. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)



Sd Generator L3L1 > Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L3L1 > Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 3 and 1. The following setpoints are related to it: Generator Overvoltage Sd (page 307) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator L3L1 < Voltage

Alarm Type	Shutdown
Alarmlist message	Sd Generator L3L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 3 and 1. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

Sd Generator > Frequency

Alarm Type	Shutdown
Alarmlist message	Sd Generator > Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Overfrequency BOC (page 310) Generator <> Frequency Delay (page 311)

O back to List of alarms level 2

Sd Generator < Frequency

Alarm Type	Shutdown
Alarmlist message	Sd Generator < Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Underfrequency BOC (page 311) Generator <> Frequency Delay (page 311)

ComAp >

O back to List of alarms level 2

Sd Generator Voltage Unbalance Ph-Ph

Alarm Type	Shutdown
Alarmlist message	Sd Generator Voltage Unbalance Ph-Ph
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the unbalance of the phase to phase voltage, i.e. the difference between highest and lowest phase to phase voltage at any given time. The following setpoints are related to it: Voltage Unbalance BOC (page 309) adjusts the maximum allowed difference between the highest and lowest phase voltage at any given time. Bus Voltage Unbalance BOC Delay (page 310) adjusts the alarm delay.

O back to List of alarms level 2

Sd Generator Voltage Unbalance Ph-N

Alarm Type	Shutdown
Alarmlist message	Sd Generator Voltage Unbalance Ph-N
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the unbalance of the phase voltage, i.e. the difference between highest and lowest phase voltage at any given time. The following setpoints are related to it: Voltage Unbalance BOC (page 309) adjusts the maximum allowed difference between the highest and lowest phase voltage at any given time. Bus Voltage Unbalance BOC Delay (page 310) adjusts the alarm delay.

O back to List of alarms level 2

Sd Oil Pressure

Alarm Type	Shutdown
Alarmlist message	Sd Oil Pressure
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	This alarm indicates that the oil pressure is lover than the pressure set in Oil Pressure Sd (page 288) setpoint.

O back to List of alarms level 2

Sd Overload

Alarm Type	Shutdown
Alarmlist message	Sd Overload
Alarm evaluated	All the time


Related applications	MINT, SPtM
Description	The alarm is issued when the gen-set power is over the limit for time period longer than the delay. The behavior of the overload alarm is adjusted by the following setpoints:
	Overload BOC (page 304) adjusts the overload limit.
	Overload Delay (page 304) adjusts the delay

O back to List of alarms level 2

Sd Overspeed

Alarm Type	Shutdown
Alarmlist message	Sd Overspeed
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This alarm occurs immediately when the engine speed has exceeded the limit. The behavior of the overspeed alarm is adjusted by the following setpoints: Overspeed Sd (page 285) adjust the overspeed limit

O back to List of alarms level 2

Sd RPM Measurement Fail

Alarm Type	Shutdown
Alarmlist message	Sd RPM Measurement Fail
Alarm evaluated	During cranking
Related applications	MINT, SPtM
Description	The alarm is issued if the engine speed has not exceeded the Starting RPM (page 273) within the Maximum Cranking Time (page 272) , although some of additional running engine indication sources indicate that the engine has started.

O back to List of alarms level 2

Sd Short Circuit

Alarm Type	Shutdown
Alarmlist message	Sd Short Circuit
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This is a fast overcurrent protection. The following setpoints are related to this alarm: Short Circuit BOC (page 305) adjusts the short current limit Short Circuit BOC MPR Delay (page 305) adjusts the delay in fine steps

O back to List of alarms level 2



Sd Start Fail

Alarm Type	Shutdown
Alarmlist message	Sd Start Fail
Alarm evaluated	When the gen-set is being started
Related applications	MINT, SPtM
Description	 This alarm will be issued after all attempts to start the gen-set have run out but the gen-set did not start. The following setpoints are related to this alarm: Cranking Attempts (page 271) adjust the number of attempts

O back to List of alarms level 2

Sd Underspeed

Alarm Type	Shutdown
Alarmlist message	Sd Underspeed
Alarm evaluated	Engine running only
Related applications	MINT, SPtM
Description	This alarm will be issued when the gen-set is running and then stops by itself, i.e. the RPM drops under the value of setpoint Starting RPM (page 273) .
	The underspeed alarm starts to be evaluated after successful gen-set start and is being evaluated for the entire time that the fuel solenoid is on.

O back to List of alarms level 2

Other type

BOC AIN Prot

Alarm Type	BOC
Alarmlist message	BOC + Name of analog input
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the value of general analog protection is out of BOC protection limit.

O back to List of alarms level 2

BOC BIN Protection

Alarm Type	BOC
Alarmlist message	BOC + Name of binary input
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	Binary input also can be adjusted like alarm. In this case message in alarmlist contains prefix - BOCMPRBOR and binary input name. This alarm occurs, when appropriate binary input is active.

O back to List of alarms level 2



BOC Coolant Temp

Alarm Type	BOC
Alarmlist message	BOC Coolant Temperature
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the coolant temperature is higher than the temperature set in Coolant Temperature Sd (page 290) setpoint.

O back to List of alarms level 2

BOC Current Unbalance

Alarm Type	BOC
Alarmlist message	BOC Current Unbalance
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This alarm evaluates the unbalance of the phase currents, i.e. the difference between highest and lowest phase current at any given time. The following setpoints are related to it: Current Unbalance BOC (page 307) adjusts the maximum allowed difference between the highest and lowest phase current at any given time. Current Unbalance BOC Delay (page 307) adjusts the alarm delay.

O back to List of alarms level 2

BOC Excitation Loss

Alarm Type	BOC
Alarmlist message	BOC Excitation Loss
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	The alarm is issued when the level of reactive power (-kVAr) gets under limit given by setpoint Excitation Loss Level (page 312) for time longer then the value of setpoint Excitation Loss Delay (page 313) .

O back to List of alarms level 2

BOC Fence 1 Alarm

Alarm Type	BOC
Alarmlist message	BOC Fence 1 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it:
Description	Geo-Fencing (page 448)
	Fence 1 Protection (page 449)
	Fence Radius 1 (page 447)



O back to List of alarms level 2

BOC Fence 2 Alarm

Alarm Type	BOC
Alarmlist message	BOC Fence 2 Alarm
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm evaluates the GPS position of gen-set. The following setpoint are related to it:
	Geo-Fencing (page 448)
	Fence 1 Protection (page 449)
	Fence Radius 1 (page 447)

O back to List of alarms level 2

BOC Fuel Level

Alarm Type	BOC
Alarmlist message	BOC Fuel Level
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the fuel level is lower than the level set level in Fuel Level Sd (page 296) setpoint.

O back to List of alarms level 2

BOC Generator L1 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phases 1. The following setpoints are related to it:
	Generator Undervoltage BOC (page 308)
	Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

BOC Generator L1L2 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L1L2 < Voltage
Alarm evaluated	Generator excited only



Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase to phase voltage between phases 1 and 2. The following setpoints are related to it:
	Generator Undervoltage BOC (page 308)
	Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

BOC Generator L2 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L2 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phases 2. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

BOC Generator L2L3 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L2L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 2 and 3. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

BOC Generator L3 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L3 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	This alarm evaluates the generator phase voltage in phases 3. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2



BOC Generator L3L1 < Voltage

Alarm Type	BOC
Alarmlist message	BOC Generator L3L1 < Voltage
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator phase to phase voltage between phases 3 and 1. The following setpoints are related to it: Generator Undervoltage BOC (page 308) Generator <> Voltage Delay (page 309)

O back to List of alarms level 2

BOC Generator > Frequency

Alarm Type	BOC
Alarmlist message	BOC Generator > Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Overfrequency BOC (page 310) Constant Constant Constant Palaty (page 311)

O back to List of alarms level 2

BOC Generator < Frequency

Alarm Type	BOC
Alarmlist message	BOC Generator < Frequency
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the generator frequency in the phase L1. The following setpoints are related to it: Generator Underfrequency BOC (page 311) Generator <> Frequency Delay (page 311)

O back to List of alarms level 2

BOC Gen Voltage Unbalance Ph-Ph

Alarm Type	BOC
Alarmlist message	BOC Gen Voltage Unbalance ph-ph
Alarm evaluated	Generator excited only



Related applications	MINT, SPtM
	This alarm evaluates the unbalance of the phase to phase voltages, i.e. the difference between highest and lowest phase to phase voltage at any given time. The following setpoints are related to it:
Description	 Voltage Unbalance BOC (page 309) adjusts the maximum allowed difference between the highest and lowest phase voltage at any given time. Bus Voltage Unbalance BOC Delay (page 310) adjusts the alarm delay.

O back to List of alarms level 2

BOC Gen Voltage Unbalance Ph-N

Alarm Type	BOC
Alarmlist message	BOC Gen Voltage Unbalance ph-n
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	 This alarm evaluates the unbalance of the phase voltages, i.e. the difference between highest and lowest phase voltage at any given time. The following setpoints are related to it: Voltage Unbalance BOC (page 309) adjusts the maximum allowed difference between the highest and lowest phase voltage at any given time. Bus Voltage Unbalance BOC Delay (page 310) adjusts the alarm delay.

O back to List of alarms level 2

BOC NCB Fail

Alarm Type	BOC
Alarmlist message	BOC NCB Fail
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This alarm will occur when the NCB FEEDBACK (PAGE 673) input does not match the expected position given by the NCB CLOSE/OPEN (PAGE 730) output. It stays active until the mismatch between the output and feedback persists. If there was no command issued by the controller and the breaker
	(feedback) changes suddenly the position itself, the alarm will be issued immediately.
	The alarm will be also issued if the breaker does not respond to an open or close command within 5 seconds.

O back to List of alarms level 2

BOC Oil Pressure

Alarm Type	BOC
Alarmlist message	BOC Oil Pressure
Alarm evaluated	All the time



Related applications	MINT, SPtM
Description	This alarm indicates that the oil pressure is lover than the pressure set in Oil
	Pressure Sd (page 288) setpoint.

O back to List of alarms level 2

BOC Overcurrent IDMT

Alarm Type	Shutdown
Alarmlist message	Sd + Name of binary input
Alarm evaluated	Generator excited only
Related applications	MINT, SPtM
Description	The overcurrent alarm is based on IDMT principle. The reaction time of an IDMT alarm is not fixed, but depends on how much is the protected value (generator current in this case) above the limit (Nominal Current (page 243)). The higher is the overcurrent, the shorter the reaction time will be. All generator phases are evaluated.
	 IDMT Overcurrent Delay (page 306) defines the reaction time of the protection when the current is twice the amount of nominal value. Nominal Current (page 243) set the nominal current level, where the alarm starts to be evaluated. The reaction time is infinite at this point.

O back to List of alarms level 2

BOC Overload

Alarm Type	BOC
Alarmlist message	BOC Overload
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 The alarm is issued when the gen-set power is over the limit for time period longer than the delay. The behavior of the overload alarm is adjusted by the following setpoints: Overload BOC (page 304) adjusts the overload limit. Overload Delay (page 304) adjusts the delay

O back to List of alarms level 2

BOC Rental Timer

Alarm Type	Shutdown
Alarmlist message	BOC Rental Timer
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when Rental Timer BOC (page 445) elapses.

O back to List of alarms level 2



BOC Reverse Power

Alarm Type	BOC
Alarmlist message	BOC Reverse Power
Alarm evaluated	Gen-set is running
Related applications	MINT, SPtM
Description	The alarm is issued when the level of active power (-kW) gets under limit given by setpoint Reverse Power Level (page 312) for time longer then the value of setpoint Reverse Power Delay (page 312) .

O back to List of alarms level 2

BOC Short Circuit

Alarm Type	BOC
Alarmlist message	BOC Short Circuit
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	 This is a fast overcurrent protection. The following setpoints are related to this alarm: Short Circuit BOC (page 305) adjusts the short current limit Short Circuit BOC MPR Delay (page 305) adjusts the delay in fine steps

O back to List of alarms level 2

STP Bus Measurement Error

Alarm Type	STP
Alarmlist message	STP Bus Measurement Error
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	The alarm is issued when any controller on the CAN has closed its GCB, or MCB feedback is active and voltage on bus is within limits.

O back to List of alarms level 2

STP Synchronization Fail

Alarm Type	STP
Alarmlist message	STP Synchronization Fail
Alarm evaluated	During synchronization
Related applications	MINT, SPtM
Description	This alarm is issued when gen-set is synchronizing to the mains/bus via GCB and Synchronization Timeout (page 358) gets elapsed.

O back to List of alarms level 2

9.2.3 Fail sensor and other types

Fls Coolant Temp	
------------------	--

ComAp >

Fls Fuel Level	0
	0
Fls AIN Protect 2	0
Fls AIN Protect 3	1
Fls AIN Protect 4	1
Fls AIN Protect 5	1
Fls AIN Protect 6	1
Fls AIN Protect 7	2
Fls AIN Protect 8	2
Fls AIN Protect 9	2
Fls AIN Protect 10	2
Fls AIN Protect 11	3
Fls AIN Protect 12	3
Fls AIN Protect 13	3
Fls AIN Protect 14	3
Fls AIN Protect 15	4
Fls AIN Protect 16	4
-Is AIN Protect 17	4
Fls AIN Protect 18	4
Fls AIN Protect 19	5
Fls AIN Protect 20	5
Fls Oil Pressure	5

For full list of Fails sensor and other types of alarms go to List of fail sensor alarms (page 839).

What Fail sensor and other types of alarms are

If the measured resistance on an analog input exceeds the valid range, a sensor fail will be detected and a sensor fail message will appear in the Alarmlist. For more information **see Sensor fail detection (FLS) on page 114**.



List of fail sensor alarms

Fls Coolant Temp	840
Fls Fuel Level	840
FIs AIN Prot 1	840
FIs AIN Protect 2	840
FIs AIN Protect 3	841
FIs AIN Protect 4	841
FIs AIN Protect 5	841
FIs AIN Protect 6	841
FIs AIN Protect 7	842
FIs AIN Protect 8	842
FIs AIN Protect 9	842
FIs AIN Protect 10	842
FIs AIN Protect 11	843
Fls AIN Protect 12	843
FIs AIN Protect 13	843
FIs AIN Protect 14	843
FIs AIN Protect 15	844
Fls AIN Protect 16	844
FIs AIN Protect 17	844
FIs AIN Protect 18	844
FIs AIN Protect 19	845
FIs AIN Protect 20	845
Fls Oil Pressure	845



Fail sensor

Fis Coolant Temp

Alarm Type	Fls
Alarmlist message	Fls Coolant Temperature
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of coolant temperature is out of range or is missing.

back to List of fail sensor alarms

Fis Fuel Level

Alarm Type	Fls
Alarmlist message	Fls Fuel Level
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of fuel level is out of range or is missing.

• List of fail sensor alarms (page 839)

Fls AIN Prot 1

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 1
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm indicates that the value of general analog protection is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 2

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 2
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 2 is out of range or is missing.

O back to List of fail sensor alarms



Alarm Type	Fls
Alarmlist message	Fls + name of analog input 3
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 3 is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 4

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 4
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 4 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 5

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 5
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 5 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 6

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 6
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 6 is out of range or is missing.

back to List of fail sensor alarms



Alarm Type	Fls
Alarmlist message	Fls + name of analog input 7
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 7 is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 8

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 8
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 8 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 9

Alarm Type	FIs
Alarmlist message	Fls + name of analog input 9
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 9 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 10

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 10
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 10 is out of range or is missing.

O back to List of fail sensor alarms



Alarm Type	Fls
Alarmlist message	Fls + name of analog input 11
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 11 is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 12

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 12
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 12 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 13

Alarm Type	FIs
Alarmlist message	Fls + name of analog input 13
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 13 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 14

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 14
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 14 is out of range or is missing.

O back to List of fail sensor alarms



Alarm Type	Fls
Alarmlist message	Fls + name of analog input 15
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 15 is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 16

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 16
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 16 is out of range or is missing.

back to List of fail sensor alarms

Fls AIN Protect 17

Alarm Type	FIs
Alarmlist message	Fls + name of analog input 17
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 17 is out of range or is missing.

back to List of fail sensor alarms

FIs AIN Protect 18

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 18
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 18 is out of range or is missing.

back to List of fail sensor alarms



Alarm Type	Fls
Alarmlist message	Fls + name of analog input 19
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 19 is out of range or is missing.

O back to List of fail sensor alarms

FIs AIN Protect 20

Alarm Type	Fls
Alarmlist message	Fls + name of analog input 20
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of analog input 20 is out of range or is missing.

back to List of fail sensor alarms

Fls Oil Pressure

Alarm Type	FIs
Alarmlist message	Fls Oil Pressure
Alarm evaluated	All the time
Related applications	MINT, SPtM
Description	This alarm occurs when measurement value of oil pressure is out of range or is missing.

O back to List of fail sensor alarms



9.3 AVR interfaces

IMPORTANT: Read carefully AVR instructions before connecting to a controller! It is not sufficient to use suggested wiring settings, it is necessary as well to adjust AVR settings!

9.3.1 AVR interfaces alphabetically

AVK Newage Cosimat N+



AVK Newage MA330, 327, 321, 341



Basler: APR 63-5, AEC 63-7, KR-FX, KR-FFX



AVRi output is connected instead of external resistor for voltage adjusting.

Basler: DECS 100



ComAp >

Basler: DECS 200



Catterpillar CDVR



Pin 44 on DVR – PF regulation directly from DVR is not connected.

Catterpillar DVR



 ${\sf Pin}\,44\,{\sf on}\,{\sf DVR-PF}\,{\sf regulation}\,{\sf directly}\,{\sf from}\,{\sf DVR}\,{\sf is}\,{\sf not}\,{\sf connected}.$

Catterpillar VR6, VR3F



For VR3F link 4-7 has to be removed.

Catterpillar VR6-B



ENGGA WT-2



ENGGA WT-3



KATO KCR 360



KATO KCR 760



KATO KCR K-65-12B



ComAp >

ComAp

Kutai EA448



AVRi output is connected instead Remote voltage trimmer 470 Ω to terminal ST4. Module R726 is not required.

Leroy Somer: R 129



Voltage Control:

Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 1.00 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

Voltage Regulator Character = POSITIVE

Voltage Regulator Bias = 1.00 V

Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

AVRi output is connected instead Remote voltage trimmer 470 Ω to terminal J2. module R726 is not required.

Leroy Somer: R 221, R 222





Leroy Somer: R 230



Leroy Somer: R 230



ComAp >

Leroy Somer: R 250



Leroy Somer: R 438 LS, R448



AVRi output is connected (Undefined variable: Specific.Remote Voltage trimmer 470 Ω to terminals) ST4. (Undefined variable: Specific.Module R726 is not reauired.).

Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 1.00 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

Leroy Somer: R 449



Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 0.00 V Voltage Regulator Low Limit = -2.00 V Voltage Regulator High Limit = 2.00 V

Module R726 is not required..

Leroy Somer: R 450



Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 1.00 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

Use Avri instead pf potentiometer 1000 $\Omega.$ Read Leroy Somer R 450 manual before use.

Marathon DVR2000E



ComAp >

Marathon PM100, 200



MarelliGenerators MARK 5 (M16FA655A)



MarelliMotori (M40FA610A)



MarelliMotori Mark I (M40FA640A/A)



Mecc Alte Der 1





Mecc Alte DSR



range of up to $\pm 10\%$ (parameter 16, by default the setting is $\pm 5\%$) with respect to the value set. If you want to use continuous voltage, it will be effective if it is in the range between 0 V and +2,5 V. The input tolerates voltages from -5 V to +5 V, but for values exceeding the limits of 0 V / +2,5 V (or in the event of disconnection) it is automatically disabled and the voltage adjustment goes back to the value set through the trimmer (if enabled) or through parameter 19 (as shown on the picture). Changing of DSR parameters requires PC with dedicated software and DI1-DSR unit! DSR automatically detects presence of transformer for parallel operation (if used it works with droop, if not used it works isochronous).

Mecc Alte Spa: S.R:7/2



ComAp

Mecc Alte Spa U.V.R.6



AVRi output is connected instead Remote voltage trimmer 100 Kohm (T55 OUT = top position wire and T54 COM = second top position).

Newer Leroy Somer



Voltage Control:

Voltage Regulator Character = NEGATIVE Voltage Regulator Bias = 7.50 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 10.00 V

Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 0.00 V Voltage Regulator Low Limit = -2.50 V Voltage Regulator High Limit = 2.50 V

Regulation signal +/- 0...2,5 V

Piller



Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = -0.44 V Voltage Regulator Low Limit = -2.00 V Voltage Regulator High Limit = 2.00 V

AVRi output is connected instead Remote voltage trimmer 100 k Ω .

SINCRO AVR BL4 or AVR BL3



Stamford AS480



Voltage Control: Voltage Regulator Character = NEGATIVE

Voltage Regulator Bias = 1.00 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

AVRi output is connected instead of external resistor for voltage adjusting.

ComAp >

Stamfrod MX 341



Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 1.00 V Voltage Regulator Low Limit = 0.00 V Voltage Regulator High Limit = 2.00 V

Disconnect the droop CT (terminal S1&S2) and short the droop CT leads.

Stamford SX 440, AS 440, MX 321, SX 421



Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 0.00 V Voltage Regulator Low Limit = -2.00 V Voltage Regulator High Limit = 2.00 V

PFC3 module is not required.

Stamford SX 460



AVRi output is connected instead of external resistor for voltage adjusting.

Voltage Control:

Voltage Regulator Character = POSITIVE Voltage Regulator Bias = 0.00 V Voltage Regulator Low Limit = -2.00 V Voltage Regulator High Limit = 2.00 V

O back to Appendix



9.4 Speed governor interfaces

IMPORTANT: Read carefully Speed governor instructions before connecting controller Speed governor interface! It is not sufficient to use suggested wiring settings, it is necessary as well to adjust speed governor settings!

9.4.1 Electronic engines interface

All below mentioned interface examples describe analog interface even if they are (in some cases) used for Electronic Control Units (electronic engines) with CAN data bus. There are several possibilities to connect CAN bus interface between Electronic engine and ComAp controller. Refer to ComAp Electronic Engines Support manual.

9.4.2 Controller Speed Regulator Output voltage limits

Setpoints **Sync/Load Control:** Speed Governor Low Limit [0.01 V] and Speed Governor High Limit [0.01 V] limit low and high levels of output voltage. E.g. instead of full -10 V to +10 V Speed governor output range can be set Speed Governor Low Limit = 0.00 V and Speed Governor High Limit = 5.00 V to reduce the output range from 0 to 5 V.

9.4.3 Speed governors interfaces alphabetically

Barber Colman DYN1 10684



Barber Colman DYNA 8000



Caterpillar ADEM + Signal convertor





Caterpillar ADEM



Caterpillar PEEC + Signal convertor



Caterpillar PEEC



Caterpillar Signal Converter





Cummins ECPG



Cummins EFC



Cummins GCS



Cummins ONAN





Cummins QSL9



Cummins QST30



DEUTZ BF6M



ECON 4





GAC EGS 104B



GAC ESD 5330



GAC ESD 5500



GAC SDG 735





Heinzmann E6



Heinzmann E16



Heinzmann KG-1-03F



Heinzmann PANDAROS DC6





Heinzmann PANDAROS DC6



MTU MDEC 2000, 4000



PERKINS 1300 EDi



PERKINS 2300, 2800





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WOODWARD 2301A LS and Speed



WOODWARD 2301A Speed Control



WOODWARD 2301D Speed Control





WOODWARD DPG 2201



WOODWARD EPG 1712/512 (1724/524)



WOODWARD EPG



WOODWARD Flo - tech Speed Control




WOODWARD L - series



WOODWARD Proact II



back to Appendix

9.5 Modules

9.5.1 Plug-In modules	
9.5.2 CAN modules	

9.5.1 Plug-In modules

Communication modules	
Extension modules	

IMPORTANT: 2nd generation of InteliGen 500 controllers does not support new modules and 3rd generation does not support all old modules.

The available communication plug-in modules are:

- CM-RS232-485 communication module for connection via RS232 or RS485 line
- CM-4G-GPS communication module for connection via 4G
- CM-GPRS communication module for connection via GPRS
- Ethernet communication module for internet connection via Ethernet

The available extension plug-in modules are:

EM-BIO8-EFCP - extension module with 8 binary inputs/outputs

Note: Controller has plug-in module slot.

Communication modules

CM-RS232-485	66
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ComAp >

CM-GPRS	
CM-4G-GPS	

CM-RS232-485

CM-RS232-485 is optional plug-in card to enable InteliGen 500 the RS232 and RS485 communication. This is required for computer or MODBUS connection. The CM-RS232-485 is a dual port module with RS232 and RS485 interfaces at independent COM channels. The RS232 is connected to COM1 and RS485 to COM2.



Image 9.218 CM-RS232-485 interface

IMPORTANT: Any manipulation with plug-in module shall be done with disconnected power supply to controller.





SERIAL "CROSS-WIRED" CABLE



Image 9.219 Pinout of RS-232 line

GND

DTF

TxD

RxD

DCD









Balancing resistor GND

Image	9.221	Jumpers	description
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Note: Balancing resistors shall be both closed at only one device in whole RS485 network.

Maximal distance of line is 10m for RS232 line and 1200m for RS485 line.

Terminator 120Ω

Balancing resistor +5V

Technical data

Power consumption	40 mA / 8 VDC
	26 mA / 12 VDC
	14 mA / 24 VDC
	10 mA / 36 VDC
Isolation	Galvanic separation

Firmware upgrade

- Download the newest FW of module from ComAp website (in form of PSI file or installation package)
- Instal package to computer or open PSI to instal it into InteliConfig
- Plug the module into the controller and power the controller on.
- Open a connection with controller via InteliConfig
- ▶ Go the menu Tools -> Firmware upgrade, select the Plug-in modules tab and select the appropriate firmware



you want to program into the module (in InteliConfig).

Press the OK button to start upgrade of firmware.

The firmware update process may be performed via any kind of connection including connection via the same module in which the firmware is to be updated. The connection is reestablished again automatically when the update process is finished.

CM-GPRS



Image 9.222 CM-GPRS module

IMPORTANT: Any manipulation with plug-in module shall be done with disconnected power supply to controller.

IMPORTANT: CM-4G-GPS and CM-GPRS modules can't be used in one controller in the same time.

Note: GPRS and CSD services must be provided by your GSM/GPRS operator for successful operation.

Note: The GPRS and CSD connection should not be used for the firmware update process.

Technical data

Power consumption	32 mA / 8 VDC
	18 mA / 12 VDC
	10 mA / 24 VDC
	12 mA / 36 VDC

SIM card settings

SIM card to be used in CM-4G-GPS or CM-GPRS modules must be adjusted as follows:

- SMS service enabled
- Packet data (Internet access) enabled (when required for the selected mode of operation)
- PIN code security disabled

How to start using CM-GPRS module

> You will need a controller, CM-GPRS module, antenna and SIM card with SMS and packet data service.

Make sure that your SIM supports the packet data network type you want to use. I.e. if you want to use the module in GPRS (2,5G) network you have to confirm with the operator that the particular SIM card does support 2,5G network.



- Make sure SIM card does not require PIN code. Use any mobile phone to switch the SIM PIN security off.
- Place the SIM card into slot on CM-GPRS card
- Connect the antenna to Cellular module antenna connector.
- Switch off the controller.
- Insert CM-GPRS module into controller
- Power up the controller.



Image 9.223 Main screen of CM-GPRS module

GSM Diag Code - Diagnostic code for CM-GPRS modem

GSM Diag Code – Common list of diagnostic codes for cellular modules

Code	Description
0	OK. No error.
1	Not possible to hang up.
2	Modul is switched off
3	Module is switched on
4	Module – error in initialization
5	Module – not possible to set the APN
6	Module – not possible to connect to GPRS network
7	Module – not possible to retrieve IP address
8	Module – not accepted DNS IP address
9	Error in modem detection
10	Error in initialization of analog modem
11	SIM card is locked (Possibly PIN code required, PIN needs to be deactivated) or unknown status of SIM locking
12	No GSM signal
13	Not possible to read the SIM card parameters
14	GSM modem did not accepted particular initialization command, possibly caused by locked SIM card
15	Unknown modem
16	Bad answer to complement initialization string



17	Not possible to read GSM signal strength
18	CDMA modem not detected
19	No CDMA network
20	Unsuccessful registration to CDMA network
21	SIMCom/ME909s: can't read FW version
22	SIMCom: GSM signal not found
23	SIMCom: can't detect module speed
24	SIMCom: HW reset issued
25	PUK is required
26	Error of SIM card detected
27	ME909s: can't set module bps
28	ME909s: can't set link configuration
29	ME909s: can't do power-off
30	ME909s: can't do power-on
31	ME909s: can't do hardware reset
32	ME909s: ME909s not started
33	ME909s: switch off issued
34	ME909s: switch on issued
35	ME909s: HW reset issued
36	ME909s: can't switch echo off
37	ME909s: can't find out state of registration
38	ME909s: GSM signal not found
39	ME909s: no SIM memory for SMS
40	ME909s: waiting for registration
41	Can't read operator name
42	ME909s: can't set flow control
43	APN not typed
255	Only running communication is needed to indicate

Firmware upgrade

- > Download the newest FW of module from ComAp website (in form of PSI file or installation package)
- Instal package to computer or open PSI to instal it into InteliConfig
- Plug the module into the controller and power the controller on.
- Open a connection with controller via InteliConfig
- Go the menu Tools -> Firmware upgrade, select the Plug-in modules tab and select the appropriate firmware you want to program into the module (in InteliConfig).
- Press the OK button to start upgrade of firmware.

The firmware update process may be performed via any kind of connection including connection via the same module in which the firmware is to be updated. The connection is reestablished again automatically when the update process is finished.



CM-4G-GPS



Image 9.224 CM-4G-GPS module

IMPORTANT: Any manipulation with plug-in module shall be done with disconnected power supply to controller.

IMPORTANT: CM-4G-GPS and CM-GPRS modules cant be used in one controller in the same time.

IMPORTANT: Operating temperature of module is from -30°C to +75°C.

Note: Cellular data service must be enabled in your SIM card by your mobile operator for successful operation.

Supported 4G bands are as follows:

- FDD LTE: Band 1, Band 2, Band 3, Band 4, Band 5, Band 7, Band 8, Band 20, all bands with diversity
- WCDMA/HSDPA/HSUPA/HSPA+: Band 1, Band 2, Band 5, Band 8, all bands with diversity
- GSM/GPRS/EDGE: 850 MHz/900 MHz/1800 MHz/1900 MHz

Technical data

Power consumption	55 mA / 8 VDC
	35 mA / 12 VDC
	8 mA / 24 VDC
	5 mA / 36 VDC

SIM card settings

SIM card to be used in CM-4G-GPS or CM-GPRS modules must be adjusted as follows:

- SMS service enabled
- Packet data (Internet access) enabled (when required for the selected mode of operation)
- PIN code security disabled

How to start using CM-4G-GPS module

> You will need a controller, CM-4G-GPS module, antenna and SIM card with SMS and packet data service.

Note: Make sure that your SIM supports the packet data network type you want to use. - i.e. if you want to use the module in LTE (4G) network you have to confirm with the operator that the particular SIM card supports 4G network.

- Make sure SIM card does not require PIN code. Use any mobile phone to switch the SIM PIN security off.
- Place the SIM card into slot on CM-4G-GPS card



- Connect the antenna to Cellular module antenna connector.
- Switch off the controller.
- Insert CM-4G-GPS module into controller
- Power up the controller.



Image 9.225 Main screen of CM-4G-GPS module

GSM Diag Code - Common list of diagnostic codes for cellular modules

GSM Diag Code - Common list of diagnostic codes for cellular modules

Code	Description
0	OK. No error.
1	Not possible to hang up.
2	Modul is switched off
3	Module is switched on
4	Module – error in initialization
5	Module – not possible to set the APN
6	Module – not possible to connect to GPRS network
7	Module – not possible to retrieve IP address
8	Module – not accepted DNS IP address
9	Error in modem detection
10	Error in initialization of analog modem
11	SIM card is locked (Possibly PIN code required, PIN needs to be deactivated) or unknown status of SIM locking
12	No GSM signal
13	Not possible to read the SIM card parameters
14	GSM modem did not accepted particular initialization command, possibly caused by locked SIM card
15	Unknown modem
16	Bad answer to complement initialization string
17	Not possible to read GSM signal strength
18	CDMA modem not detected



19	No CDMA network
20	Unsuccessful registration to CDMA network
21	SIMCom/ME909s: can't read FW version
22	SIMCom: GSM signal not found
23	SIMCom: can't detect module speed
24	SIMCom: HW reset issued
25	PUK is required
26	Error of SIM card detected
27	ME909s: can't set module bps
28	ME909s: can't set link configuration
29	ME909s: can't do power-off
30	ME909s: can't do power-on
31	ME909s: can't do hardware reset
32	ME909s: ME909s not started
33	ME909s: switch off issued
34	ME909s: switch on issued
35	ME909s: HW reset issued
36	ME909s: can't switch echo off
37	ME909s: can't find out state of registration
38	ME909s: GSM signal not found
39	ME909s: no SIM memory for SMS
40	ME909s: waiting for registration
41	Can't read operator name
42	ME909s: can't set flow control
43	APN not typed
255	Only running communication is needed to indicate

Firmware upgrade

- Download the newest FW of module from ComAp website (in form of PSI file or installation package)
- Instal package to computer or open PSI to instal it into InteliConfig
- Plug the module into the controller and power the controller on.
- Open a connection with controller via InteliConfig
- Go the menu Tools -> Firmware upgrade, select the Plug-in modules tab and select the appropriate firmware you want to program into the module (in InteliConfig).
- Press the OK button to start upgrade of firmware.

The firmware update process may be performed via any kind of connection including connection via the same module in which the firmware is to be updated. The connection is reestablished again automatically when the update process is finished.

Extension modules

EM-BIO8-EFCP	74
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EM-BIO8-EFCP

EM-BIO8-EFCP is optional plug-in card. Through this card controller can accommodate up to 8 binary inputs or outputs. In InteliConfig PC configuration tool it is possible to easily choose if particular I/O will be binary input or output.



Image 9.226 EM-BIO8-EFCP interface

IMPORTANT: Any manipulation with plug-in module shall be done with disconnected power supply to controller.



Image 9.227 Overview of EM-BIO8-EFCP





Image 9.228 EM-BIO8-EFCP wiring

EM-BIO8-EFCP technical data

Power supply

Power supply range	8-36 VDC
Power consumption	40 mA / 8 VDC
	27 mA / 12 VDC
	22 mA / 24 VDC
	19 mA / 36 VDC

Binary inputs

Number	Up to 8, non-isolated
Close/Open indication	0-2 VDC close contact
	>6 VDC open contact

Binary outputs

Number	Up to 8 , non-isolated
Max. current	0,5A
Switching to	positive supply terminal

Earth fault current measurement

The Earth Fault protection is done by the extension module EM-BIO8-EFCP.

When the measured current exceeds the set value, which indicates that part of the current is dispersed to earth, and when the set Earth Fault Delay (page 490) time elapses, the Earth Fault Current Protection (page 489), Sd Earth Fault Current (page 822) alarm and AL EARTH FAULT (PAGE 688) output are activated. Earth Fault protection is not active when gen-set does not run and when the Earth Fault Current Protection (page 489) is disabled.

IMPORTANT: Earth fault current measurement is not intended to protect human health, but the machines!





Image 9.229 Earth fault current protection

Firmware upgrade

- > Download the newest FW of module from ComAp website (in form of PSI file or installation package)
- Instal package to computer or open PSI to instal it into InteliConfig
- Plug the module into the controller and power the controller on.
- Open a connection with controller via InteliConfig
- Go the menu Tools -> Firmware upgrade, select the Plug-in modules tab and select the appropriate firmware you want to program into the module (in InteliConfig).
- Press the OK button to start upgrade of firmware.

The firmware update process may be performed via any kind of connection including connection via the same module in which the firmware is to be updated. The connection is reestablished again automatically when the update process is finished.

9.5.2 CAN modules

The available extension CAN modules are:

- Inteli AIN8 extension CAN module with 8 analog inputs
- Inteli IO8/8 extension CAN module with 8 binary inputs, 8 binary outputs and 2 analog outputs
 - this CAN module can be switched to Inteli IO16/0 extension CAN module with 16 binary inputs and 2 analog outputs

Supported combinations of modules

Slot	Inteli AIN8	Inteli AIN8TC	Inteli IO8/8	Inteli IO16/0	IGL-RA15	IGS-PTM	Inteli AIO9/1
1	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
1	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
3	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\times	\times



Slot	Inteli AIN8	Inteli AIN8TC	Inteli IO8/8	Inteli IO16/0	IGL-RA15	IGS-PTM	Inteli AIO9/1
4	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\times	\times
5	×	\times	\checkmark	\checkmark	\times	\times	\times

IMPORTANT: In slot 3, 4 and 5 CAN modules Inteli IO8/8 and Inteli IO16/0 are supported without analog outputs. Analog outputs of these CAN modules are supported only in slot 1 and 2.

It is possible to add up to 80 binary inputs or up to 68 binary outputs or up to 32 analog inputs on CAN modules.

Extension modules

Inteli AIN8	877
Inteli AIN8TC	883
Inteli IO8/8	886
IGS-PTM	893

Inteli AIN8

Inteli AIN8 module is extension module equipped with analog inputs. Inteli AIN8 module is connected to controller by CAN1 bus.



Image 9.230 Inteli AIN8





Image 9.231 Inteli AIN8 dimensions

Note: All dimensions are in mm.

Terminals



Analog input	8 analog Inputs
CAN	CAN1 line
Power	Power supply
CAN LED Tx, Rx	Indication transmitted or received data
Status LED	LED indication of correct function
CAN terminator	Terminating CAN resistor (active in position "ON" - switch both switches)



Analog inputs

- 8 channels
- can be configured as:
 - resistor three wire input
 - current input
 - voltage input

All inputs can be configured to any logical function or protection.

IMPORTANT: Impulse input is not supported in controller.

Supported sensors

Sensors				
User curves	NI100 [°F] (fix)	0-5V		
PT100 [°C] (fix)	NI1000 [°F] (fix)	0-10V		
PT1000 [°C] (fix)		4-20mA passive		
NI100 [°C] (fix)	0-2400ohm	4-20mA active		
NI1000 [°C] (fix)	0-10k ohm	0-20mA passive		
PT100 [°F] (fix)	+-1V	+-20mA active		
PT1000 [°F] (fix)	0-2.4V			

CAN address

DIP switch determinates CAN address for analog inputs.



Note: In case of setting the CAN address to zero, the appropriate group of signals is deactivated.

Programming firmware

Firmware upgrade process:

- 1. Disconnect all terminals from the unit.
- 2. Separate the top cover of module
- 3. Put the TEST jumper on a pins

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4. Connect the unit with PC via RS232-null modem cable and AT-Link conv



- 5. Connect power supply of the module (status LED lights continuously)
- 6. Launch FlashPgr.exe PC software (version 4.2 or higher)
- 7. In FlashPrg program choose card Inteli AIN8 and load FW for the module
- 8. Set the proper COM port (connected with the unit) and press Start button
- 9. Wait till process is done (If the process doesn't start after 60 second the "Timeout" will be evaluated. In this case please check:
 - You have proper connection with the unit
 - COM port selection is correct
 - Module has power supply, (no CAN bus connection, status LED lights continuously)
- 10. After successful programming disconnect AT-Link conv, remove TEST jumper and disconnect power supply
- 11. Connect power supply again (status LED should blinking)
- 12. Module FW is upgraded

LED indication

LED status	Description	
Dark	Fw in module does not work correctly.	
Flashing	Module does not communicate with controller (in case non-zero CAN address).	
Lights	Power supply is in the range and the communication between Intell AIN8 and controller works properly.	
	module doesn't communicate with the controller).	

Wiring

The following diagrams show the correct connection of sensors.







Resistance sensor - 3 wires



Note: Ranges: Pt100, Pt1000, Ni100, Ni1000, $0 - 2400 \Omega$, $0 - 10 k\Omega$

Resistance sensor - 2 wires



Note: Ranges: Pt100, Pt1000, Ni100, Ni1000, 0 – 2400 Ω, 0 – 10 kΩ



Note: Ranges: ±20 mA, 4 – 20 mA



Current sensor - passive



Note: Ranges: 0 – 20 mA, 4 – 20 mA

Voltage sensor



Note: Ranges: ±1 V, 0-2,5 V, 0-5 V, 0-10 V

Technical data

General data

Power supply	8 to 36 V DC
Current consumption	35 mA at 24 V ÷ 100 mA at 8 V
Interface to controller	CAN1
Protection	IP20
Storage temperature	- 40 °C to + 80 °C
Operating temperature	- 30 °C to + 70 °C
Dimensions (WxHxD)	110x110x46 mm (4,3"x4,3"x1,8")
Weight	221,5 grams

Analog inputs

Number of channels	8
Veltere	Range 0-10 V
voltage	Accuracy: $\pm 0,25$ % of actual value + ± 25 mV
Current	Range: ±20 mA



	Accuracy: $\pm0,25$ % of actual value + $\pm50\mu\text{A}$
Resistive	Range: 0- 10 kΩ
	Accuracy: $\pm 0,5$ % of actual value + $\pm 2 \Omega$

Inteli AIN8TC

Inteli AIN8TC module is extension module equipped with 8 analog inputs dedicated for thermocouple sensors only.

Inteli AIN8TC module is connected to controller by CAN1 bus.



Image 9.232 Inteli AIN8TC



Image 9.233 Inteli AIN8TC dimensions

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Terminals



Analog input	8 analog Inputs
CAN	CAN1 line
Power	Power supply
CAN LED Tx, Rx	Indication transmitted or received data
Status LED	LED indication of correct function
CAN terminator	Terminating CAN resistor (active in position "ON" - switch both switches)

Note: Impulse input is not supported.

Analog inputs

- 8 channels
- Can be configured as thermocouple sensors only

All inputs can be configured to any logical function or protection

Supported sensors

Sensors		
Thermocpl J [°C] (fix)	Thermocpl (nc) J [°C] (fix)	
Thermocpl K [°C] (fix)	Thermocpl (nc) K [°C] (fix)	
Thermocpl L [°C] (fix)	Thermocpl (nc) L [°C] (fix)	
Thermocpl J [°F] (fix)	Thermocpl (nc) J [°F] (fix)	
Thermocpl K [°F] (fix)	Thermocpl (nc) K [°F] (fix)	
Thermocpl L [°F] (fix)	Thermocpl (nc) L [°F] (fix)	



Note: "nc" means" not cold junction compensation (by external sensor). In this case is used internal temperature sensor on the PCB

CAN address

DIP switch determinates CAN address for analog inputs.



Note: In case of setting the CAN address to zero, the appropriate group of signals is deactivated.

Programming firmware

Firmware is upgraded via AT-link (TTL). For programming it is necessary to close jumper TEST.

For programming FlashProg PC tool version 4.2 or higher must be used.

LED indication

LED status	Description	
Dark	Fw in module does not work correctly.	
Flashing	Module does not communicate with controller (in case non-zero CAN address)	
Fast flashing	Detection of CAN communication speed	
Lights	Power supply is in the range and the communication between Inteli AIN8TC and controller works properly. Or power supply is in range and zero CAN address is set. (in case zero CAN address module doesn't communicate with the controller)	

Wiring

The following diagrams show the correct connection of sensors.

Thermocouple





Terminator



Technical data

General data

Power supply	8 to 36 V DC
Current consumption	35 mA at 24 V ÷ 100 mA at 8 V
Interface to controller	CAN1
Protection	IP20
Storage temperature	- 40 °C to + 80 °C
Operating temperature	- 30 °C to + 70 °C
Dimensions (WxHxD)	110 × 110 × 46 mm (4.3" × 4.3" × 1.8")
Weight	237.5 grams

Analog inputs

Number of channels	8, no galvanic separated
	Range: ± 100 mV
Voltage	Accuracy: ± 0.1 % of actual value + $\pm 100 \mu$ V
	(±3°C)

Inteli IO8/8

Inteli IO8/8 module is an extension module equipped with binary inputs, binary outputs and analog outputs.

Inteli IO8/8 is the name of the module, but it is possible to configure the module (by internal switch) to two configurations:

- Inteli IO8/8 8 binary inputs, 8 binary outputs and 2 analog outputs
- Inteli IO16/0 16 binary inputs, 0 binary outputs and 2 analog outputs

The detection of communication speed is indicated by fast flashing of status LED. Once the speed is detected the module remains set for the speed even when the communication is lost. Renewal of communication speed detection is done by reset of the module.





Image 9.234 Inteli IO8/8



Image 9.235 Inteli IO8/8 dimensions

Note: All dimensions are in mm.

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Terminals



Binary inputs	8 binary inputs
Binary outputs	8 binary outputs (8 binary inputs)
Analog outputs	2 analog outputs
CAN	CAN1 line
Power	Power supply
Binary inputs LEDs	8 LEDs for binary input indication
Binary outputs LEDs	8 LEDs for binary output indication
CAN LED	Indication transmitted or received data
Status	LED indication of correct function
CAN terminator	Terminating CAN resistor (active in position "ON" - switch both switches)

Inputs and outputs

Binary inputs

- 8 channels
- can be configured as:
 - pull up
 - pull down

All 8 inputs are configured to one type together.

All inputs can be configured to any logical function or protection.

Binary outputs



- 8 channels
- can be configured as:
 - High side switch
 - Low side switch

Always all 8 inputs are configured to one type (HSS/LSS) together. All 8 outputs can be modified to inputs by switch on the PCB (Inteli IO8/8 to Inteli IO16/0).

Analog outputs

- 2 channels
- can be configured as:
 - voltage 0-10V
 - current 0-20mA
 - PWM (level 5V, with adjustable frequency from 200Hz to 2400Hz, with step 1Hz)

All inputs/outputs can be configured to any logical function or protection.

Output state check

Output state check function evaluates in real time the state of binary outputs and adjusted (required) state. In case of failure (different state of required state and real state) history record and alarm are issued (type of the alarm is set by "Protection upon module failure" - (No protection / Warning / Shutdown)).

This function is designed for short-circuit or other failure, which causes change of set state of binary output.

CAN address

In Inteli IO8/8 mode CAN address for binary inputs is determined by DIP switch A, CAN address for binary output and analog outputs is determined by DIP switch B.

In Inteli IO16/0 mode CAN address for binary inputs is determined by DIP switch A, first group of 8 input has address A, second group of 8 inputs has address A+1. CAN address of analog outputs is set by DIP switch B.



Note: In case of setting the CAN address to zero, the appropriate group of signals is deactivated.

Programming firmware

Firmware upgrade process:

- 1. Disconnect all terminals from the unit.
- 2. Separate the top cover of module
- 3. Put the TEST jumper on a pins

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4. Connect the unit with PC via RS232-null modem cable and AT-Link conv



- 5. Connect power supply of the module (status LED lights continuously)
- 6. Launch FlashPgr.exe PC software (version 4.2 or higher)
- 7. In FlashPrg program choose card Inteli IO8/8 and load FW for the module
- 8. Set the proper COM port (connected with the unit) and press Start button
- 9. Wait till process is done (If the process doesn't start after 60 second the "Timeout" will be evaluated. In this case please check:
 - You have proper connection with the unit
 - COM port selection is correct
 - Module has power supply, (no CAN bus connection, status LED lights continuously)
- 10. After successful programming disconnect AT-Link conv, remove TEST jumper and disconnect power supply
- 11. Connect power supply again (status LED should blinking)
- 12. Module FW is upgraded

LED indication

Binary input

Each binary input has LED which indicates input signal. LED is shining when input signal is set, and LED is dark while input signal has other state.

Binary output

Each binary output has LED which indicates output signal. Binary output LED is shining when binary output is set. When this LED is shining, then module is configured as 8 binary inputs and 8 binary outputs. When this LED is dark, then the module is configured as 16 binary inputs.

LED at power connector - status LED



LED status	Description	
Dark	Fw in module does not work correctly.	
Flashing	Module does not communicate with controller (in case non-zero CAN address).	
Lights	Power supply is in the range and the communication between Inteli IO8/8 and controller works properly.	
Ū	Or power supply is in range and zero CAN address is set. (in case zero CAN address module doesn't communicate with the controller).	

Wiring

The following diagrams show the correct connection of inputs and outputs.

Binary inputs - pull up



There are two options of wiring. On upper picture you can see case when binary input is connected between BIN2 and COM (COM is connected internally to the GND (-) - dashed line).

On lower picture is case of wiring between BIN2 and GND (-). Both ways are correct.

Binary inputs - pull down



There are two options of wiring. On upper picture you can see case when binary input is connected between BIN2 and COM (COM is connected internally to the Ucc (+) - dashed line).

On lower picture is case of wiring between BIN2 and Ucc (+). Both ways are correct.



Binary outputs - high side



When high side setting of outputs is chosen - binary output must be connected to the minus potential directly Terminal VHS (voltage High side) has to be connected to positive potential directly. Maximal current of each binary output is 500 mA. Size of fuse depends on load.

Binary outputs - low side



When low side setting of outputs is chosen - binary output must be connected to the plus potential of power supply directly. Minus potential is connected internally - dashed line.

Analog outputs



Note: Limit of analog ground (AGND) is 100mA.

IMPORTANT: Terminator for analog output has special analog ground (AGND), which must not be connected to the GND.

Technical data

General data

Power supply	8 to 36 V DC
Current consumption	35 mA at 24 V ÷ 100 mA at 8 V
Interface to controller	CAN1
Protection	IP20
Storage temperature	- 40 °C to + 80 °C



Operating temperature	- 30 °C to + 70 °C
Dimensions (WxHxD)	110x110x46 mm (4,3"x4,3"x1,8")
Weight	240 grams

Analog outputs

Number of channels	2
	Range 0-10 V
Voltage	Accuracy: $\pm 20 \text{ mV} + \pm 0,5 \%$ of actual value
	Imax 5 mA
	Range: 0-20 mA
Current	Accuracy: \pm 100 μ A + \pm 0,5 % of actual value
	Rmax 500 Ω
	Level 5 V
PWM	Frequency - adjustable 200÷2400 Hz
	Imax 20 mA

Binary inputs

Number of channels	8 for Inteli IO8/8, 16 for Inteli IO16/0
Input resistance	4400 Ω
Input range	0 to 36 V DC
Switching voltage level for open contact indication	0 to 2 V DC
Max voltage level for close contact indication	6 to 36 V DC

Binary outputs

Number of channels	8 for Inteli IO8/8, 0 for Inteli IO16/0
Max current	500 mA
Max switching voltage	36 V DC

IGS-PTM

IGS-PTM module is extension module equipped with binary inputs, binary outputs, analog inputs and analog output. IGS-PTM module is connected to controller by CAN1 bus.





Image 9.236 IGS-PTM



Image 9.237 IGS-PTM dimensions



Terminals



Binary inputs	8 binary inputs	
Analog inputs	4 analog inputs	
Analog outputs	1 analog output	
Binary outputs	8 binary outputs	
CAN	CAN1 line	
RS232-TTL	Interface for programming	
Power	Power supply	

Analog inputs

Analog inputs can be configured for:

- Resistance measurement
- Current measurement
- Voltage measurement

The type of analog inputs is configured via jumpers RUI located on lower PCB.

RUI	Analog input configuration
1-2	Resistance measuring
2-3	Current measuring
no jumper	Voltage measuring

Supported sensors

Sensors		
PT100 [°C] (fix)	User curves	
NI100 [°C] (fix)	0-100 mV	
PT100 [°F] (fix)	0-2400 ohm	
NI100 [°F] (fix)	±20 mA	



CAN address

Controller type selection

The type of controller to be used with IGS-PTM must be selected via jumper labeled IGS accessible at the lower PCB.

IGS jumper	Controller type
OPEN	IL-NT, IC-NT
CLOSE	IG-NT, IS-NT, InteliGen

Address configuration

If InteliGen controller type is selected (by IGS jumper), address of IGS-PTM could be modified via jumpers labeled ADR1 and ADR2.

ADR1	ADR2	ADR offset	BIN module	BOUT module	AIN module
Open	Open	0 (default)	1	1	1
Close	Open	1	2	2	2
Open	Close	2	3	3	3
Close	Close	3	4	4	4

Programing firmware

Firmware upgrade is via AT-link (TTL). For programming is necessary to close jumper BOOT. RESET jumper is used to reset the device. Close jumper to reset the device. For programming is used FlashProg PC tool.

LED indication

Binary input

Each binary input has LED which indicates input signal. LED is shining when input signal is set, and LED is dark while input signal has other state.

Binary output

Each binary output has LED which indicates output signal. Binary output LED is shining when binary output is set.

LED at power connector - status LED

LED status	Description
Dark	No required power connected.
Quick flashing	Program check failure.
One flash and pause	Compensation fail.
Three flashes and pause	Compensation successful.
Flashes	There is no communication between IGS-PTM and the controller.
Lights	Power supply is in the range and communication between IGS-PTM and controller properly works.



Wiring

Binary inputs



Binary outputs



Resistance sensor



Note: Range: 0- 2400 Ω

IMPORTANT: Physical analog input range is 0-250 Ω . In sensor configuration in PC tool it is necessary to chose 0-2400 Ω sensor HW type to ensure proper function of analog input.



Note: Range 0-100 mV



Current sensor - passive



Note: Range: ± 0-20 mA

IMPORTANT: Physical analog input range is 0-20mA. In sensor configuration in PC tool it is necessary to chose +- 20mA active sensor HW type to ensure proper function of analog input.

Analog outputs

Analog output



Note: Range: 0 to 20 mA ± 0,33 mA

Technical data

General data

Power supply	8 to 36 V DC
Current consumption	100 mA at 24V ÷ 500 mA
Interface to controller	CAN1
Protection	IP20
Storage temperature	- 40 °C to + 80 °C
Operating temperature	- 30 °C to + 70 °C
Dimensions (WxHxD)	95×96×43 mm (3.7'×3.8'×1.7')

Analog inputs

Number of channels	8
Voltage	Range 0-100 mV
	Accuracy: 1,5 % \pm 1 mV out of measured value
Current	Range: 0-20 mA
	Accuracy: 2.5 $\%$ ± 0,5 ohm out of measured value
Resistive	Range: 0- 250 Ω
	Accuracy: 1 % \pm 2 ohm out of measured value



Analog outputs

Number of channels	1
Current	Range: 0 to 20 mA ± 0,33 mA
	Resolution 10 bit

Binary inputs

Number of channels	8
Input resistance	4700 Ω
Input range	0 to 36 V DC
Switching voltage level for open contact indication	0 to 2 V DC
Max voltage level for close contact indication	8 to 36 V DC

Binary outputs

Number of channels	8
Max current	500 mA
Max switching voltage	36 V DC
Number of channels	8
Voltage	Range 0-100 mV
	Accuracy: 1,5 % \pm 1 mV out of measured value
Current	Range: 0-20 mA
	Accuracy: 2.5 $\%$ ± 0,5 ohm out of measured value
Resistive	Range: 0- 250 Ω
	Accuracy: 1 % \pm 2 ohm out of measured value

IGL-RA15

Remote annunciator (IGL-RA15) is designed as an extension signaling unit.

The unit is equipped with a fully configurable tri color (red, orange, green) LED for intuitive operation together with high functionality.



Image 9.238 IGL-RA15





Image 9.239 IGL-RA15 dimensions

Terminals

Horn	Horn
CAN	CAN1 line
Power	Power supply

CAN address

Address	Jumper A	Jumper B
1	OPEN	OPEN
5+6	CLOSED	OPEN
Customer defined	CLOSED	CLOSED

SW changing of CAN1 address is enabled only when both jumpers are closed. Any one of these addresses (1+2 or 3+4 or 5+6 or 7+8) can be set by following steps:

- Switch to programming mode (Hold the Horn reset and Lamp test when unit is powering on). Status led is yellow
- Press Lamp test sixteen times
- Set the address up by pressing Horn reset.
 - The number of red luminous LEDs means the CAN1 addresses (two for addresses 1+2, four for addresses 3+4, six for addresses 5+6 and eight for addresses 7+8)
- Press Lamp test

LED indication

Each LED color is adjusted independently of controller output settings. If controller output 1 is set as "Common Shutdown" it doesn't mean red LED1 color for iGL-RA15. The LEDs color can by adjust by following steps:

- Switch to programming mode (Hold the Horn reset and Lamp test when unit is powering on). Status led is yellow
- Press Horn reset to change the LED1 color (green, yellow, red)


- Press Lamp test to switch to the next LED color adjusting
- Continue to adjust all LEDs color
- After LED15 color adjusting press three times Lamp test

Note: If there is no operator action during address setting, color adjusting or timeout setting, the unit returns to normal operation without changes saving.

Status LED

The signals LEDs are handled like binary outputs. It means all what can be configured to binary outputs can be also configured to the LEDs of IGL-RA15.

LED status	Description
Lights	Configured logical output is active on the controller
Dark green LED	Configured logical output is not active on the controller
Dark yellow or red LED	Configured logical output is not active on the controller and horn reset was pressed.
Yellow or red LED blinks	Configured logical output is not active on the controller and horn reset was still not pressed.

Power LED

LED status	Description
Blinking green	The unit is OK and the communication to the master controller is OK.
Blinking red	The unit is OK, but the communication to the master controller is not running.
Blinking yellow	EEPROM check not passed OK after power on
Yellow	Horn timeout or controller address adjustment

Horn setting

The horn output is activated if any of red or yellow LED is on. Output is on until pressing Horn reset or horn timeout counts down. The timeout can by set by following steps:

- Switch to programming mode (Hold the Horn reset and Lamp test when unit is powering on). Status led is yellow
- Press Lamp test fifteen times
- Set the horn timeout by pressing Horn reset.
 - The number of green luminous LEDs means timeout in 10 s (any for disabling horn output, 1 for 10s timeout, 2 for 10s timeout, 15 for disabling horn timeout).
 - Press Lamp test two times

Note: If there is no operator action during address setting, color adjusting or timeout setting, the unit returns to normal operation without changes saving.

The horn is activated if:

- Some of red or yellow LED lights up or
- At the end of the extended lamp test. See chapter Lamp and horn test (page 902)

The horn can be silenced:



- By pressing horn reset button or
- It silences automatically after adjusted time

Lamp and horn test

Pressing and holding lamp test button for less than 2 s execute the basic lamp test. All LEDs light up with the configured colour. If the button is hold longer than 2 s, an extended test is started. Every LED is tested step-by-step in green colour and then in red colour. The horn is activated at the end of the test. After that the unit returns to normal operation. The horn can be silenced with horn reset.

Wiring



* terminator resistor only when iGL-RA 15 is the last unit on the CAN1 bus.

Note: The shielding of the CAN bus cable has to be grounded at one point only!

Note: See the section Technical data (page 902) for recommended CAN bus cable type

Technical data

General data

Power supply	8 to 36 V DC
Current consumption	0.35-0.1A (+1Amax horn output) depends on supply voltage
Protection	IP65
Humidity	85%
Storage temperature	- 30 °C to + 80 °C
Operating temperature	- 20 °C to + 70 °C
Dimensions (WxHxD)	180x120x55 mm
Weight	950 g



Horn output

Horn output	
Maximum current	1.0 A
Maximum switching voltage	36 V DC

CAN bus interface

Galvanic separated			
Maximal CAN bus length	200 m		
Speed	250 kBd		
Nominal impedance	120 Ω		
Cable type	twisted pair (shielded)		
Following dynamic cable parameters are important especially for maximal 200 meters CAN bus length			
Nominal Velocity of Propagation	min. 75 % (max. 4,4 ns/m)		
Wire crosscut	min.0,25 mm ²		
Maximal attenuation (at 1 MHz)	2 dB/100m		
Recommended Industrial Automation & Process Control Cables			
	3082A DeviceBus for Allen-Bradley DeviceNet		
	3083A DeviceBus for Allen-Bradley DeviceNet		
	3086A DeviceBus for Honeywell SDS		
BELDEN (www.belden.com)	3087A DeviceBus for Honeywell SDS		
	3084A DeviceBus for Allen-Bradley DeviceNet		
	3085A DeviceBus for Allen-Bradley DeviceNet		
	3105A Paired EIA Industrial RS485 cable		
	Unitronic BUS DeviceNet Trunk Cable		
	Unitronic BUS DeviceNet Drop Cable		
LAPP CABLE (www.iappcable.com)	Unitronic BUS CAN		
	Unitronic-FD BUS P CAN UL/CSA		